Uninstructed Robot

(working title)

Presenter: Daewon Choi

ROBOTS WITH HUMANS LABORATORY

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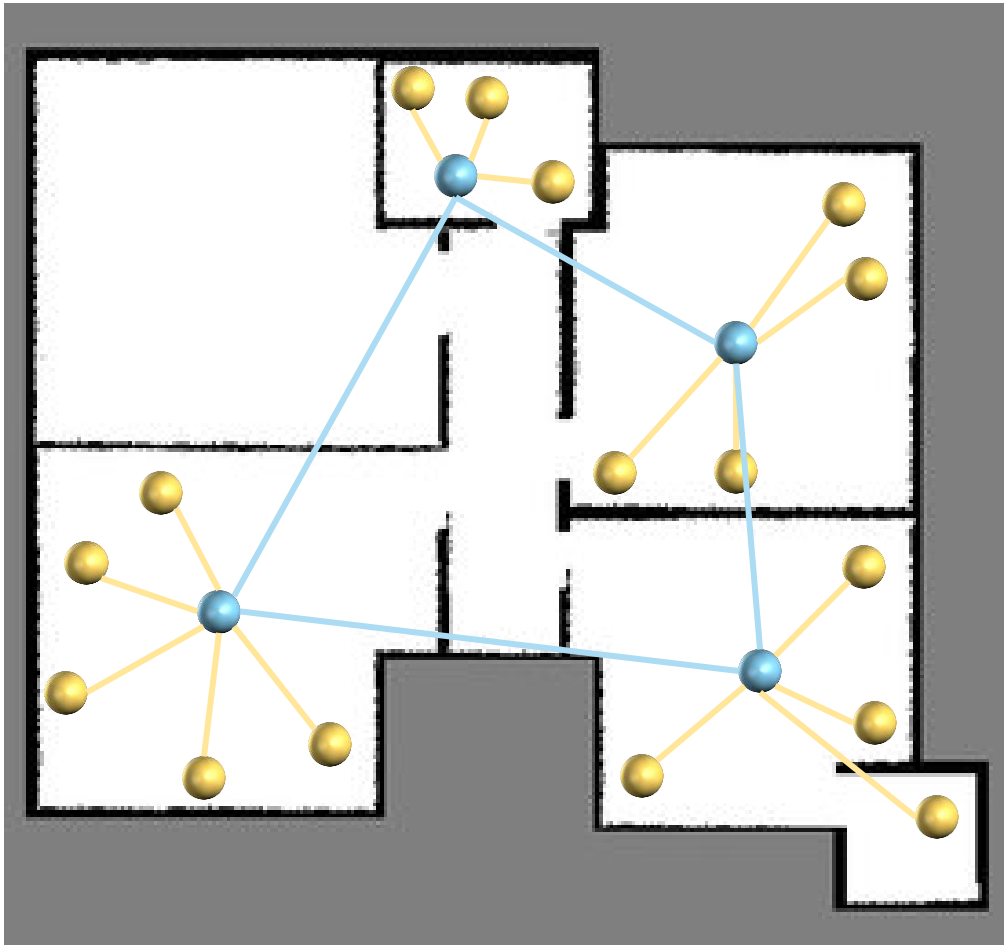
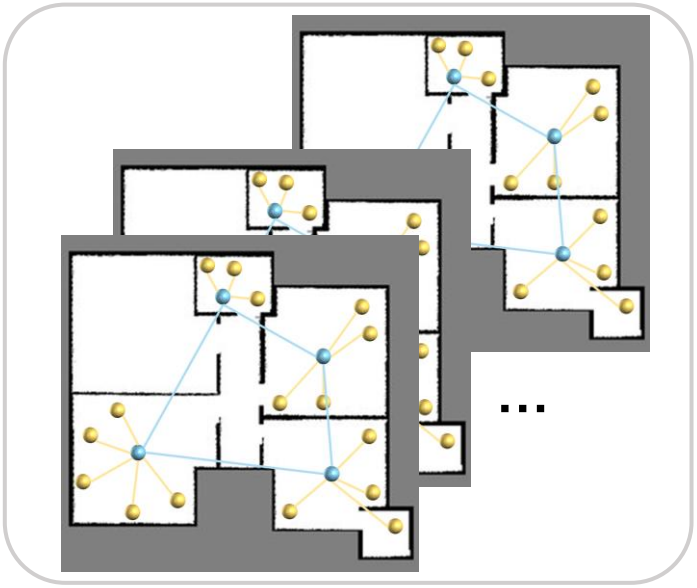
Introduction

Introduction



Introduction



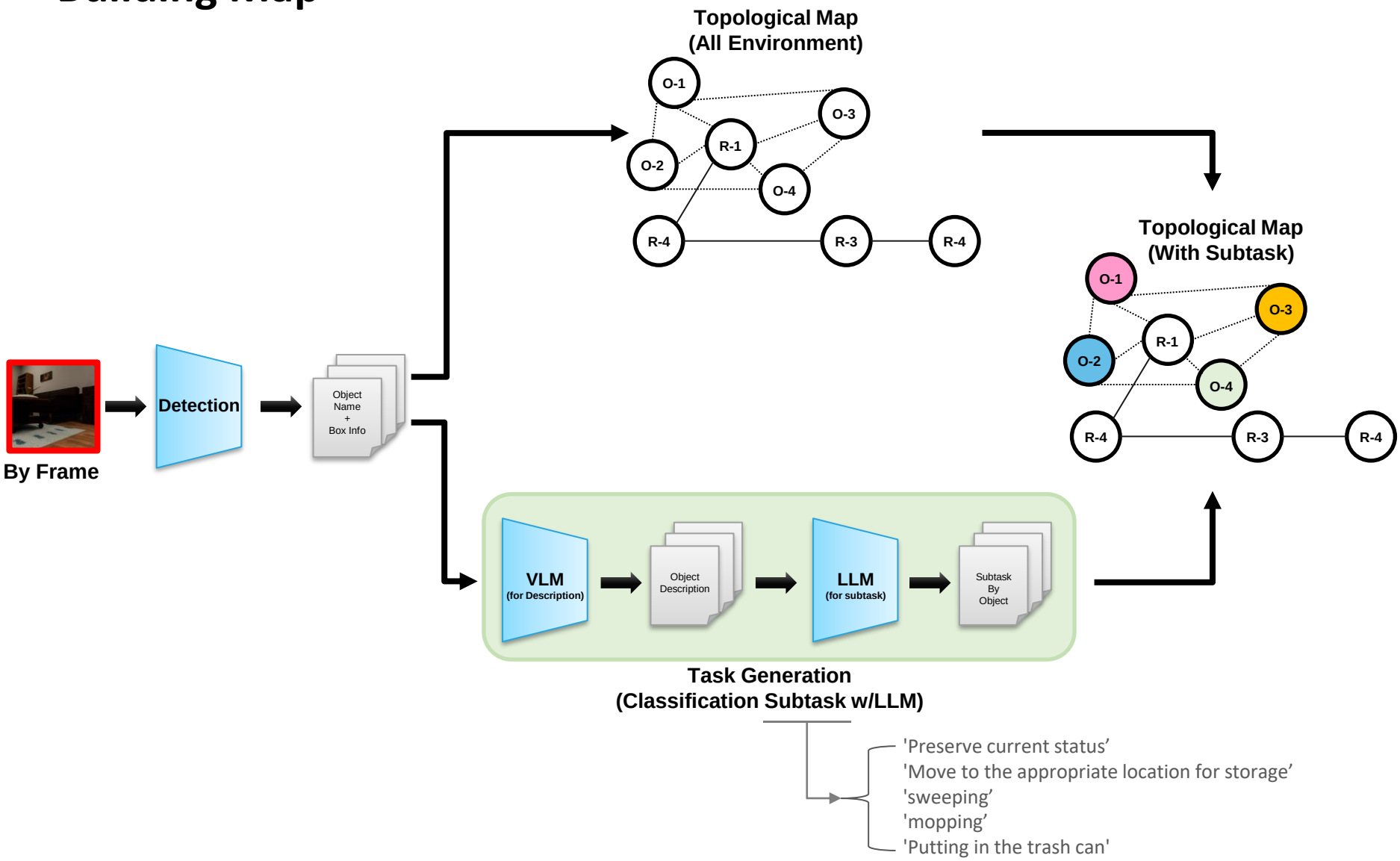
Task – relation of object

General

Personal

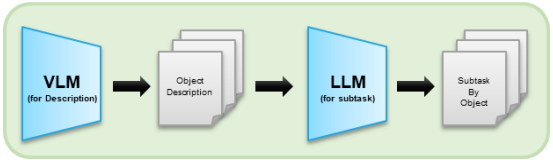
Framework

- **Building Map**



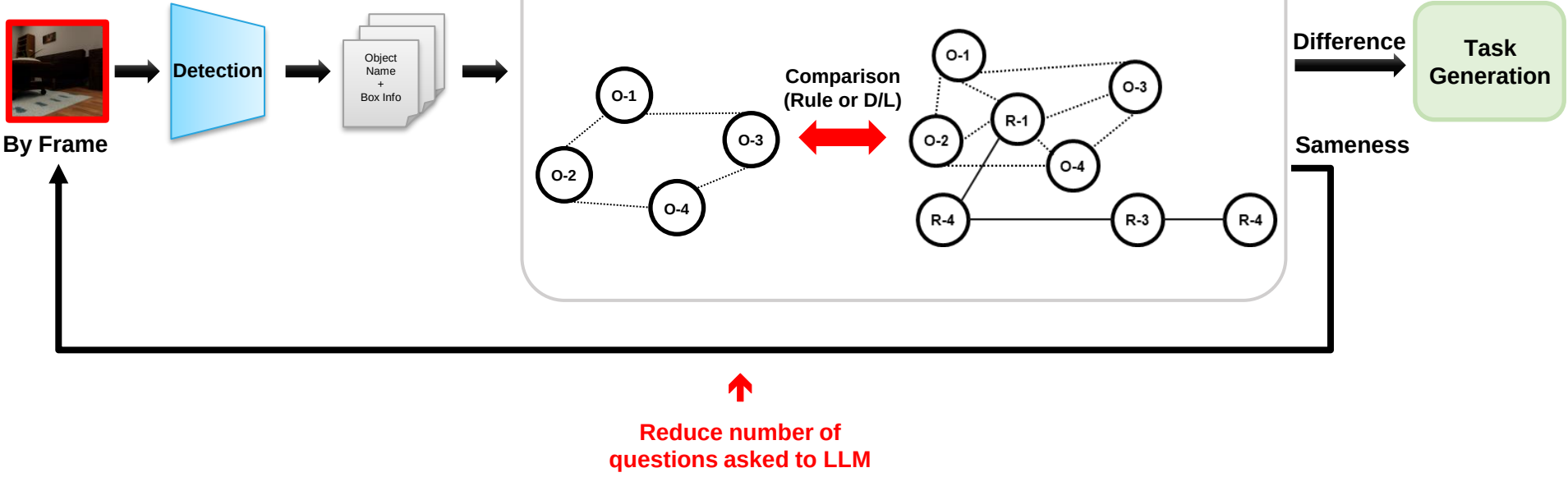
Framework

- **Managing Object (1)**



Task Generation

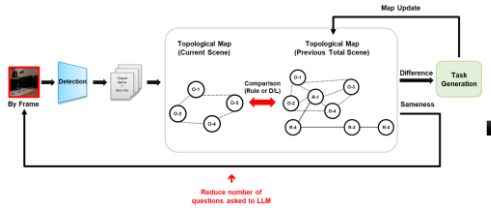
Map Update



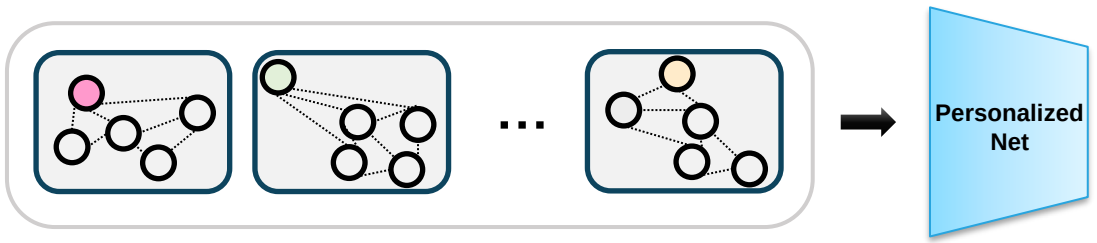
Reduce number of questions asked to LLM

Framework

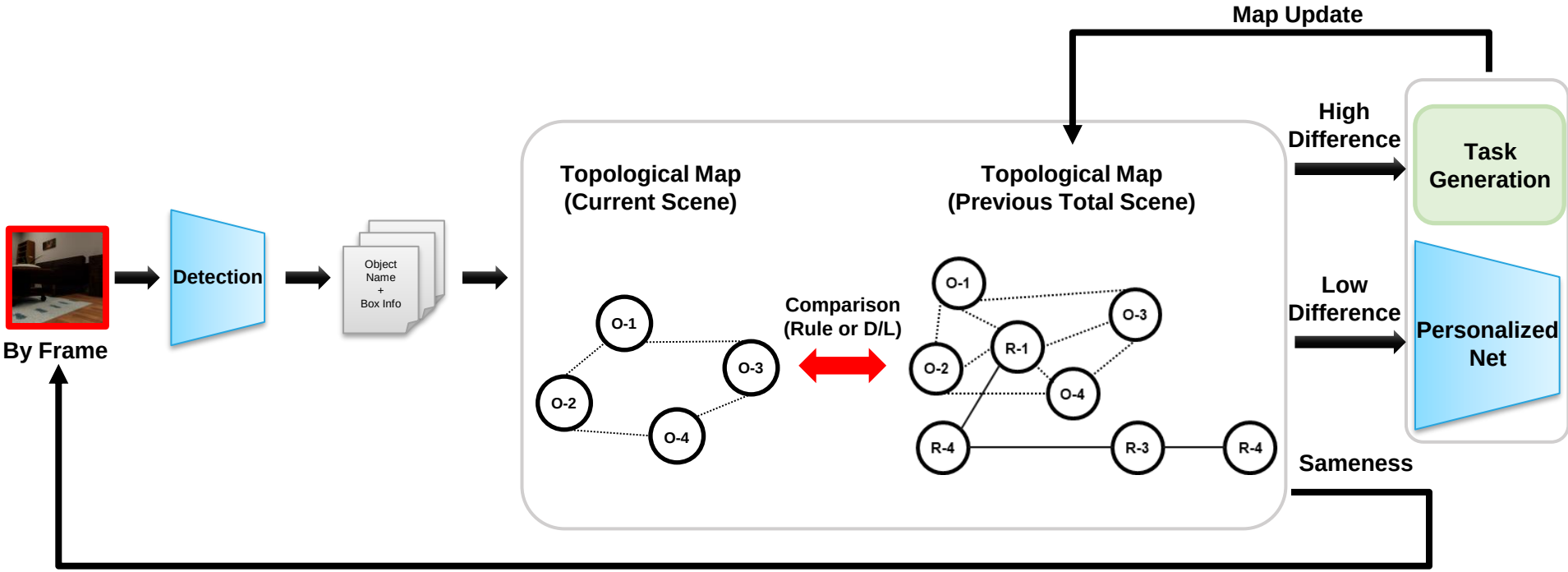
Managing Object (2)



Managing Object (1)

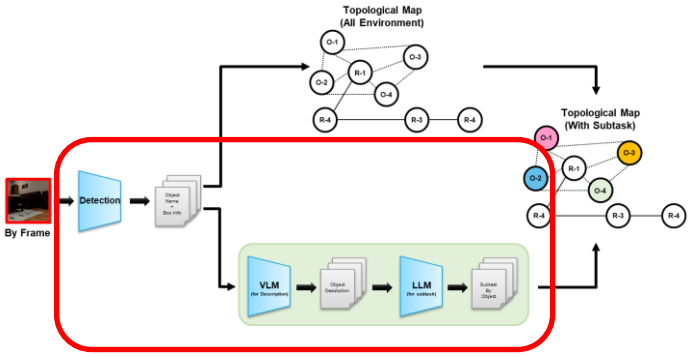


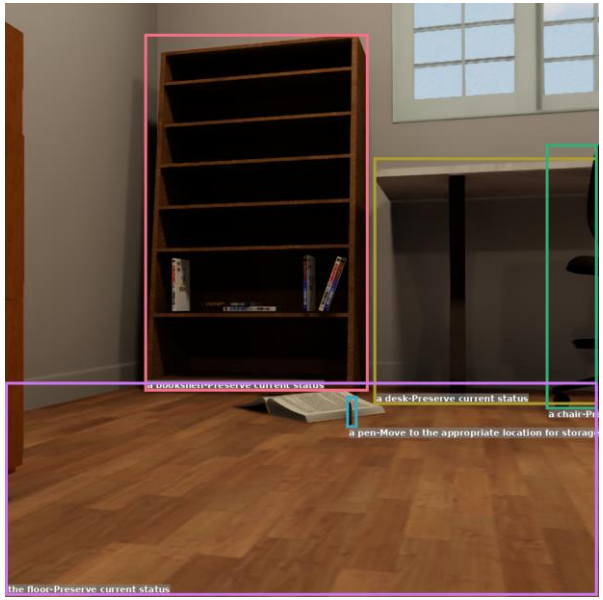
Task – relation of object

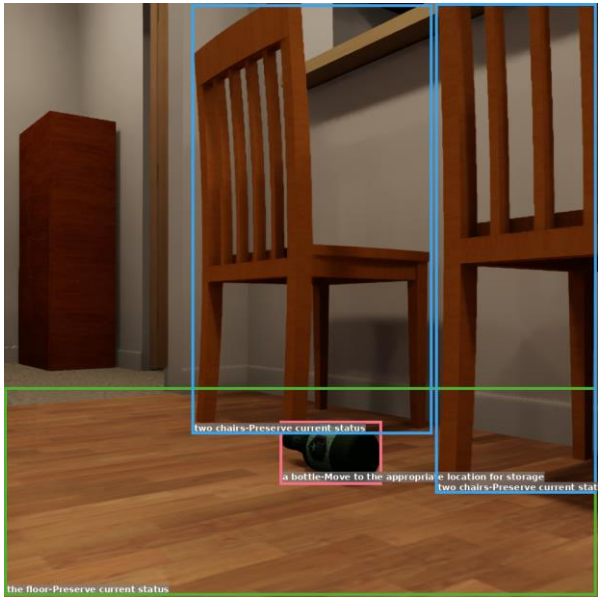


Experiments

- **Task Generation**

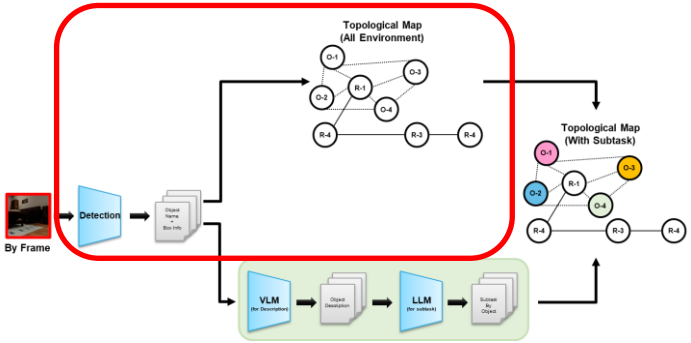


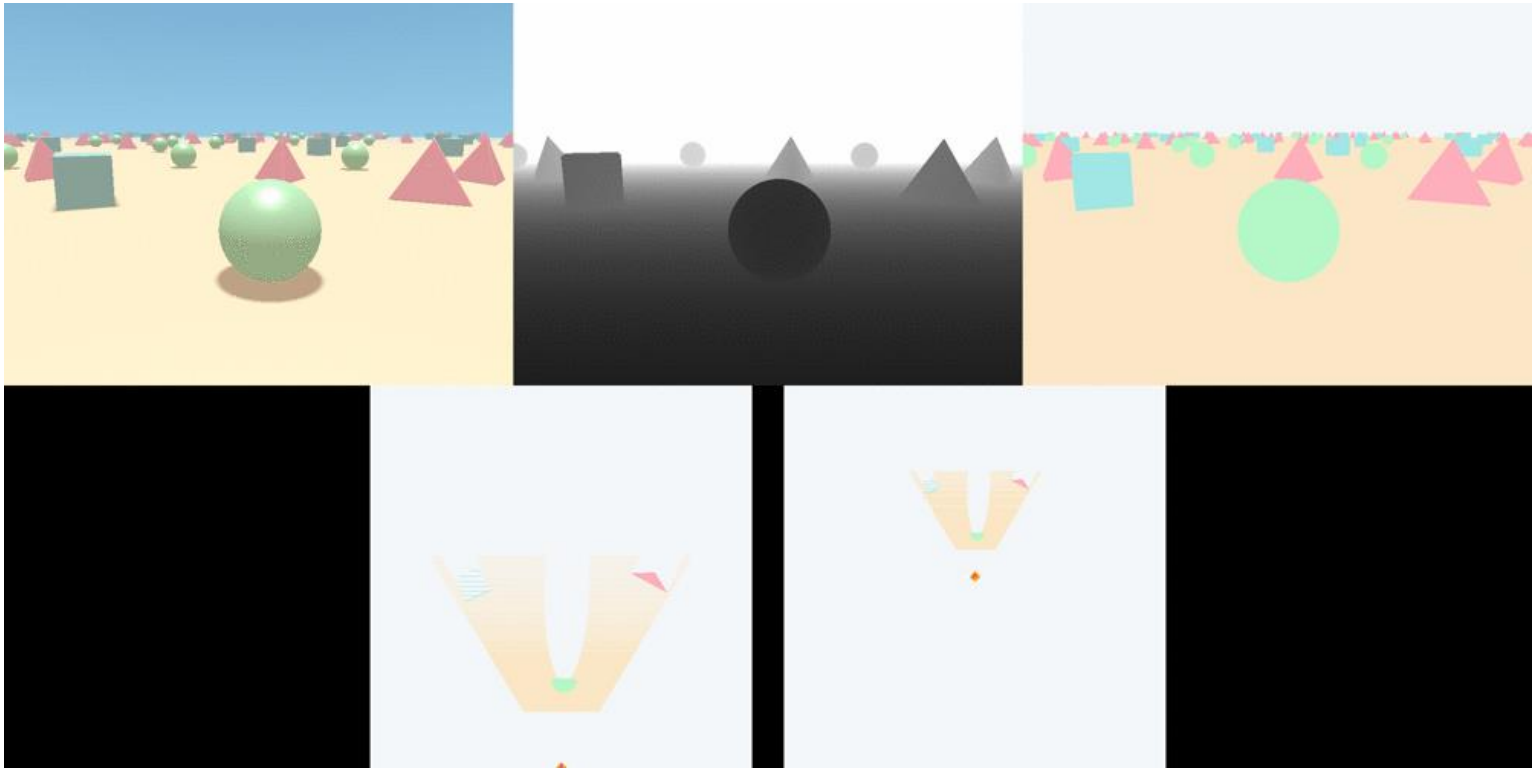




Ongoing Work

- **Building Topological Map**





Thank you

Q & A

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