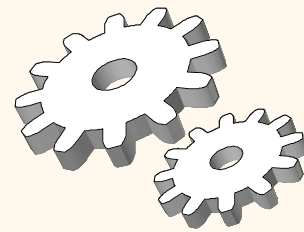


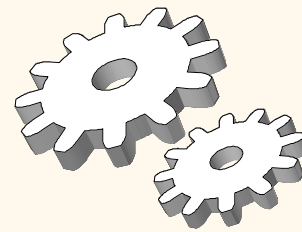
Concurrency Control

Chapter 17

Conflict Serializable Schedules



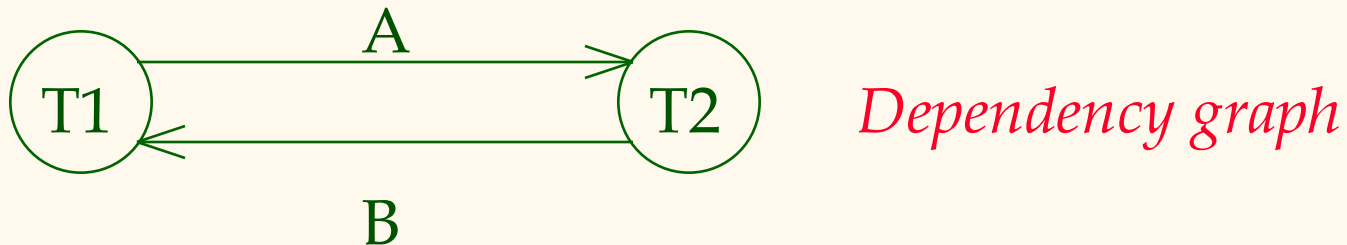
- ❖ Two schedules are **conflict equivalent** if:
 - Involve the same actions of the same transactions
 - Every pair of conflicting actions is ordered the same way
- ❖ Schedule S is **conflict serializable** if S is conflict equivalent to some serial schedule
- ❖ Every **conflict serializable** schedule is **serializable** but the reverse is not true
- ❖ Dependency graph: One node per Xact; edge from T_i to T_j if T_j reads/writes an object last written by T_i .
- ❖ Theorem: Schedule is conflict serializable if and only if its dependency graph is acyclic



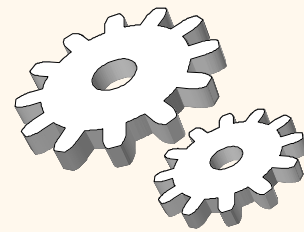
Example

- ❖ A schedule that is not conflict serializable:

T1:	R(A), W(A),	R(B), W(B)
T2:	R(A), W(A), R(B), W(B)	

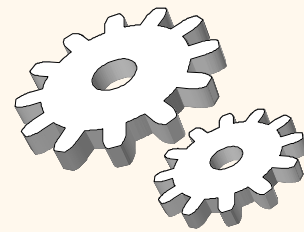


- ❖ The cycle in the graph reveals the problem. The output of T1 depends on T2, and vice-versa.



Review: Strict 2PL

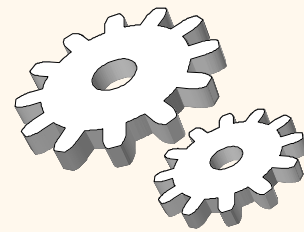
- ❖ Strict Two-phase Locking (Strict 2PL) Protocol:
 - Each Xact must obtain a **S (shared) lock** on object before reading, and an **X (exclusive) lock** on object before writing.
 - All locks held by a transaction are released when the transaction completes
 - If an Xact holds an X lock on an object, no other Xact can get a lock (S or X) on that object.
- ❖ Strict 2PL allows only schedules whose precedence graph is acyclic



Two-Phase Locking (2PL)

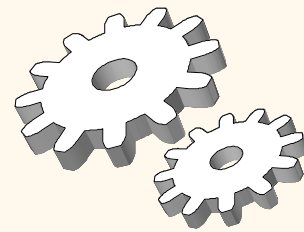
❖ Two-Phase Locking Protocol

- Each Xact must obtain a S (*shared*) lock on object before reading, and an X (*exclusive*) lock on object before writing.
- A transaction can not request additional locks once it releases any locks.
- If an Xact holds an X lock on an object, no other Xact can get a lock (S or X) on that object.



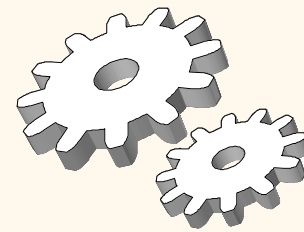
Lock Management

- ❖ Lock and unlock requests are handled by the lock manager
- ❖ Lock table entry:
 - Transactions currently holding a lock
 - Type of lock held (shared or exclusive)
 - Pointer to queue of lock requests
- ❖ Locking and unlocking have to be atomic operations
- ❖ Lock upgrade: transaction that holds a shared lock can be upgraded to hold an exclusive lock



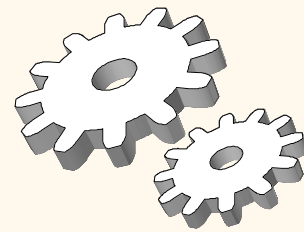
Deadlocks

- ❖ Deadlock: Cycle of transactions waiting for locks to be released by each other.
- ❖ Two ways of dealing with deadlocks:
 - Deadlock prevention
 - Deadlock detection



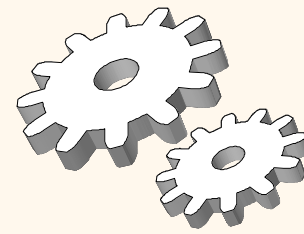
Deadlock Prevention

- ❖ Assign priorities based on timestamps.
Assume T_i wants a lock that T_j holds. Two policies are possible:
 - **Wait-Die:** If T_i has higher priority, T_i waits for T_j ; otherwise T_i aborts
 - **Wound-wait:** If T_i has higher priority, T_j aborts; otherwise T_i waits
- ❖ If a transaction re-starts, make sure it has its original timestamp



Deadlock Detection

- ❖ Create a **waits-for graph**:
 - Nodes are transactions
 - There is an edge from T_i to T_j if T_i is waiting for T_j to release a lock
- ❖ Periodically check for cycles in the waits-for graph



Deadlock Detection (Continued)

Example:

T1: S(A), R(A), S(B)

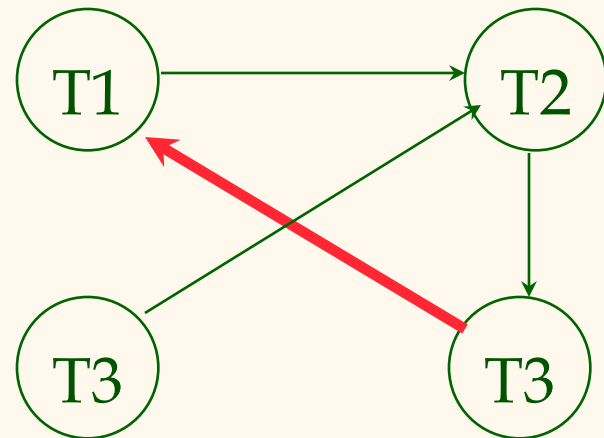
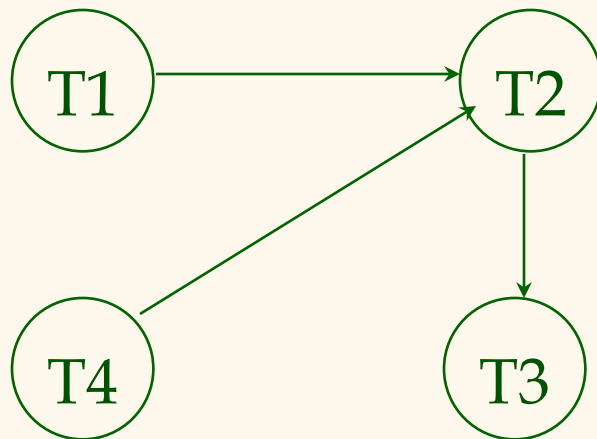
T2: X(B), W(B)

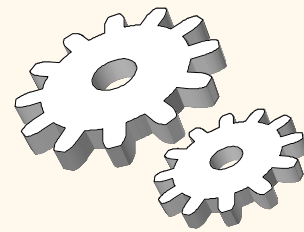
T3: S(C), R(C)

T4: X(B)

X(C)

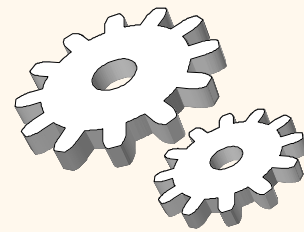
X(A)





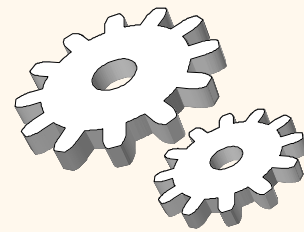
Optimistic CC

- ❖ Locking is a conservative approach in which conflicts are prevented. Disadvantages:
 - Lock management overhead.
 - Deadlock detection/resolution.
 - Lock contention for heavily used objects.
- ❖ If conflicts are rare, we might be able to gain concurrency by not locking, and instead checking for conflicts before Xacts commit.



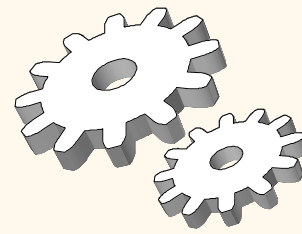
Optimistic CC Model

- ❖ Xacts have three phases:
 - **READ:** Xacts read from the database, but make changes to private copies of objects.
 - **VALIDATE:** Check for conflicts.
 - **WRITE:** Make local copies of changes public.



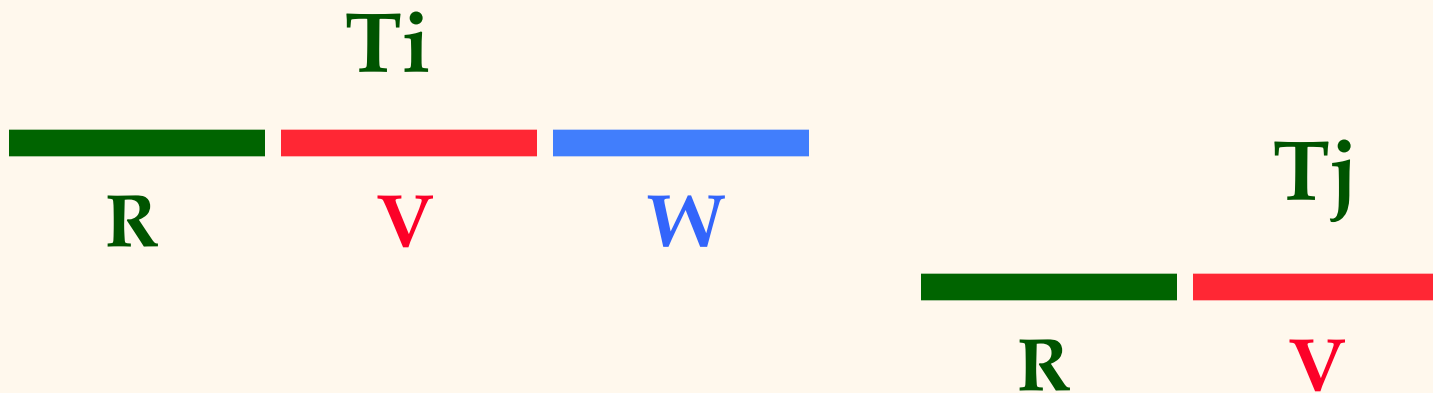
Validation

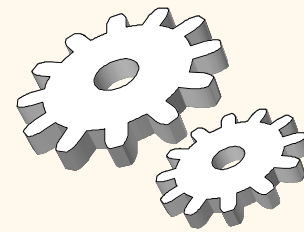
- ❖ Test conditions that are **sufficient** to ensure that no conflict occurred.
- ❖ Each Xact is assigned a numeric id.
 - Just use a **timestamp**.
- ❖ Xact ids assigned at end of READ phase, just before validation begins.
- ❖ **ReadSet(Ti)**: Set of objects read by Xact Ti.
- ❖ **WriteSet(Ti)**: Set of objects modified by Ti.



Test 1

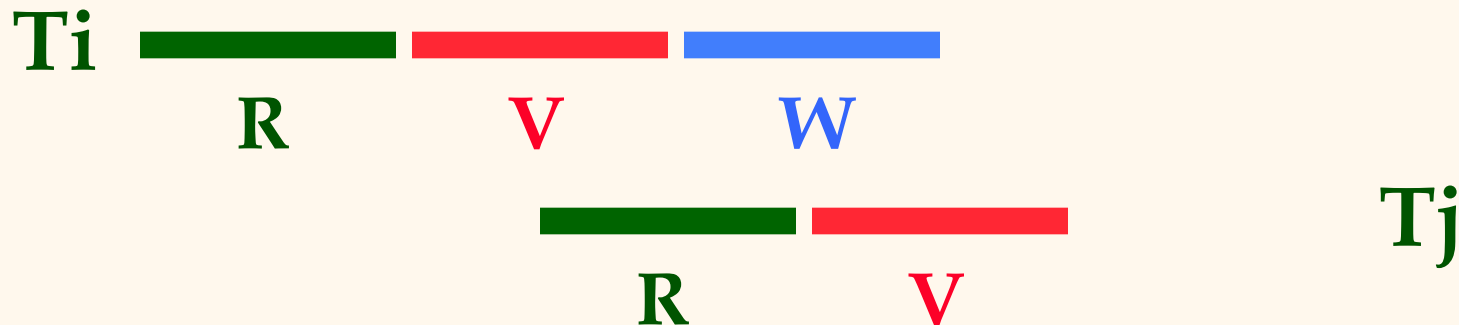
- ❖ For all i and j such that $T_i < T_j$, check that T_i completes before T_j begins.



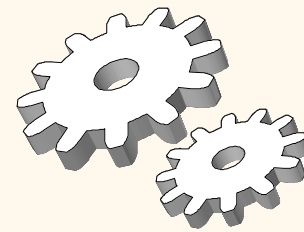


Test 2

- ❖ For all i and j such that $T_i < T_j$, check that:
 - T_i completes before T_j begins its Write phase +
 - $\text{WriteSet}(T_i) \cap \text{ReadSet}(T_j)$ is empty.

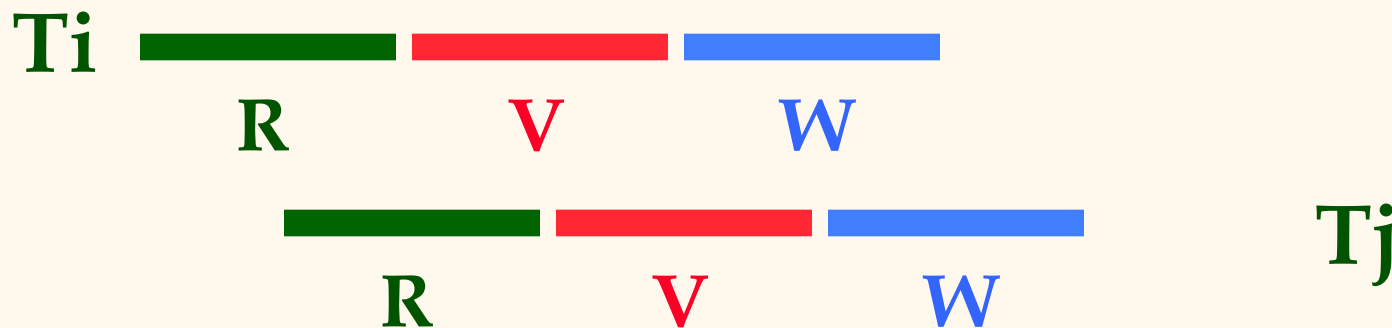


Does T_j read dirty data? Does T_i overwrite T_j 's writes?

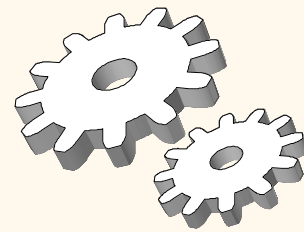


Test 3

- ❖ For all i and j such that $T_i < T_j$, check that:
 - T_i completes Read phase before T_j does +
 - $\text{WriteSet}(T_i) \cap \text{ReadSet}(T_j)$ is empty +
 - $\text{WriteSet}(T_i) \cap \text{WriteSet}(T_j)$ is empty.



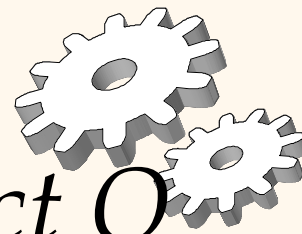
Does T_j read dirty data? Does T_i overwrite T_j 's writes?



Timestamp CC

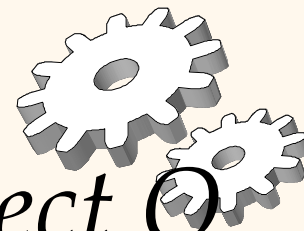
❖ Idea:

- Give each Xact a timestamp (TS) when it begins
- Give each object a read-timestamp (RTS) and a write-timestamp (WTS) as the timestamp of the youngest transaction that reads/writes the object:
 - If action a_i of Xact T_i conflicts with action a_j of Xact T_j , and $TS(T_i) < TS(T_j)$, then a_i must occur before a_j . Otherwise, restart violating Xact.



When Xact T wants to read Object O

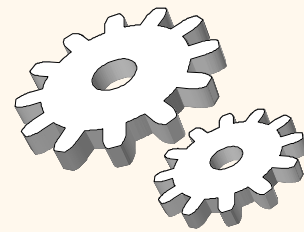
- ❖ If $TS(T) < WTS(O)$, this violates timestamp order of T w.r.t. writer of O.
 - So, abort T and restart it with a new, larger TS. (If restarted with same TS, T will fail again!)
- ❖ If $TS(T) > WTS(O)$:
 - Allow T to read O.
 - Reset $RTS(O)$ to $\max(RTS(O), TS(T))$
- ❖ Change to $RTS(O)$ on reads must be written to disk! This and restarts represent overheads.



When Xact T wants to Write Object O

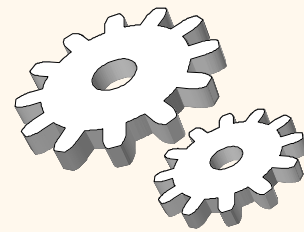
- ❖ If $TS(T) < RTS(O)$, this violates timestamp order of T w.r.t. writer of O; abort and restart T.
- ❖ If $TS(T) < WTS(O)$, violates timestamp order of T w.r.t. writer of O.
 - **Thomas Write Rule:** We can safely ignore such outdated writes; need not restart T! (T's write is effectively followed by another write, with no intervening reads.) Allows some serializable but non conflict serializable schedules:
- ❖ Else, allow T to write O, set $WTS(O)$.

T1	T2
R(A)	W(A) Commit
W(A) Commit	



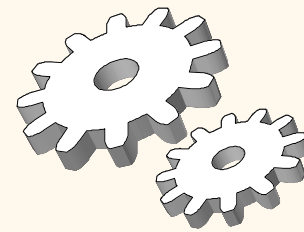
Summary

- ❖ There are several lock-based concurrency control schemes (Strict 2PL, 2PL). Conflicts between transactions can be detected in the dependency graph
- ❖ The lock manager keeps track of the locks issued. Deadlocks can either be prevented or detected.



Summary (Contd.)

- ❖ Multiple granularity locking reduces the overhead involved in setting locks for nested collections of objects (e.g., a file of pages); should not be confused with tree index locking!
- ❖ Optimistic CC aims to minimize CC overheads in an ``optimistic'' environment where reads are common and writes are rare.
- ❖ Optimistic CC has its own overheads however; most real systems use locking.
- ❖ SQL-92 provides different isolation levels that control the degree of concurrency



Summary (Contd.)

- ❖ Timestamp CC is another alternative to 2PL; allows some serializable schedules that 2PL does not (although converse is also true).
- ❖ Ensuring recoverability with Timestamp CC requires ability to block Xacts, which is similar to locking.
- ❖ Multiversion Timestamp CC is a variant which ensures that read-only Xacts are never restarted; they can always read a suitable older version. Additional overhead of version maintenance.