Q-Network - Quiz

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이름 : 정현일

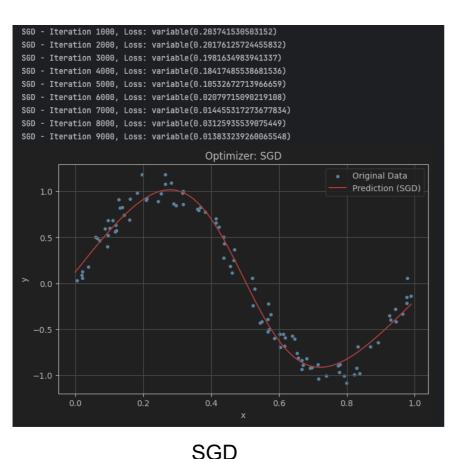
2025.05.01.

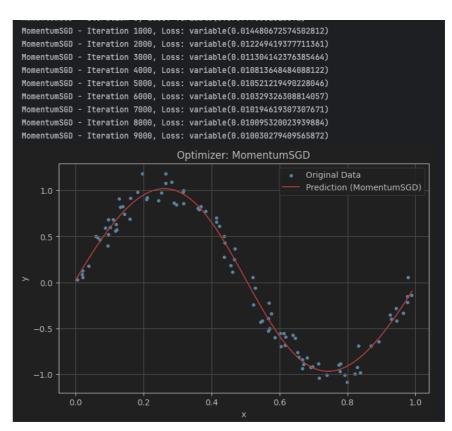
## (Q1) 위 실습에서 다음의 optimizer 를 실행하여 결과를 비교하라.

class MomentumSGD(Optimizer):

class AdaGrad(Optimizer):

class Adam(Optimizer):

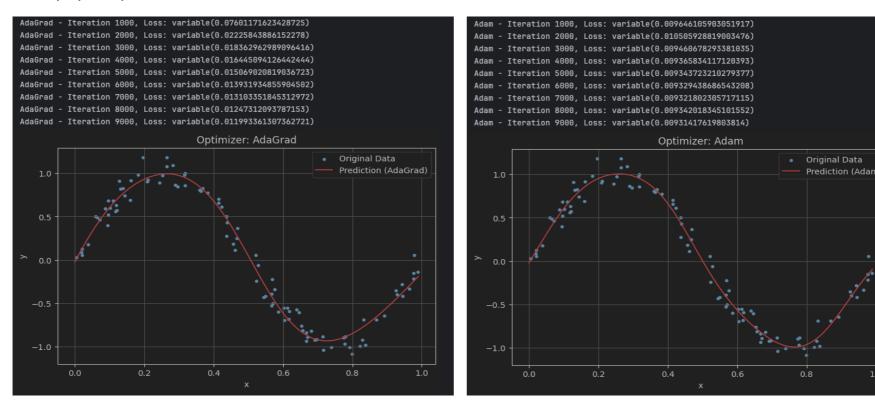




MomentumSGD

### (Q1) 위 실습에서 다음의 optimizer 를 실행하여 결과를 비교하라.

Optimizer 모드 각각 시험해본 결과 Adam 0.00931417619803814 으로 제일 적은 loss값을 나타낸다



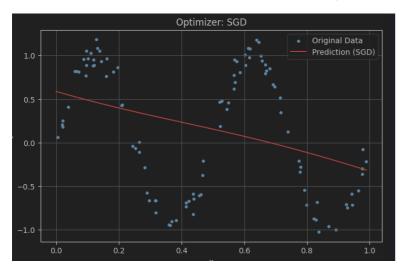
AdaGrad SGD: 0.013833239260065548 AdaGrad: 0.011993361307362721

MomentumSGD: 0.010030279409565872

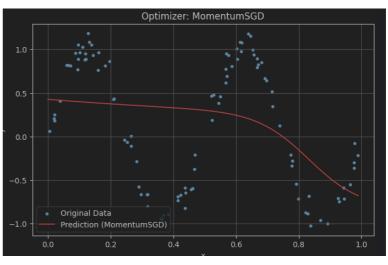
Adam

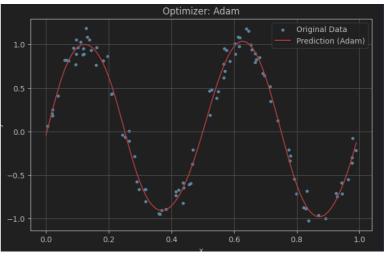
Adam: 0.00931417619803814

(Q2)  $y = \sin(4\pi x)$  (0  $\le x \le 1$ ) 에 대한 loss 가 최소화 되도록 신경망을 최적화하고 결과를 출력하라.









# (Q3) Q-Network 를 적용하여 5x5 Grid World 에 대한 Q 테이블을 완성하고 . policy 를 구하라. 단, 신경망의 최적화를 위한 파라메터를 설정하라.

### [민테이블]

```
State: (2, 0), Action: 0, Q-value: 0.5319892764091492
State: (0, 0), Action: 0, Q-value: 0.5082912445068359
                                                          State: (2, 0), Action: 1, Q-value: 0.5564687252044678
State: (0, 0), Action: 1, Q-value: 0.4714983105659485
                                                          State: (2, 0), Action: 2, Q-value: 0.591364860534668
State: (0, 0), Action: 2, Q-value: 0.4341954290866852
                                                          State: (2, 0), Action: 3, 0-value: 0.6222833395004272
State: (0, 0), Action: 3, Q-value: 0.8370070457458496
                                                          State: (2, 1), Action: 0, Q-value: 0.6198688745498657
State: (0, 1), Action: 0, Q-value: 0.6570677161216736
                                                          State: (2, 1), Action: 1, Q-value: 0.5100265145301819
State: (0, 1), Action: 1, Q-value: 0.6117208003997803
                                                          State: (2, 1), Action: 2, Q-value: 0.5905502438545227
State: (0, 1), Action: 2, Q-value: 0.6710969805717468
                                                          State: (2, 1), Action: 3, Q-value: 0.6299696564674377
State: (0, 1), Action: 3, Q-value: 0.8939908146858215
                                                          State: (2, 2), Action: 0, Q-value: 0.7750536799430847
State: (0, 2), Action: 0, Q-value: 0.8971067667007446
                                                          State: (2, 2), Action: 1, Q-value: 0.5740088820457458
State: (0, 2), Action: 1, Q-value: 0.7862273454666138
                                                          State: (2, 2), Action: 2, Q-value: 0.6239744424819946
State: (0, 2), Action: 2, Q-value: 0.7411519885063171
                                                          State: (2, 2), Action: 3, Q-value: 0.6203243136405945
State: (0, 2), Action: 3, Q-value: 0.9715120196342468
                                                          State: (2, 3), Action: 0, Q-value: -0.00357205793261528
State: (0, 3), Action: 0, Q-value: 0.5105817914009094
                                                          State: (2, 3), Action: 1, Q-value: 0.372499018907547
State: (0, 3), Action: 1, Q-value: 0.45226749777793884
                                                          State: (2, 3), Action: 2, Q-value: 0.722237765789032
State: (0, 3), Action: 2, Q-value: 0.45922234654426575
                                                          State: (2, 3), Action: 3, Q-value: 0.3673689365386963
State: (0, 3), Action: 3, Q-value: 0.580070972442627
State: (1, 0), Action: 0, Q-value: 0.5291873812675476
                                                          [Policy]
State: (1, 0), Action: 1, Q-value: 0.5850884318351746
State: (1, 0), Action: 2, Q-value: 0.2875347137451172
State: (1, 0), Action: 3, Q-value: 0.3879384994506836
                                                           State: (0, 0), Best Action: RIGHT
                                                           State: (0, 1), Best Action: RIGHT
State: (1, 1), Action: 0, Q-value: 0.7368839979171753
                                                           State: (0, 2), Best Action: RIGHT
State: (1, 1), Action: 1, Q-value: 0.7735257148742676
                                                           State: (0, 3), Best Action: RIGHT
State: (1, 1), Action: 2, Q-value: 0.8471799492835999
                                                           State: (1, 0), Best Action: DOWN
                                                           State: (1, 1), Best Action: LEFT
State: (1, 1), Action: 3, Q-value: 0.7462244629859924
                                                           State: (1, 2), Best Action: UP
State: (1, 2), Action: 0, Q-value: 0.8802248239517212
                                                           State: (1, 3), Best Action: UP
State: (1, 2), Action: 1, Q-value: 0.7530813217163086
                                                           State: (2, 0), Best Action: RIGHT
State: (1, 2), Action: 2, Q-value: 0.8204984068870544
                                                           State: (2, 1), Best Action: RIGHT
                                                           State: (2, 2), Best Action: UP
State: (1, 2), Action: 3, Q-value: -0.14373673498630524
                                                           State: (2, 3), Best Action: LEFT
State: (1, 3), Action: 0, Q-value: 1.033362865447998
State: (1, 3), Action: 1, Q-value: 0.6747794151306152
State: (1, 3), Action: 2, Q-value: 0.7625390291213989
State: (1, 3), Action: 3, Q-value: 0.3932201862335205
```

(Q3) Q-Network 를 적용하여 5x5 Grid World 에 대한 Q 테이블을 완성하고 . policy 를 구하라. 단, 신경망의 최적화를 위한 파라메터를 설정하라.

### [실행결과]

