

CSDS 455: Homework 21

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Due and submitted on 11/09/2020
Fall 2020, Dr. Connamacher

Problem 1

I have consulted <https://core.ac.uk/download/pdf/81147875.pdf> and couple of papers which cited this paper. However, I don't quite get the whole picture of the proof and can't jump right into these lemmas as I don't know how are they contributing to the proof.

Say the algorithm finding r -vertex-disjoint-path in G takes $O(X)$ time where X is a polynomial of $V(G)$. Denotes vertices in G as $v_1, v_2, \dots, v_j, v_k, \dots, v_n$, we design a data structure that if v_j and v_k ever jointed together by edge contraction, we have the new vertex to be v_{jk} – where the original label j, k is still remembered by the new vertex made by contraction.

If H with u_1, u_2, \dots, u_k for $k \leq n$ is a minor of G . W.L.O.G. We know that the vertex-disjoint-path from u_a to u_b must be a subset of the r -vertex-disjoint-path in G from v_a to v_b : as for if a path P_H in H from u_a to u_b is $< u_a, u_1, u_2, u_3, u_4, u_b$, we must have path P_G in G like $< v_a, v_1, v_2, v_3, v_4, v_5, u_b$ where every vertex in P_H is “covered” in a corresponding P_G .

So we may simply calculate the r_G -vertex-disjoint-path in G between every two vertices, which will take $\binom{n}{2}O(X_G)$ which is a polynomial of n . Similarly, we calculate the same r_H -vertex-disjoint-path in H which takes $\binom{k}{2}O(X_H)$. Then we try to figure if every path in r_H has a corresponding path in r_G . If so, H is a minor G ; and otherwise it is not.