

$\Sigma =$ 

	$u$	$u_1$	$u_2$	$u_L$	$u_C$	$i$	$i_1$	$i_2$	$i_L$	$i_C$	$\bar{c}$	
		1					1				1	$u_1 = i_1 R_1$
			1					1			1	$u_2 = i_2 R_1$
				1					0		0	$u_L = i_L L$
			1	1							1	$u_L = u_2$
							1	1	1		1	$i_1 = i_2 + i_L$
		1	1		0						1	$u_C = u_1 + u_2$
					0					1	0	$i_C = i_c C$
	1										1	$u = \sin(t)$
	1	1	1								1	$u = u_1 + u_2$
						1	1			1	0	$i = i_1 + i_c$
$\bar{d}$	0	0	0	0	0	1	0	0	0	1		