

Q11 [5 points] In HW23, you were asked to implement a data structure using the disjoint-set API to maintain an array of bits $X[1 \dots n]$ along with these operations.

(i) Init() : Initialization. All bits of X are initialized to 0.

(ii) Set(i) : Set $X[i]=1$. It is guaranteed that $i \leq n-1$ so the rightmost bit of $X[]$ is never set.

(iii) IsSet(i): return $X[i]$

(iv) NextUnset(i): return the next largest smallest $j \geq i$ s.t. $X[j]=0$. This will always return some index.

Which disjoint-set implementation will you choose, and why, if you require that Set() has amortized complexity $O(\log n)$ and NextUnset() has worst-case complexity $O(1)$? Explain.

Ans: Set() is implemented using 1 Union() and NextUnset() is implemented using 1 Find().

We should use the shallow-tree+threading+union_by_rank implementation. The amortized cost of Union() in this implementation is $O(\log n)$ and the cost of Find() is $O(1)$.

Path-compression+union-by-rank is not suitable here since its Find() has $O(\log n)$ worst-case complexity.

Q12. [5 points] Suppose I am trying to find the shortest distances from a source vertex s on a graph G using the Bellman-Ford algorithm. While filling the memo $OPT[i,v]$, where i is an integer and v is a vertex, in the increasing order of i (starting at $i=0$ and filling the table row-wise), I observe that for one particular k , $OPT[k-1,u] = OPT[k,u]$ for all vertices u .

Suppose $dist(s,u)$ denotes the shortest distance between s and u . Which of the following is true and why?

(a) $OPT[k,u] < dist(s,u)$ (b) $OPT[k,u] \leq dist(s,u)$ (c) $OPT[k,u] = dist(s,u)$

(d) $OPT[k,u] \geq dist(s,u)$ (e) $OPT[k,u] > dist(s,u)$ (f) None (answer depends on G)

Ans: The basic idea is the recurrence formula for $OPT[j,.]$ depends only on $OPT[j-1,.]$:

$$OPT[j,u] = \max_v \{ OPT[j-1,u], OPT[j-1,v] + w(v,u) \}$$

So, the values for any j (i.e., the j -th row in the memo storing the OPT values) can be filled entirely from the values for $j-1$ (the $(j-1)$ th row). Since the $k-1$ and k -th rows are identical, this would mean the $(k+1)$ -th row would be the same as them, and so will be all the next rows, including the $(n-1)$ -th row. The $(n-1)$ th row stores the distances $dist(s,u)$. So $dist(s,u)=OPT[n-1,u]=OPT[k,u]$.

Problem 3

Let TT be a free tree with positive weights assigned to its vertices. A vertex VV is called a **center** of TT if it satisfies the following condition:

- If VV and its adjoining edges are removed, no connected component of the remaining tree has a total weight greater than half the total weight of TT .

For example, consider a tree with a total weight of 31:

- Vertex D is a center because, upon removing D, the remaining components have weights $\{A,B,C\}=9$, $\{E\}=9$, and $\{F,G,H,I,J\}=11$, none of which exceeds half the total weight (15.5).
- Vertex F is not a center because removing F leaves a component $\{A,B,C,D,E\}$ with a total weight of 20, which is greater than half of 31.

Let T be a tree with positive weights on the vertices. A vertex V is a center of T if the following holds: If you delete

V and its adjoining edges, then none of the remaining connected pieces has more than half the total weight of

T

. For instance, the tree below has a total cost of 31. Vertex D is a center, because if you delete D the remaining pieces are

{
A,B,C
}

with cost 9;

{
E
}

with cost 9;

and

{
F,G,H,I,J
}

with cost 11. Vertex F is not a center, because the piece

{
A,B,C,D,E
}

has cost

20, which is more than half of 31.

Give an

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(

N

) algorithm to find the center of a free tree. Hint: begin by converting the tree to a rooted tree, with an arbitrarily chosen root.

Answer:

Let R be a vertex in T . Let T' be the rooted tree corresponding to T with root R .

Note that if you delete node N from T , the connected components are the subtrees rooted at children of N and the collection of all nodes not in the subtree rooted at N . We will call this the "outer" component.

Using DFS, compute for every node N in T' the total cost of the subtree rooted at N .

```

N = R;
Total = R.cost;
while (true) {
  if (there exists a child C of N such that C.cost >= Total/2)
    N = C;
  else return N;
}
}

```

It is clear that if T has a center, then the subtree of the child C that is chosen must contain the center, and that the loop will stop if N is the center. Therefore, if T has a center, then the algorithm returns that center. It is possible to prove that every tree has a center

Q9. [5 points] We call a graph ‘compact’ if there is a path with at most 2 edges between any two vertices in the same connected component.

```

def reduce(G): // G is any unweighted undirected graph
  G' = copy of G
  Add a vertex v to G'
  Add edges from v to every vertex
  Add another vertex u and add edge (u,v)
  Return G'

```

Lemma: G has a Hamiltonian path iff reduce(G) is compact and has a Hamiltonian path.

Fill in the blanks above such that reduce() is a polynomial-time algorithm and it satisfies the lemma below. Explain how both these criteria are satisfied.

Ans:

Reduce() adds 2 vertices and $n+1$ edges to a n -node graph. Hence, it takes polynomial time.

G' is compact since (1) u can reach v with 1 edge and reach every other vertex w within 2 edges, u to v and v to w , (2) v can reach every vertex with 1 edge, (3) all other vertices can reach any other vertex within 2 edges by going through v .

If G has a Hamilton path p then G' has this Hamiltonian path: $u - v - p$

If G' has a Hamiltonian path p then p must start at u (since u has degree 1), go to v , then visit all the other vertices. The subpath after v is then a Hamiltonian path of G .

Q10. [5 points] Complete the following divide and conquer algorithm to find all elements in an n -sized integer array that appear $n/5$ or more number of times. Note that there can be at most 5 such elements. Explain your approach and discuss the time complexity of your algorithm.

```

def FindFrequent(A[1...n]): // returns at most 5 numbers
  AL = A[1... n/2]
  AR = A[n/2+1 ... n]
  (u1,u2,u3,u4,u5) = FindFrequent(AL) // some of these could be Null
  (v1,v2,v3,v4,v5) = FindFrequent(AR) // some of these could be Null
  i=1, w1=w2=w3=w4=s5=NULL
  for each element x in {u1,u2,u3,u4,u5,v1,v2,v3,v4,v5}:
    t = number of copies of x in A

```

```
If t >= n/5: wi = x, i=i+1 // x is frequent element  
return (w1,w2,w3,w4,w5) // some of these could be Null
```

Explanation and analysis:

Recurrence $T(n) = 2T(n/2) + O(n)$ // the loop makes a linear pass and the loop is over at most 10 elements. Solution of recurrence : $O(n \log n)$

If x is a frequent element, then frequency of x in A $\geq n/5$. However, if $\text{freq}(x \text{ in AL}) < (n/2)/5$ and $\text{freq}(x \text{ in$

AR) $< (n/2)/5$ then $\text{freq}(x \text{ in AL+AR}) < n/5$. So, x should appear at least 20% of the time in at least one of AL or AR. The algorithm identifies all elements that appear at least 20% of the time in both AL and AR

and checks which of them appear at least 20% of the time in A by calculating their frequency making

linear passes over the array.