

Overview of Query Evaluation

Chapter 12





- Query Plan:
 - Tree of relational algebra operators
 - with choice of algorithm for each operator.
- ❖ Example: What are the names of sailors who have reserved boat 103
 - What are the operators

```
SELECT S.name
FROM Sailors S, Reserves R
WHERE S.sid=R.sid AND R.bid=103
```

Overview of Query Evaluation



- Two main issues in query optimization:
 - For a given query, what plans are considered?
 - Algorithm to search plan space for cheapest (estimated) plan.
 - How is the cost of a plan estimated?
- Ideally: Want to find best plan.
 - Practically: Avoid worst plans!
- * Each operator is typically implemented using a `pull' interface: when an operator is `pulled' for the next output tuples, it `pulls' on its inputs and computes them.

Some Common Techniques



- * Algorithms for evaluating relational operators use some simple ideas extensively:
 - Indexing: Can use WHERE conditions to retrieve small set of tuples (selections, joins)
 - Iteration: Sometimes, faster to scan all tuples even if there is an index. (And sometimes, we can scan the data entries in an index instead of the table itself.)
 - Partitioning: By using sorting or hashing, we can partition the input tuples and replace an expensive operation by similar operations on smaller inputs.



Statistics and Catalogs

- Need information about the relations and indexes involved. *Catalogs* typically contain at least:
 - # tuples (NTuples) and # pages (NPages) for each relation.
 - # distinct key values (NKeys) and NPages for each index.
 - Index height, low/high key values (Low/High) for each tree index.



Statistics and Catalogs

- Catalogs are updated periodically.
 - Updating whenever data changes is too expensive; lots of approximation anyway, so slight inconsistency ok.
- * More detailed information (e.g., histograms of the values in some field) are sometimes stored.

A Note on Complex Selections



(day<8/9/94 AND rname='Paul') OR bid=5 OR sid=3

❖ Selection conditions are first converted to <u>conjunctive</u> <u>normal form (CNF)</u>:

```
(day<8/9/94 OR bid=5 OR sid=3 ) AND (rname='Paul' OR bid=5 OR sid=3)
```

❖ We only discuss case with no ORs; see text if you are curious about the general case.

Access Paths



- An <u>access path</u> is a method of retrieving tuples:
 - File scan, or index that *matches* a selection (in the query)
- ❖ A tree index <u>matches</u> (a conjunction of) terms that involve only attributes in a *prefix* of the search key.
 - E.g., Tree index on $\langle a, b, c \rangle$ matches the selection a=5 AND b=3, and a=5 AND b>6, but not b=3.
- ❖ A hash index <u>matches</u> (a conjunction of) terms that has a term <u>attribute</u> = <u>value</u> for every attribute in the search key of the index.
 - E.g., Hash index on $\langle a, b, c \rangle$ matches a=5 AND b=3 AND c=5; but it does not match b=3, or a=5 AND b=3, or a>5 AND b=3 AND c=5.

The Selection Operator

- * Most selective access path: An index or file scan that we estimate will require the fewest page I/Os.
- ❖ Find the most selective access path, retrieve tuples using it, and apply any remaining terms that don't match the index:
 - Terms that match this index reduce the number of tuples *retrieved*; other terms are used to discard some retrieved tuples, but do not affect number of tuples/pages fetched.
 - Consider day<8/9/94 AND bid=5 AND sid=3. A B+ tree index on day can be used; then, bid=5 and sid=3 must be checked for each retrieved tuple. Similarly, a hash index on <bid, sid> could be used; day<8/9/94 must then be checked.

The Selection Operator: Reduction factor

- * *Reduction factor*. The fraction of tuples in a table that satisfy a given conjunct
 - When there are several primary conjuncts, the total reduction factor is the product of all reduction factors (approximately)
- ❖ If there is no available information about the reduction factor, we can assume either uniform distribution, or simply reduction factor is set to a default value (0.1)
 - More sophisticated techniques use histograms
- ❖ Based on the reduction factor, we may decide upon several index choices

Using an Index for Selections



- Cost depends on #qualifying tuples, and clustering.
 - Cost of finding qualifying data entries (typically small) plus cost of retrieving records (could be large w/o clustering).
 - In example, assuming uniform distribution of names, about 10% of tuples qualify (100 pages, 10000 tuples).
 With a clustered index, cost is little more than 100 I/Os; if unclustered, upto 10000 I/Os!

```
SELECT *
FROM Reserves R
WHERE R.rname < 'C%'
```

Projection



SELECT DISTINCT R.sid, R.bid FROM Reserves R

- Projection is: (1) Dropping unwanted columns, and (2) Removing duplicates
- The expensive part is removing duplicates.
 - SQL systems don't remove duplicates unless the keyword DISTINCT is specified in a query.
- If no duplicate elimination is needed, an iteration is performed either on the table or an index whose key contains all the projection fields

Projection with duplicate elimination



- Sorting Approach: Sort on <sid, bid> and remove duplicates. (Can optimize this by dropping unwanted information while sorting.)
- * Hashing Approach: Hash on <sid, bid> to create partitions. Load partitions into memory one at a time, build in-memory hash structure, and eliminate duplicates.
- ❖ If there is an index with both R.sid and R.bid in the search key, may be cheaper to sort data entries!

Join:



SELECT S.sid, S.name, R.bid FROM Sailors S, Reserves R WHERE S.sid=R.sid

- Join is the most common and most expensive query operator
- Joins are widely studied and systems support several join algorithms
- A straightforward way for the join is an exhaustive nested loop

```
For each tuple r in R do

For each tuple s in S

if r_{.sid} == s_{.sid} do

add \langle r, s \rangle to result
```

Join: Index Nested Loops



❖ If there is an index on the join column of one relation (say S), can make it the inner and exploit the index.

- ❖ For each R tuple, cost of probing S index is about 1.2 for hash index, 2-4 for B+ tree. Cost of then finding S tuples depends on clustering.
 - Clustered index: 1 I/O (typical), unclustered: upto 1
 I/O per matching S tuple.

Examples of Index Nested Loops



- Assuming the availability of hash index on both tables:
 - Page size = 80 tuples/Sailors and 100 tuples/Reserves
 - Cardinality of Sailors = $40,000 \rightarrow 500$ pages
 - Cardinality of Reserves = 100,000 → 1000 pages
 - Retrieving a page through hashing costs 1.2 I/O

- Hash-index on sid of Sailors (as inner):
 - Scan Reserves: 1000 page I/Os, 100*1000 tuples.
 - For each Reserves tuple: 1.2 I/Os to get data entry in index, plus 1 I/O to get (the exactly one) matching Sailors tuple. Total: 1000 + 100,000 * 2.2 = 221,000 I/Os.

Examples of Index Nested Loops



- Hash-index on sid of Reserves (as inner):
 - Scan Sailors: 500 page I/Os, 80*500 tuples.
 - For each Sailors tuple: 1.2 I/Os to find index page with data entries, plus cost of retrieving matching Reserves tuples. Assuming uniform distribution, 2.5 reservations per sailor (100,000 / 40,000). Cost of retrieving them is 2.5 I/Os for an unclustered index.
 - 500 + 40,000 * 3.7 = 148,500 I/Os

Join: Sort-Merge $(R \bowtie_{i=j} S)$



Sort R and S on the join column, then scan them to do a "merge" (on join col.), and output result tuples.

sid	sname	rating	age
22	dustin	7	45.0
28	yuppy	9	35.0
31	lubber	8	55.5
44	guppy	5	35.0
58	rusty	10	35.0

sid	<u>bid</u>	day	rname
28	103	12/4/96	guppy
28	103	11/3/96	yuppy
31	101	10/10/96	dustin
31	102	10/12/96	lubber
31	101	10/11/96	lubber
58	103	11/12/96	dustin

Cost of Sort-Merge Join



- * Sorting takes two passes, for each pass, we need to scan (read and write) each data record:
 - Cost for sorting Reserves: 2 * 2 * 1000 = 4000
 - Cost for sorting Sailors: 2 * 2 * 500 = 2000
- Merging needs only one global pass over the two tables with read only
 - Merging cost = 1000+500 = 1500
- \star Total cost = 4000 + 2000 + 1500 = 7500
- Why bother by indexing..??!!

Highlights of System R Optimizer



Impact:

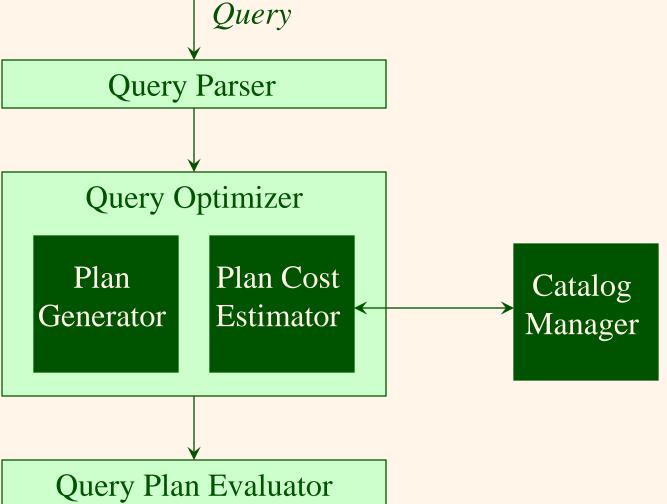
• Most widely used currently; works well for < 10 joins.

Cost estimation:

- Statistics, maintained in system catalogs, used to estimate cost of operations and result sizes.
- Considers combination of CPU and I/O costs.
- Plan Space: Too large, must be pruned.
 - Only the space of *left-deep plans* is considered.
 - Left-deep plans allow output of each operator to be <u>pipelined</u> into the next operator without storing it in a temporary relation.
 - Cartesian products avoided.

Query Planning, Optimization, and Evaluation







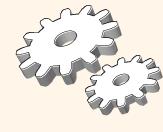
Cost Estimation

- For each plan considered, must estimate cost:
 - Must estimate *cost* of each operation in plan tree.
 - Depends on input cardinalities.
 - We've already discussed how to estimate the cost of operations (sequential scan, index scan, joins, etc.)
 - Must also estimate size of result for each operation in tree!
 - Use information about the input relations.
 - For selections and joins, assume independence of predicates.

Size Estimation and Reduction Factors

SELECT attribute list FROM relation list ❖ Consider a query block: | WHERE term1 AND ... AND termk

- Maximum # tuples in result is the product of the cardinalities of relations in the FROM clause.
- * *Reduction factor (RF)* associated with each *term* reflects the impact of the term in reducing result size. Result cardinality = Max # tuples * product of all RF's.
 - Implicit assumption that *terms* are independent!
 - Term col=value has RF 1/NKeys(I), given index I on col
 - Term col1=col2 has RF 1/MAX(NKeys(I1), NKeys(I2))
 - Term col>value has RF (High(I)-value)/(High(I)-Low(I))



Schema for Examples

Sailors (*sid*: integer, *sname*: string, *rating*: integer, *age*: real) Reserves (*sid*: integer, *bid*: integer, *day*: dates, *rname*: string)

* Reserves:

• Each tuple is 40 bytes long, 100 tuples per page, 1000 pages.

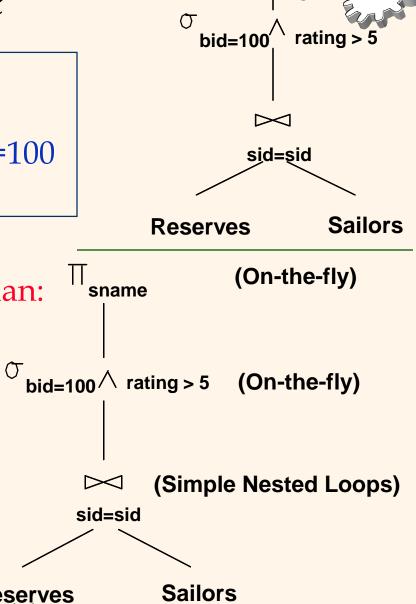
* Sailors:

Each tuple is 50 bytes long, 80 tuples per page, 500 pages.

Motivating Example

SELECT S.sname FROM Reserves R, Sailors S WHERE R.sid=S.sid AND R.bid=100 AND S.rating>5

- ◆ Cost: 500+500*1000 I/Os
- By no means the worst plan!
- Misses several opportunities: selections could have been `pushed' earlier, no use is made of any available indexes, etc.
- * Goal of optimization: To find more efficient plans that compute the same answer.



RA Tree:

Plan:

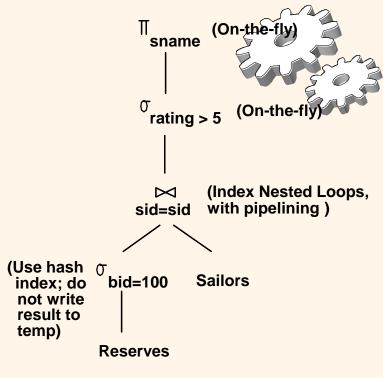
Alternative Plans 1 (No Indexes)

- (Scan; write to temp T1)

 | Sname (On-the-Tily) |
 | (Sort-Merge Join) |
 | (Scan; write to temp T2) |
 | Reserves | Sailors
- * Main difference: push selects.
- Cost of plan
 - Scan Reserves (1000) + write temp T1 (10 pages, if we have 100 boats, uniform distribution).
 - Scan Sailors (500) + write temp T2 (250 pages, if we have 10 ratings).
 - Sort T1 (2*2*10), sort T2 (2*2*250), merge (10+250)
 - Total: 3060 page I/Os.
- * If we 'push' projections, T1 has only sid, T2 only sid and sname:
 - T1 fits in 3 pages, cost of BNL drops to under 250 pages, total < 2000.

Alternative Plans 2 With Indexes

- With clustered index on bid of Reserves, we get 100,000/100 = 1000 tuples on 1000/100 = 10 pages.
- INL with <u>pipelining</u> (outer is not materialized).
 - -Projecting out unnecessary fields from outer doesn't help.
- v Join column *sid* is a key for Sailors.
 - -At most one matching tuple, unclustered index on sid OK.
- v Decision not to push *rating>5* before the join is based on availability of *sid* index on Sailors.
- v Cost: Selection of Reserves tuples (10 I/Os); for each, must get matching Sailors tuple (1000*1.2); total 1210 I/Os.



Summary

- ❖ There are several alternative evaluation algorithms for each relational operator.
- * A query is evaluated by converting it to a tree of operators and evaluating the operators in the tree.
- * Must understand query optimization in order to fully understand the performance impact of a given database design (relations, indexes) on a workload (set of queries).
- Two parts to optimizing a query:
 - Consider a set of alternative plans.
 - Must prune search space; typically, left-deep plans only.
 - Must estimate cost of each plan that is considered.
 - Must estimate size of result and cost for each plan node.
 - *Key issues*: Statistics, indexes, operator implementations.