Chung Hee (John) Kim

CURRICULUM VITAE

CONTACT INFORMATION

Pittsburgh, PA, United States
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EDUCATION

Carnegie Mellon University — AUG 2021 – PRESENT
Ph.D. in Robotics (Advisor: Dr. George Kantor)

The Hong Kong University of Science and Technology — FEB 2018 – FEB 2020
M.Phil. in Electronic and Computer Engineering (Advisor: Dr. Jungwon Seo)

The Hong Kong University of Science and Technology — SEP 2012 – DEC 2017
B.Eng. in Mechanical Engineering (First Class Honors)
* Overseas Student Exchange Program: **Georgia Institute of Technology**

RESEARCH EXPERIENCE

Robotics Institute, Carnegie Mellon University — PITTSBURGH, PA
Research Assistant — AUG 2021 – PRESENT
- Research focus: Intelligent robotic manipulation and perception
- Engineered and deployed an autonomous robotic system for pepper harvesting, applying imitation learning to train manipulation policies
- Developed an award-winning vision system for reconstructing the 3D branching structure of tree canopies

HKUST Robotics Institute — HONG KONG
Research Assistant — FEB 2018 – JUN 2020
- Research focus: Dexterous robotic manipulation
- Developed an award-winning dexterous manipulation technique on an industrial robot arm with applications in assembly automation

PROFESSIONAL EXPERIENCE

Amazon Robotics — BOSTON, MA
Applied Scientist II Intern — MAY 2025 – AUG 2025
- Developed a tactile sensing-driven framework for 3D object reconstruction with robotic hands

Applied Science and Technology Research Institute — HONG KONG
Engineer — AUG 2020 – JUL 2021
- Conducted research on customized synthetic face generation using generative adversarial networks
- Developed a web application enabling users to submit tasks for execution on a GPU server

XYZ Robotics Inc. — SHANGHAI, CHINA
Robotics Engineer Intern — JUNE 2019 – AUG 2019
- Developed a Mini-ASRS (Automated Storage & Retrieval System) software package for calibration, trajectory planning, and robotic execution

PUBLICATIONS AND PATENTS

[1] **C. H. Kim**, A. Silwal, G. Kantor "Autonomous Robotic Pepper Harvesting: Imitation Learning in Unstructured Agricultural Environments", *IEEE Robotics and Automation Letters*, 2025

[2] **C. H. Kim**, M. Lee, O. Kroemer, G. Kantor "Towards Robotic Tree Manipulation: Leveraging Graph Representations", *International Conference on Robotics and Automation (ICRA)*, 2024

[3] **C. H. Kim**, G. Kantor, "Occlusion Reasoning for Skeleton Extraction of Self-Occluded Tree Canopies", *International Conference on Robotics and Automation (ICRA)*, 2023

[4] H. Freeman, E. Schneider, **C. H. Kim**, M. Lee, G. Kantor "3D Reconstruction-Based Seed Counting of Sorghum Panicles for Agricultural Inspection", *International Conference on Robotics and*

Automation (ICRA), 2023

[5] **C. H. Kim**, J. Seo, "System and Methods for Robotic Precision Placement and Insertion," *U.S. Patent No. 11,628,561*, 18 Apr 2023.

[6] **C. H. Kim**, K. H. Mak, J. Seo, "Planning for Dexterous Ungrasping: Secure Ungrasping through Dexterous Manipulation", *IEEE Robotics and Automation Letters*, 2022

[7] K. H. Mak, **C. H. Kim**, J. Seo, "Robust Ungrasping of High Aspect Ratio Objects Through Dexterous Manipulation", *IEEE Robotics and Automation Letters*, 2022

[8] Z. Tong, Y. H. Ng, **C. H. Kim**, T. He, J. Seo, "Dig-Grasping via Direct Quasistatic Interaction Using Asymmetric Fingers: An Approach to Effective Bin Picking", *IEEE Robotics and Automation Letters*, 2021

[9] Z. Tong, T. He, **C. H. Kim**, Y. Ng, Q. Xu, and J. Seo, "Picking Thin Objects by Tilt-and-Pivot Manipulation and Its Application to Bin Picking", *International Conference on Robotics and Automation (ICRA)*, 2020

[10] **C. H. Kim**, J. Seo, "Shallow-Depth Insertion: Peg in Shallow Hole through Robotic In-Hand Manipulation", *IEEE Robotics and Automation Letters*, 2019

Honors and Awards

ICRA 2023 Outstanding Sensors and Perception Paper Award	May 2023
ICRA 2023 Outstanding Student Paper Finalist	May 2023
ICRA 2019 Best Paper Award in Robot Manipulation	May 2019
HKUST Academic Achievement Medal (*top 1% of graduates*)	Jun 2017

Presentations

ICRA 2024 Oral and Poster Presentation, Yokohama, Japan	May 2024
ICRA 2023 Oral and Poster Presentation, London	May 2023
ICRA 2022 Oral and Poster Presentation, Philadelphia, PA	May 2022
MLCAS 2022 Poster Presentation, Ames, IA	Oct 2022
ICRA 2019 Oral and Poster Presentation, Montreal, Canada	May 2019

Teaching

Robot Localization and Mapping, Teaching Assistant — Sept 2023 – Dec 2023
Carnegie Mellon University

Computer Vision, Teaching Assistant — Jan 2023 – May 2023
Carnegie Mellon University

Introduction to Electro-Robot Design, Teaching Assistant — Sept 2018 – May 2019
The Hong Kong University of Science and Technology

Graduate Courseworks

CMU 16-825	Learning for 3D Vision	Spring 2023
CMU 16-711	Kinematics, Dynamics, and Control	Spring 2023
CMU 16-740	AI for Manipulation	Fall 2022
CMU 10-715	Advanced Introduction to Machine Learning	Fall 2022
CMU 11-785	Introduction to Deep Learning	Spring 2022
CMU 16-833	Robot Localization and Mapping	Spring 2022
CMU 16-720	Computer Vision	Fall 2021
CMU 16-811	Math Fundamentals for Robotics	Fall 2021
HKUST ELEC5660	Introduction to Aerial Robotics	Spring 2019
HKUST ELEC5640	Robotic Manipulation	Fall 2018
HKUST COMP5212	Machine Learning	Fall 2018
HKUST ELEC6910	Robot Perception and Learning	Spring 2018

HKUST EESM5730 Modern Control Systems Design SPRING 2018

SKILLS

Languages English (*native*), Korean (*native*), Mandarin Chinese (*conversational*)

Skills Python, MATLAB, PyTorch, ROS, git, SolidWorks, OnShape, Adobe Photoshop & Illustrator, LaTeX