

Tutorial Questions: LTIC Systems

1. Impulse function and Digital Signals

- (a) Draw three impulse function, $\delta[n - v]$ for values of $v = 0$, $v = 5$ and $v = -3$.
- (b) Given a function $g(n) = 5$ draw $g(k)\delta[n - k]$ for values of $-5 < k < 5$:
- (c) If a continuous sine wave is defined as $x(t) = a \sin(2\pi f t)$ define the digital version using n for the samples and T_s seconds for the sample interval.
- (d) State the sample frequency of this digitized sine wave (remember to include the units):
- (e) If the frequency of the sine wave is 8000 Hertz what is the period (remember to include the units)?

2. Linear Time Invariant Systems and Digital Convolution

- (a) What is the *Principle of Superposition* and why is it useful?
- (b) Draw the system diagram using time delays, addition and multiplication for a moving average filter,

$$y[n] = \frac{x[n] + x[n-1] + x[n-2] + x[n-3] + x[n-4]}{5}$$

- (c) Calculate the impulse response of this moving average filter (5 stage) showing all steps:
- (d) Convolve, showing all calculation steps this moving average filter with a unit step function,

$$u[n] = \begin{cases} 1 & \text{if } n \geq 0 \\ 0 & \text{if } n < 0 \end{cases}.$$

- (e) $y[n] = \frac{1}{4}(x[n+1] + x[n] + x[n-1] + x[n-2])$ and $y[n] = \frac{1}{4}(x[n] + x[n-1] + x[n-2] + x[n-3])$ are 4 term non-causal and causal moving average filters respectively. What does *non-causal* mean? (Explain in 1 sentence.)
- (f) The equations for these 4 term moving average filters are known as a difference equations. Most difference equations for Linear Time Invariant (LTI) systems can be put into the form:

$$\sum_{m=0}^N a[m]y[n-m] = \sum_{m=0}^M b[m]x[n-m].$$

Place the 4 term moving average filters into this more general form.

- (g) Convolve a 2 term causal moving average filter $y[n]$ with the following signal:

$$f[n] = \begin{cases} 2 & \text{when } n = 3, \\ 0.5 & \text{when } 0 \leq n \leq 2, \\ 0.7 & \text{when } 4 \leq n \leq 7, \\ 0 & \text{everywhere else.} \end{cases}$$

Show all essential working and steps.