

# CS 519: Scientific Visualization

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## Network Visualization

Eric Shaffer

**Some slides adapted from:**

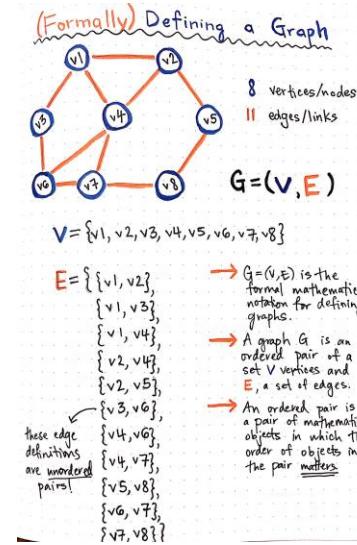
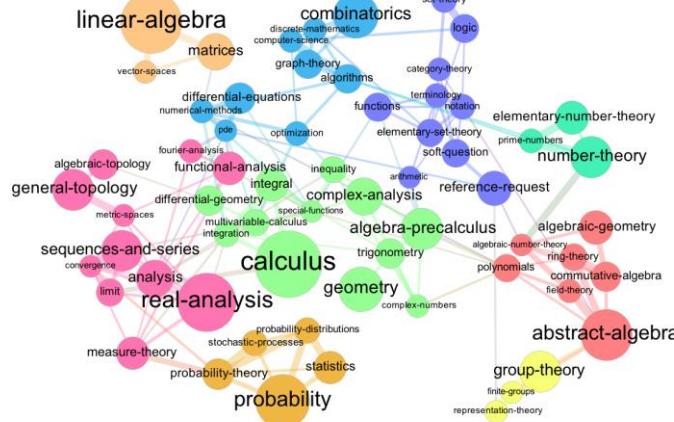
Alexandru Telea, *Data Visualization Principles and Practice*  
Professor Tamara Munzner, University of British Columbia

# Network Visualization

**Graph drawing** is an area of mathematics and computer science combining methods from geometric graph theory and information visualization to derive two-dimensional depictions of graphs arising from applications such as social network analysis, cartography, linguistics, and bioinformatics.<sup>[1]</sup>

A drawing of a graph or **network diagram** is a pictorial representation of the vertices and edges of a graph.

- Wikipedia



# Network Visualization

## Arrange networks and trees

### → Node–Link Diagrams

Connection Marks

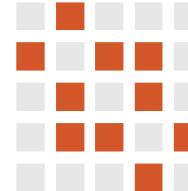
NETWORKS  TREES



### → Adjacency Matrix

Derived Table

NETWORKS  TREES



### → Enclosure

Containment Marks

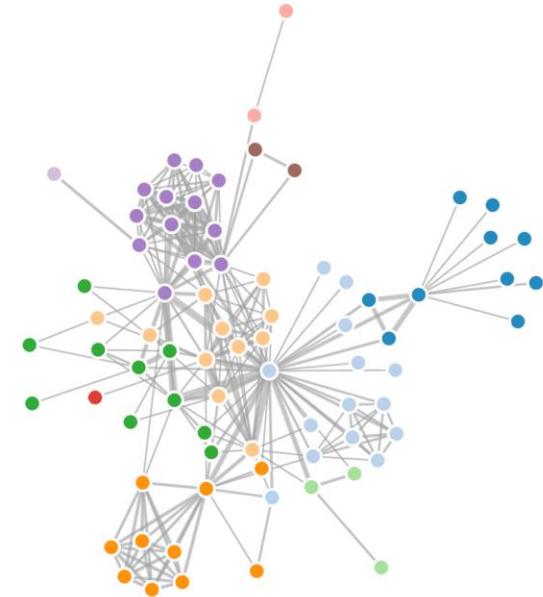
NETWORKS  TREES



# Force-Directed Graph Layout

## Idiom: **force-directed placement**

- visual encoding
  - link connection marks, node point marks
- considerations
  - spatial position: no meaning directly encoded
    - left free to minimize crossings
  - proximity semantics?
    - sometimes meaningful
    - sometimes arbitrary, artifact of layout algorithm
    - tension with length
      - long edges more visually salient than short
- tasks
  - explore topology; locate paths, clusters
- scalability
  - node/edge density  $E < 4N$



<http://mbostock.github.com/d3/ex/force.html>

# Force-Directed Layouts

- Can be applied to general graphs (not just directed or trees, etc.)
- design an energy function  $E : \mathbf{R}^m \rightarrow \mathbf{R}_+$  which is low when layout is ‘good’
  - connected nodes should be close
  - layout distance should reflect graph-theoretic distance
  - nodes should not overlap
  - aspect ratio should be balanced
- define  $E$  in terms of forces

[Fruchterman and Reingold ‘91]

[Eades ‘84]

$$\begin{aligned}\mathbf{F}_a(n_i, n_j) &= \frac{|\mathbf{p}_i - \mathbf{p}_j|^2}{k}, & \mathbf{F}_a(n_i, n_j) &= k \log |\mathbf{p}_i - \mathbf{p}_j| \\ \mathbf{F}_r(n_i, n_j) &= -\frac{k^2}{|\mathbf{p}_i - \mathbf{p}_j|} & \mathbf{F}_r(n_i, n_j) &= -\frac{k}{|\mathbf{p}_i - \mathbf{p}_j|^2}.\end{aligned}$$

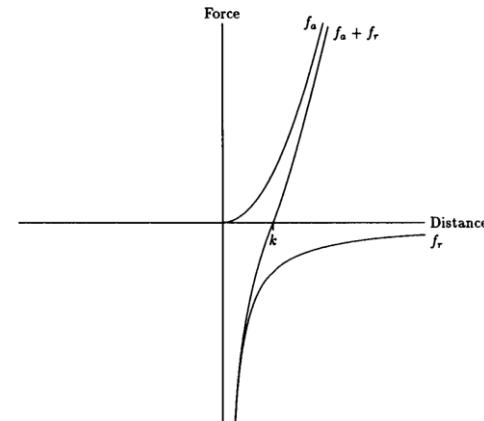
- find node positions  $p_i$  by minimizing  $E$ :
  - move nodes iteratively along  $F$  with some small distance
  - compute  $F_r$  only w.r.t. close nodes (to save time)
  - use spatial search structures (e.g. octrees) to find close nodes
  - stop when  $E$  low enough or max #iterations reached

# Fruchterman-Reingold

$$\mathbf{F}_a(n_i, n_j) = \frac{|\mathbf{p}_i - \mathbf{p}_j|^2}{k},$$

$$\mathbf{F}_r(n_i, n_j) = -\frac{k^2}{|\mathbf{p}_i - \mathbf{p}_j|}$$

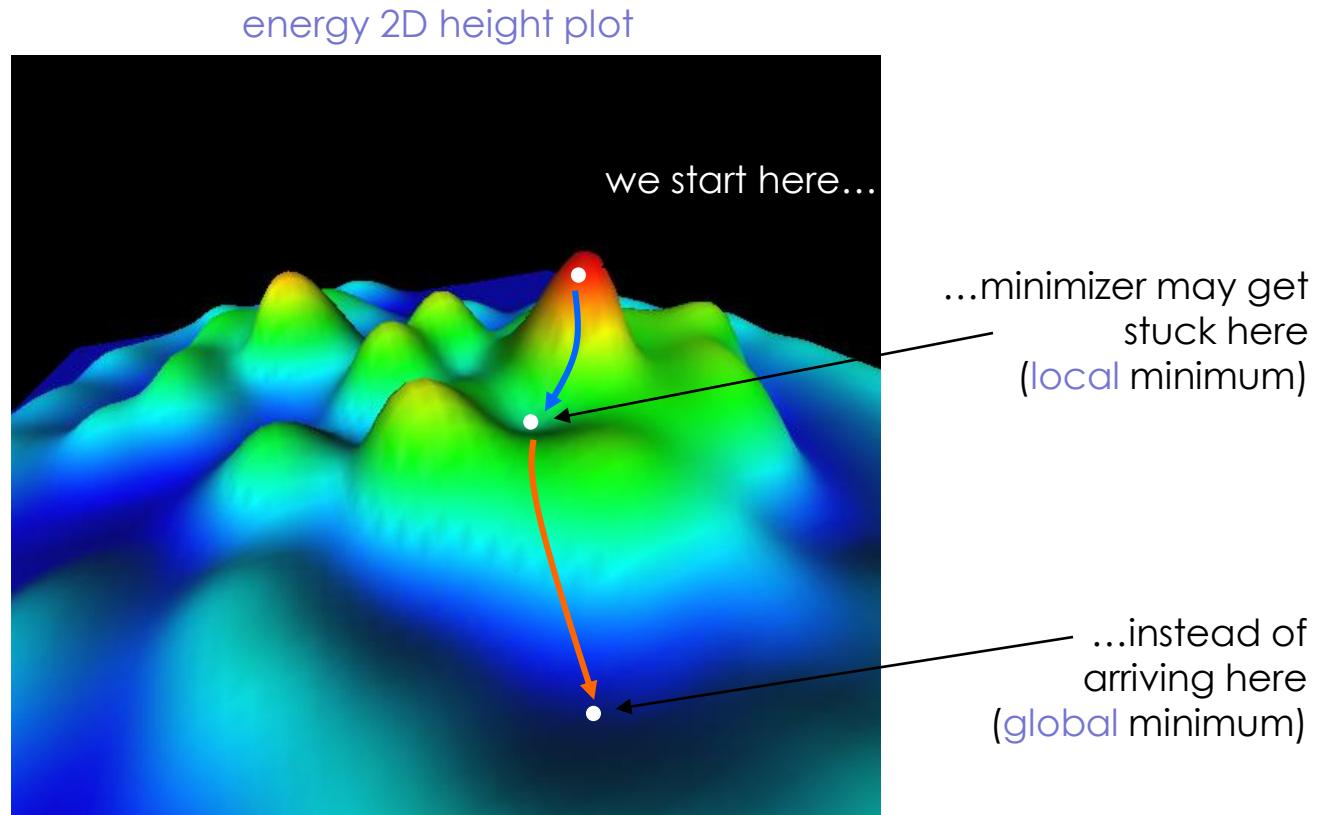
- We move  $n_i$  according to the force vectors above
  - Move along the line between  $n_i$  and  $n_j$
- $F_a$  (attraction) only applies to  $n_i$  and  $n_j$  that share an edge
- $F_r$  (repulsion) applies to all pairs of vertices
- $K$  is a constant, original paper uses  $k = c \sqrt{\frac{WL}{|V|}}$ 
  - $W$ =width of canvas
  - $L$ =length of canvas
  - $|V|$  is number of vertices
  - $C$  is “found experimentally”
  - Goal is to distribute vertices uniformly
    - But with connected vertices close to each other
  - $K$  is radius of empty circle around a vertex...
  - $K$  is the distance at which the forces balance....



# Force-Directed Layouts

## Problems:

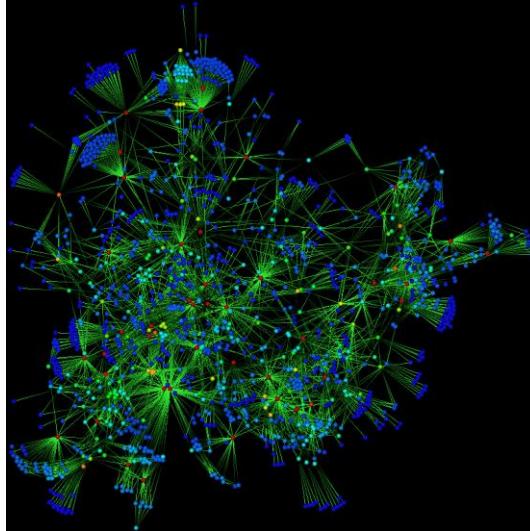
- the energy function is not monotonic!
- minimizers such as previous gradient descent work locally → can get stuck in local minima
- solve this by more advanced minimizers (see e.g. [Di Battista et al '94])
- drawings not intuitive; no clear ordering → where to start reading the drawing??



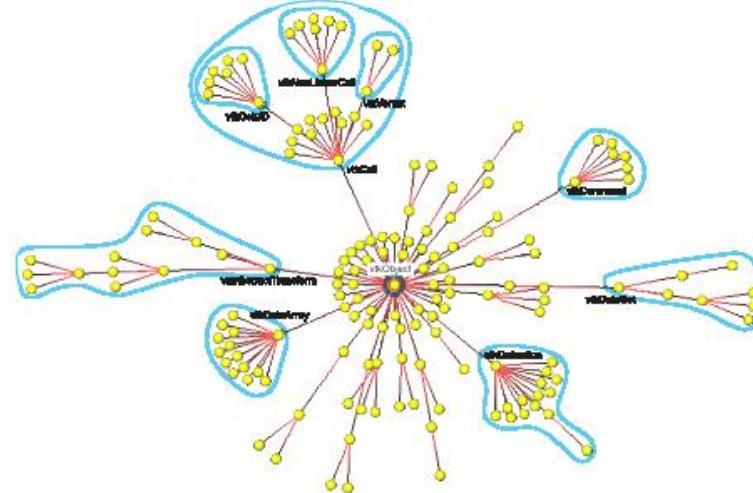
# Force-Directed Layouts

## Examples

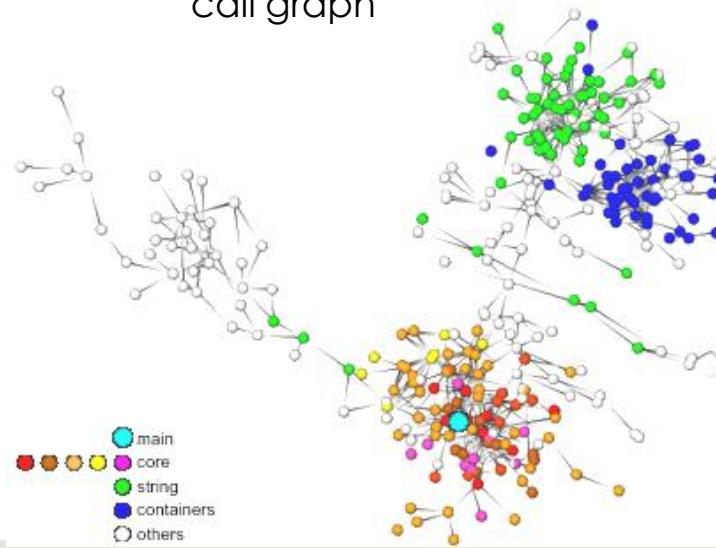
call graph



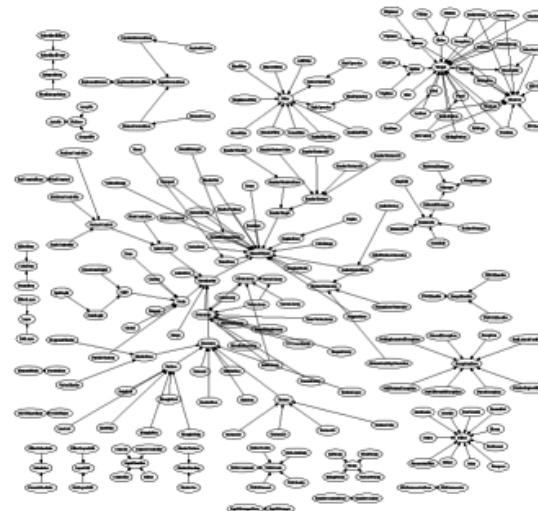
inheritance tree



call graph



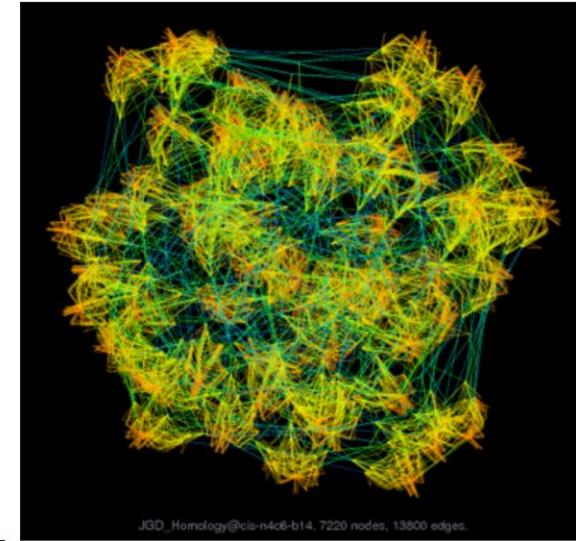
inheritance forest



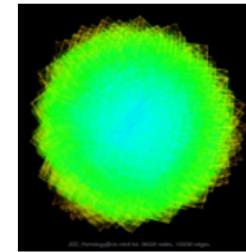
# Multi-Level Force-Directed Graph Layout

## Idiom: **sfdp** (multi-level force-directed placement)

- data
  - original: network
  - derived: cluster hierarchy atop it
- considerations
  - better algorithm for same encoding technique
    - same: fundamental use of space
    - hierarchy used for algorithm speed/quality but not shown explicitly
- scalability
  - nodes, edges: 1K-10K
  - hairball problem eventually hits



[Efficient and high quality force-directed graph drawing.  
Hu. *The Mathematica Journal* 10:37–71, 2005.]

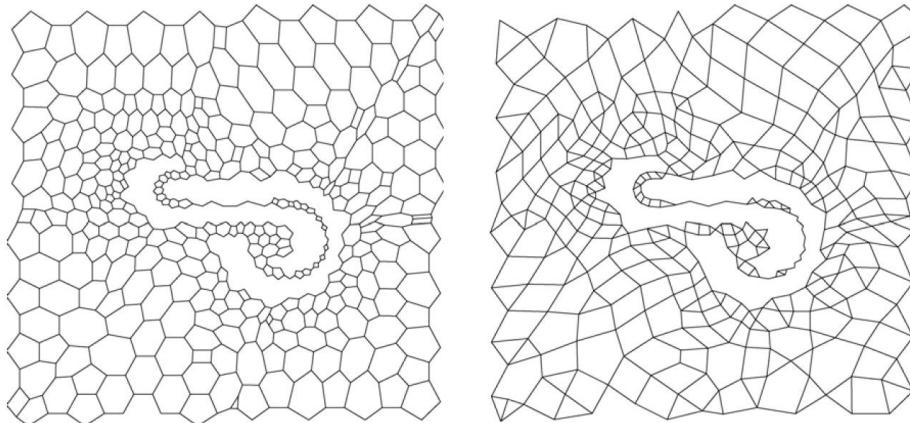


<http://www.research.att.com/yifanhu/GALLERY/GRAPHS/index1.html>

# Multi-Level Force-Directed Graph Layout

The multilevel approach has three distinctive phases: coarsening, coarsest graph layout, and prolongation and refinement. In the coarsening phase, a series of coarser and coarser graphs,  $G^0, G^1, \dots, G^l$ , are generated. The aim is for each coarser graph  $G^{k+1}$  to encapsulate the information needed to lay out its “parent”  $G^k$  while containing fewer vertices and edges. The coarsening continues until a graph with only a small number of vertices is reached. The optimal layout for the coarsest graph can be found cheaply. The layouts on the coarser graphs are recursively prolonged to the finer graphs, with further refinement at each level.

- Efficient, high-quality force-directed graph drawing by Hu

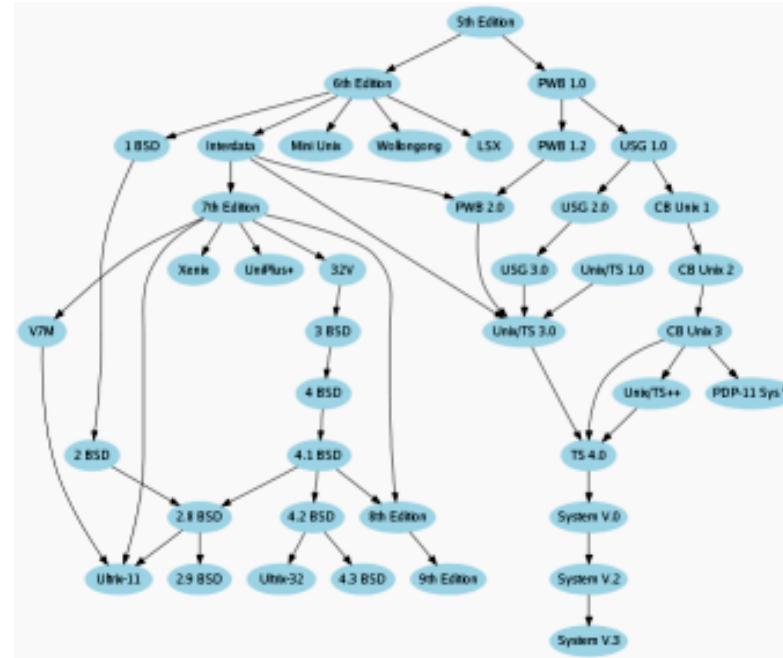


Graph coarsening example

# Directed Acyclic Graphs

- class hierarchies (multiple inheritance)
- organization structure (multiple bosses)
- also created from general graphs by removing cycles

Hierarchical layout [Sugiyama et al '81]



UNIX system history drawn with the GraphViz package ([www.graphviz.org](http://www.graphviz.org))

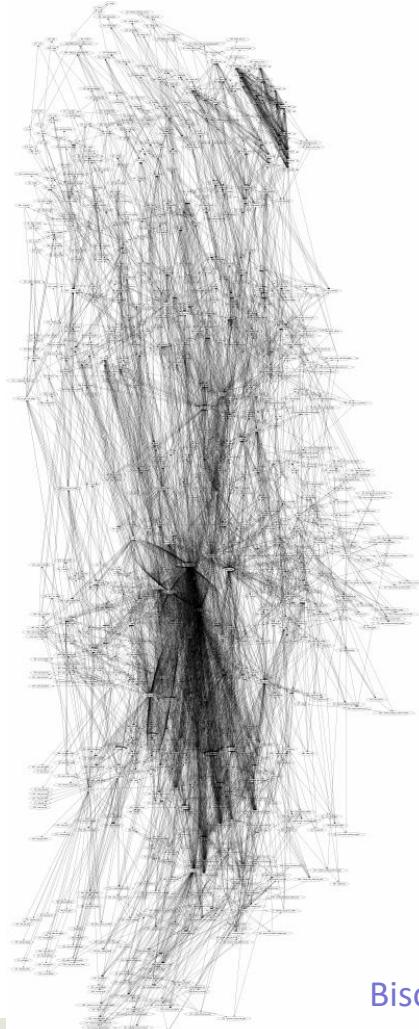
Algorithm:

- swap edges to eliminate cycles and get a directed (rooted) graph
- for every level, starting from root:
  - assign  $y$  coordinate as function of level
  - permute nodes on level to minimize edge lengths/crossings
- edges drawn as **curves** (splines) to minimize crossings

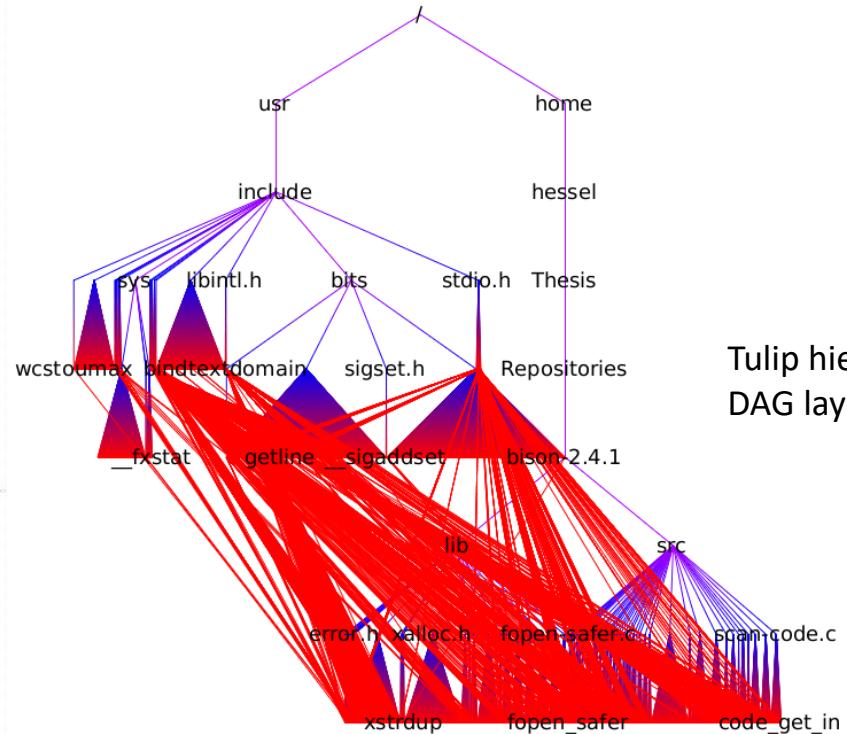
# Directed Acyclic Graphs

## Hierarchical layout scalability

- OK for < 1000 nodes or edges
- too many crossings and/or bad aspect ratios for large graphs
- we shall see later how to handle large graphs



GraphViz hierarchical  
DAG layout



Tulip hierarchical  
DAG layout

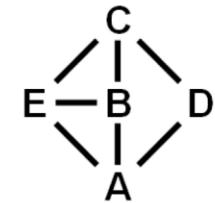
Bison library call graph (3.214 nodes, 14.382 edges)

# Adjacency Matrix Representation

## Idiom: adjacency matrix view

- data: network
  - transform into same data/encoding as heatmap
- derived data: table from network
  - 1 quant attrib
    - weighted edge between nodes
  - 2 categ attribs: node list x 2
- visual encoding
  - cell shows presence/absence of edge
- scalability
  - 1K nodes, 1M edges

A	A	B	C	D	E
B		B			
C			C		
D				D	
E					E

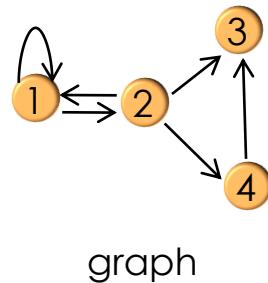


[NodeTrix: a Hybrid Visualization of Social Networks.  
Henry, Fekete, and McGuffin. IEEE TVCG (Proc. InfoVis)  
13(6):1302-1309, 2007.]



[Points of view: Networks. Gehlenborg and Wong. Nature Methods 9:115.]

# Matrix Representation



ingoing edges

	1	2	3	4
1	X	X		
2	X			
3		X		X
4		X		

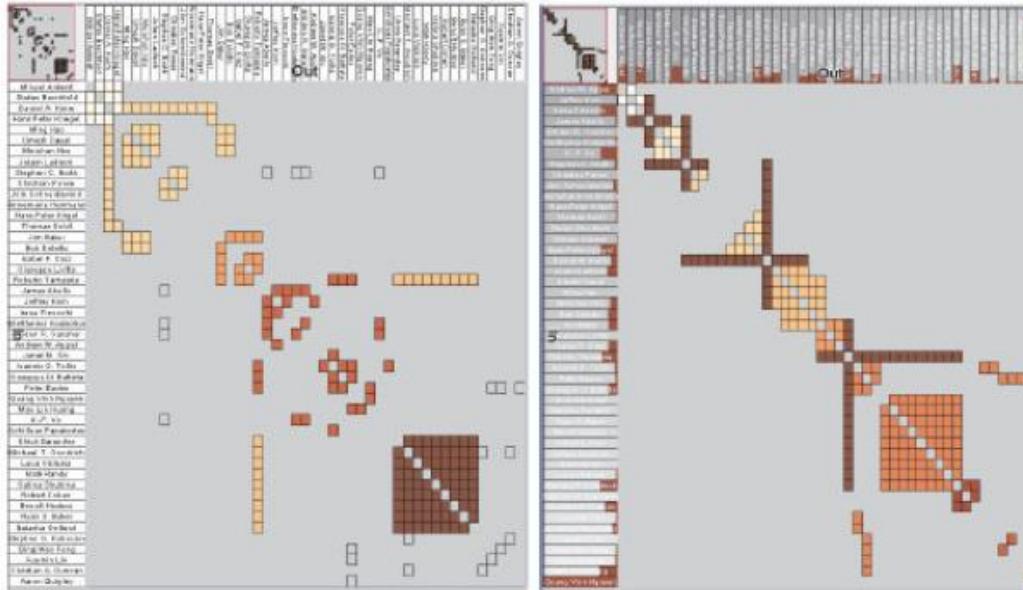
directed adjacency matrix

	1	2	3	4
1	X	X		
2	X		X	X
3		X		X
4		X	X	

undirected adjacency matrix

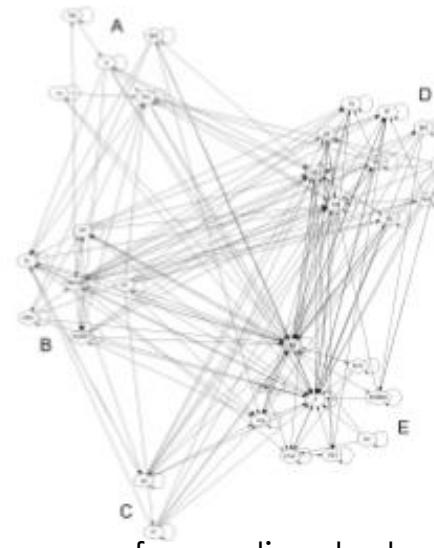
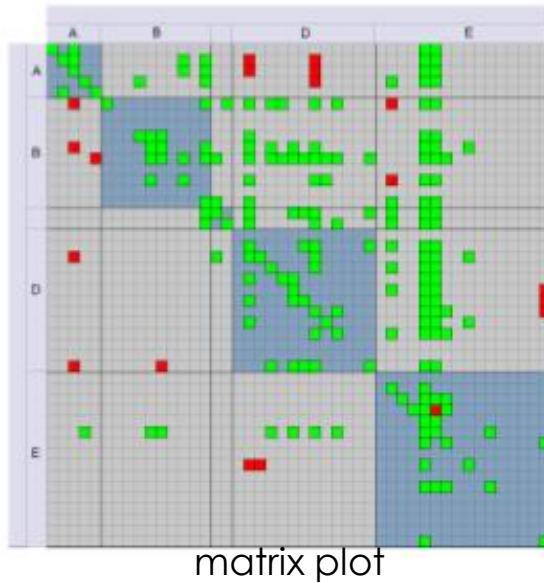
social network  
graph

- order of rows and columns highly impacts the visualization, e.g. spotting clusters



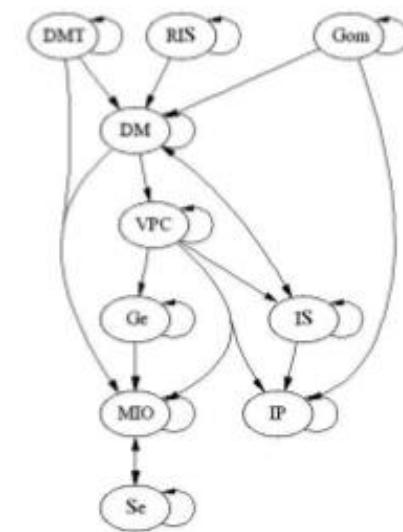
# Application: Visualizing Software Structure

- consider a software **call graph**
  - nodes: functions; edges: call relations ( $f$  calls  $g$  – directed graph)
  - functions are contained in modules ( $f \in A, g \in B, \dots$ )
  - some calls are allowed, some now (depending on system architecture)
- which layout is best for spotting call structure problems?



force directed

- some connected components visible
- image is cluttered...  
...even if this graph is really small
- least preferred option



hierarchical DAG  
(for a subgraph only)

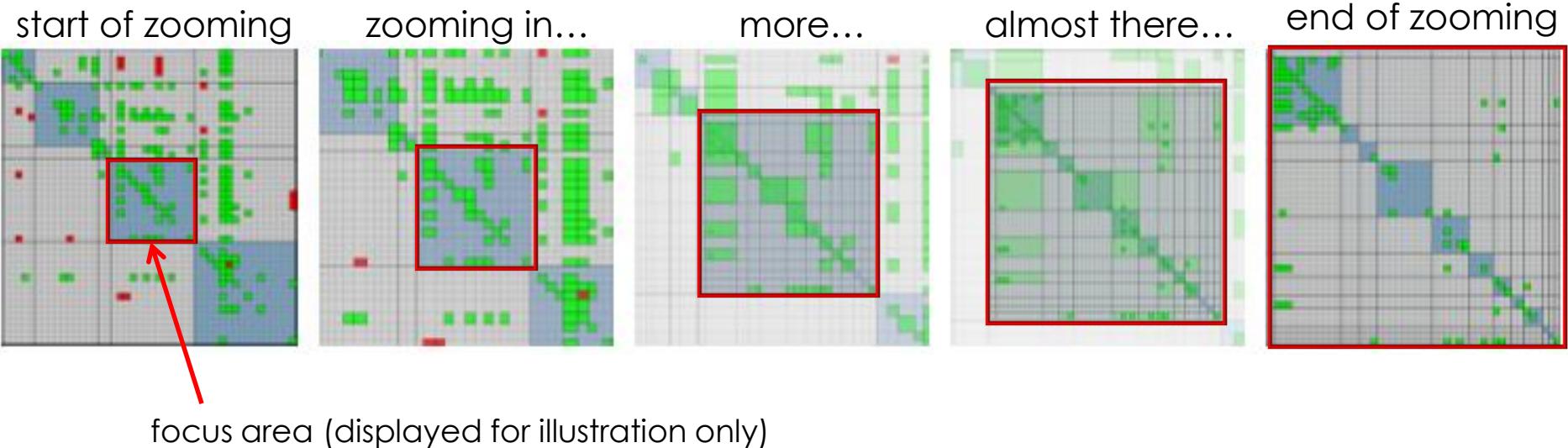
- good for path tracing
- some structure is apparent...  
...but is it a layout artefact?
- top-down order meaningful

- no clutter, clean image
- show violations by colors (red=not allowed)
- tracing call paths is hard
- detecting 'connected components' is hard

# Matrix Plots

## Interaction

- zoom in and out – display the matrix at different levels of detail
- smoothly interpolate the cell sizes (using alpha blending) during zooming



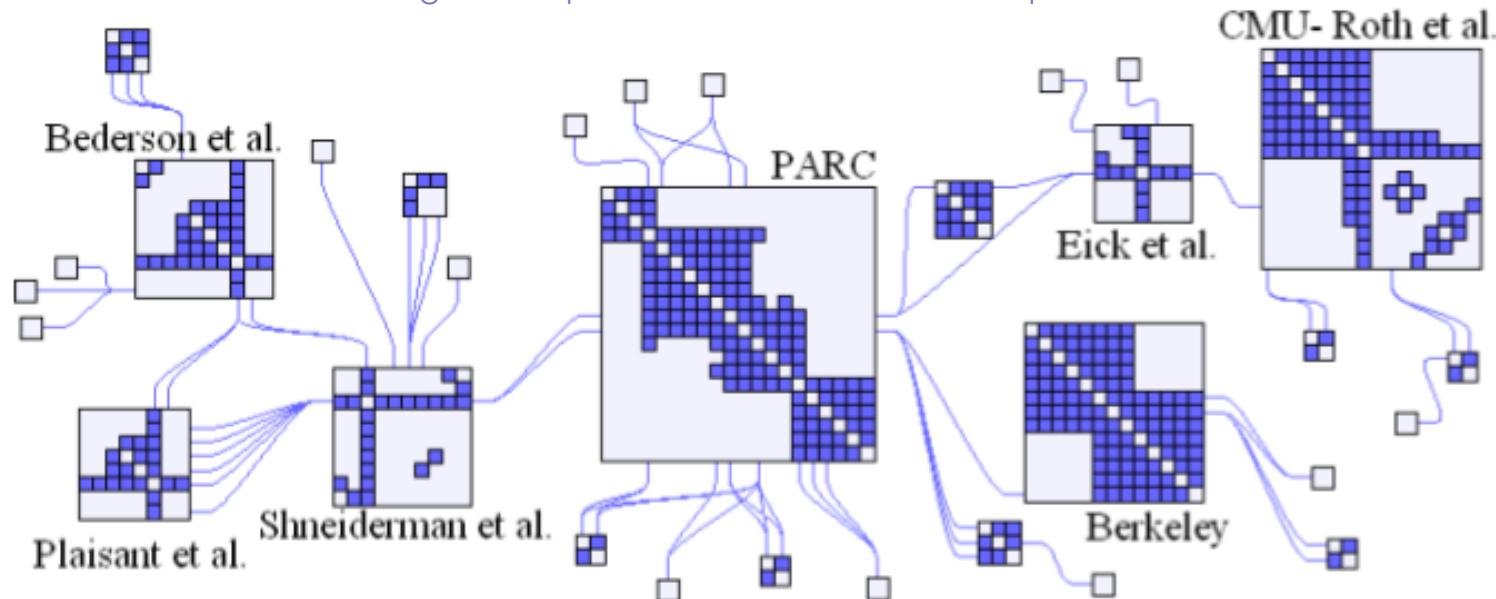
# Matrix Plots and Node-Link Layouts

- matrix plots are compact and clean, but don't clearly show structure
- node-link layouts show structure, but get cluttered

## Idea

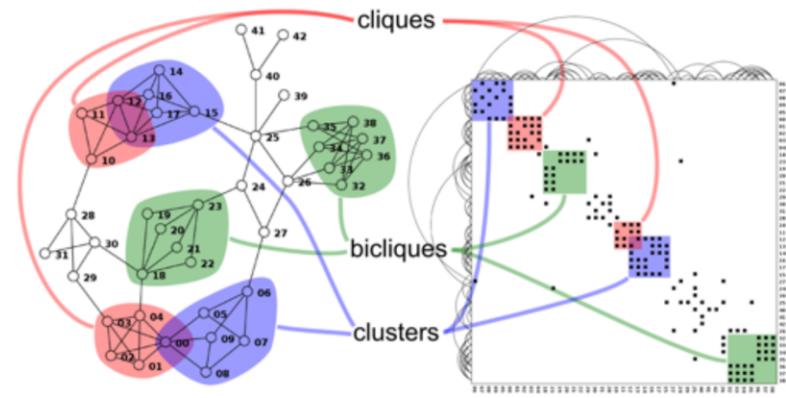
- aggregate graph (find clusters of strongly-connected components)
- show each cluster with a matrix plot
- show cluster-graph with a node-link layout

Largest component of InfoVis co-authorship network



# Connection Versus Adjacency Comparison

- adjacency matrix strengths
  - predictability, scalability, supports reordering
  - some topology tasks trainable
- node-link diagram strengths
  - topology understanding, path tracing
  - intuitive, no training needed
- empirical study
  - node-link best for small networks
  - matrix best for large networks
    - if tasks don't involve topological structure!



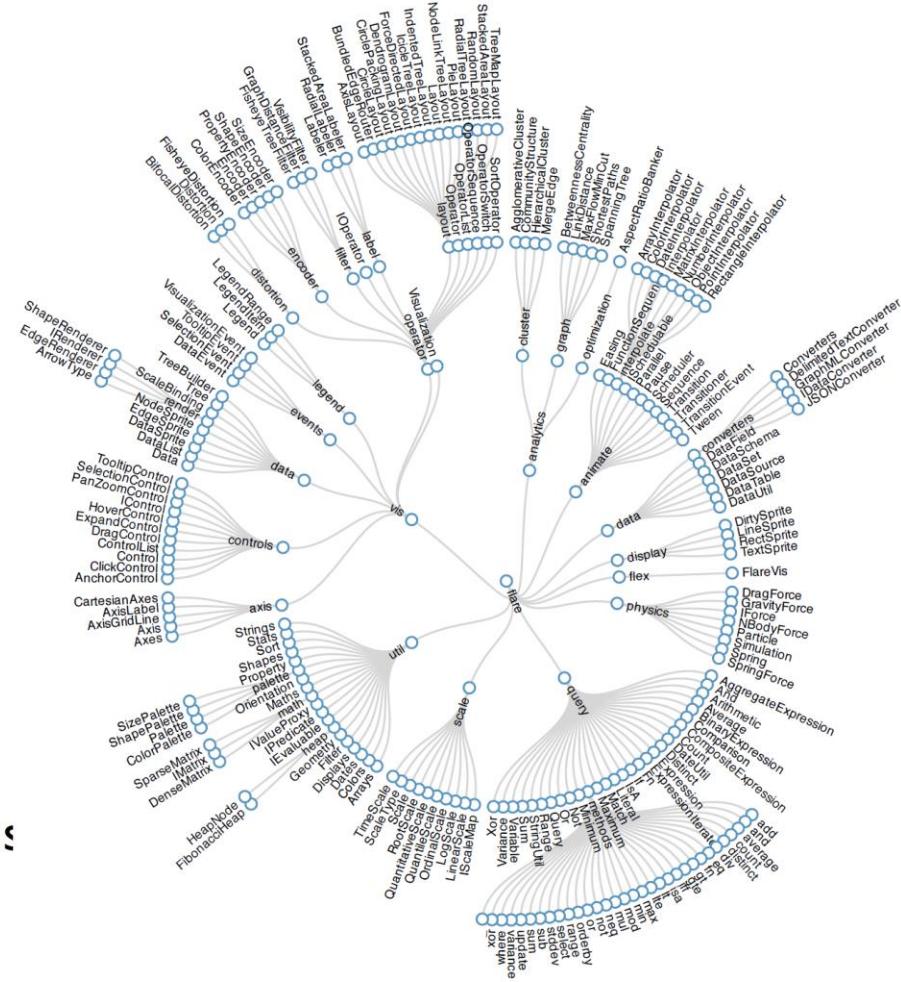
<http://www.michaelmcguffin.com/courses/vis/patternsInAdjacencyMatrix.png>

[On the readability of graphs using node-link and matrix-based representations: a controlled experiment and statistical analysis.  
Ghoniem, Fekete, and Castagliola. *Information Visualization* 4:2 (2005), 114–135.]

# Radial Tree Layout

## Idiom: radial node-link tree

- data
    - tree
  - encoding
    - link connection marks
    - point node marks
    - radial axis orientation
      - angular proximity: siblings
      - distance from center: depth in tree
  - tasks
    - understanding topology, following paths
  - scalability
    - 1K - 10K nodes

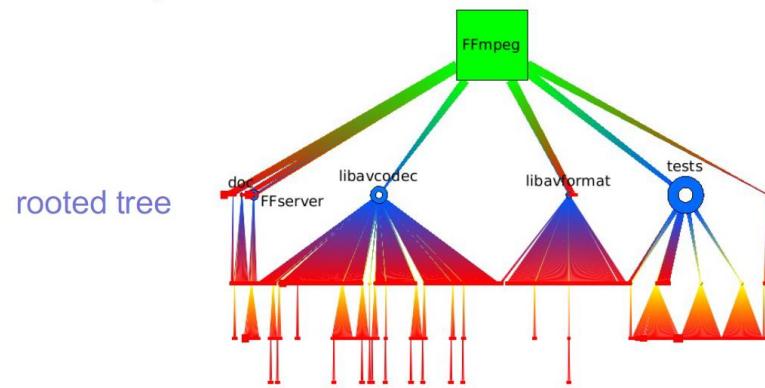


# Tree Layout Idioms

Trees are acyclic graphs

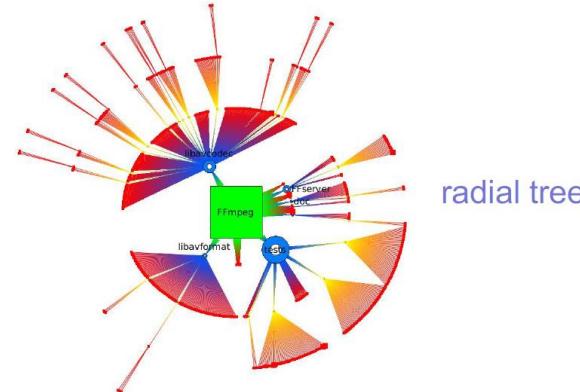
## Examples

- icon size: folder size
- icon shape+color: level in tree

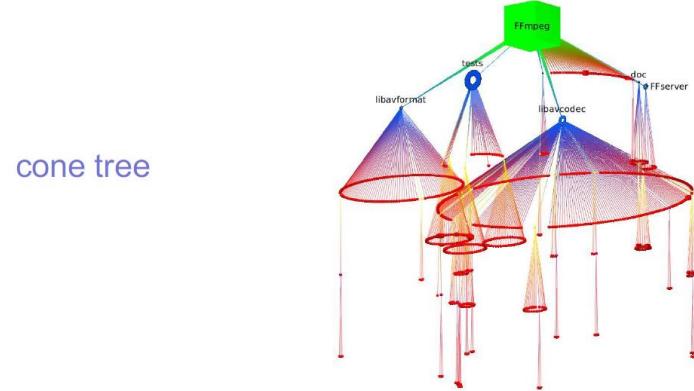


rooted tree

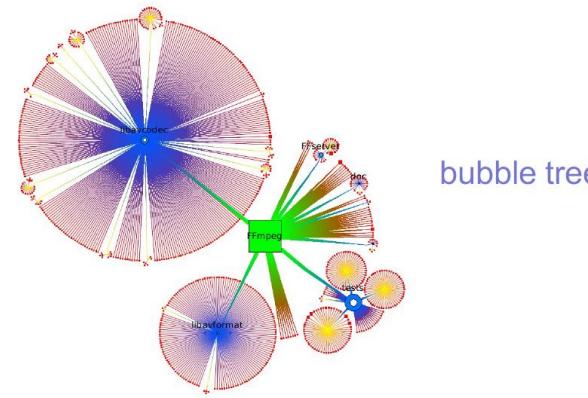
ffmpeg video code C library: 785 files, 42 folders



radial tree



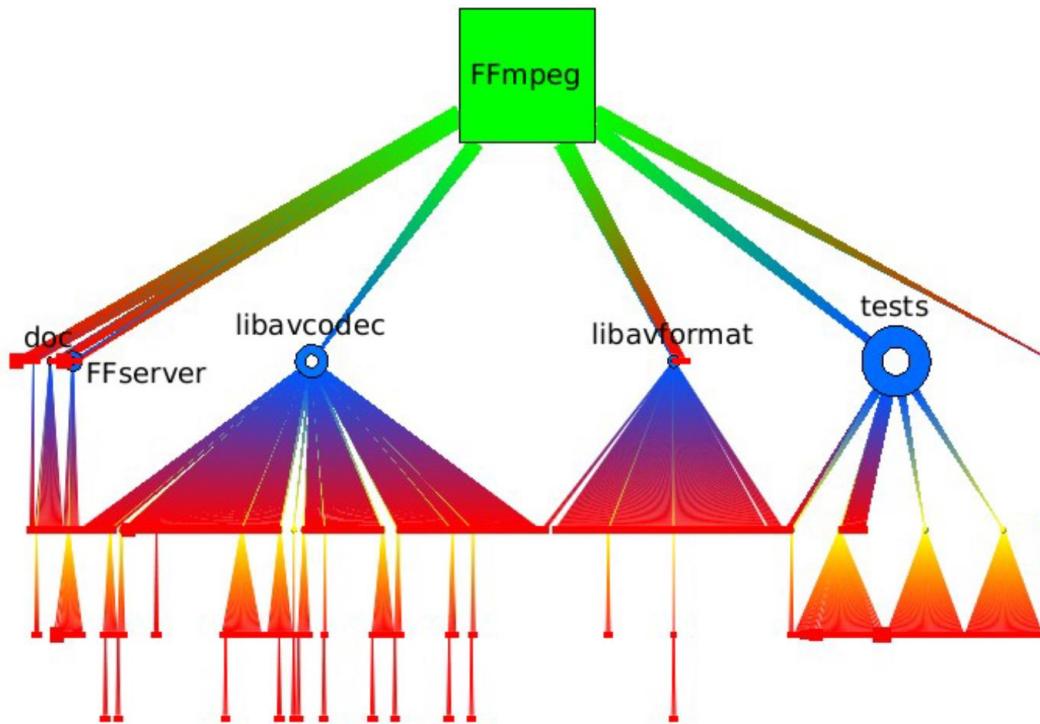
cone tree



bubble tree

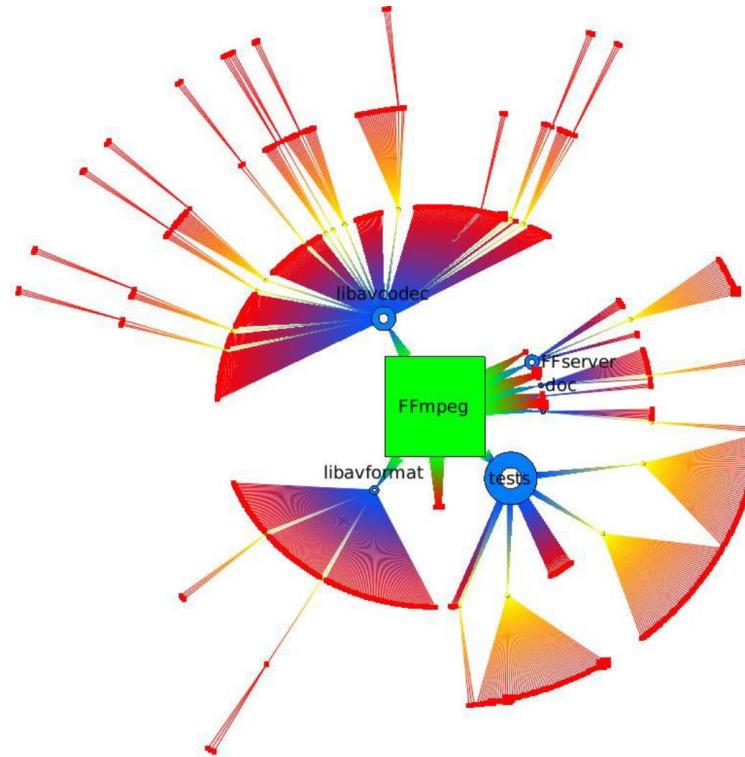
Legend:  
■ root  
● level 2  
○ level 3  
■ others

# Tree Layout: Rooted Layout



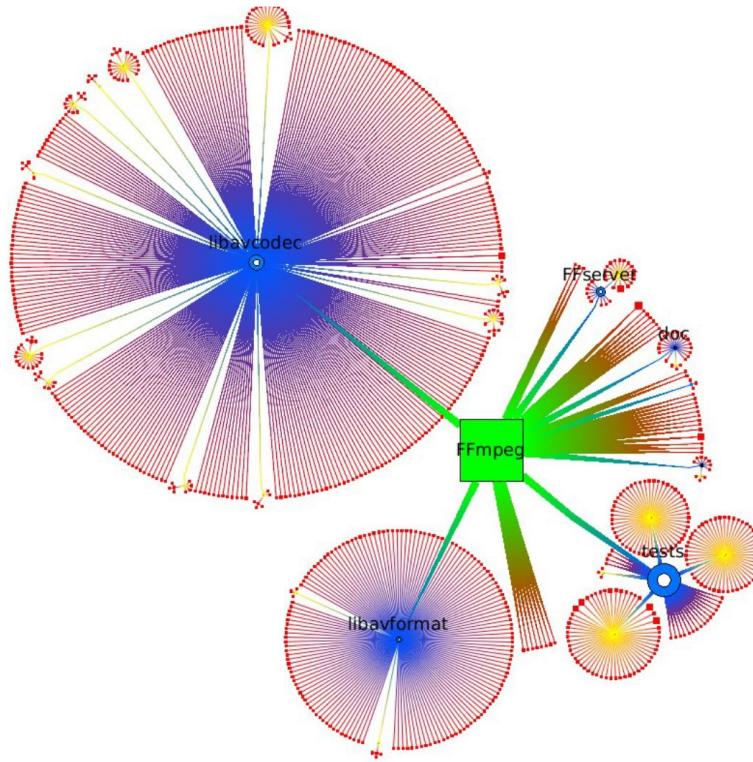
- very familiar to virtually everybody
- size (# children) and depth of sub-trees easy to perceive
- smooth edge shading → emphasize colors of small nodes
- unbalanced aspect ratios can occur → **limited scalability**

# Tree Layout: Radial Layout



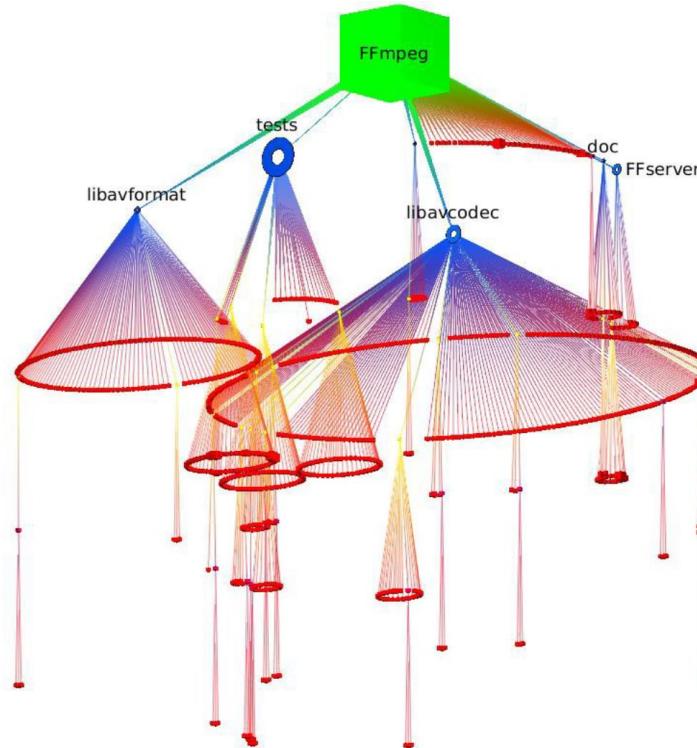
- like rooted tree, but arc-length used instead of  $x$  axis
  - size (# children) and depth of sub-trees easy to perceive
  - good aspect ratio guaranteed
  - nodes close to root get **less space**

# Tree Layout: Bubble Layout



- a subtree gets a full circle instead of a circle sector
  - better spreading of the nodes for large trees
  - variable edge lengths
  - hard to distinguish node **depth** in the tree

# Cone Tree

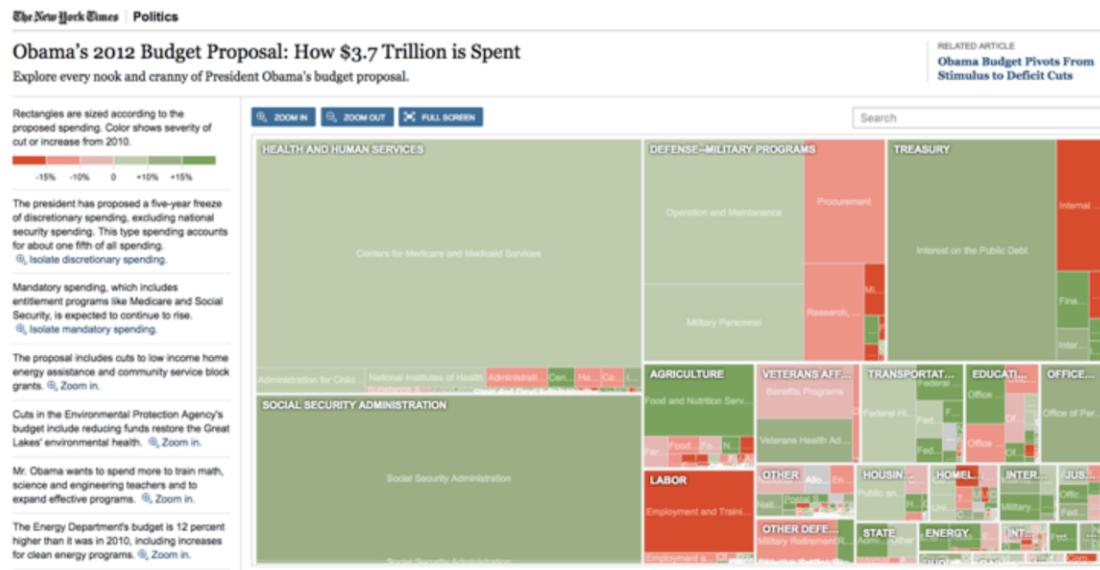


- a subtree gets a full cone instead of a sector / circle / line
- 3D effectively shows the tree depth
- combines bubble tree (seen from above) with rooted tree (seen from profile)
- **3D is tricky:** occlusions, perspective shortening, navigation

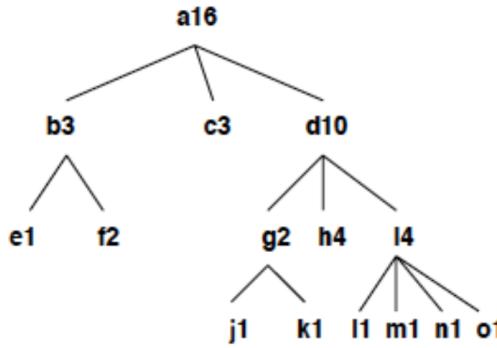
# TreeMaps

## Idiom: treemap

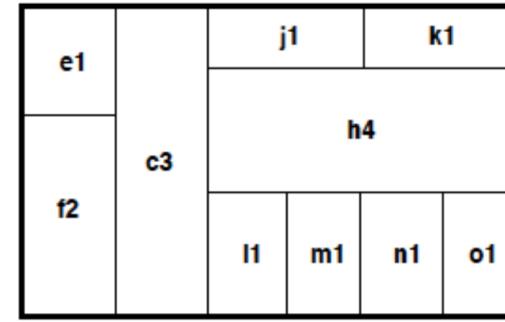
- data
  - tree
  - I quant attrib at leaf nodes
- encoding
  - area containment marks for hierarchical structure
  - rectilinear orientation
  - size encodes quant attrib
- tasks
  - query attribute at leaf nodes
- scalability
  - IM leaf nodes



# TreeMap Layout Algorithm



(a) Tree diagram

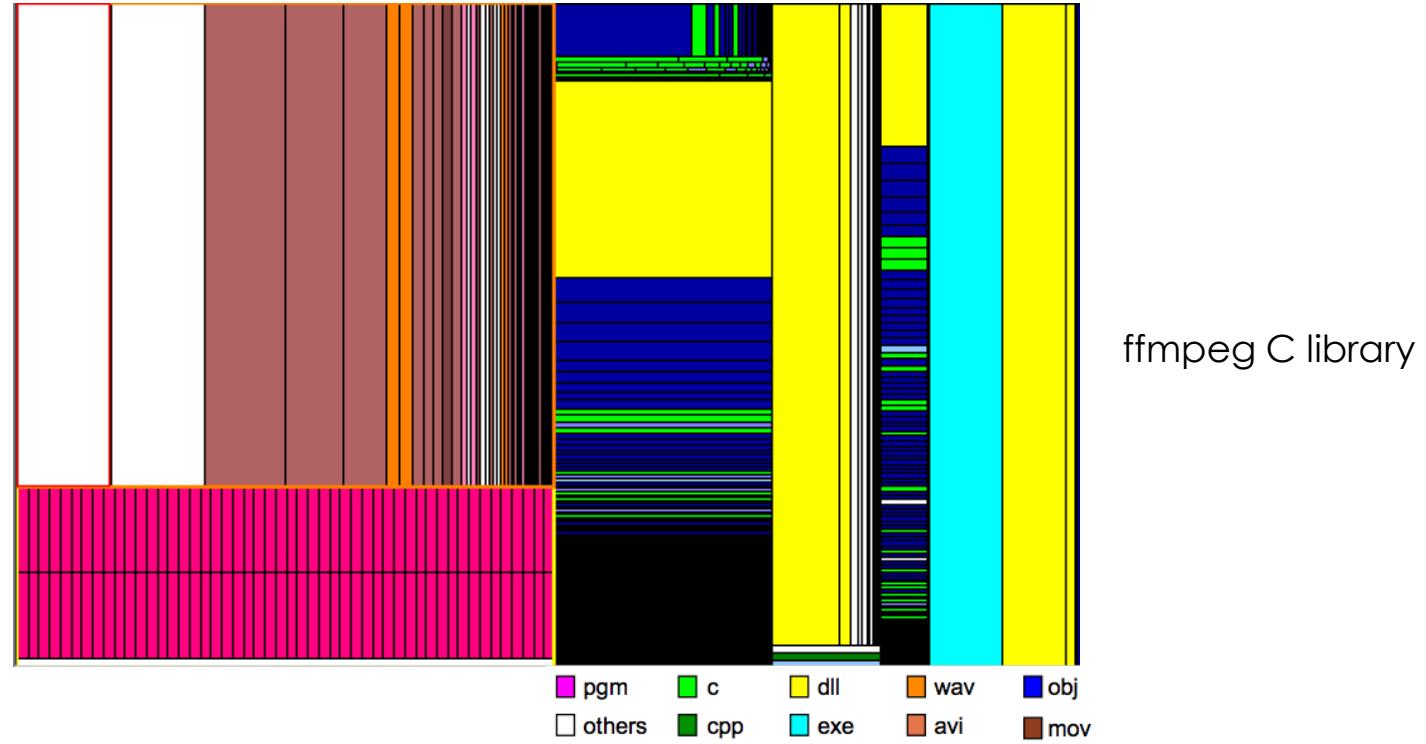


(b) Treemap

## Treemap “Slice and Dice” Layout Algorithm

- Alternate the axis you divide each level
- Divide the axis into lengths based on a metric..
  - Examples: uniform, number of nodes in subtree, application specific importance
- Recurse until all the nodes have been processed
- Only leaves explicitly visible

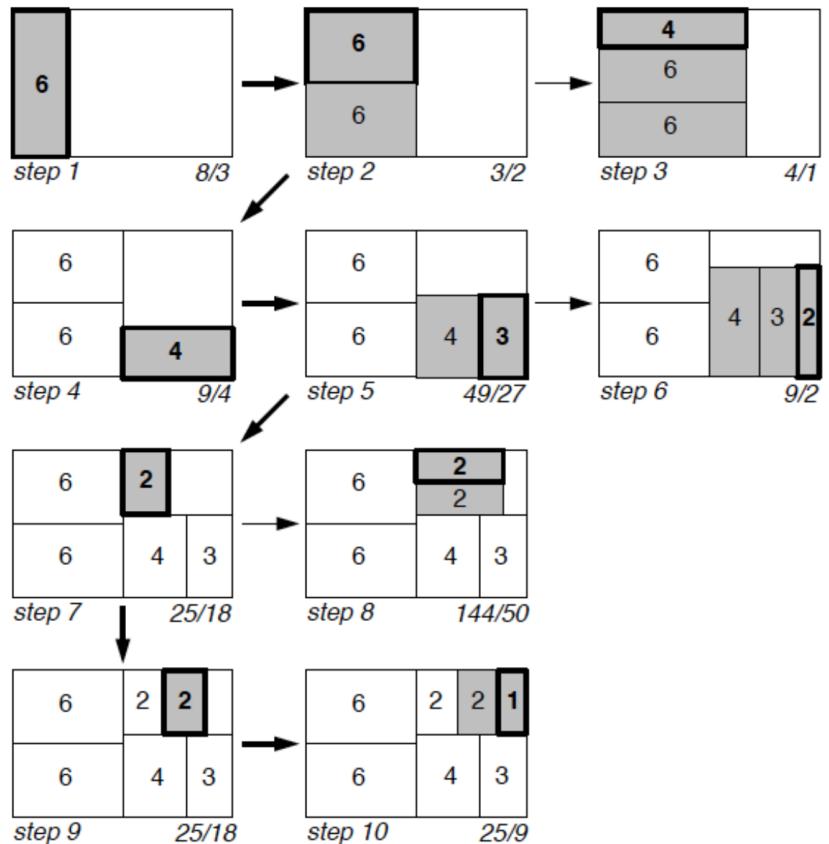
# Treemaps



Basic idea: 'slice and dice' layout

- 1 node = 1 rectangle
- child node rectangles: nested in the parent node rectangle (recursive subdivision)
- leaf rectangle size and color show data attributes
- edges: *not drawn explicitly!*
- very compact: tens of thousands of nodes on one screen
- hierarchy depth unclear

# Squarified Treemap Layout



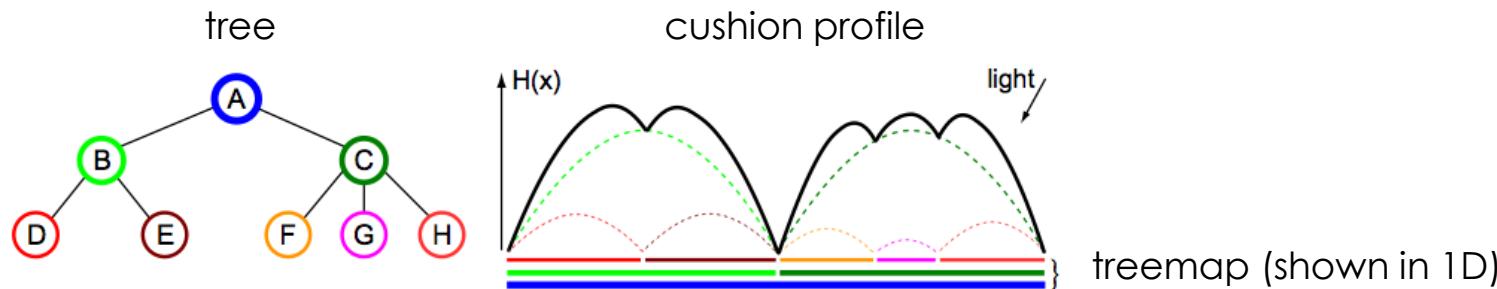
## Treemap “Squarified” Layout Algorithm

- Start with list of child nodes
- Sort by area, largest first
- Split the longest axis
- Start filling one “half” in alternate direction of the split (step 2)
  - Keep filling until aspect ratios get worse (step 3)
- Repeat process on the unfilled portion of the original

# Squarified TreeMaps

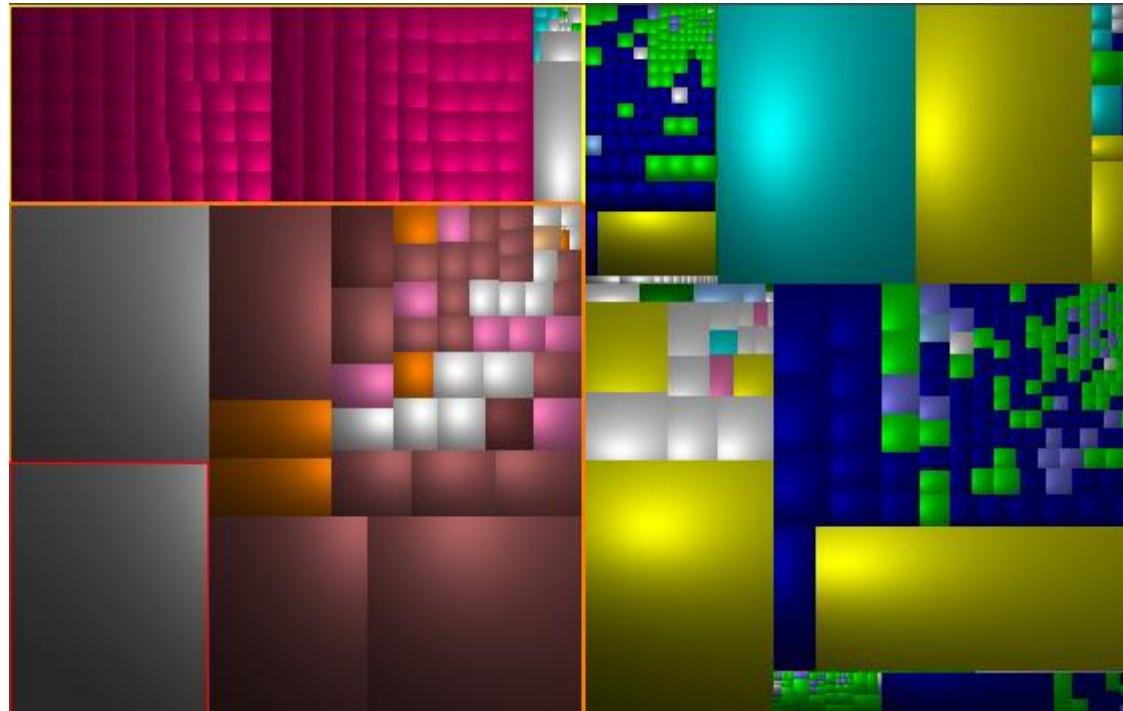
Two extensions:

- enforce near-square aspect ratios during rectangle subdivision [Bruls et al '00]
- use shading: [cushion profiles](#) to convey hierarchical structure [Van Wijk et al '99]



- for each rectangle  $r_i$  (except root)
  - define 2D parabola  $h_i(x,y)$  with height  $H_i = f^d$  ( $d$  = depth of  $r_i$  in tree)
- compute global height  $h = \sum_i h_i$
- for each image pixel  $I(x,y)$ 
  - $I(x,y) = shading(h(x,y))$
  - use an oblique light source for better results

# Squarified Cushion Treemaps



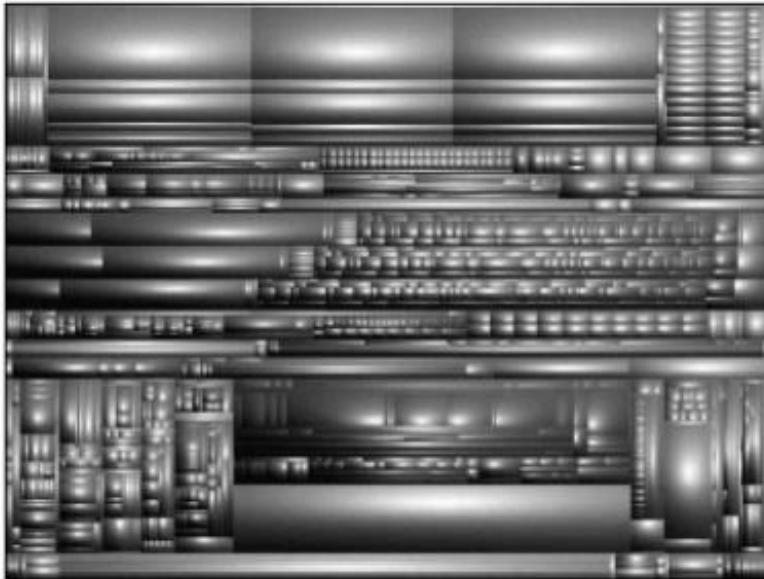
ffmpeg C library

- rectangle borders are not *explicitly* drawn → gain space
- borders are *implicit* in the shading discontinuities
- discontinuity strength conveys tree depth levels

# Squarified Cushion Treemaps

Comparison of methods

hard disk, ~30K files



- slice and dice layout
- unbalanced sizes
- structure is not very clear

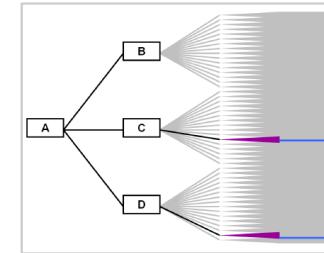
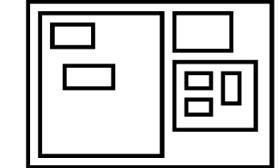
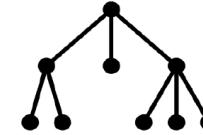


- squarified layout
- balanced sizes
- structure is extremely salient

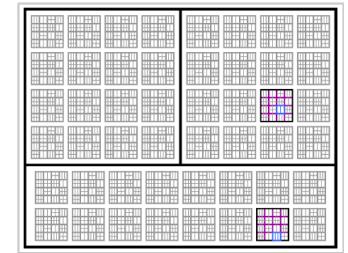
# Link Marks: Connection and Containment

- marks as links (vs. nodes)
  - common case in network drawing
  - 1D case: connection
    - ex: all node-link diagrams
    - emphasizes topology, path tracing
    - networks and trees
  - 2D case: containment
    - ex: all treemap variants
    - emphasizes attribute values at leaves (size coding)
    - only trees

→ Connection → Containment



**Node-Link Diagram**

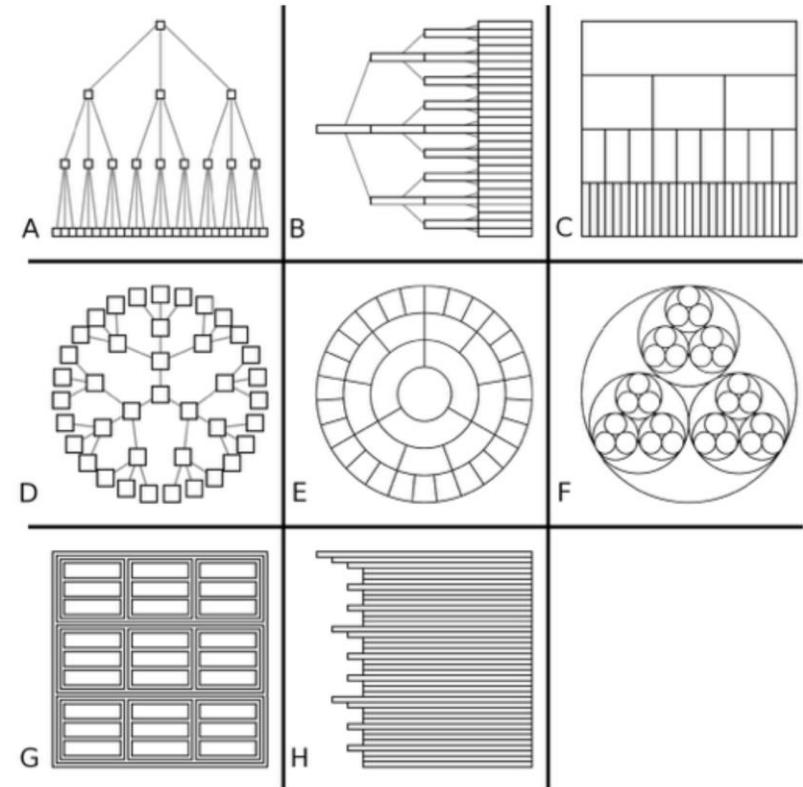


**Treemap**

[*Elastic Hierarchies: Combining Treemaps and Node-Link Diagrams*. Dong, McGuffin, and Chignell. Proc. InfoVis 2005, p. 57-64.]

# Tree Drawing Comparisons

- data shown
  - link relationships
  - tree depth
  - sibling order
- design choices
  - connection vs containment link marks
  - rectilinear vs radial layout
  - spatial position channels
- considerations
  - redundant? arbitrary?
  - information density?
    - avoid wasting space



[*Quantifying the Space-Efficiency of 2D Graphical Representations of Trees. McGuffin and Robert. Information Visualization 9:2 (2010), 115–140.*]