TODO

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1 Summary

1.1 Context and background

Lacotte et al. [7] study the performance of iterative Hessian sketch (IHS) [10] for overdetermined least squares problems of the form

$$\mathbf{b}^* = \arg \min_{\mathbf{b} \in \mathbb{R}^d} \left\{ f(\mathbf{b}) = \frac{1}{2} \|\mathbf{X}\mathbf{b} - \mathbf{y}\|^2 \right\}$$

where $\mathbf{X} \in \mathbb{R}^{n \times d}$, $n \geq d$, is a given full rank data matrix and $\mathbf{y} \in \mathbb{R}^n$ is a vector of observations. IHS is an iterative method based on random projections that is effective for large data and ill-conditioned problems. Given step sizes $\{\alpha_t\}$ and momentum parameters $\{\beta_t\}$, the IHS solution is iteratively updated using

$$\mathbf{b}_{t+1} = \mathbf{b}_t - \alpha_t \mathbf{H}_t^{-1} \nabla f(\mathbf{b}_t) + \beta_t (\mathbf{b}_t - \mathbf{b}_{t-1})$$

where $\mathbf{H}_t = \mathbf{X}^\top \mathbf{S}_t^\top \mathbf{S}_t \mathbf{X}$ is an approximation of the Hessian $\mathbf{H} = \mathbf{X}^\top \mathbf{X}$ given refreshed (i.i.d.) $m \times n$ sketching (random) matrices $\{\mathbf{S}_t\}$ with $m \ll n$. The performance of IHS with Gaussian sketches (i.e., where $(\mathbf{S}_t)_{ij}$ are i.i.d. $N(0, m^{-1})$) has been studied, but IHS with other sketches have only been empirically studied. In their work, Lacotte et al. [7] draw on results from random matrix and free probability theory and show that the following sketches (asymptotically) converge faster to the optimal solution compared to Gaussian sketches:

1. Truncated Haar sketch, where the rows of $\mathbf{S}_t$ are orthonormal. Orthogonal sketches are preferred over i.i.d. sketches as they do not distort the projection, but orthogonality in general Haar matrices come at the expense of requiring the Gram-Schmidt procedure, which has cost $O(nm^2)$ larger than the $O(nmd)$ cost when using Gaussian sketches.

2. A version of the subsampled randomized Hadamard transform (SRHT), with $\mathbf{S}_t$ constructed from $\mathbf{R}_t = n^{-\frac{1}{2}} \mathbf{B}_t \mathbf{W}_n \mathbf{D}_t \mathbf{P}_t$ where $\mathbf{B}_t$ is a $n \times n$ diagonal matrix of i.i.d. Bernoulli$\left(\frac{m}{n}\right)$ samples, $\mathbf{D}_t$ is a $n \times n$ diagonal matrix of i.i.d. Rademacher samples, $\mathbf{P}_t$ is a $n \times n$ uniformly sampled row permutation matrix, and $\mathbf{W}_n$ is the $n \times n$ Walsh-Hadamard matrix defined recursively as

$$\mathbf{W}_n = \begin{bmatrix} \mathbf{W}_{\frac{n}{2}} & \mathbf{W}_{\frac{n}{2}} \\ \mathbf{W}_{\frac{n}{2}} & -\mathbf{W}_{\frac{n}{2}} \end{bmatrix}$$

where $\mathbf{W}_1 = 1$. $\mathbf{S}_t$ is taken as $\mathbf{R}_t$ with the zeros rows removed (as selected by $\mathbf{B}_t$). Note that due to this subsampling, $\mathbf{S}_t$ is a $M \times n$ matrix with $\mathbb{E}[M] = m$. By construction, SRHT sketches are orthogonal. Sketching with SRHT only requires $O(nd \log M)$.

1.2 Main contributions

The main contributions of Lacotte et al. [7] include several theoretical results that describe the (asymptotically) optimal value of the parameters for IHS with Haar or SRHT sketches, the corresponding convergence rates of IHS with these parameters, and closed form expressions for the inverse moments of SRHT sketches. These results are obtained based on

asymptotic results from random matrix theory, in which it is assumed that the matrix dimensions satisfy the aspect ratios $\frac{d}{n} \to \gamma \in (0,1)$ and $\frac{m}{n} \to \xi \in (\gamma, 1)$ as $n, d, m \to \infty$.

The main results are Theorems 3.1 and 4.1. Theorem 3.1 says that for IHS with Haar sketches, the optimal convergence rate ρ_H of the relative prediction error is

$$\rho_H = \left(\lim_{n \to \infty} \frac{\mathbb{E}\left[\|\mathbf{X}(\mathbf{b}_t - \mathbf{b}^*)\|^2\right]}{\|\mathbf{X}(\mathbf{b}_0 - \mathbf{b}^*)\|^2} \right)^{\frac{1}{t}} = \rho_G \cdot \frac{\xi(1-\xi)}{\gamma^2 + \xi - 2\xi\gamma}$$

where ρ_G is the optimal rate of IHS with Gaussian sketches. The aspect ratio scaling factor is less than 1, implying that $\rho_H < \rho_G$ and that IHS with Haar sketches converges faster than with Gaussian sketches. Theorem 4.1 states a similar conclusion for IHS with SRHT sketches where under an additional mild assumption on the initialization of the least squares problem (which is necessary for drawing on existing results in random matrix theory), the optimal rate ρ_S is the same as that with Haar sketches, i.e., $\rho_S = \rho_H$. Theorem 3.1 also states that the optimal convergence rate for IHS with Haar sketches is obtained using momentum values $\beta_t = 0$ (i.e., momentum does not help) and step sizes $\alpha_t = \frac{\theta_{1,H}}{\theta_{2,H}}$ where $\theta_{k,H}$ is the k-th inverse moment of the Haar sketch defined as

$$\theta_{k,H} = \lim_{n \to \infty} \frac{1}{d}\mathbb{E}\left[\text{trace}\left((\mathbf{U}^\top\mathbf{S}^\top\mathbf{S}\mathbf{U})^{-k}\right)\right]$$

for $m \times n$ Haar matrix $\mathbf{S}$ and $n \times d$ deterministic matrix $\mathbf{U}$ with orthonormal columns. Closed-form expressions for the first two inverse moments are provided in Lemma 3.2 and are given by

$$\theta_{1,H} = \frac{1-\gamma}{\xi-\gamma}, \qquad\qquad \theta_{2,H} = \frac{(1-\gamma)(\gamma^2 + \xi - 2\gamma\xi)}{(\xi-\gamma)^3} .$$

Theorem 4.1 and Lemma 4.3 together state that the limiting distribution of Haar and SRHT sketches are the same and therefore so is the optimal step size when there is no momentum. However, the optimality of $\beta_t = 0$ for IHS with SRHT sketches is only a conjecture based on numerical simulations.

Other contributions of Lacotte et al. [7] include a complexity analysis of IHS with SRHT sketches and an empirical study of the theoretical results. The complexity analysis concludes that the asymptotic performance of IHS with SRHT sketches is faster than that of the preconditioned conjugate gradient method (pCG) [12] by a factor of $\log(d)$. The empirical study verifies that the limiting results can apply in the finite case where the convergence of IHS with Haar and with SRHT sketches are similar and faster than that of Gaussian sketches on ill-conditioned synthetic and real datasets of moderate size ($n \geq 4000$, $d \geq 200$), and that the IHS with SRHT sketches refreshed every iteration has faster convergence than pCG on a similar synthetic dataset.

1.3 Limitations

Limitations of the work by Lacotte et al. [7] include the reliance on asymptotic theory, the empirical evaluation of results on mostly synthetic datasets, the comparison of sketches based

on a single criterion, and the unclear generalizability of results to more complicated problems.

Lacotte et al. [7] obtain the convergence rates of IHS with different sketching matrices by drawing on results from asymptotic random matrix theory. While their simulations show that the theory does apply in moderately-sized datasets, the datasets that they examine are primarily synthetic and designed to satisfy assumptions even if ill-conditioned. However, there is also the counterargument that IHS would only be considered over standard solvers for large data problems, and so these limitations are relatively minor.

Another limitation of their work is that only a single criterion—namely the prediction error between the sketched solution and the optimal solution—is used to compare the performance of the sketching matrices. Other criteria have also been considered in the literature, such as those based on other losses or those based on out-of-sample prediction [4, 10]. While certain criteria are intrinsically related [5], they may still have differing properties and lead to differing results [4].

The main limitation of the work by Lacotte et al. [7] is the simple problem context that the results are derived for. While the theory shows that IHS is promising for large data, overdetermined least squares problems, standard solvers would still be preferred over IHS in large data problems if the appropriate computational resources were available. It is unclear whether the theory could generalize to more complicated problems, such as to undetermined least squares problems or optimization problems with other losses. It would be particularly useful to understand whether there are problems for which IHS would be preferred over conventional solvers in the general case.

1.4 Related literature

Works that analyze the impact of sketch type in sketching methods make up a small portion of the sketching literature. The work by Lacotte et al. [7] is said to be inspired by and therefore most similar to the work by Dobriban and Liu [4], which appears to be the first in the literature to leverage results from asymptotic random matrix theory. Analysis in the asymptotic regime appears to be key in being able to differentiate between the analytical performance of different sketching matrices, which was a challenge in previous works [1, 10, 11]. More recently, Lacotte and Pilanci [6] directly extended their analysis of IHS to a related first-order method with fixed sketches that has better guarantees.

Recent related works in the literature also include those that propose extensions of IHS, e.g., IHS with momentum and fixed sketches [9], distributed IHS [2], IHS with adaptive sketch sizes [8], and sparse IHS [3]. Analyses of the performance in these works generally are intended as a point of comparison against existing methods, are done empirically or make use of conventional analysis techniques rather than asymptotic theory, and do not particularly examine the impact of specific sketching matrices.

2   Mini-proposals

2.1   Proposal 1: MY PROPOSAL TITLE

2.2   Proposal 2: MY OTHER PROPOSAL TITLE

3   Project report

References

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