

신경망 네트워크와 수학적 기반

Linear Independence Linear dependence



• set of *n*-vectors $\{a_1, \ldots, a_k\}$ (with $k \ge 1$) is *linearly dependent* if

$$\beta_1 a_1 + \cdots + \beta_k a_k = 0$$

holds for some β_1, \ldots, β_k , that are not all zero

- \bullet equivalent to : at least one a_i is a linear combination of the others
- we say ' a_1, \ldots, a_k are linearly dependent'
- $\{a_1\}$ is linearly dependent only if $a_1 = 0$
- $\{a_1, a_2\}$ is linearly dependent only if one a_i is a multiple of the other

Linear Independence Example



the vectors

$$a_1 = \begin{bmatrix} 0.2 \\ -7 \\ 8.6 \end{bmatrix}, \quad a_2 = \begin{bmatrix} -0.1 \\ 2 \\ -1 \end{bmatrix}, \quad a_3 = \begin{bmatrix} 0 \\ -1 \\ 2.2 \end{bmatrix}$$

are linearly dependent, since $a_1 + 2a_2 - 3a_3 = 0$

 \diamond can express any of them as linear combination of the other two, e.g.,

$$a_2 = (-1/2) a_1 + (3/2) a_3$$

Linear Independence Linear independence



• set of *n*-vectors $\{a_1, \ldots, a_k\}$ (with $k \ge 1$) is *linearly independent* if it is not linearly dependent, i.e.,

$$\beta_1 a_1 + \cdots + \beta_k a_k = 0$$

- \bullet holds only when $\beta_1 = \cdots = \beta_k = 0$
- \bullet a_1, \ldots, a_k are linearly independent
- \bullet equivalent to: no a_i is a linear combination of the others
- \bullet example: the unit *n*-vectors e_1, \ldots, e_n are linearly independent

Linear Independence

Linear combinations of linearly independent vectors



• suppose x is linear combination of linearly independent vectors a_1, \ldots, a_k :

$$x = \beta_1 a_1 + \cdots + \beta_k a_k$$

• the coefficients β_1, \ldots, β_k are unique, *i.e.*, if

$$x = \gamma_1 a_1 + \cdot \cdot \cdot + \gamma_k a_k$$

then $\beta_i = \gamma_i$ for $i = 1, \dots, k$

- lack this means that (in principle) we can deduce the coefficients from x
- to see why, note that

$$(\beta_1 - \gamma_1) a_1 + \cdot \cdot \cdot + (\beta_k - \gamma_k) a_k = 0$$

and so (by linear independence) $\beta_1 - \gamma_1 = \cdots = \beta_k - \gamma_k = 0$

Linear Independence Independence-dimension inequality



- *♦* a linearly independent set of n-vectors can have at most n elements
- \bullet put another way: any set of n+1 or more n-vectors is linearly dependent

Linear Independence Basis



- \bullet a set of *n* linearly independent *n*-vectors a_1, \ldots, a_n is called a *basis*
- ◆ any *n*-vector *b* can be expressed as a linear combination of them:

$$b = \beta_1 a_1 + \cdots + \beta_n a_n$$

for some β_1, \ldots, β_n

- and these coefficients are unique
- \bullet formula above is called *expansion of b in the a*₁,..., *a*_n basis
- \bullet example: e_1, \ldots, e_n is a basis, expansion of b is

$$b = b_1 e_1 + \cdots + b_n e_n$$

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- set of *n*-vectors a_1, \ldots, a_k are (mutually) orthogonal if $a_i \perp a_j$ for $i \neq j$
- they are *normalized* if $||a_i|/=1$ for $i=1,\ldots,k$
- they are *orthonormal* if both hold
- can be expressed using inner products as

$$a_i^T a_j = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

- orthonormal sets of vectors are linearly independent
- lack by independence-dimension inequality, must have $k \le n$
- when $k = n, a_1, \ldots, a_n$ are an *orthonormal basis*

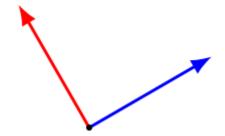
Linear Independence

Examples of orthonormal bases

- standard unit *n*-vectors e_1, \ldots, e_n
- the 3-vectors

$$\begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix}, \qquad \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \qquad \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$$

• the 2-vectors shown below





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• if a_1, \ldots, a_n is an orthonormal basis, we have for any *n*-vector x

$$x = (a_1^T x)a_1 + \dots + (a_n^T x)a_n$$

- ◆ called *orthonormal expansion of x* (in the orthonormal basis)
- lacktriangle to verify formula, take inner product of both sides with a_i