### ECCV 2020 Workshop Paper Summary

1등부터 5등 + Hoya님의 솔루션 정리

## 1 Overview Overview

### Overview

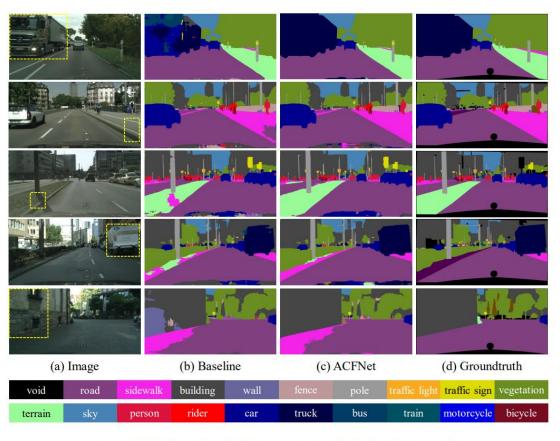


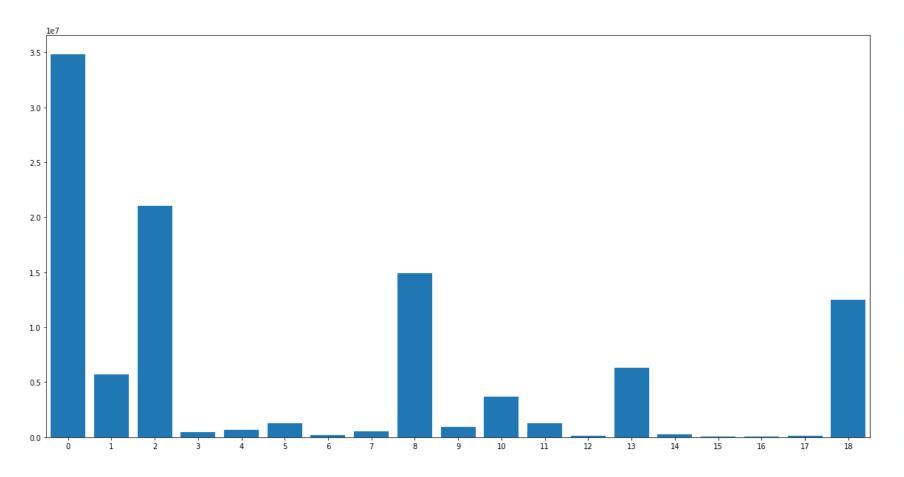
Figure 7. Visualization results of ACFNet based on ResNet-101 network on Cityscapes val set.

Original: Training Set 2975장, Validation Set 500장, Test Set 1525장

MiniCity: Training Set 200장, Validation Set 100장, Test Set 200장

# Overview • (1) Overview





classes	IoU	nIoU
	. 0 063	
road	: 0.963	nan
sidewalk	: 0.762	nan
building	: 0.856	nan
wall	: 0.120	nan
fence	: 0.334	nan
pole	: 0.488	nan
traffic light	: 0.563	nan
traffic sign	: 0.631	nan
vegetation	: 0.884	nan
terrain	: 0.538	nan
sky	: 0.901	nan
person	: 0.732	0.529
rider	: 0.374	0.296
car	: 0.897	0.822
truck	: 0.444	0.218
bus	: 0.244	0.116
train	: 0.033	0.006
motorcycle	: 0.492	0.240
bicycle	: 0.638	0.439
Score Average	: 0.573	0.333

# 2. Hoya's Solution





2048

#### 최근 SOTA

- Batch 1 1024X2048 학습

### Hoya (2080ti 4대)

- Batch 8: ResNet50 DeepLabv3 (crop 576 x 1152)
- Batch 8: ResNet101 DeepLabv3 (crop 384 x 786)

#### Loss

- CrossEntropy Loss

#### Unbalanced에 좋은 Loss

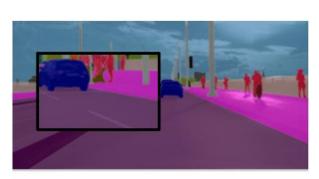
- Focal Loss
- Weighted Cross Entropy Loss

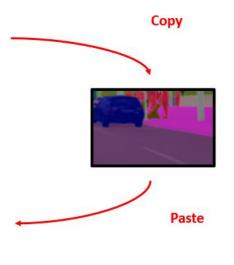
# 2 Hoya's Solution (2) Augmentation

### Augmentation

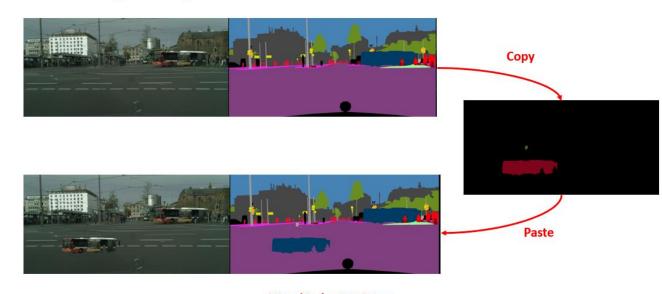
#### "CutMix" Augmentation







#### "Copy Blob" Augmentation



#### **Visual Inductive Prior**

Wall is located on the sidewalk

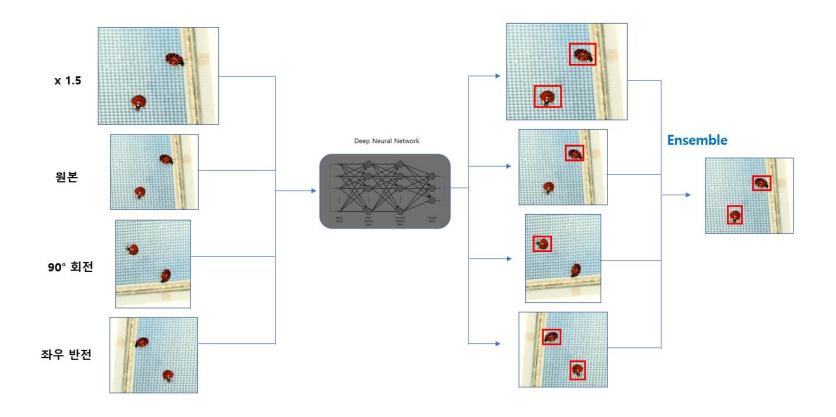
Fence is located on the sidewalk

**Bus** is located on the **Road Train** is located on the **Road** 

# 2. Hoya's Solution (3) Inference



### Multi Scale Inference



### 3. Top Solution





Multi-level tail pixel cutmix and scale attention for long-tailed scene parsing

### 문제

Long-tailed Label Distribution (Unbalanced)

#### Previsious Work

- Re-sampling
- Re-weighting

### 한계

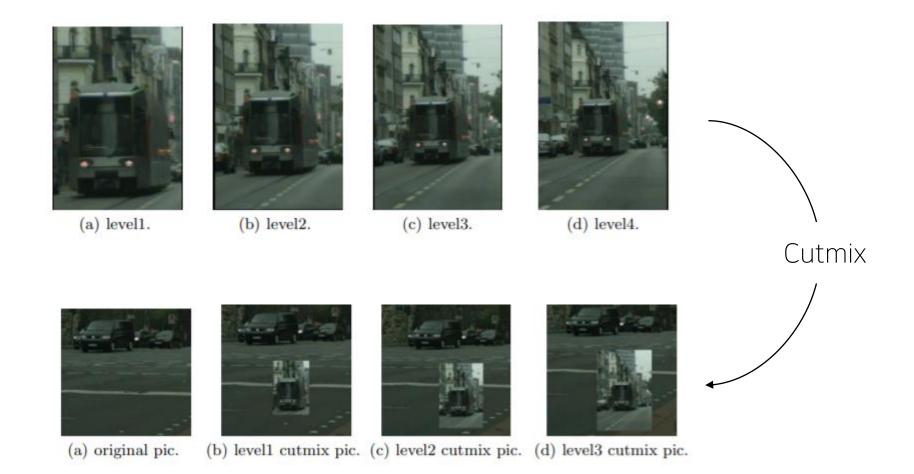
- 전체 이미지에서 특정 픽셀에 대해서 sampling 하는 것이 힘듦 (balancing 불가 <- sampling)
- Weight 같은 경우도 Random Crop / Resize 등에 의해서 Weight Map이 변경되는 문제 발생

### 제안

- Long tail pixel distribution 을 이용한 Multi-level tail pixel cutmix
- New cutmix with scale attention model 사용

# 3. Top Solution 1. Solution

### Multi-level tail pixel cutmix

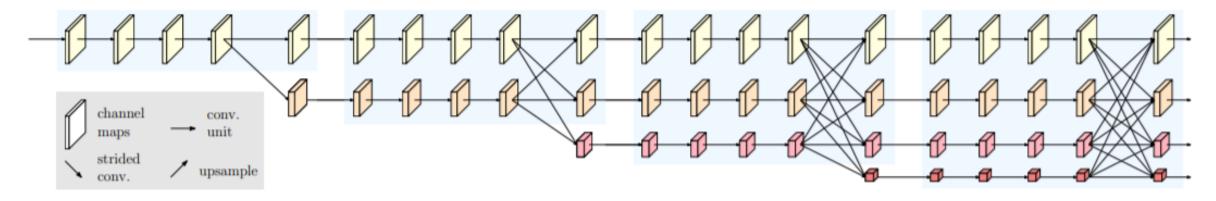


# 3. Top Solution 1. Solution





출처 : Jingdong Wang, Ke Sun, Tianheng Cheng, Borui Jiang, Chaorui Deng, Yang Zhao, Dong Liu, Yadong Mu, Mingkui Tan, Xinggang Wang, Wenyu Liu, Bin Xiao, Deep High-Resolution Representation Learning for Visual Recognition



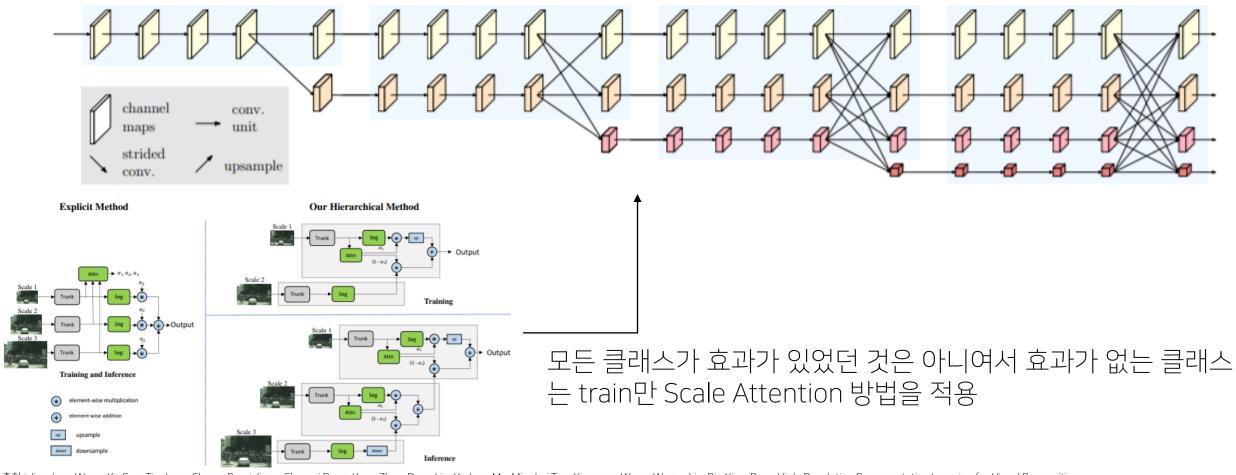
Convolution Layer -> 3x3Conv(BN) - ReLU - 3x3Conv(BN) - ReLU - 1x1Conv

# 3. Top Solution 1. Top Solution





출처 : Jingdong Wang, Ke Sun, Tianheng Cheng, Borui Jiang, Chaorui Deng, Yang Zhao, Dong Liu, Yadong Mu, Mingkui Tan, Xinggang Wang, Wenyu Liu, Bin Xiao, Deep High-Resolution Representation Learning for Visual Recognition



출처 : Jingdong Wang, Ke Sun, Tianheng Cheng, Borui Jiang, Chaorui Deng, Yang Zhao, Dong Liu, Yadong Mu, Mingkui Tan, Xinggang Wang, Wenyu Liu, Bin Xiao, Deep High-Resolution Representation Learning for Visual Recognition

## 3 Top Solution



Oiversification is All You Need: Towards Data Effcient Image Understanding

### 문제

Lack of enough number of labeled images

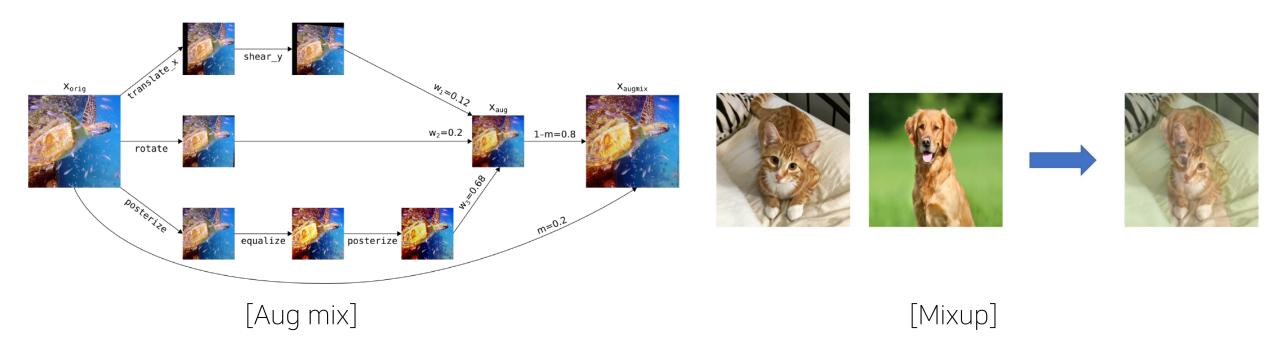
### 제안

- Augmix + mixup within class diversification and between class diversification
- seeAugmix: Extend Augmix
- Frequency weighted model ensemble

# 3. Top Solution (2) 2<sup>nd</sup> Solution



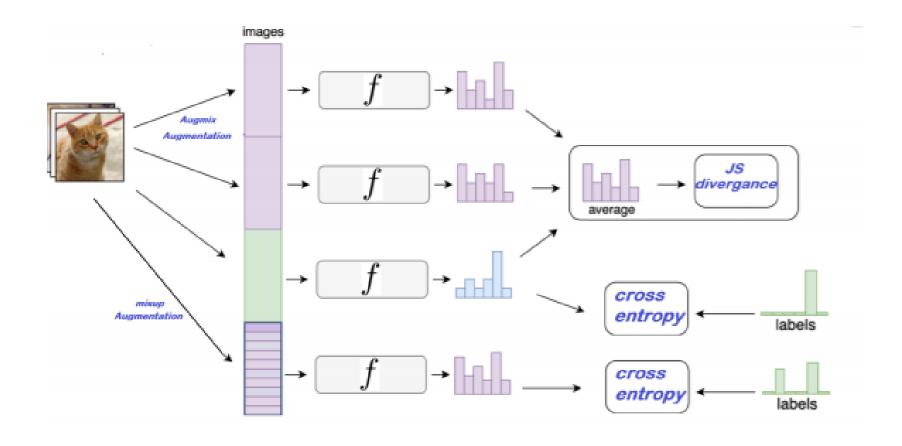
Augmix + mixup within class diversification and between class diversification



# 3. Top Solution (2) 2nd Solution

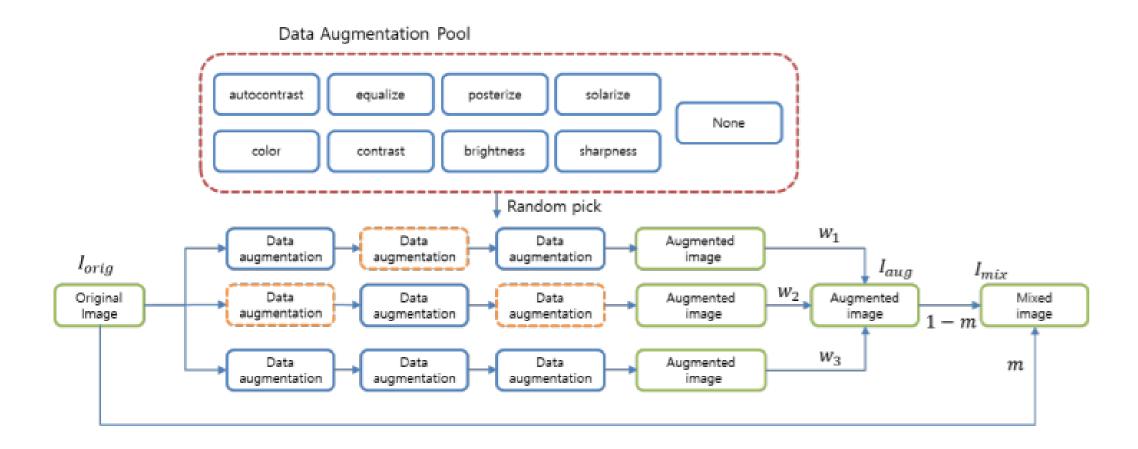


Augmix + mixup within class diversification and between class diversification



# 3. Top Solution (2) 2nd Solution

seeAugmix: Extend Augmix



# 3. Top Solution Solution

### **Solution** Frequency Weighted Ensemble

Method	mIoU (%) validation dataset	
HRNetV2-W48 + OCR	59.21	
HRNetV2-W48 + OCR + OHEM	59.25	
$\overline{\text{HRNetV2-W48} + \text{OCR} + \text{seg-Augmix}}$	59.84	
Average ensemble of above	59.85	
FW model ensemble	60.60	

**Table 7.** The performance of HRNetV2-W48 + OCR, HRNetV2-W48 + OCR + OHEM, HRNetV2-W48 + OCR + seg-Augmix models, average model ensemble of them, and Frequency Weighted model ensemble of them on validation dataset of MiniC-ity.

## Top Solution



Edge-Preserving Guided Semantic Segmentation for VIPriors Challenge

### 문제

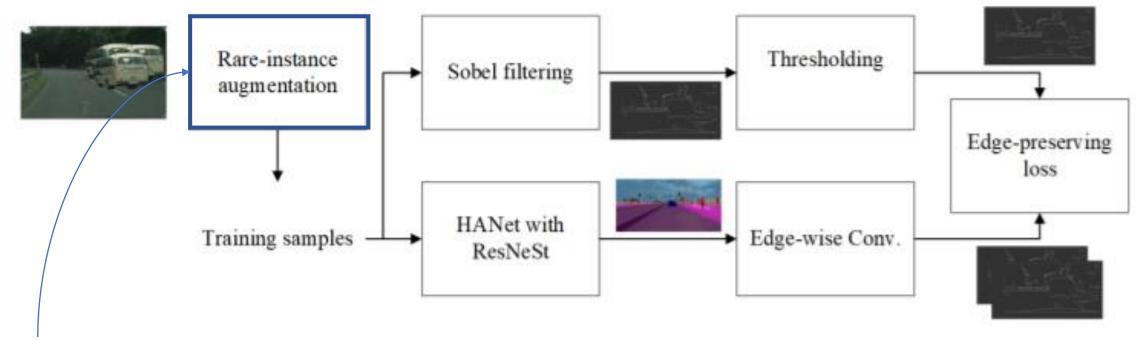
- 학습시킬 데이터의 부족

### 제안

- Edge-preserving guidance to obtain the extra prior information (prior 정보로 edge 활용)
  - Two channeled convolution layer is concatenated to the last layer
  - Edge map is calculated from the ground truth by sobel operation
  - Sobel operation followed by concatenating a hard thresholding operation to indicate whether the pixel edge or not
  - Calculate the loss "Predicted edge map edge preserving loss"

# 3. Top Solution (3) 3rd Solution

Stage-Preserving Guidance to obtain the extra prior information



클래스의 라벨이 적은 "rare"한 instance만 augmentation 하는 방법

# 3. Top Solution (4) 4th Solution



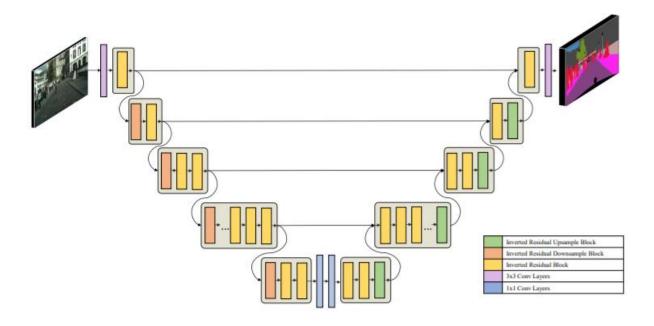


Fig. 2. EfficientSeg architecture. There are 5 different type of blocks. Inverted Residual Blocks are MobileNetV3 blocks described as in the paper. 1x1 and 3x3 blocks are standard convolution blocks which has activation and batch normalization. Downsampling operations are done with increasing the stride and for upsampling, linear interpolation is used.

# 3. Top Solution (5) 5th Solution

Oata-efficient semantic segmentation via extremely perturbed data augmentation

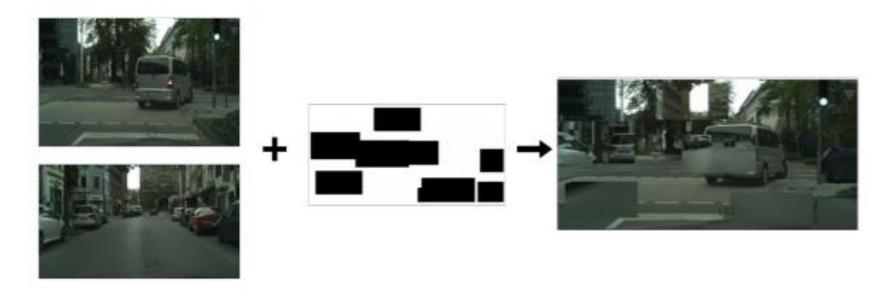


Fig. 3: Example of CutMix Sprinkles in semantic segmentation setup.