$\Sigma =$

u	u_1	u_2	u_L	i	i_1	i_2	i_L	$\bar{c}$	
	1				1			0	$u_1 = i_1 R_1$
		1				1		1	$u_2 = i_2 R_1$
			1				0	0	$u_L = \dot{i_L} L$
		1	1					1	$u_L = u_2$
				1	1	1		1	$i_1 = i_2 + i_L$
1								1	$u = sin(t)$
1	1	1						0	$u = u_1 + u_2$
				1	1			0	$i = i_1$
$\bar{d}$	0	1	1	0	1	0	0	0	