

# MeshStereo: A Global Stereo Model with Mesh Alignment Regularization for View Interpolation



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 $E_{\text{UPPER}} = E_{\text{Alignment}} + E_{\text{SplitPenalty}} + E_{\text{SplitSmooth}}$ 

 $E_{\text{LOWER}} = E_{\text{Alignment}} + E_{\text{MatchingCost}} + E_{\text{NormalSmooth}}$ 

Optimize alternatively between

the two layers until convergence

#### Motivation

- Output high-quality meshes for view interpolation
- Unify depth map estimation and mesh generation

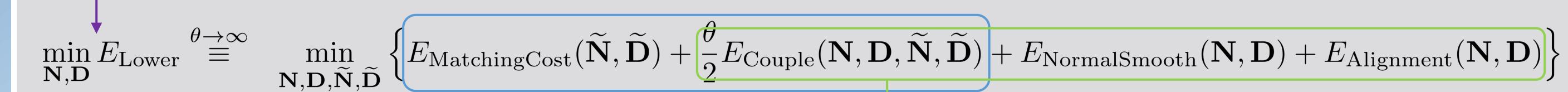
### Variables

- A splitting probability for each 2D vertex
- A depth value for each barycenter
  - A normal for each triangle

## **Optimization**

- Quadratic in lpha , has closed-form solution
- $\min_{\mathbf{N},\mathbf{D}} E_{ ext{LOWER}}$ Non-convex, difficult,

Relax it and optimize in another loop

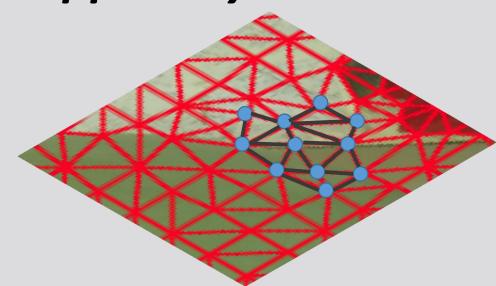


- where  $E_{\text{Couple}}(\mathbf{N}, \mathbf{D}, \widetilde{\mathbf{N}}, \widetilde{\mathbf{D}}) = \sum_{i} (\mathbf{\Pi}_{i} \widetilde{\mathbf{\Pi}}_{i})^{\top} \Sigma (\mathbf{\Pi}_{i} \widetilde{\mathbf{\Pi}}_{i})$ where  $\mathbf{\Pi}_i = [\mathbf{n}_i^\top, d_i]^\top$ , and  $\sigma = \text{diag}(\sigma_n, \sigma_n, \sigma_n, \sigma_d)$
- Increase  $\theta$  from 0 to  $\infty$ , optimize alternatively between blue and green
  - Optimize blue part by PatchMatch Optimize green part in closed-form

#### Formulation

 $E_{\text{All}}(\mathbf{N}, \mathbf{D}, \boldsymbol{\alpha}) = E_{\text{MatchingCost}} + E_{\text{NormalSmooth}} + E_{\text{Alignment}} + E_{\text{SplitPenalty}} + E_{\text{SplitSmooth}}$ 

## **Upper Layer MRF:**



Lower Layer MRF:

- $E_{\text{SplitPenalty}}(\boldsymbol{\alpha}) = \sum \alpha_s \cdot \tau_s$
- $\tau_s = \exp(-|\nabla I^3(x_s, y_s)|/\gamma_1)$
- $E_{\text{SplitSmooth}}(\boldsymbol{\alpha}) \sum w_{st}(\alpha_s \alpha_t)^2$
- $w_{st} = \exp(-|k(\mathbf{x}_s) k(\mathbf{x}_t)|/\gamma_2)$  $k(\mathbf{x}) = \arg\max\{|I^l(\mathbf{x}) - I(\mathbf{x})| < 10, \forall l \le j\}$

- Penalize splitting at homogeneous regions
- Encourage similar splitting properties when neighboring vertices have similar 'visual complexity'
- $E_{\text{MatchingCost}}(\mathbf{N}, \mathbf{D}) = \sum \sum \rho(\mathbf{n}_i, d_i, p)$
- Each depth-normal pair induce a disparity plane over that triangle
- Matching cost combines census and gradient features
- $E_{\text{NormalSmooth}}(\mathbf{N}) = \sum_{i=1}^{n} w_{ij} (\mathbf{n}_i \mathbf{n}_j)^{\top} (\mathbf{n}_i \mathbf{n}_j)$

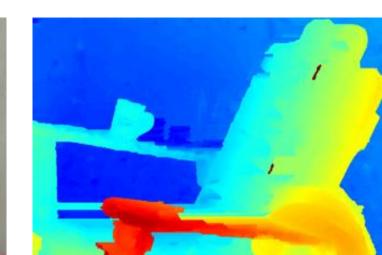
Encouraged Discouraged

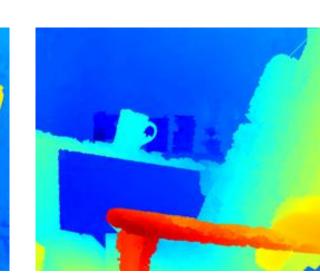
- $E_{\mathrm{Alignment}}(\mathbf{N}, \mathbf{D}, \boldsymbol{\alpha}) =$  $\sum (1 - \alpha_s) \cdot \sum w_{ij} \left( \mathcal{D}_i(\mathbf{x}_s) - \mathcal{D}_j(\mathbf{x}_s) \right)^2$
- Require tight alignment at nonsplitting vertices
- Not active at splitting vertices

## **Stereo Results**

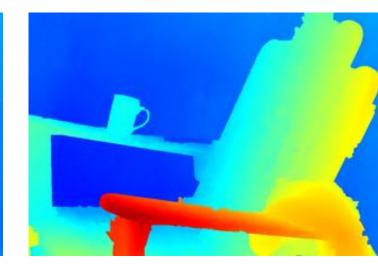


Color





SGM

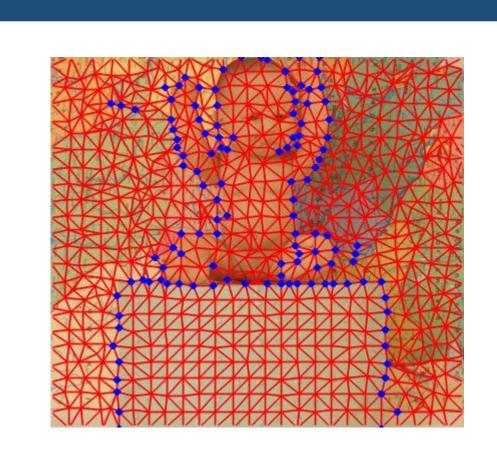


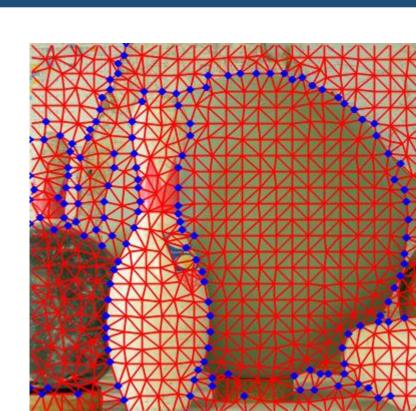
Ours

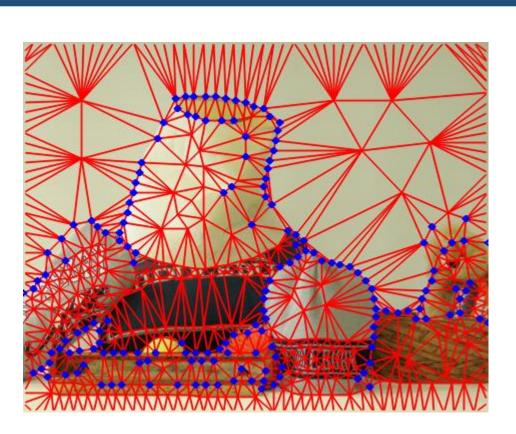
- Preserve fine structures
- First place on Middlebury 3.0 at submission time

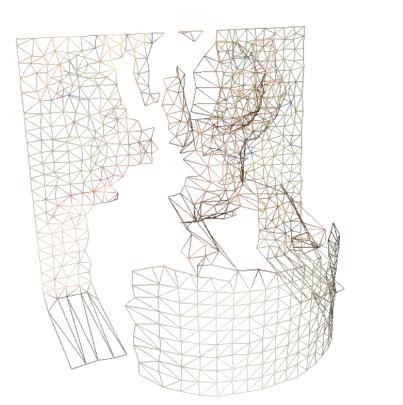
ELAS

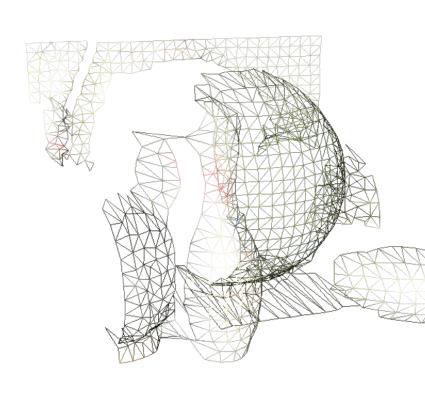
## **Generated Meshes**

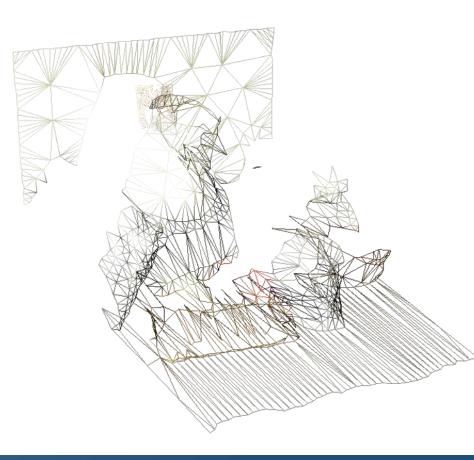




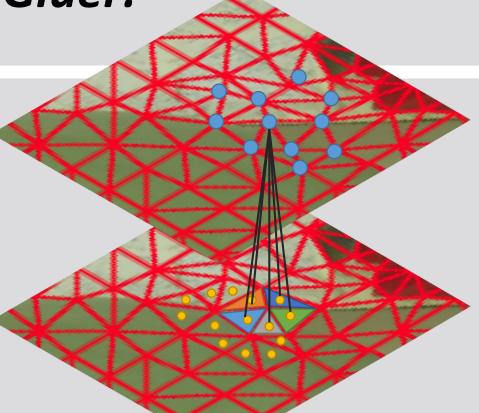












 $i p \in \text{Tri}_i$