Vectors

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Introduction

- Stacks and Queues are examples of ADTs that support insertion and removal at pre-specified points.
 - Stacks: insertion / removal at the top
 - Queues: insertion at the tail / removal at the head
- We have explored two basic techniques for implementing these two ADTs:
 - Arrays
 - Links
- Next, we will explore some ADTs that support insertion and removal at various points.
 - Collectively, these are known as Sequence ADTs.

Sequence ADTs

- Vectors
 - Support insertion / removal by rank (index).
- Lists
 - Support insertion / removal by position (I.e. you can insert a new item relative to an existing item).
- Sequences
 - Combination of a Vector & a List
- Iterators
 - Auxiliary ADT that supports traversal of other Sequence ADTs

Vectors: Concept

- A Vector supports insertion, removal and accessing of objects based on rank.
- Terminology:
 - Rank: The rank of an object e is an integer value that specifies the number of objects that come before e in vector.
- Example:

Rank ->

0	1	2	3	4	5	6	7	8	9
Α	В	С	D	F	G				

- Vectors are similar to but not the same as arrays:
 - KEY DIFFERENCES: No fixed capacity / object ranks change

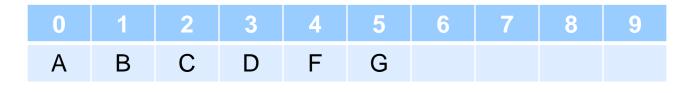
Vectors: Insertion

- Insertion is performed based on a given rank.
 - E.g. insert Z with rank 4
- After insertion, the rank of some of the other objects in the vector may change
- Example: "Insert Z with rank 4"

0	1	2	3	4	5	6	7	8	9
Α	В	С	D	F	G				

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- Example: "Insert Z with rank 4"



0	1	2	3	4	5	6	7	8	9
Α	В	С	D	Z	F	G			

Vectors: Removal

- Removal is performed based on a given rank.
 - E.g. Remove the item with rank 4
- Again, after removal, the rank of some of the other objects in the vector may change
- Example: "Remove the item with rank 3"

0		1	2	3	4	5	6	7	8	9
P	\	В	С	D	Z	F	G			

Vectors: Removal

- Removal is performed based on a given rank.
 - E.g. Remove the item with rank 4
- Again, after removal, the rank of some of the other objects in the vector may change
- Example: "Remove the item with rank 3"

0	1	2	3	4	5	6	7	8	9
Α	В	С	D	Z	F	G			

0	1	2	3	4	5	6	7	8	9
Α	В	С	Z	F	G				

Vectors: Function Specification

- Core Operations:
 - elemAtRank(r):
 Return the object with rank r: an error condition occurs if the vector is empty or

r < 0 or r > size()-1

replaceAtRank(r, e):Replace the object at rank r with e: an

error condition occurs if the vector is

empty or r < 0 or r > size() -1

insertAtRank(r, e): Insert a object e into the vector with rank

r: an error condition occurs if

r < 0 or r > size()

removeAtRank(r):Remove the object at rank r: an error

condition occurs if S is empty or

r < 0 or r > size() -1

- Support Operations:
 - isEmpty()
 Returns true if the vector is empty, or false otherwise
 - size()
 Returns the number of elements in the

vector

Vectors: Java Interface

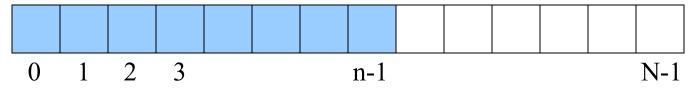
```
public interface Vector {
  public int size();
  public boolean isEmpty();
  public Object elemAtRank(int rank)
               throws RankOutOfBoundsException;
  public Object replaceAtRank(int rank, Object element)
               throws RankOutOfBoundsException;
  public void insertAtRank(int rank, Object element)
               throws RankOutOfBoundsException;
  public Object removeAtRank(int rank)
               throws RankOutOfBoundsException;
```

Vectors: Impl. Strategies

- Array-based Implementation:
 - Objects stored in an array
 - After each operation, the index of the object corresponds to the rank
 - Keep track of n, the current size of the vector
 - Finite Capacity (for now)
- Link-based Implementation:
 - Objects stored in special "nodes"
 - Nodes maintain ordering information
 - Link to the next and previous objects in the Vector.
 - Need auxiliary references for "front" and "rear" nodes.

Simple Array-based Impl.

- Approach: store the objects in an array, A, of size N
 - The rank of an object is very similar to the index of an array.
 - However, unlike an array, a Vector cannot have "gaps" between objects.
 - When an object is removed, the remaining objects must be squashed up to maintain the correspondance between the rank and index of an object.
- Below is a (Vector) array of size N that currently holds n objects.
 - The objects are located in indices 0 to n-1.



Vectors: Pseudo Code

```
Algorithm: insertAtRank(r, e):
    if (r < 0) or (r > n) then
      throw a RankOutOfBoundsException
    if (n == N) then
      throw a VectorFullException
    for i = n, n-2, ..., r+1 do
     A[i] \leftarrow A[i-1]
    A[r] \leftarrow e
    n \leftarrow n + 1
Algorithm: elemAtRank(r):
    if (r < 0) or (r > n-1) then
      throw a RankOutOfBoundsException
    return A[r]
Algorithm isEmpty():
    return n == 0
```

```
Algorithm insertAtRank(r, e):
    if (r < 0) or (r > n-1) then
      throw a RankOutOfBoundsException
    e \leftarrow A[r]
    for i = r, r+1, ..., n-2 do
      A[i] \leftarrow A[i+1]
    A[n-1] \leftarrow null
    n \leftarrow n - 1
    return e
Algorithm replaceAtRank(r,e):
    if (r < 0) or (r > n-1) then
      throw a RankOutOfBoundsException
    A[r] \leftarrow e
Algorithm size():
    return n
```

Vectors: Dry Runs

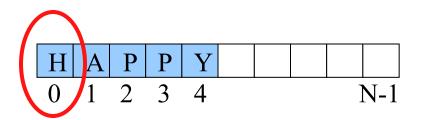
- Follow a similar pattern to other array-based implementations and record:
 - the array state
 - the number of objects in the array, and
 - the operations carried out
- Example: a Vector with array size 6

Operation	n	0	1	2	3	4	5
Initial State	0						
insertAtRank(0, A)	1	Α					
insertAtRank(1, P)	2	Α	Р				
insertAtRank(2, Y)	3	Α	Р	Υ			
insertAtRank(0, H)	4	Н	Α	Р	Υ		
insertAtRank(2, P)	5	Н	Α	Р	Р	Y	

Runtime Performance of Vectors

- The majority of methods for the Vector class have a running time of O(1).
- The exceptions to this are the insertAtRank(r,e) and the removeAtRank(r) methods.
 - These methods have O(n) running time because of the shift operations that must be performed on the arrays.
 - In the worst case, elements are inserted or removed with rank 0.
 - In this case, n-1 elements must be shifted, hence the O(n) running time.

Method	Size
size()	O(1)
isEmpty()	O(1)
elemAtRank(r)	O(1)
replaceAtRank(r,e)	O(1)
insertAtRank(r,e)	O(n)
removeAtRank(r)	O(n)



Extendable Arrays

- Current Approach: Array => Finite Capacity
 - At capacity throw an unchecked VectorFullException
- Alternative: Extendable Arrays
 - When the array is full, replace it with a new bigger array that is initialised to contain the current state of the Vector.
 - Typical Strategy: Double the array size
 - Impacts only the insertAtRank(r, e) operation
- Why double?
 - Fixed increments not efficient (10 + 1000 / 10000000 + 1000)
 - Doubling is the smallest integer multiple (vs tripling / quadrupling)
 - Tries to minimize wastage of space

Revised Insertion Algorithm

```
Algorithm: insertAtRank(r, e):
   if (r < 0) or (r > n) then
      throw a RankOutOfBoundsException
   if n = capacity then
      capacity \leftarrow capacity * 2;
      B \leftarrow new array of size capacity
      for i = 0, 1, ..., n-1 do
         B[i] \leftarrow A[i]
      A \leftarrow B
   for i = n-1, n-2, ..., r do
      A[i+1] \leftarrow A[i]
   A[r] \leftarrow e
   n \leftarrow n + 1
```

Amortization

- Goal: To calculate the running time for the algorithm that inserts items into an extendable array.
 - Let us consider only insertion at the end of the array (we can always add the O(n) shift operation later).
- Approach: Conduct an amortized analysis of the algorithm.
 - We adopt a view of the computer as a coin-operated appliance that takes one dollar as payment for a fixed amount of computing time.
 - When an operation is executed, we should have enough dollars in the "account" to pay for that operations running-time.
- NOTE: The idea behind this approach is to spread out the payments so that we get an idea for the overall performance of the algorithm.

- Assumptions:
 - One dollar is enough to pay for the insertion of an element into the vector S.
 - Growing the array from size k to size 2k costs k dollars.
- We charge 3 dollars per insertion.
 - So, we overcharge by 2 dollars, and store the additional cash in the "account".
- An overflow occurs when there are i elements in the array (i ≥ 0).
 - Growing the array will cost 2i dollars.
 - Fortunately, this cash has accumulated in the account since the last overflow:
 - 2 dollars per operation * i operations = 2i dollars

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account

Array



Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$

Array

Н

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$ \$ \$ \$

Array

H A

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$ \$ \$ \$ \$ \$

Array

H A P

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$ \$ \$ \$ \$ \$ \$ \$

Array

H A P P

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$ \$ \$ \$ \$ \$ \$ \$

Array H A P P

Overflow occurred adding "Y"...

Cost of extending an array from k to 2k costs k dollars Currently the array is size 4, hence cost is 4

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$ \$ \$

Array



But we still have to add "Y" at a price of 3

Start with an array of size 4, and add "H", "A", "P", "P", "Y"...

Account \$ \$ \$ \$ \$ \$ \$

Array H A P P Y

The outstanding 4 dollars comes from the initial size of the array (4) – this never gets spent! Keep on adding "B" "I" "R" "T" to confirm!

Now adding "B" "I" "R" "T" to confirm analysis

Account \$ \$ \$ \$ \$ \$ \$

Array H A P P Y B

Now adding "B" "I" "R" "T" to confirm analysis

Account \$ \$ \$ \$ \$ \$ \$ \$ \$

Array H A P P Y B I

Now adding "B" "I" "R" "T" to confirm analysis

Account \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$ \$

Array

H A P P Y B I R

Now adding "B" "I" "R" "T" to confirm analysis

Overflow occurred adding "T"...

Cost of extending an array from k to 2k costs k dollars

Currently the array is size 8, hence cost is 8

Now adding "B" "I" "R" "T" to confirm analysis

Account \$ \$ \$ \$ \$

Array



And finally, we add the "T"

Now adding "B" "I" "R" "T" to confirm analysis

Account \$ \$ \$ \$ \$ \$ \$ \$ \$

Array H A P P Y B I R T ...

- This means that, 3 dollars per insertion covers the cost of extending the array (whenever that extension occurs).
- So, if we insert n items into an extendable vector, then the cost will be 3n dollars:
 - This means that inserting n items takes O(n) time.
 - This is because the amortized running time of each insertion is O(1)!

I DIDN'T EXPECT THAT ONE!

Linked Lists and Vectors

- Given the success we had with linked lists and Stacks and Queues, why don't we use them for Vectors?
- REMEMBER: In a linked list, we store direct references to only the first and the last nodes in the list.
 - To get to the other nodes, we must "follow the links".
- If there are "n" links in a linked list implementation of a Vector, then in the worst case, traversing the list to a given rank in the list will take n-1 steps.
 - Can improve this to at most n/2 steps but still not O(1)!

Linked Lists and Vectors

- Each Vector update method requires we traverse the list to a specified rank.
 - This means that ALL of these methods will have a running time of O(n).
- For insertAtRank(r,e) and removeAtRank(r):
 - We have replaced the need for shift operation with the need for a traversal operation.
- For elemAtRank(r) and replaceAtRank(r,e):
 - We have introduced the need for a traversal operation.

Method	Size
size()	O(1)
isEmpty()	O(1)
elemAtRank(r)	O(n)
replaceAtRank(r,e)	O(n)
insertAtRank(r,e)	O(n)
removeAtRank(r)	O(n)

This means that array-based implementations of Vectors are better!