



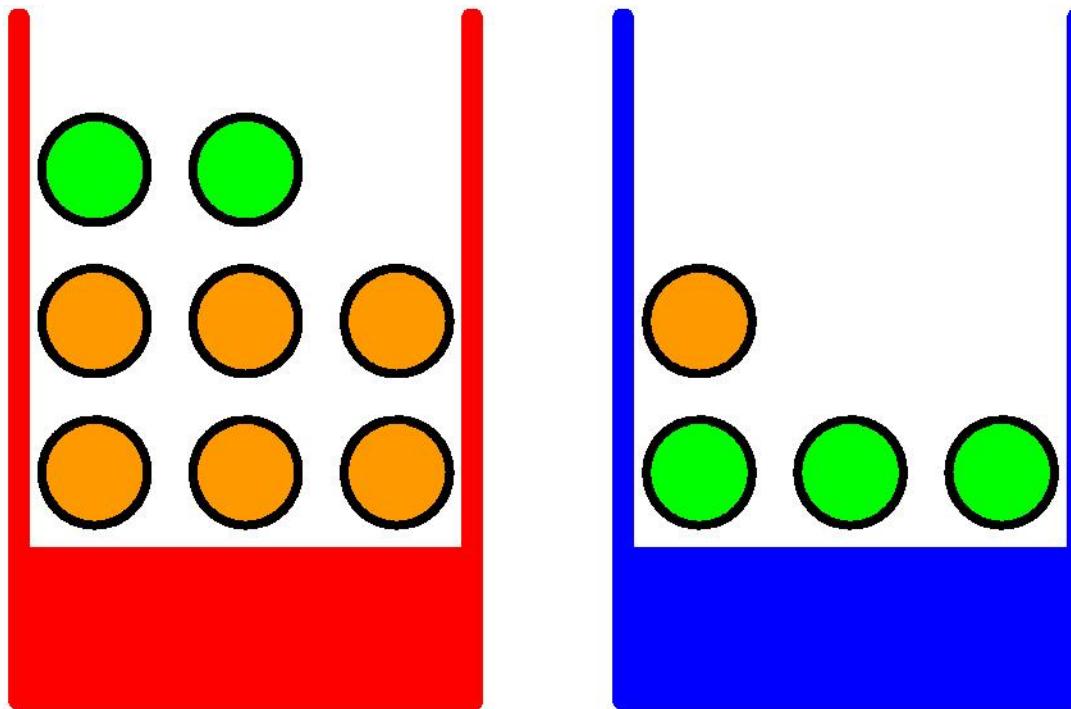
CPE/EE 695: Applied Machine Learning

Lecture 2 -2 : Review to Probability Theory

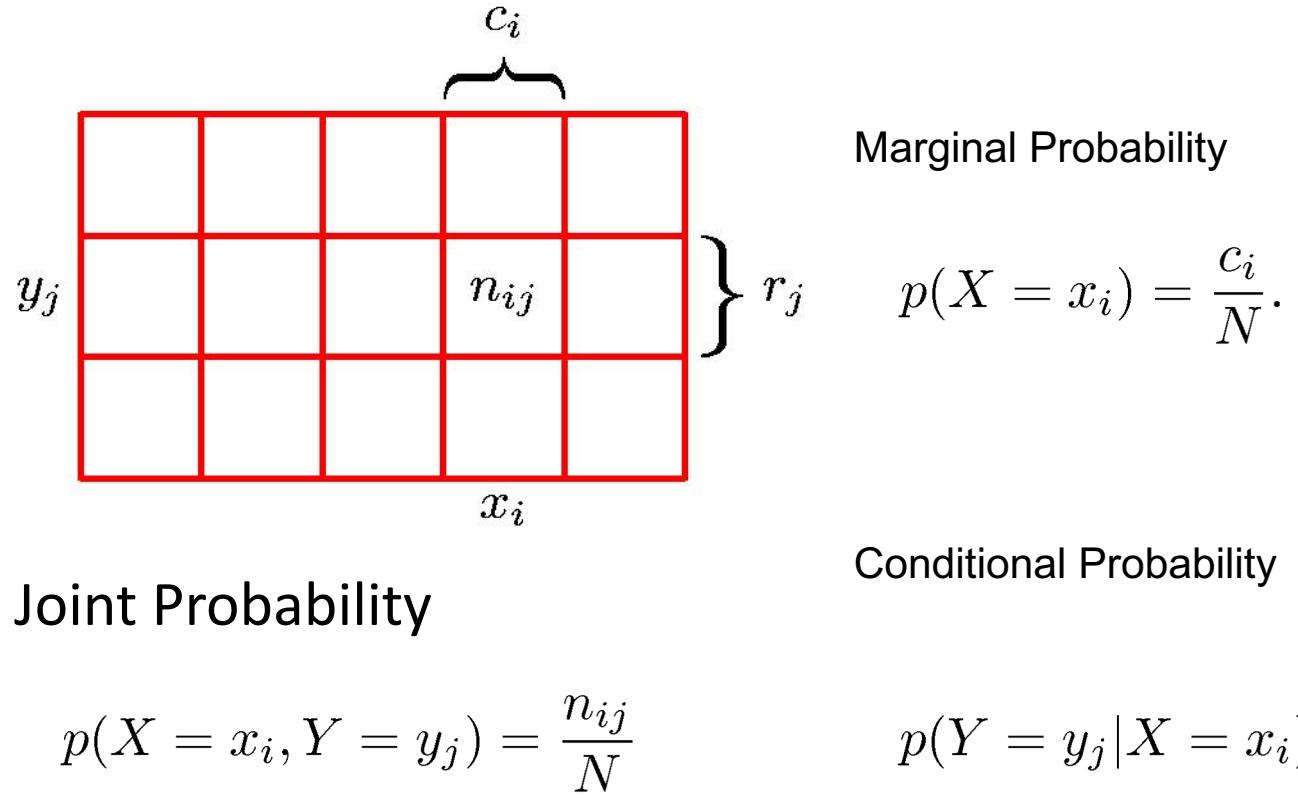
Dr. Shucheng Yu, Associate Professor
Department of Electrical and Computer Engineering
Stevens Institute of Technology

Probability Theory

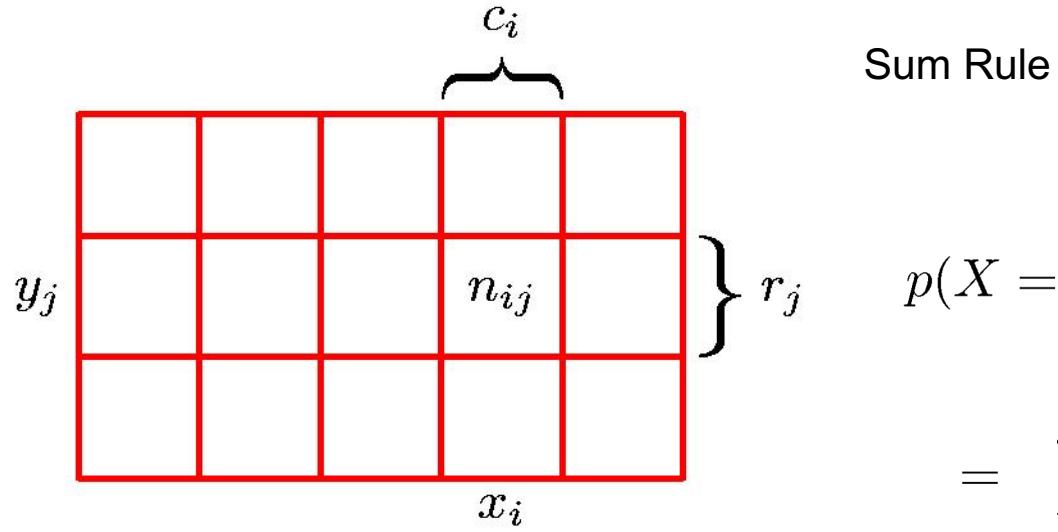
Apples and Oranges



Probability Theory



Probability Theory



$$\begin{aligned}
 p(X = x_i) &= \frac{c_i}{N} = \frac{1}{N} \sum_{j=1}^L n_{ij} \\
 &= \sum_{j=1}^L p(X = x_i, Y = y_j)
 \end{aligned}$$

Product Rule

$$\begin{aligned}
 p(X = x_i, Y = y_j) &= \frac{n_{ij}}{N} = \frac{n_{ij}}{c_i} \cdot \frac{c_i}{N} \\
 &= p(Y = y_j | X = x_i) p(X = x_i)
 \end{aligned}$$



The Rules of Probability

Sum Rule

$$p(X) = \sum_Y p(X, Y)$$

Product Rule

$$p(X, Y) = p(Y|X)p(X)$$



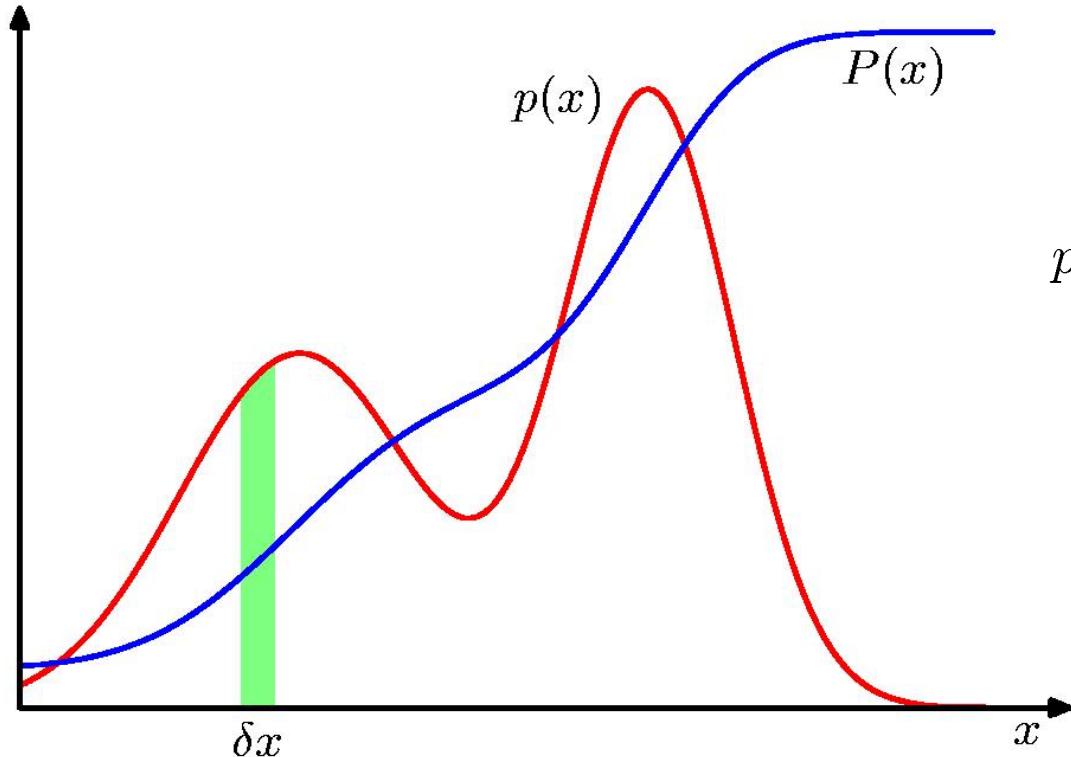
Bayes' Theorem

$$p(Y|X) = \frac{p(X|Y)p(Y)}{p(X)}$$

$$p(X) = \sum_Y p(X|Y)p(Y)$$

posterior \propto likelihood \times prior

Probability Densities



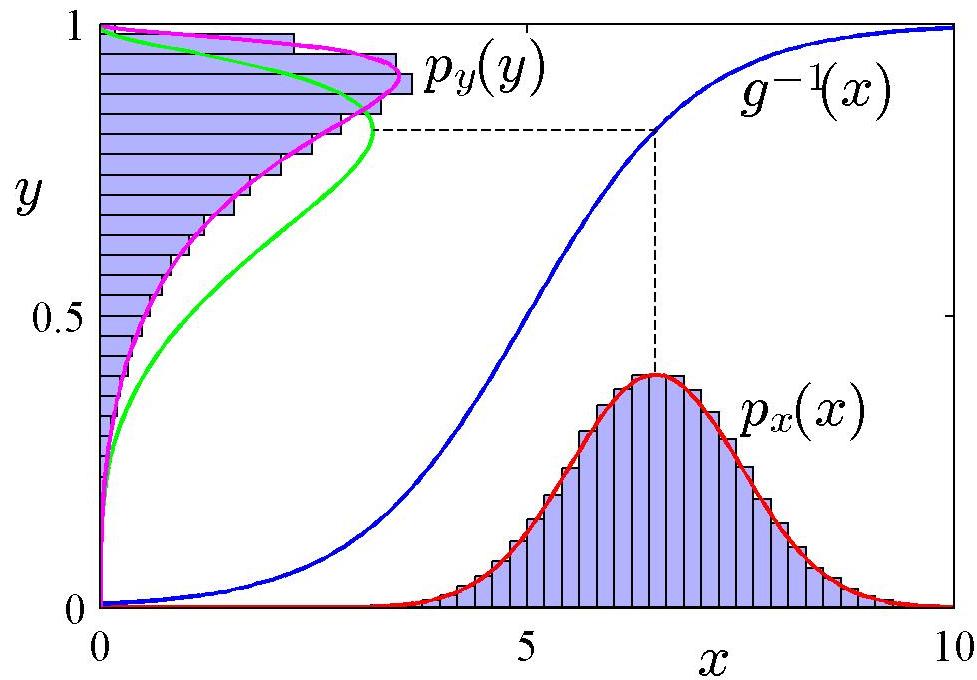
$$p(x \in (a, b)) = \int_a^b p(x) \, dx$$

$$P(z) = \int_{-\infty}^z p(x) \, dx$$

$$p(x) \geq 0$$

$$\int_{-\infty}^{\infty} p(x) \, dx = 1$$

Transformed Densities



$$\begin{aligned} p_y(y) &= p_x(x) \left| \frac{dx}{dy} \right| \\ &= p_x(g(y)) |g'(y)| \end{aligned}$$



Expectations

$$\mathbb{E}[f] = \sum_x p(x)f(x)$$

$$\mathbb{E}[f] = \int p(x)f(x) dx$$

$$\mathbb{E}_x[f|y] = \sum_x p(x|y)f(x)$$

Conditional Expectation
(discrete)

$$\mathbb{E}[f] \simeq \frac{1}{N} \sum_{n=1}^N f(x_n)$$

Approximate Expectation
(discrete and continuous)



Variances and Covariances

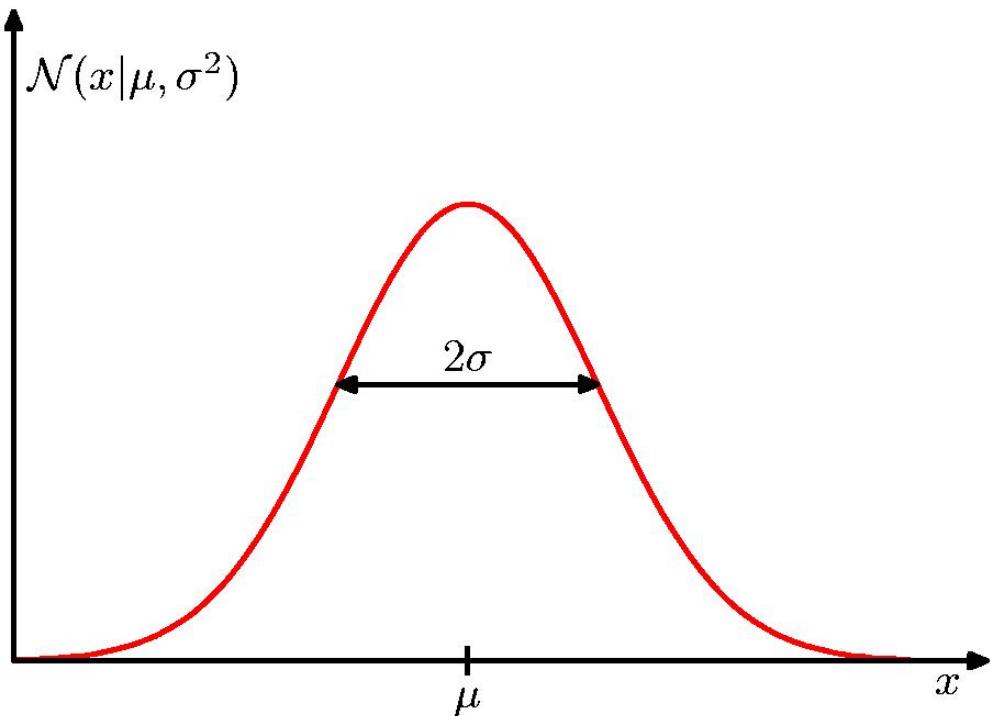
$$\text{var}[f] = \mathbb{E} \left[(f(x) - \mathbb{E}[f(x)])^2 \right] = \mathbb{E}[f(x)^2] - \mathbb{E}[f(x)]^2$$

$$\begin{aligned}\text{cov}[x, y] &= \mathbb{E}_{x,y} [\{x - \mathbb{E}[x]\} \{y - \mathbb{E}[y]\}] \\ &= \mathbb{E}_{x,y}[xy] - \mathbb{E}[x]\mathbb{E}[y]\end{aligned}$$

$$\begin{aligned}\text{cov}[\mathbf{x}, \mathbf{y}] &= \mathbb{E}_{\mathbf{x},\mathbf{y}} [\{\mathbf{x} - \mathbb{E}[\mathbf{x}]\}\{\mathbf{y}^T - \mathbb{E}[\mathbf{y}^T]\}] \\ &= \mathbb{E}_{\mathbf{x},\mathbf{y}}[\mathbf{x}\mathbf{y}^T] - \mathbb{E}[\mathbf{x}]\mathbb{E}[\mathbf{y}^T]\end{aligned}$$

The Gaussian Distribution

$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left\{ -\frac{1}{2\sigma^2}(x - \mu)^2 \right\}$$



$$\mathcal{N}(x|\mu, \sigma^2) > 0$$

$$\int_{-\infty}^{\infty} \mathcal{N}(x|\mu, \sigma^2) dx = 1$$



Gaussian Mean and Variance

$$\mathbb{E}[x] = \int_{-\infty}^{\infty} \mathcal{N}(x|\mu, \sigma^2) x \, dx = \mu$$

$$\mathbb{E}[x^2] = \int_{-\infty}^{\infty} \mathcal{N}(x|\mu, \sigma^2) x^2 \, dx = \mu^2 + \sigma^2$$

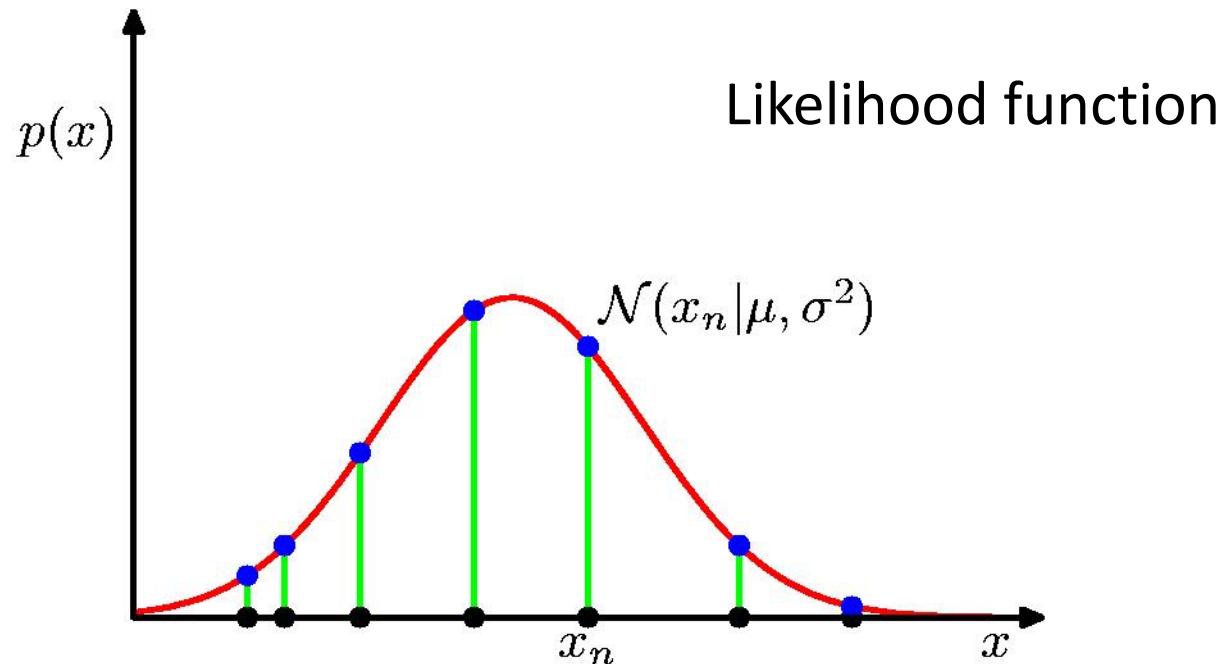
$$\text{var}[x] = \mathbb{E}[x^2] - \mathbb{E}[x]^2 = \sigma^2$$



The Multivariate Gaussian

$$\mathcal{N}(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{D/2}} \frac{1}{|\boldsymbol{\Sigma}|^{1/2}} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}$$

Gaussian Parameter Estimation



$$p(\mathbf{x}|\mu, \sigma^2) = \prod_{n=1}^N \mathcal{N}(x_n|\mu, \sigma^2)$$



Maximum (Log) Likelihood

$$\ln p(\mathbf{x}|\mu, \sigma^2) = -\frac{1}{2\sigma^2} \sum_{n=1}^N (x_n - \mu)^2 - \frac{N}{2} \ln \sigma^2 - \frac{N}{2} \ln(2\pi)$$

$$\mu_{\text{ML}} = \frac{1}{N} \sum_{n=1}^N x_n \quad \sigma_{\text{ML}}^2 = \frac{1}{N} \sum_{n=1}^N (x_n - \mu_{\text{ML}})^2$$

Sample mean

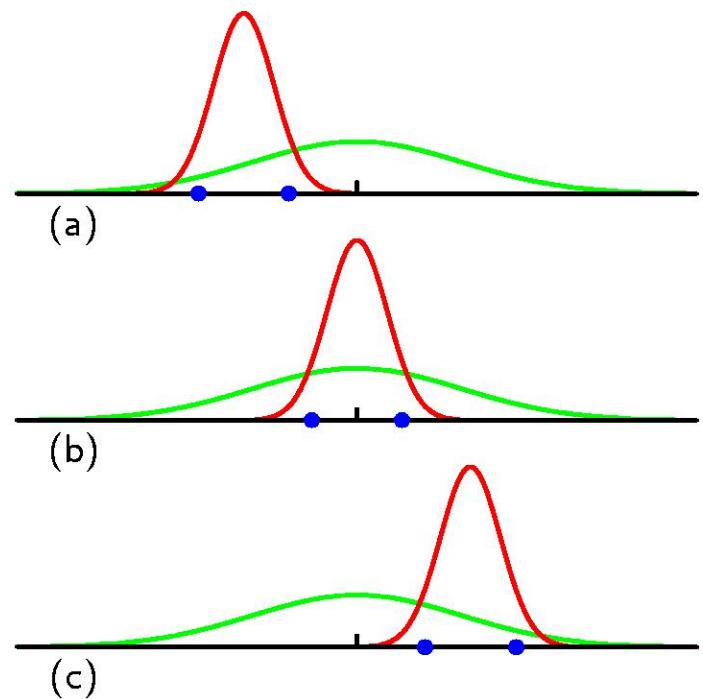
Sample variance

Properties of μ_{ML} and σ_{ML}^2

$$\mathbb{E}[\mu_{\text{ML}}] = \mu$$

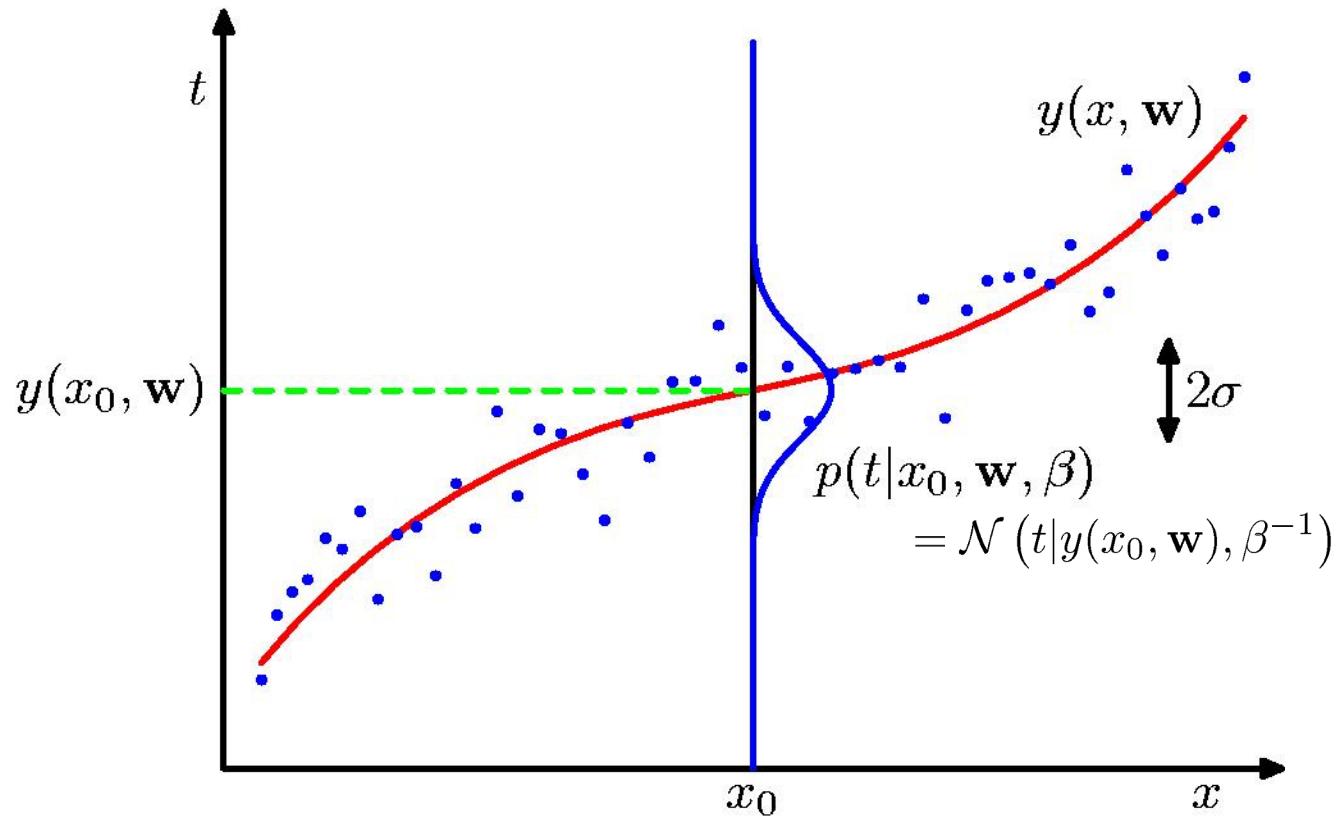
$$\mathbb{E}[\sigma_{\text{ML}}^2] = \left(\frac{N-1}{N} \right) \sigma^2$$

$$\begin{aligned}\tilde{\sigma}^2 &= \frac{N}{N-1} \sigma_{\text{ML}}^2 \\ &= \frac{1}{N-1} \sum_{n=1}^N (x_n - \mu_{\text{ML}})^2\end{aligned}$$



Sample variance is biased by a factor of $(N-1)/N$.

Curve Fitting Re-visited





Maximum Likelihood

$$p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta) = \prod_{n=1}^N \mathcal{N}(t_n | y(x_n, \mathbf{w}), \beta^{-1})$$

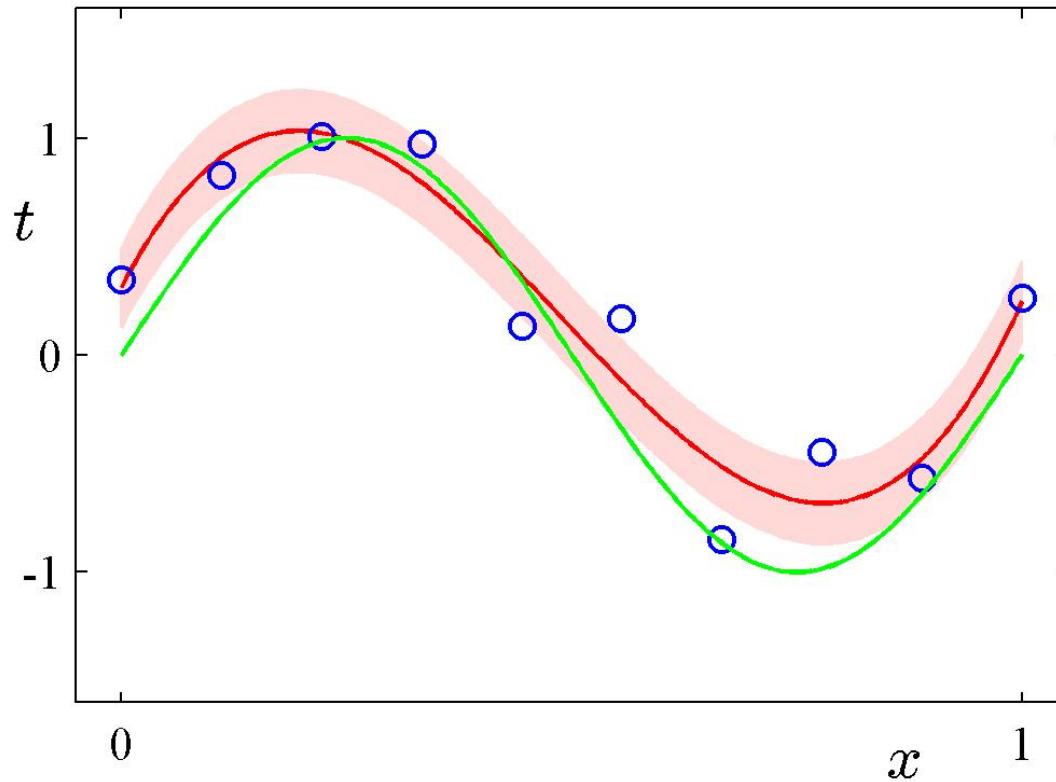
$$\ln p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta) = -\underbrace{\frac{\beta}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2}_{\beta E(\mathbf{w})} + \frac{N}{2} \ln \beta - \frac{N}{2} \ln(2\pi)$$

Determine \mathbf{w}_{ML} by minimizing sum-of-squares error, $E(\mathbf{w})$.

$$\frac{1}{\beta_{\text{ML}}} = \frac{1}{N} \sum_{n=1}^N \{y(x_n, \mathbf{w}_{\text{ML}}) - t_n\}^2$$

Predictive Distribution

$$p(t|x, \mathbf{w}_{\text{ML}}, \beta_{\text{ML}}) = \mathcal{N}(t|y(x, \mathbf{w}_{\text{ML}}), \beta_{\text{ML}}^{-1})$$





Maximum Posterior (MAP)

$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I}) = \left(\frac{\alpha}{2\pi}\right)^{(M+1)/2} \exp\left\{-\frac{\alpha}{2}\mathbf{w}^T\mathbf{w}\right\}$$

$$p(\mathbf{w}|\mathbf{x}, \mathbf{t}, \alpha, \beta) \propto p(\mathbf{t}|\mathbf{x}, \mathbf{w}, \beta)p(\mathbf{w}|\alpha)$$

$$\beta \tilde{E}(\mathbf{w}) = \frac{\beta}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2 + \frac{\alpha}{2} \mathbf{w}^T \mathbf{w}$$

Determine \mathbf{w}_{MAP} by minimizing regularized sum-of-squares error, $\tilde{E}(\mathbf{w})$.



Bayesian Curve Fitting

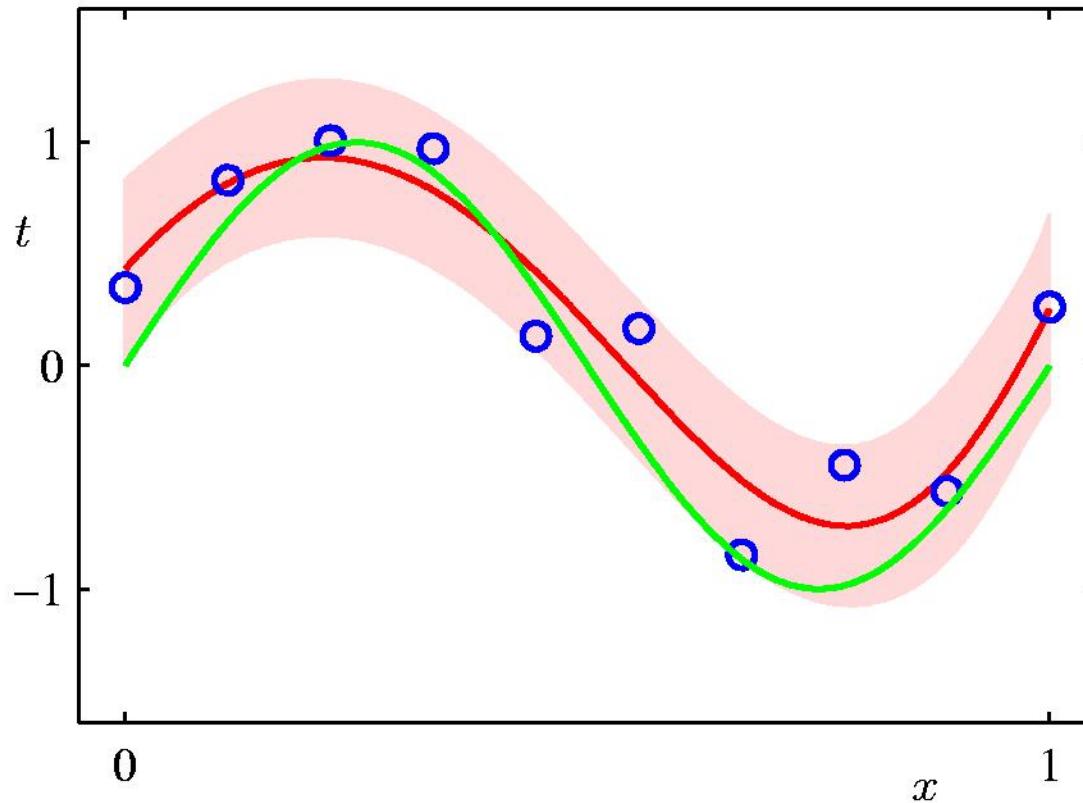
$$p(t|x, \mathbf{x}, \mathbf{t}) = \int p(t|x, \mathbf{w})p(\mathbf{w}|\mathbf{x}, \mathbf{t}) d\mathbf{w} = \mathcal{N}(t|m(x), s^2(x))$$

$$m(x) = \beta \boldsymbol{\phi}(x)^T \mathbf{S} \sum_{n=1}^N \boldsymbol{\phi}(x_n) t_n \quad s^2(x) = \beta^{-1} + \boldsymbol{\phi}(x)^T \mathbf{S} \boldsymbol{\phi}(x)$$

$$\mathbf{S}^{-1} = \alpha \mathbf{I} + \beta \sum_{n=1}^N \boldsymbol{\phi}(x_n) \boldsymbol{\phi}(x_n)^T \quad \boldsymbol{\phi}(x_n) = (x_n^0, \dots, x_n^M)^T$$

Bayesian Predictive Distribution

$$p(t|x, \mathbf{x}, \mathbf{t}) = \mathcal{N}(t|m(x), s^2(x))$$

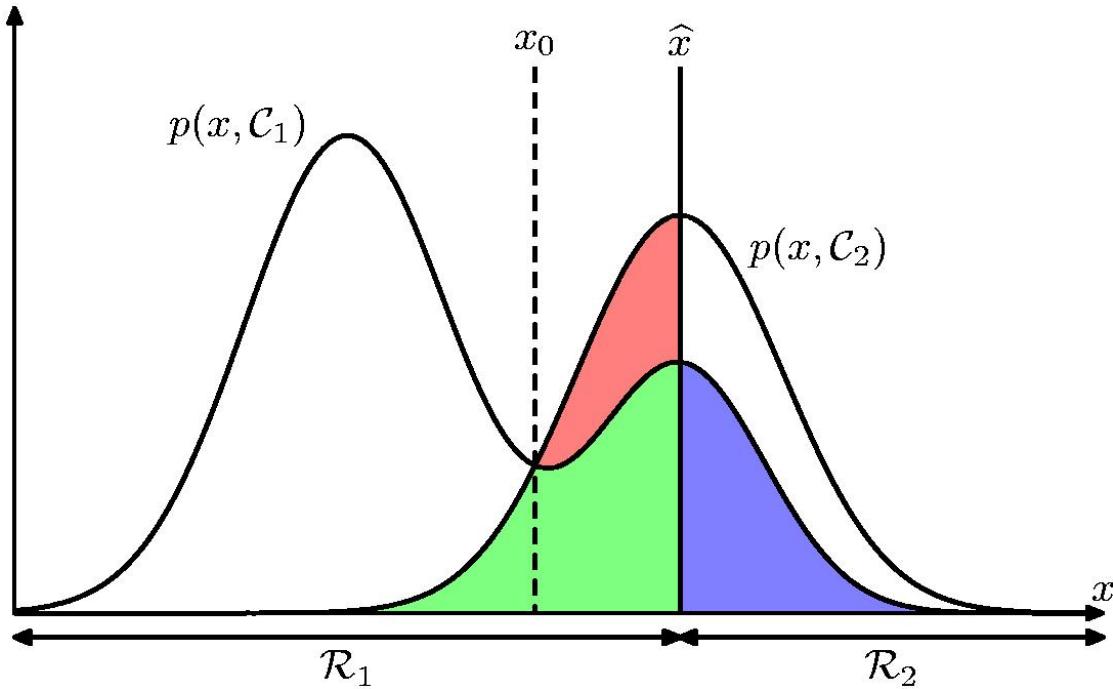




Decision Theory

- Inference step
Determine either $p(t|x)$ or $p(x,t)$.
- Decision step
For given x , determine optimal t .

Minimum Misclassification Rate



$$\begin{aligned}
 p(\text{mistake}) &= p(\mathbf{x} \in \mathcal{R}_1, \mathcal{C}_2) + p(\mathbf{x} \in \mathcal{R}_2, \mathcal{C}_1) \\
 &= \int_{\mathcal{R}_1} p(\mathbf{x}, \mathcal{C}_2) d\mathbf{x} + \int_{\mathcal{R}_2} p(\mathbf{x}, \mathcal{C}_1) d\mathbf{x}.
 \end{aligned}$$



Minimum Expected Loss

- Example: classify medical images as ‘cancer’ or ‘normal’

| | | Decision | |
|-------|--------|----------|--------|
| | | cancer | normal |
| Truth | cancer | 0 | 1000 |
| | normal | 1 | 0 |



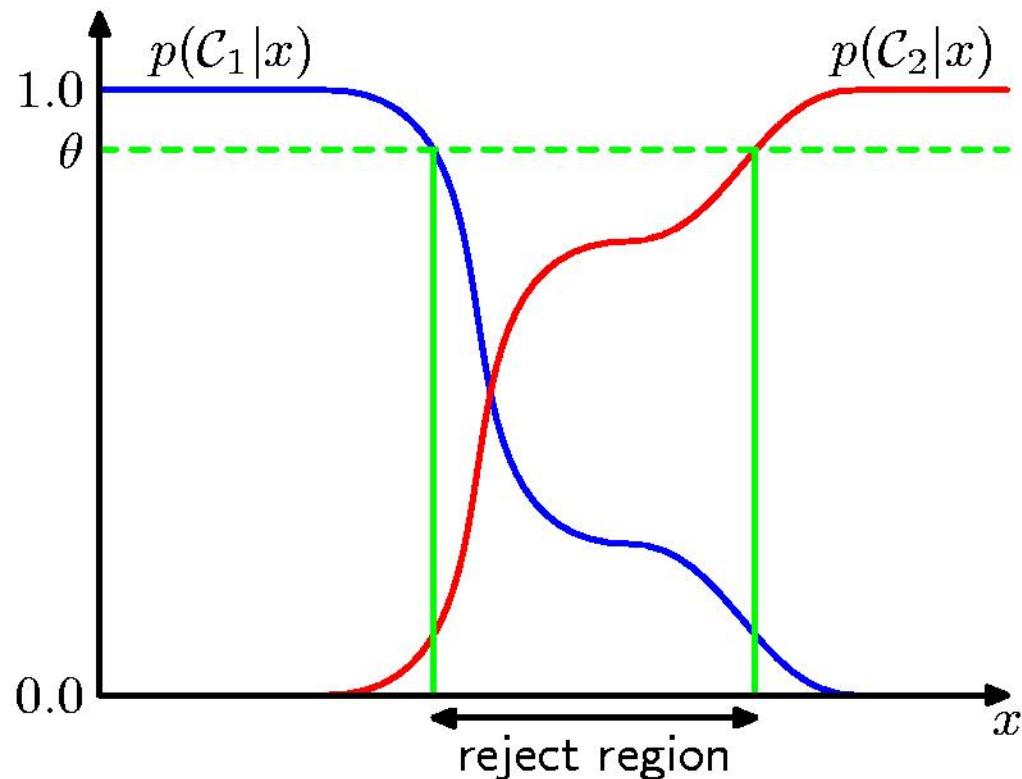
Minimum Expected Loss

$$\mathbb{E}[L] = \sum_k \sum_j \int_{\mathcal{R}_j} L_{kj} p(\mathbf{x}, \mathcal{C}_k) d\mathbf{x}$$

Regions \mathcal{R}_j are chosen to minimize

$$\mathbb{E}[L] = \sum_k L_{kj} p(\mathcal{C}_k | \mathbf{x})$$

Reject Option





Acknowledgement

Significant part of the slides were based on Dr. Christopher M. Bishop's material at
<https://www.microsoft.com/en-us/research/people/cmbishop/#!prml-book?from=http%3A%2F%2Fresearch.microsoft.com%2F%7Ecmbishop%2Fprml>;

For details please read Chapter 1 of textbook "Pattern Recognition and Machine Learning", by Christopher Bishop.



STEVENS
INSTITUTE *of* TECHNOLOGY
THE INNOVATION UNIVERSITY®

stevens.edu

