

$\Sigma =$

| u | u_1 | u_2 | u_L | u_C | i | i_1 | i_2 | i_L | i_C | \bar{c} | |
|-----------|-------|-------|-------|-------|-----|-------|-------|-------|-------|-----------|-------------------|
| | 1 | | | | | 1 | | | | 1 | $u_1 = i_1 R_1$ |
| | | 1 | | | | | 1 | | | 1 | $u_2 = i_2 R_1$ |
| | | | 1 | | | | | 0 | | 0 | $u_L = i_L L$ |
| | | 1 | 1 | | | | | | | 1 | $u_L = u_2$ |
| | | | | | | 1 | 1 | 1 | | 1 | $i_1 = i_2 + i_L$ |
| | 1 | 1 | | 0 | | | | | | 1 | $u_C = u_1 + u_2$ |
| | | | | 0 | | | | | 1 | 0 | $i_C = i_c C$ |
| | 1 | | | | | | | | | 1 | $u = \sin(t)$ |
| | 1 | 1 | 1 | | | | | | | 1 | $u = u_1 + u_2$ |
| | | | | | 1 | 1 | | | 1 | 0 | $i = i_1 + i_c$ |
| \bar{d} | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 | 0 | 1 | |