

# 임베디드 시스템

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# Today

- ▶ Contiki-OS

# LED Control & UDP Communication in Contiki

# blink\_Red\_LED.c

```
blink_Red_LED.c x
#include "contiki.h"
#include "dev/leds.h"
#include <stdio.h>

PROCESS(blink_process, "LED blink process - GROUP 3");
AUTOSTART_PROCESSES(&blink_process);

PROCESS_THREAD(blink_process, ev, data)
{
    static struct etimer timer;
    PROCESS_BEGIN();

    while(1) {
        etimer_set(&timer, CLOCK_CONF_SECOND);
        PROCESS_WAIT_EVENT_UNTIL(ev == PROCESS_EVENT_TIMER);
        leds_toggle(LEDS_RED);
    }
    PROCESS_END();
}
```

void leds\_set(unsigned char leds);  
void leds\_on(unsigned char leds);  
void leds\_off(unsigned char leds);  
void leds\_toggle(unsigned char leds);

LEDS\_GREEN / LEDS\_YELLOW  
LEDS\_RED / LEDS\_BLUE / LEDS\_ALL

# RPL UDP

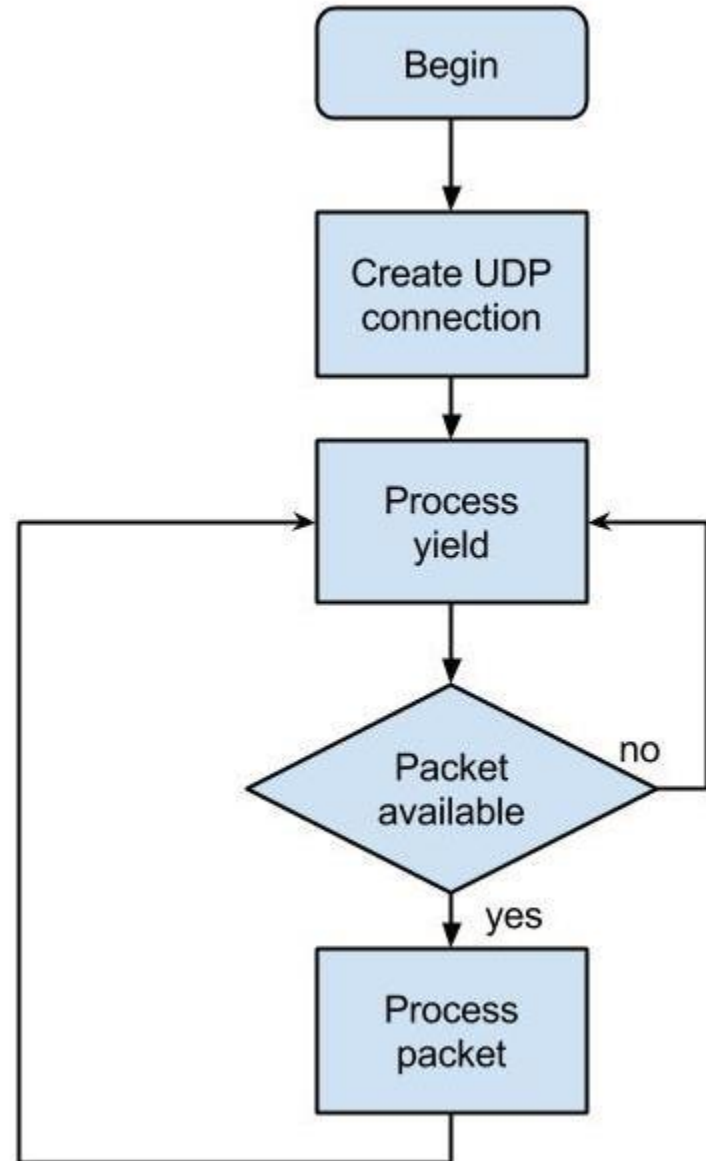
- RPL is the IPv6 Routing Protocol for Low-power and Lossy Networks (LLNs).
  - LLNs are a class of network in which both the routers and their interconnect are constrained.
    - LLN routers typically operate with constraints on processing power, memory, and energy.
  - RPL provides a mechanism whereby multipoint-to-point traffic from devices inside the LLN towards a central control point as well as point-to-multipoint traffic from the central control point to the devices inside the LLN are supported.

# UDP example

- Location: <contiki\_folder>/examples/ipv6/rpl-upl/
- In this example, UDP is implemented on top of RPL.
  - A LLN is comprised of a **UDP server**, which accepts available packets, and **several UDP clients**, which send packets periodically to server through single-hop or multi-hops.

# UDP Server

- In the example, UDP server does three tasks primarily.
  1. Initializes RPL DAG (Directed Acyclic Graph);
  2. Sets up UDP connection;
  3. Waits for packets from client, receives and print them on stdout.



# UDP Server - Initialize RPL DAG

```
uip_ds6_addr_add(&ipaddr, 0, ADDR_MANUAL);
root_if = uip_ds6_addr_lookup(&ipaddr);
if(root_if != NULL) {
    rpl_dag_t *dag;
    dag = rpl_set_root(RPL_DEFAULT_INSTANCE, (uip_ip6addr_t *)&ipaddr);
    uip_ip6addr(&ipaddr, 0xaaaa, 0, 0, 0, 0, 0, 0, 0);
    rpl_set_prefix(dag, &ipaddr, 64);
    PRINTF("created a new RPL dag\n");
} else {
    PRINTF("failed to create a new RPL DAG\n");
}
```



# UDP Server – Set up a UDP Connection

```
server_conn = udp_new(NULL, UIP_HTONS(UDP_CLIENT_PORT), NULL);  
if(server_conn == NULL) {  
    PRINTF("No UDP connection available, exiting the process!\n");  
    PROCESS_EXIT();  
}  
udp_bind(server_conn, UIP_HTONS(UDP_SERVER_PORT));  
  
PRINTF("Created a server connection with remote address ");  
PRINT6ADDR(&server_conn->ripaddr);  
PRINTF(" local/remote port %u/%u\n", UIP_HTONS(server_conn->lport),  
        UIP_HTONS(server_conn->rport));
```

# UDP Server – Receiving and Processing Incoming Packet

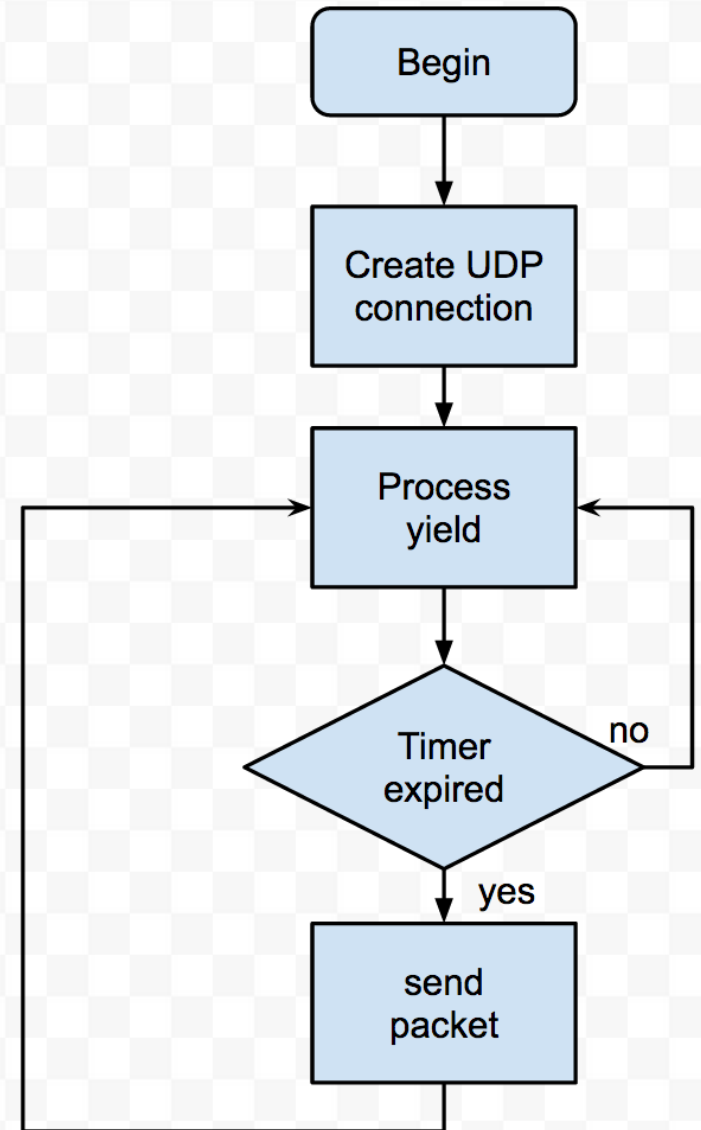
```
while(1) {
    PROCESS_YIELD();
    if(ev == tcpip_event) {
        tcpip_handler();
    } else if (ev == sensors_event && data == &button_sensor) {
        PRINTF("Initiating global repair\n");
        rpl_repair_root(RPL_DEFAULT_INSTANCE);
    }
}

static void
tcpip_handler(void)
{
    char *appdata;
    if(uip_newdata()) {
        appdata = (char *)uip_appdata;
        appdata[uip_datalen()] = 0;
        PRINTF("DATA recv '%s' from ", appdata);
        PRINTF("%d",
            UIP_IP_BUF->srcipaddr.u8[sizeof(UIP_IP_BUF->srcipaddr.u8) - 1]);
        PRINTF("\n");

        #if SERVER_REPLY
            PRINTF("DATA sending reply\n");
            uip_ipaddr_copy(&server_conn->ripaddr, &UIP_IP_BUF->srcipaddr);
            uip_udp_packet_send(server_conn, "Reply", sizeof("Reply"));
            uip_create_unspecified(&server_conn->ripaddr);
        #endif
    }
}
```

# UDP Client

- In the example, UDP client does two tasks primarily.
  1. Sets up UDP connection;
  2. Sends packet to UDP server periodically.



# UDP Client – Set up UDP Connection

```
/* new connection with remote host */
client_conn = udp_new(NULL, UIP_HTONS(UDP_SERVER_PORT), NULL);
if(client_conn == NULL) {
    PRINTF("No UDP connection available, exiting the process!\n");
    PROCESS_EXIT();
}
udp_bind(client_conn, UIP_HTONS(UDP_CLIENT_PORT));

PRINTF("Created a connection with the server ");
PRINT6ADDR(&client_conn->ripaddr);
PRINTF(" local/remote port %u/%u\n",
        UIP_HTONS(client_conn->lport), UIP_HTONS(client_conn->rport));
```

# UDP Client – Sends Packet

```
etimer_set(&periodic, SEND_INTERVAL);
while(1) {
    PROCESS_YIELD();
    if(ev == tcpip_event) {
        tcpip_handler();
    }

    if(etimer_expired(&periodic)) {
        etimer_reset(&periodic);
        ctimer_set(&backoff_timer, SEND_TIME, send_packet, NULL);
    }
}
```

---

```
static void
send_packet(void *ptr)
{
    static int seq_id;
    char buf[MAX_PAYLOAD_LEN];

    seq_id++;
    PRINTF("DATA send to %d 'Hello %d'\n",
           server_ipaddr.u8[sizeof(server_ipaddr.u8) - 1], seq_id);
    sprintf(buf, "Hello %d from the client", seq_id);
    uip_udp_packet_sendto(client_conn, buf, strlen(buf),
                          &server_ipaddr, UIP_HTONS(UDP_SERVER_PORT));
}
```

# Today's mission

- Run `blink_Red_LED.c` to control the LEDs of motes.
- Toggle the LEDs of a UDP server according to the UDP sender IDs.
  - For example,
    - If sender is Node 2, toggle the RED led.
    - If sender is Node 3, toggle the BLUE led.
    - If sender is Node 4, toggle the GREEN led.