CSE 258 — Lecture 5

Web Mining and Recommender Systems

Dimensionality Reduction

This week

How can we build **low dimensional** representations of **high dimensional** data?

- e.g. how might we (compactly!) represent
- 1. The ratings I gave to every movie I've watched?
 - 2. The complete text of a document?
- 3. The set of my connections in a social network?

Q1: The ratings I gave to every movie I've watched (or product I've purchased)



Scythe SCBSK-2100 BIG Shuriken 2 Rev. B CPU Cooler for LGA



*** Cool, Slim, Silent, Perfect

January 16, 2015

Silent and keeps the CPU cold. Installation wasn't hard either and its slim profile fits in my very tight HTPC case. What more could I ask for?



Noctua 120mm, 2 speed setting



************ Another Great PS from SS, a Little Long Though

January 16, 2015

What can you say about SeaSonic PS units. They are the premier component and keep all your other parts safe with ever ready clean and reliable power. The fact that it's silent and produces almost no heat is just icing on the cake. There is a reason why I don't use any other PS for my builds. Be warned though that this PS may be a little longer than non modular and non passive

A1: A (sparse) vector including all movies

 $F_{julian} = [0.5, ?, 1.5, 2.5, ?, ?, ..., 5.0]$

A-team

ABBA, the movie

Zoolander

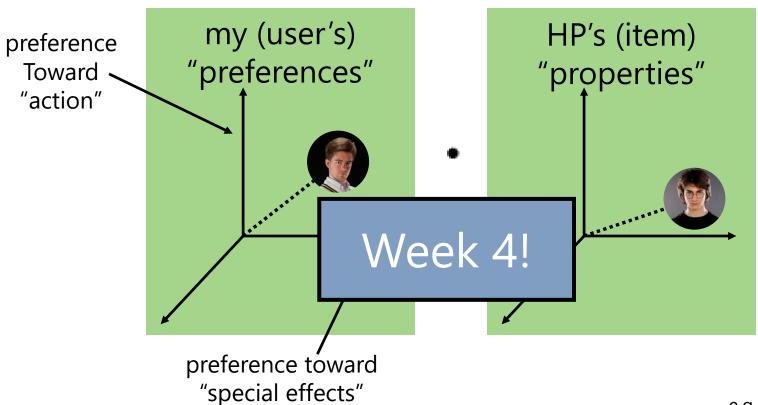
A better and more modern homage to the classic TV show. Action packed, feel good, and fun. I was



A1: A (sparse) vector including all movies

 $F_{julian} = [0.5, ?, 1.5, 2.5, ?, ?, ..., 5.0]$

A2: Describe my preferences using a **low-dimensional** vector



e.g. Koren & Bell (2011)

Q2: How to represent the complete text of a document?

The Peculiar Genius of Bjork

CULTURE | BY EMILY WITT | JANUARY 23, 2015 11:30 AM

A1: A (sparse) vector counting all words

concepts and feelings; and Bjork the producer and curator, who seeks out

nicepts and reemigs, and bjork the producer and curator, who seeks ou

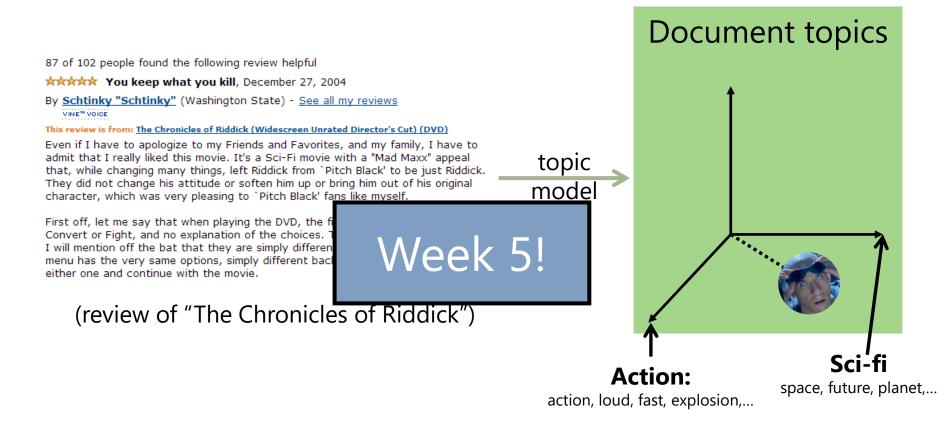
A1: A (sparse) vector counting all words

$$F_{\text{text}} = [150, 0, 0, 0, 0, 0, ..., 0]$$

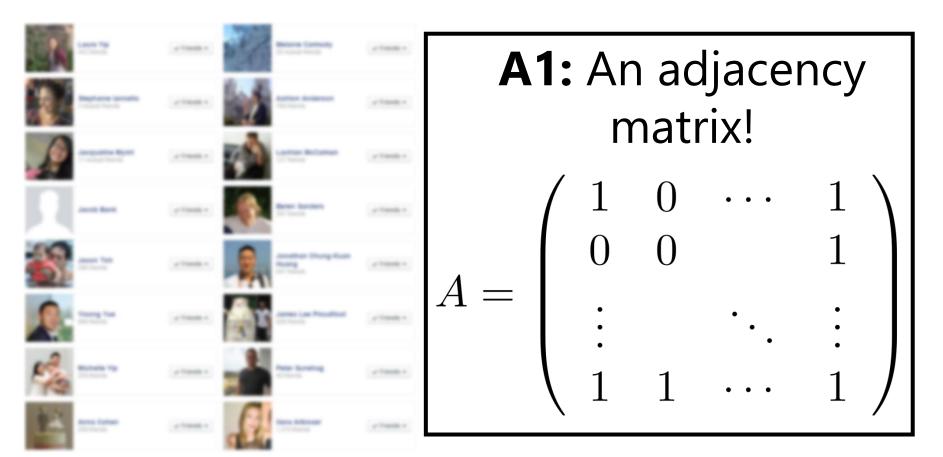
Incredibly high-dimensional...

- Costly to store and manipulate
- Many dimensions encode essentially the same thing
- Many dimensions devoted to the "long tail" of obscure words (technical terminology, proper nouns etc.)

A2: A low-dimensional vector describing the **topics in the document**



Q3: How to represent connections in a social network?



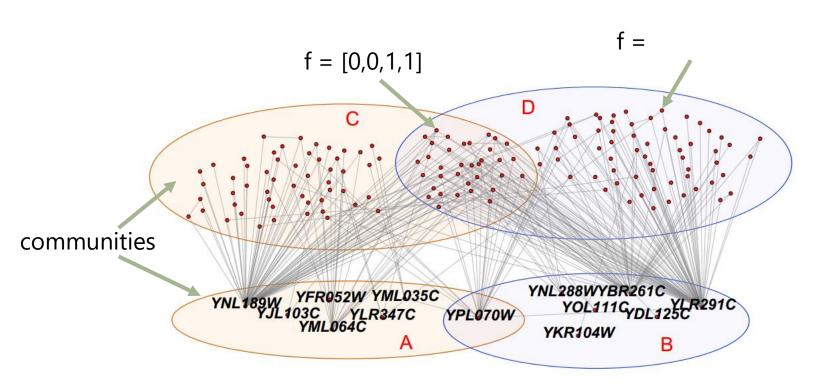
A1: An adjacency matrix

$$A = \begin{pmatrix} 1 & 0 & \cdots & 1 \\ 0 & 0 & & 1 \\ \vdots & & \ddots & \vdots \\ 1 & 1 & \cdots & 1 \end{pmatrix}$$

Seems almost reasonable, but...

- Becomes very large for real-world networks
- Very fine-grained doesn't straightforwardly encode which nodes are similar to each other

A2: Represent each node/user in terms of the **communities** they belong to



e.g. from a PPI network; Yang, McAuley, & Leskovec (2014)

Why dimensionality reduction?

Goal: take **high-dimensional** data, and describe it compactly using a small number of dimensions

Assumption: Data lies (approximately) on some low-dimensional manifold

(a few dimensions of opinions, a small number of topics, or a small number of communities)

Why dimensionality reduction?

Unsupervised learning

- Today our goal is not to solve some specific predictive task, but rather to **understand** the important features of a dataset
- We are not trying to understand the process which generated labels from the data, but rather the process which generated the data itself

Why dimensionality reduction?

Unsupervised learning

- But! The models we learn will prove useful when it comes to solving predictive tasks later on, e.g.
- Q1: If we want to predict which users like which movies, we need to understand the important dimensions of opinions
 - **Q2:** To estimate the category of a news article (sports, politics, etc.), we need to understand topics it discusses
- Q3: To predict who will be friends (or enemies), we need to understand the communities that people belong to

Today...

Dimensionality reduction, clustering, and community detection

- Principal Component Analysis
- K-means clustering
- Hierarchical clustering
- Next lecture: Community detection
 - Graph cuts
 - Clique percolation
 - Network modularity

Principal Component Analysis (PCA) is one of the oldest (1901!) techniques to understand which dimensions of a highdimensional dataset are "important"

Why?

- To select a few important features
- To compress the data by ignoring components which aren't meaningful

Motivating example: Suppose we rate restaurants in terms of: [value, service, quality, ambience, overall]

- Which dimensions are highly correlated (and how)?
- Which dimensions could we "throw away" without losing much information?
- How can we find which dimensions can be thrown away automatically?
- In other words, how could we come up with a "compressed representation" of a person's 5-d opinion into (say) 2-d?

Suppose our data/signal is an MxN matrix

N = number of observations

$$X = \begin{pmatrix} 5 & 3 & \cdots & 1 \\ 4 & 2 & & 1 \\ 3 & 1 & & 3 \\ 2 & 2 & & 4 \\ 1 & 5 & & 2 \\ \vdots & & \ddots & \vdots \\ 1 & 2 & \cdots & 1 \end{pmatrix}$$

M = number of features (each **column** is a data point)

We'd like (somehow) to recover this signal using as few dimensions as possible

signal

compressed signal (K < M)

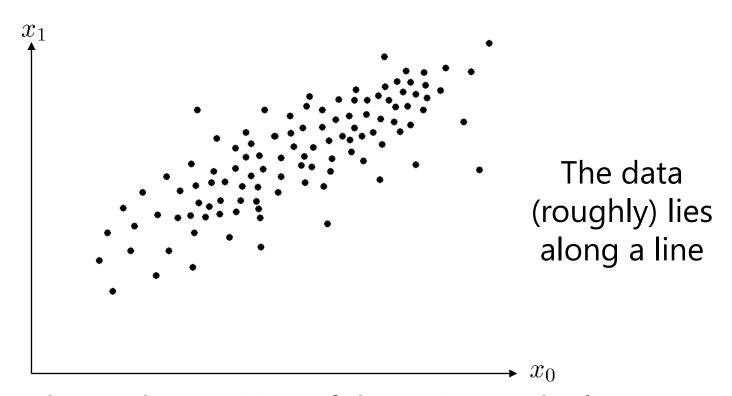
$$X \in \mathbb{R}^{M \times N}$$

$$Y' \in \mathbb{R}^{K \times N}$$

$$f(Y') \simeq X$$

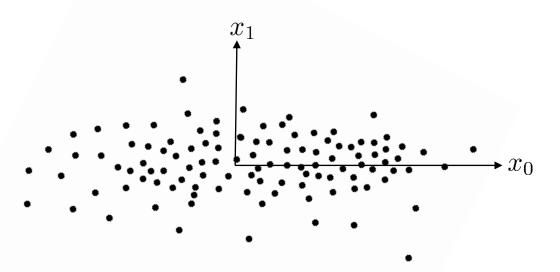
(approximate) process to recover signal from its compressed version

E.g. suppose we have the following data:



Idea: if we know the position of the point on the line (1D), we can approximately recover the original (2D) signal

But how to find the important dimensions?



Find a new basis for the data (i.e., rotate it) such that

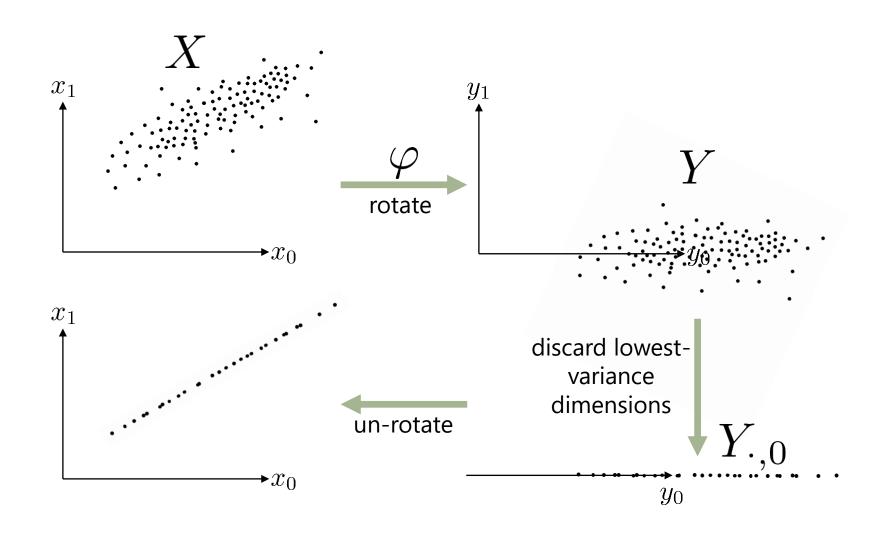
- most of the variance is along x0,
- most of the "leftover" variance (not explained by x0) is along x1,
- most of the leftover variance (not explained by x0,x1) is along x2,
- etc.

But how to find the important dimensions?

- Given an input $X \in \mathbb{R}^{M \times N}$
- Find a basis $\varphi \in \mathbb{R}^{M \times M}$

But how to find the important dimensions?

- Given an input $X \in \mathbb{R}^{M \times N}$
- Find a basis $\varphi \in \mathbb{R}^{M \times M}$
- Such that when X is rotated $(Y = \varphi X)$
 - Dimension with highest variance is y_0
 - Dimension with 2nd highest variance is y_1
 - Dimension with 3rd highest variance is y_2
 - Etc.



For a single data point:
$$y=\varphi x$$
 $x=\varphi^{-1}y=\varphi^Ty$

$$x =$$

$$x = \varphi_1 y_1 + \varphi_2 y_2 + \ldots + \varphi_M y_M = \sum_{j=1}^{M} \varphi_j y_j$$

$$x \simeq$$

We want to fit the "best" reconstruction:

$$x = \varphi^T y \qquad x_i \simeq \sum_{j=1}^K \varphi_j y_j + \sum_{j=K+1}^M \varphi_j b_j$$
 "complete" reconstruction

approximate reconstruction

i.e., it should minimize the **MSE**:

$$\min_{\varphi,b} \frac{1}{N} \sum_{y} \left\| \sum_{j=1}^{K} \varphi_j y_j + \sum_{j=K+1}^{M} \varphi_j b_j - \varphi^T y \right\|_2^2$$

Simplify...

$$\min_{\varphi,b} \frac{1}{N} \sum_{y} \left\| \sum_{j=K+1}^{M} \varphi_j(y_j - b_j) \right\|_2^2$$

Expand...

$$\min_{\varphi,b} \frac{1}{N} \sum_{y} \sum_{j=K+1}^{M} (y_j - b_j)^2$$

$$\min_{\varphi} \frac{1}{N} \sum_{y} \sum_{j=K+1}^{M} (y_j - \bar{y}_j)^2$$

Equal to the **variance** in the discarded dimensions

PCA: We want to keep the dimensions with the highest variance, and discard the dimensions with the lowest variance, in some sense to maximize the amount of "randomness" that gets preserved when we compress the data

$$\min_{arphi} rac{1}{N} \sum_{y} \sum_{j=K+1}^{M} (y_j - ar{y}_j)^2$$
 (subject to $arphi$ orthonormal)

Expand in terms of X

$$\min_{\varphi} \frac{1}{N} \sum_{j=K+1}^{M} \varphi_j (X - \bar{X})(X - \bar{X})^T \varphi_j^T \text{ (subject to } \varphi \text{ orthonormal)}$$

Lagrange multipliers:
Bishop appendix E

Solve:

$$\frac{\partial}{\partial \varphi_j} \sum_{j=K+1}^{M} \varphi_j \operatorname{Cov}(X) \varphi_j^T - \lambda_j (\varphi_j \varphi_j^T - 1) = 0$$

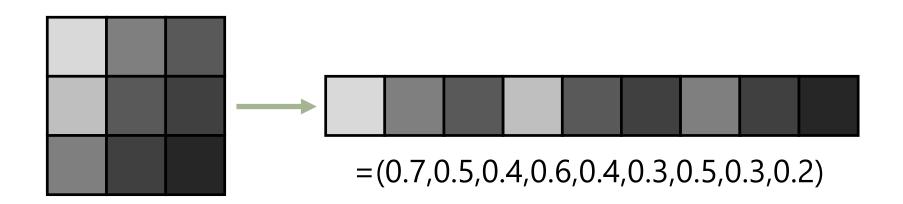
- This expression can only be satisfied if phi_j and lambda_j are an eigenvectors/eigenvalues of the covariance matrix
- So to minimize the original expression we'd discard phi_j's corresponding to the smallest eigenvalues

Moral of the story: if we want to optimally (in terms of the MSE) project some data into a low dimensional space, we should choose the projection by taking the eigenvectors corresponding to the largest eigenvalues of the covariance matrix

Example 1: What are the principal components of people's opinions on beer?

(code available on)
http://jmcauley.ucsd.edu/cse258/code/week3.py

Example 2: What are the principal dimensions of image patches?

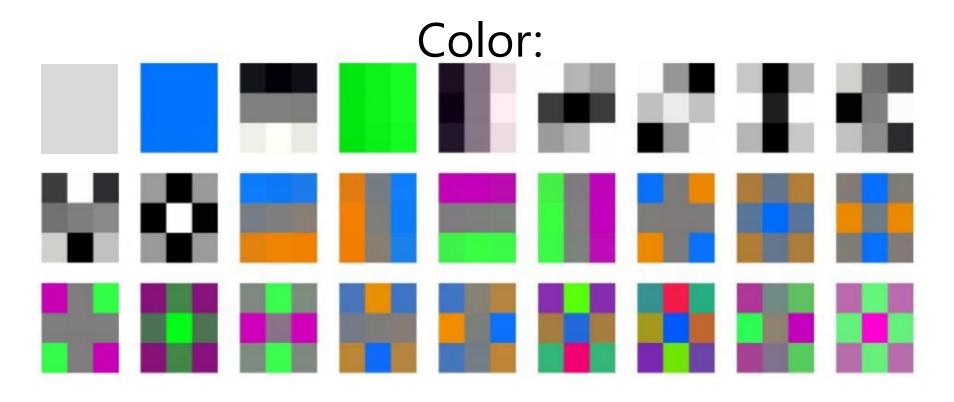


Construct such vectors from 100,000 patches from real images and run PCA:

Black and white:



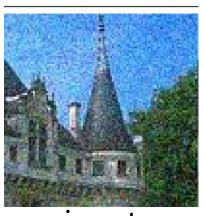
Construct such vectors from 100,000 patches from real images and run PCA:



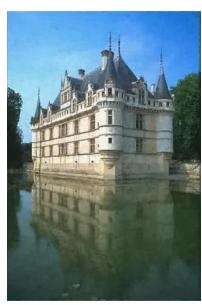
From this we can build an algorithm to "denoise" images

Idea: image patches should be **more like** the high-eigenvalue components and **less like** the low-eigenvalue components











output McAuley et. al (2006)

- We want to find a low-dimensional representation that best compresses or "summarizes" our data
- To do this we'd like to keep the dimensions with the highest variance (we proved this), and discard dimensions with lower variance.
 Essentially we'd like to capture the aspects of the data that are "hardest" to predict, while discard the parts that are "easy" to predict
- This can be done by taking the eigenvectors of the covariance matrix

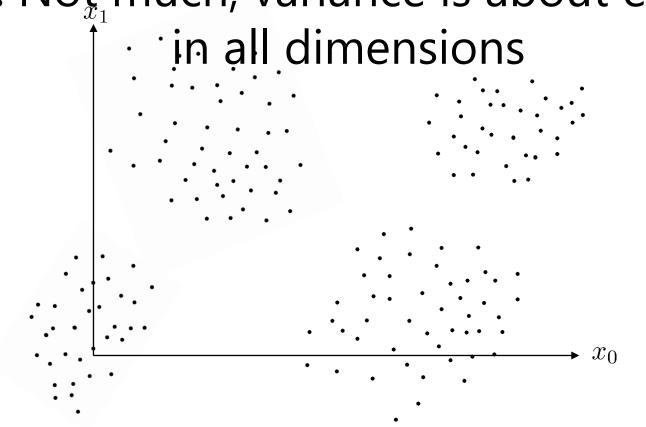
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Clustering – K-means

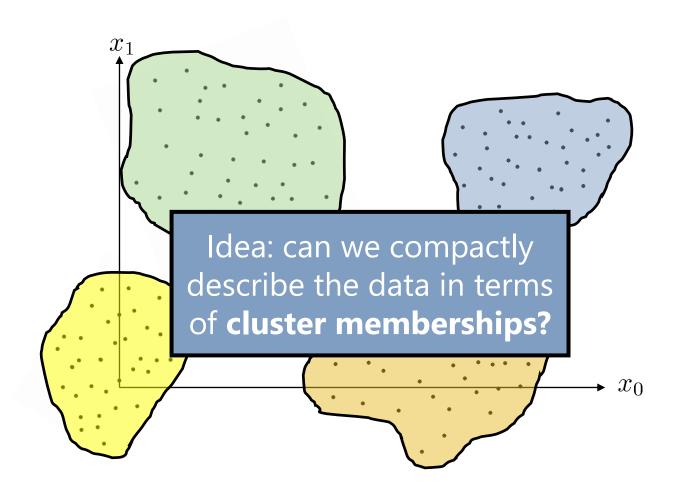
Clustering

Q: What would PCA do with this data?
A: Not much, variance is about equal



Clustering

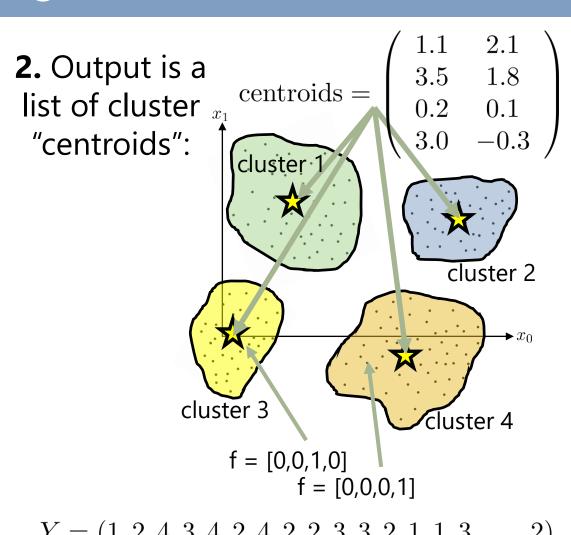
But: The data are highly clustered



1. Input is still a matrix of features:

$$X = \begin{pmatrix} 5 & 3 & \cdots & 1 \\ 4 & 2 & & 1 \\ 3 & 1 & & 3 \\ 2 & 2 & & 4 \\ 1 & 5 & & 2 \\ \vdots & & \ddots & \vdots \\ 1 & 2 & \cdots & 1 \end{pmatrix}$$

3. From this we can describe each point in X Y = (1, 2, 4, 3, 4, 2, 4, 2, 2, 3, 3, 2, 1, 1, 3, ..., 2) by its cluster membership:



Given **features** (X) our goal is to choose K **centroids** (C) and **cluster assignments** (Y) so that the reconstruction error is minimized

Number of data points

$$X \in \mathbb{R}^{N \times M}$$

Feature dimensionality

Number of clusters

$$C \in \mathbb{R}^{K \times M}$$

$$Y \in \{1 \dots K\}^N$$

reconstruction error = $\sum_{i} ||X_i - C_{y_i}||_2^2$

(= sum of squared distances from assigned centroids)

Q: Can we solve this optimally?

$$\min_{C,y} \sum_{i} ||X_i - C_{y_i}||_2^2$$

A: No. This is (in general) an **NP-Hard** optimization problem

See "NP-hardness of Euclidean sum-of-squares clustering", Aloise et. Al (2009)

Greedy algorithm:

(also: reinitialize clusters at random should they become empty)

Further reading:

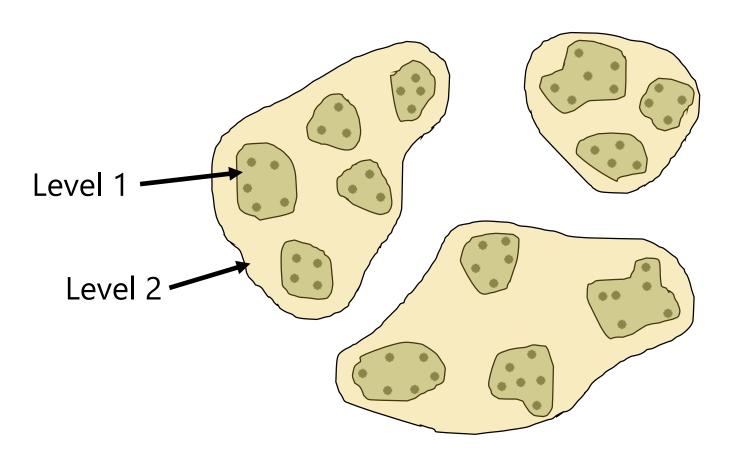
- K-medians: Replaces the mean with the meadian. Has the effect of minimizing the 1-norm (rather than the 2-norm) distance
 - **Soft** K-means: Replaces "hard" memberships to each cluster by a proportional membership to each cluster

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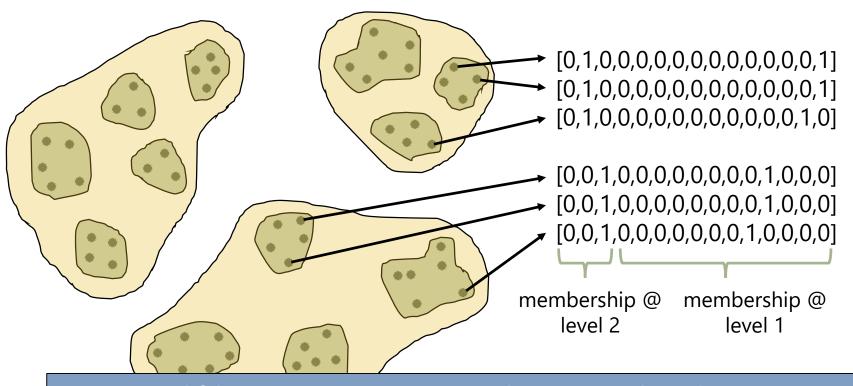
Web Mining and Recommender Systems

Clustering – hierarchical clustering

Q: What if our clusters are hierarchical?



Q: What if our clusters are hierarchical?



A: We'd like a representation that encodes that points have **some features** in common but not others

Hierarchical (agglomerative) clustering works by gradually fusing clusters whose points are closest together

```
Assign every point to its own cluster:

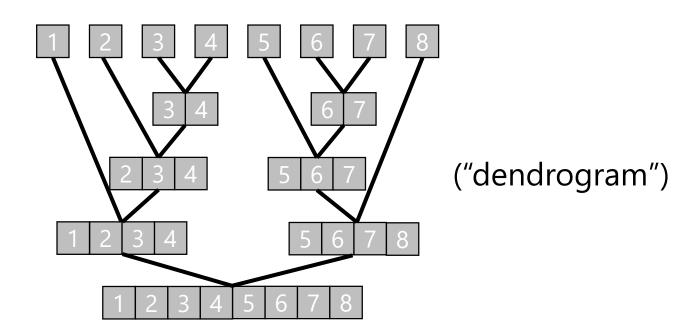
Clusters = [[1],[2],[3],[4],[5],[6],...,[N]]

While len(Clusters) > 1:

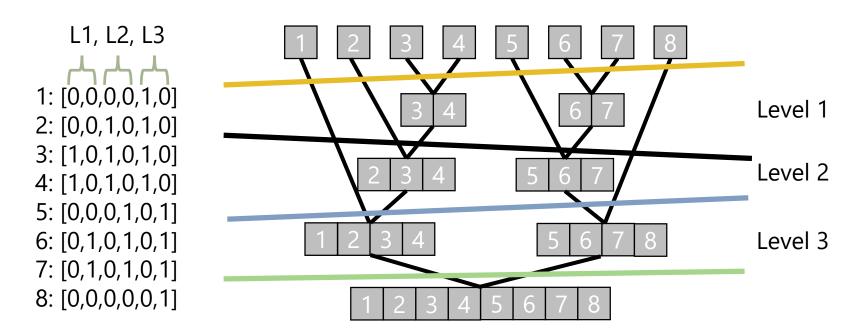
Compute the center of each cluster

Combine the two clusters with the nearest centers
```

If we keep track of the order in which clusters were merged, we can build a "hierarchy" of clusters



Splitting the dendrogram at different points defines cluster "levels" from which we can build our feature representation

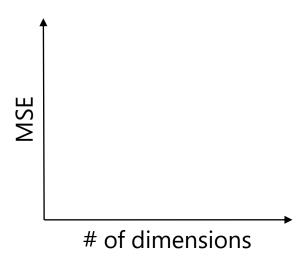


• **Q:** How to choose K in K-means? (or:

- How to choose how many PCA dimensions to keep?
- How to choose at what position to "cut" our hierarchical clusters?
- (next week) how to choose how many communities to look for in a network)

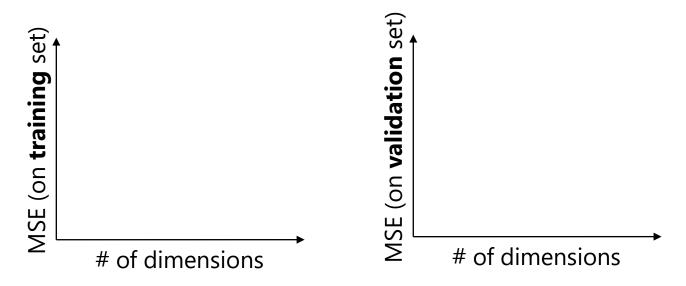
1) As a means of "compressing" our data

- Choose however many dimensions we can afford to obtain a given file size/compression ratio
- Keep adding dimensions until adding more no longer decreases the reconstruction error significantly



- 2) As a means of generating potentially useful features for some other predictive task (which is what we're more interested in in a predictive analytics course!)
 - Increasing the number of dimensions/number of clusters gives us additional features to work with, i.e., a longer feature vector
 - In some settings, we may be running an algorithm whose complexity (either time or memory) scales with the feature dimensionality (such as we saw last week!); in this case we would just take however many dimensions we can afford

 Otherwise, we should choose however many dimensions results in the best prediction performance on held out data



 Q: Why does this happen? i.e., why doesn't the validation performance continue to improve with more dimensions

Questions?

Further reading:

Ricardo Gutierrez-Osuna's PCA slides (slightly more mathsy than mine):

http://research.cs.tamu.edu/prism/lectures/pr/pr_l9.pdf

Relationship between PCA and K-means:

http://ranger.uta.edu/~chqding/papers/KmeansPCA1.pdf http://ranger.uta.edu/~chqding/papers/Zha-Kmeans.pdf