

DIGITAL IMAGE PROCESSING

-APPLIED MATHEMATICS CAPSTONE DESIGN-

D.I.P 응용수학과 김하현,최우빈

목차

- 주제 ; cats and dogs binary classification
- (1) CNN(Convolutional Neural Network, 합성 곱 신경망)을 이용한 직접 모델링 후, cats 와 dogs 의 각각 data set 을 training 한 후 accuracy 측정 Python
- (2)기존 data set의 image 들을 fourier transform의 한 종류인 DWT(Discrete Wavelet Transform)한 image 들로 training 한 후, accuracy 측정 DWT: Matlab 으로 RGB 변환
- (3)검증된 알고리즘을 통해, 기존 data set과 DWT data set 의 accuracy 측정 (Alex net, Google net)
- Matlab R2017b의 toolbox

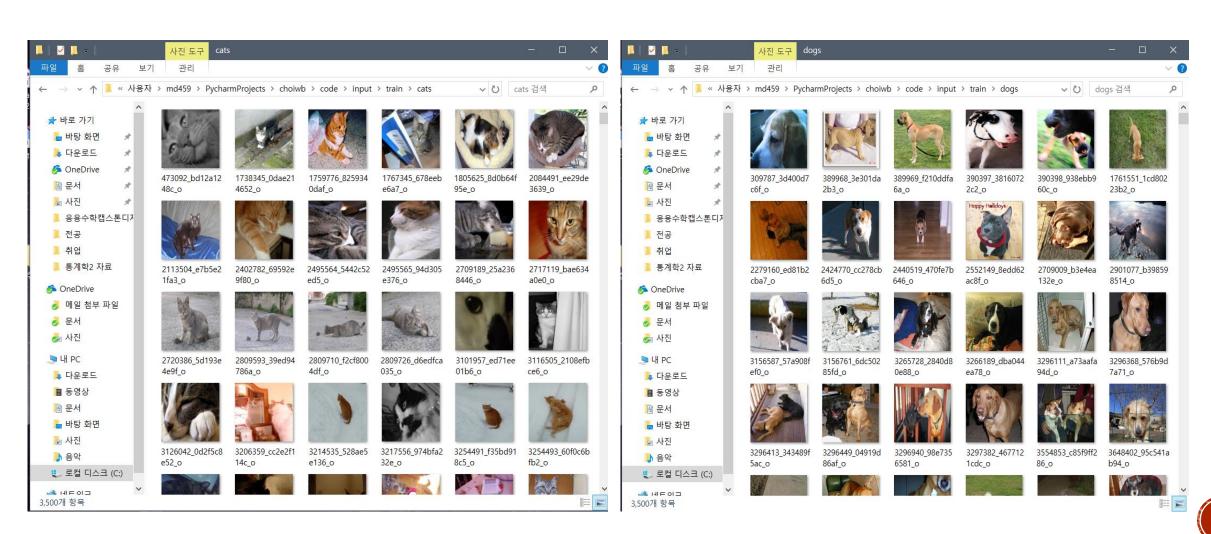


CATS AND DOGS TRAINING, TEST, AUGMENTATION SET <FILE PATH>

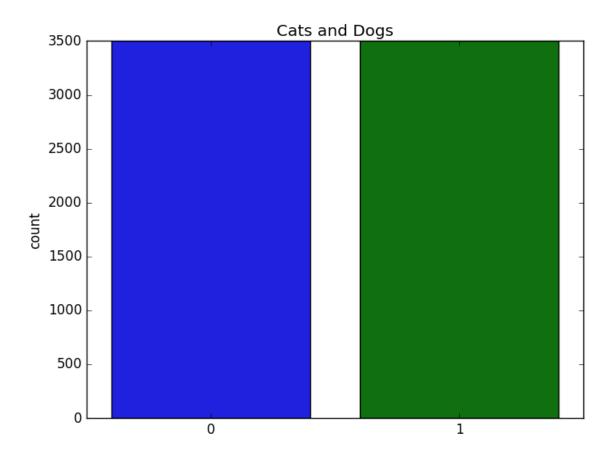
```
TRAIN_CATS_DIR = 'input/train/cats/'+
TRAIN_DOGS_DIR = 'input/train/dogs/'+
TEST_DIR = 'input/test/'+
VALD_CATS_DIR = 'input/validation/cats/'+
VALD_DOGS_DIR = 'input/validation/dogs/'+
AUG_DIR = 'input/train/aug/'+
```

Image: 128 x 128 pixels





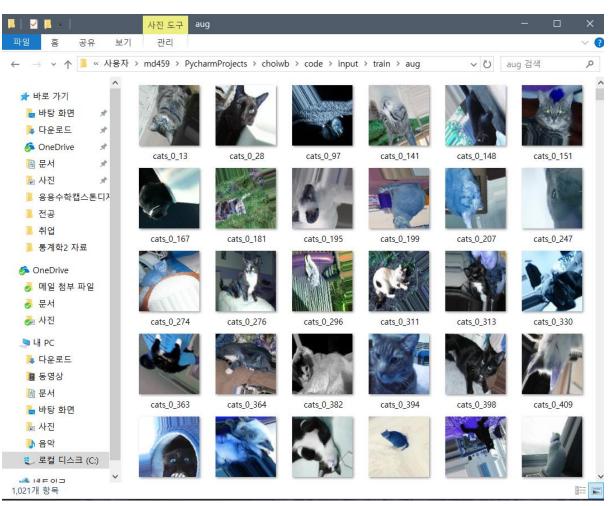
TRAINING SET (CATS:; 3500, DOGS: 3500),





AUGMENTATION 과정

- round(len(train) / 50)



TRANSPOSE(대각화): [COUNT, ROW, COLUMN, CHANNEL] -> [COUNT , CHANNEL , ROW , COLUMN]

teosorflow:[count,row,column.channel]default(기본값)시작과정 (CPU)

row major order(행 우선 순위) 속도 때문!

row-major

TensorFlow

NVIDIA cuDNN : [count , channel , row , column] default(기본값) 모델링

과정 (GPU)

- gray scale: l channel

- RGB scale: 3 channel





- Train set 형태: (7000, 3, 128, 128)

augmentation 적용

- Train set 형태: (7890, 3, 128, 128)

- Validation set 형태: (1964, 3, 128, 128)

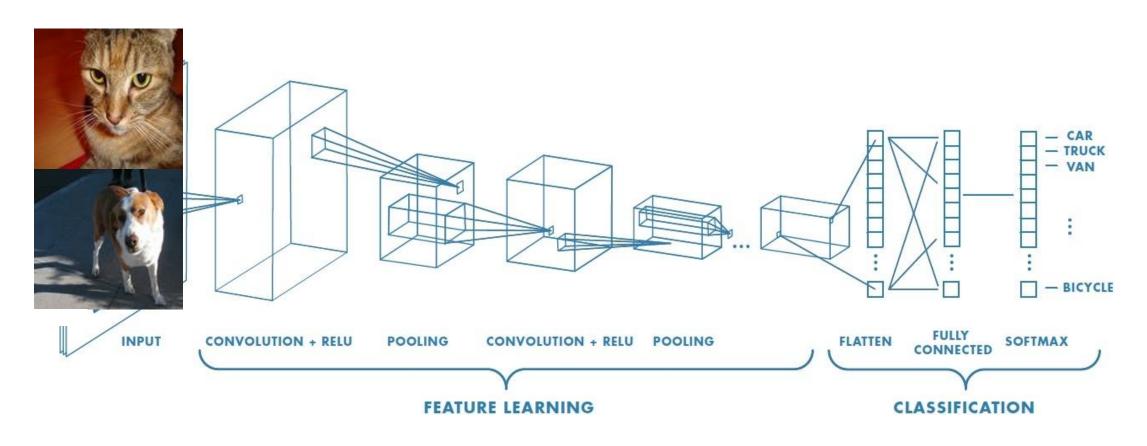
Validation_split: 20%



Train on 6312 samples, validate on 1578 samples



CNN(CONVOLUTIONAL NEURAL NETWORK) 모델링 과정





• CNN 모델링 과정

Input layer(128 X 128 픽 셀): 16 neurons, 4×4 , ReLU, max_norm = 2 Max pooling layer 3×3

Hidden layer : 32 neurons 4×4 , ReLU, max_norm = 2 Max pooling layer 3×3

Hidden layer 64 neurons 4×4 , ReLU, max_norm = 2 Max pooling layer 3×3

- Model flatten
- Output Layer 128 neurons, Sigmoid, Dropout: 0.3

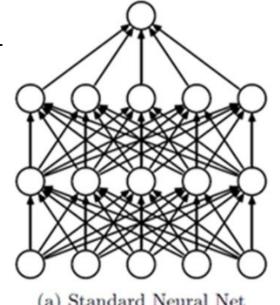


- max_norm : 정규화(normalization)의 형태, 모든 뉴런에 대한 weight vector의 크기에 upper bound를 적용하고 gradient descent를 사용

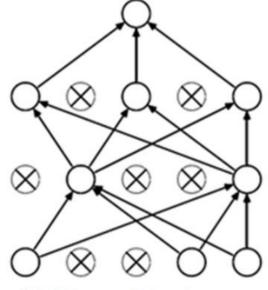
- flatten layer : 2차원 행렬 형태를 1차원 벡터 형태로 변환

- dropout:

overfitting 피하기 위함



(a) Standard Neural Net



(b) After applying dropout.



모델 연산과정

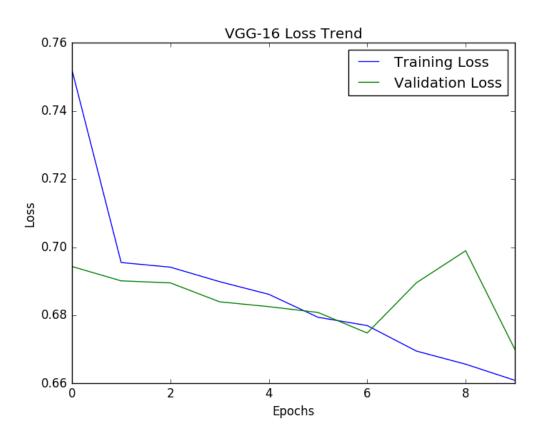
- Epoch 1/10
- 80s loss: 0.7521 acc: 0.5021 val_loss: 0.6943 val_acc: 0.5006
- Epoch 2/10
- 89s loss: 0.6955 acc: 0.5120 val_loss: 0.6901 val_acc: 0.5406
- Epoch 3/10
- 84s loss: 0.6941 acc: 0.5119 val_loss: 0.6895 val_acc: 0.5393
- Epoch 4/10
- 82s loss: 0.6899 acc: 0.5368 val_loss: 0.6840 val_acc: 0.5507
- Epoch 5/10
- 74s loss: 0.6862 acc: 0.5433 val_loss: 0.6825 val_acc: 0.5634



- Epoch 6/10
- 80s loss: 0.6794 acc: 0.5700 val_loss: 0.6808 val_acc: 0.5653
- Epoch 7/10
- 74s loss: 0.6770 acc: 0.5762 val_loss: 0.6748 val_acc: 0.5659
- Epoch 8/10
- 78s loss: 0.6695 acc: 0.5848 val_loss: 0.6896 val_acc: 0.5406
- Epoch 9/10
- 74s loss: 0.6656 acc: 0.6008 val_loss: 0.6990 val_acc: 0.5640
- Epoch 10/10
- 79s loss: 0.6609 acc: 0.6006 val_loss: 0.6700 val_acc: 0.5875
- Baseline Accuracy: 60.08%, 연산시간: 987.7676200866699,약16분 28초



LOSS TREND





<개선방향>

- 1. Train set과 augmentation set 데이터 증가
- 2. Googlenet 알고리즘 적용
- 3. Model parameter / hyper parameter 조정
- *Hyperparameter : Bayesian statistics에서 prior distribution의 parameter이다. Posterior distribution만으로 추정을 하는 것

보다 prior distribution을 알 때, 훨씬 더 잘 추정

*Neural Network에서 hyperparameter

신경망 학습을 통해서 tuning 또는 optimization 해야 하는 주 변수가 아니라 사람들이 prior 설정을 하거나, 외부 모델 메커니즘을 통해 자동으로 설정이 되는 변수



Neural Network 에서 Hyperparameter이란 (= free parameter)

Ex) learning rate , cost function(cross entropy , least square) , mini batch size , training $3 \div$, hidden layer $3 \div$, weights initialization



-cross entropy

p,m:확률 분포

$$H(p, m) = -\sum_{i} p(xi) \log(m(xi))$$

기대 값과 예측 값의 차이가 클수록 결과가 크게 나온다.

결과는 항상 양수 이다.

-cross entropy cost function

y:기대 값

a:신경망에서 출력된 값

n:훈련 데이터의 개수

$$C = -\frac{1}{n} \sum_{x} [y \ln a + (1 - y) \ln(1 - a)]$$



중간결과에서 개선점

- Training set 증가 (7000
- Batch Normalization 적용
- neuron 개수 증가 (GPU 연산)

[input - hidden1 - hidden2 - output]



$$[16 - 32 - 64 - 128]$$
 $[64 - 128 - 256 - 512]$

BATCH NORMALIZATION

Gradient Vanishing / Gradient Exploding 이 일어나지 않도록 하는 아이디어 중의 하나. 지금까지는 이 문제를 Activation 함수의 변화 (ReLU 등), Careful Initialization, small learning rate 등으로 해결하였지만, 이런 간접적인 방법보다는 training 하는 과정 자체를 전체적으로 안정화 하여 학습 속도를 가속시킬 수 있는 근본적인 방법.



Layer Normalization!

*** Internal Covariate Shift: Network의 각 층이나 Activation 마다 input의 distribution이 달라지는 현상.

각 층의 input의 distribution을 평균 0, 표준편차 1인 input으로 normalize 시키는 방법 고안.



LAYER NORMALIZATION

- State of the art한 DNN 학습시간 단축.
- 중간 층의 출력을 정규화 함으로써 실현.

***Covariate Shift(공 변량 변화)

: 입출력 규칙(주어진 입력에 대하여 출력의 생성규칙)은 training할 때와, test 할 때 다르지 않지만, 입력(공 변량)의 분포가 training 할 때와, test 할 때 다른 상황.



INTERNAL COVARIATE SHIFT

< CNN에서의 각층 마다 입력분포> (1)입력층 으로의 입력분포 평균 0,분산 1로 선형변환

(2)중간 층 으로의 입력분포 -정해진 입력분포를 유지하지 못함!

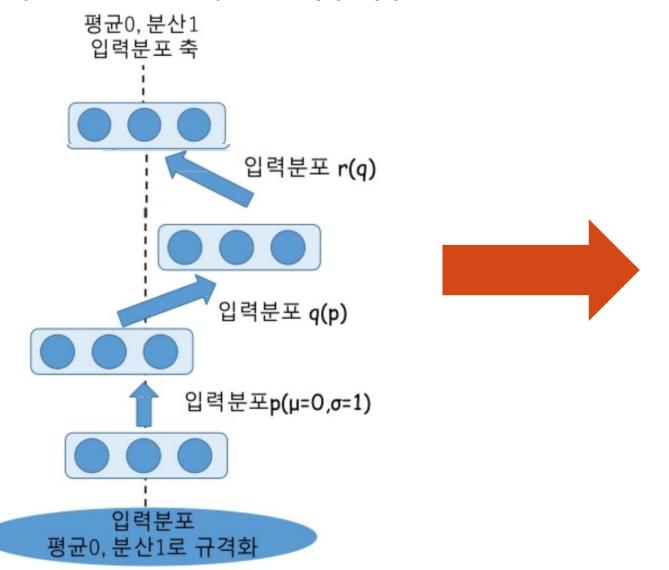


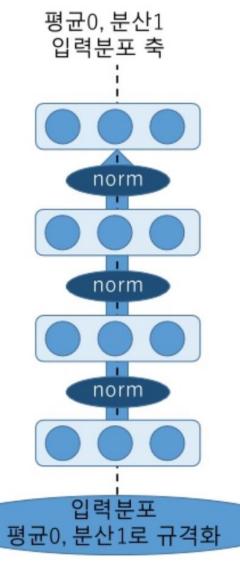
(Internal Covariate Shift)

입력분포가 변화



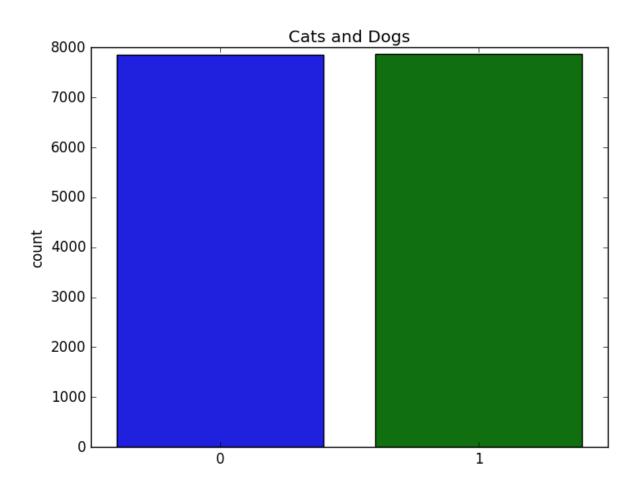
NORMALIZATION PROCESS



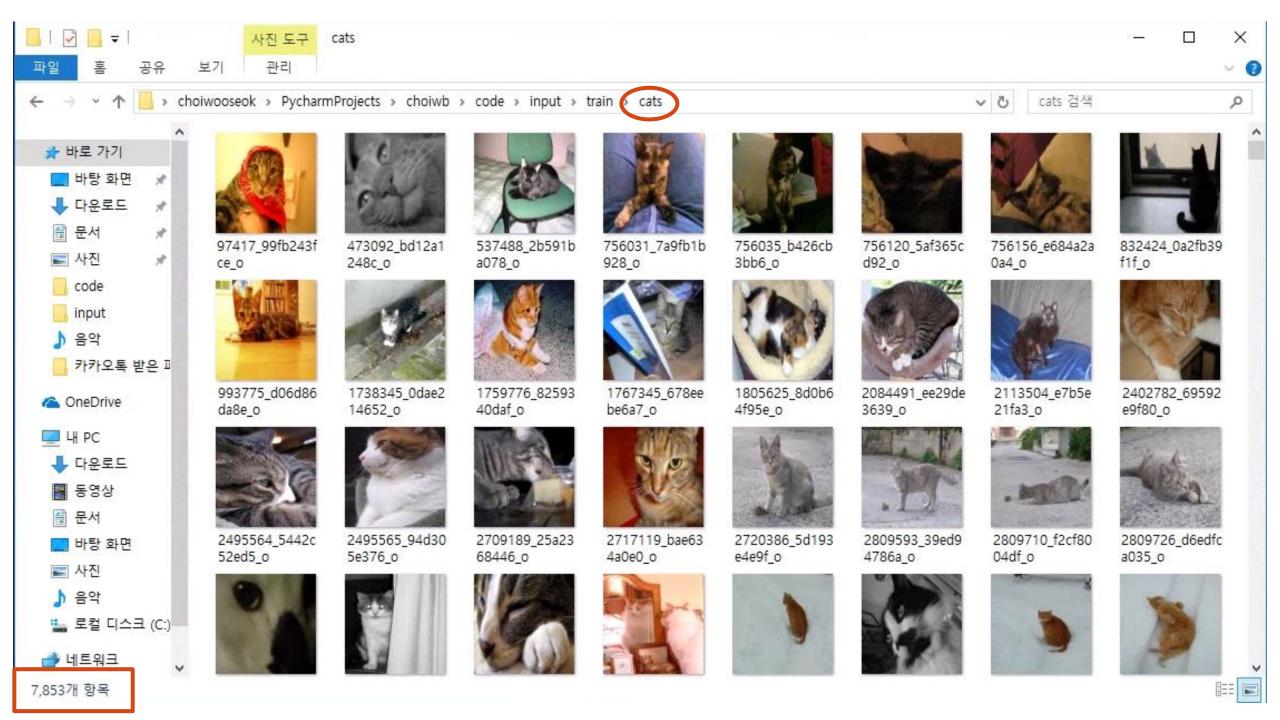


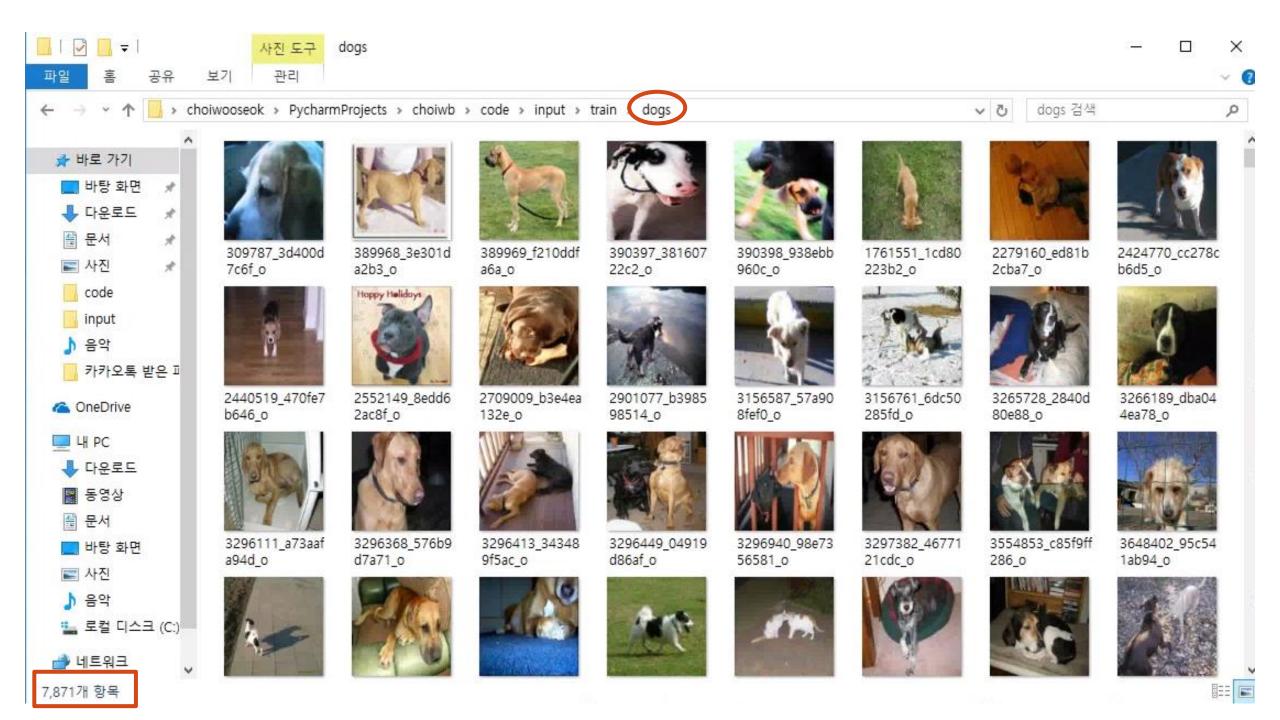


TRAINING SET (CATS:, 7853, DOGS: 7871),







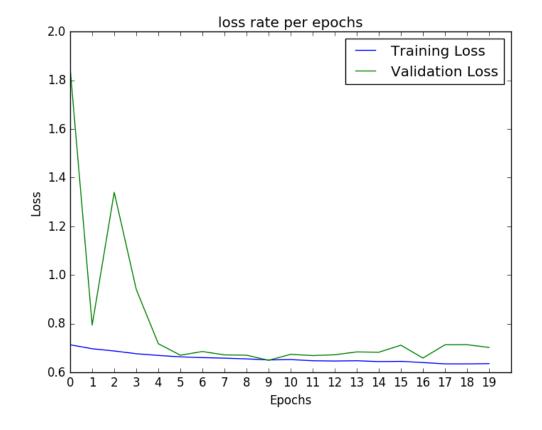


MODELING

Layer (type)	Output				Param #
conv2d_1 (Conv2D)	(None,				131136
batch_normalization_1 (Batch	(None,	3,	128,	64)	256
activation_1 (Activation)	(None,	3,	128,	64)	0
conv2d_2 (Conv2D)	(None,	3,	128,	64)	65600
batch_normalization_2 (Batch	(None,	3,	128,	64)	256
activation_2 (Activation)	(None,	3,	128,	64)	0
max_pooling2d_1 (MaxPooling2	(None,	3,	42,	21)	0
conv2d_3 (Conv2D)	(None,	3,	42,	128)	43136
batch_normalization_3 (Batch	(None,	3,	42,	128)	512
activation_3 (Activation)	(None,	3,	42 ,	128)	0
conv2d_4 (Conv2D)	(None,	3,	42 ,	128)	262272
batch_normalization_4 (Batch	(None,	3,	42,	128)	512
activation_4 (Activation)	(None,	3,	42 ,	128)	0
max_pooling2d_2 (MaxPooling2	(None,	3,	14,	42)	0
conv2d_5 (Conv2D)	(None,	3,	14,	256)	172288
batch_normalization_5 (Batch	(None,	3,	14,	 256)	1024

activation_5 (Activation)	(None,	3, 14, 256)	0
conv2d_6 (Conv2D)	(None,	3, 14, 256)	1048832
batch_normalization_6 (Batch	(None,	3, 14, 256)	1024
activation_6 (Activation)	(None,	3, 14, 256)	0
max_pooling2d_3 (MaxPooling2	(None,	3, 4, 85)	0
conv2d_7 (Conv2D)	(None,	3, 4, 512)	696832
batch_normalization_7 (Batch	(None,	3, 4, 512)	2048
activation_7 (Activation)	(None,	3, 4, 512)	0
conv2d_8 (Conv2D)	(None,	3, 4, 512)	4194816
batch_normalization_8 (Batch	(None,	3, 4, 512)	2048
activation_8 (Activation)	(None,	3, 4, 512)	0
max_pooling2d_4 (MaxPooling2	(None,	3, 1, 170)	0
flatten_1 (Flatten)	(None,	510)	0
dense_1 (Dense)	(None,	512)	261632
batch_normalization_9 (Batch	(None,	512)	2048
activation_9 (Activation)	(None,	512)	0

dropout_2 (Dropout)	(None,	512)	0
dense_3 (Dense)	(None,	1)	513
batch_normalization_11 (Batc	(None,	1)	4
activation_11 (Activation)	 (None, ======	 1) 	0 ======
Total params: 7,151,493 Trainable params: 7,145,603 Non-trainable params: 5,890			





하드웨어 사양, 연산시간, ACCURACY

■ 프로세서 : Intel(R) core TM i5 – 6500 CPU @ 3.20GHz

• RAM: 8.00 GB

GPU: NVIDIA GeForce GTX 1060 3 GB

● 연산시간 : 약 28분 4초

• Accuracy: 70.67%

Accuracy: 70.67%

[INFO] Saving the model and weights...

Saved model to disk

연산시간: 1684,4383420944214

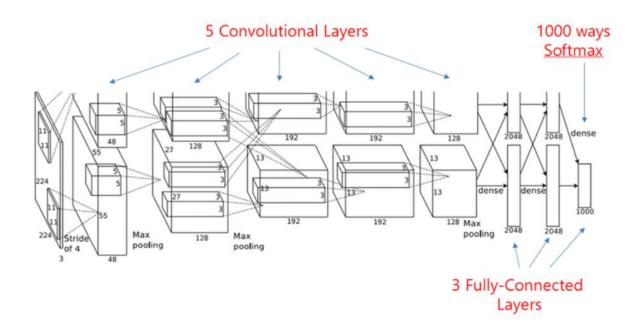


ALEX NET, GOOGLE NET

- Alex net 이란?
- ImageNet 영상 데이터 베이스를 기반으로 한, ILSVRC(ImageNet Large Scale Visual Recognition Challenge) 2012 우승 한 CNN 알고리즘



2개의 GPU를 기반으로 한 병렬 구조

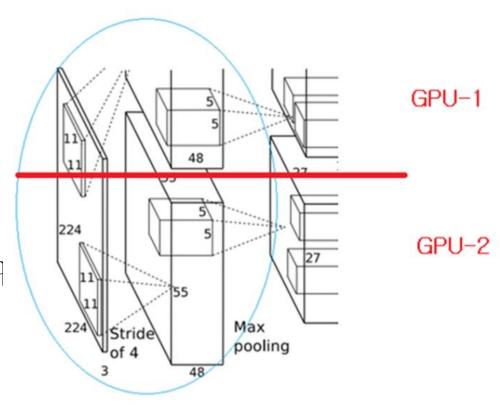


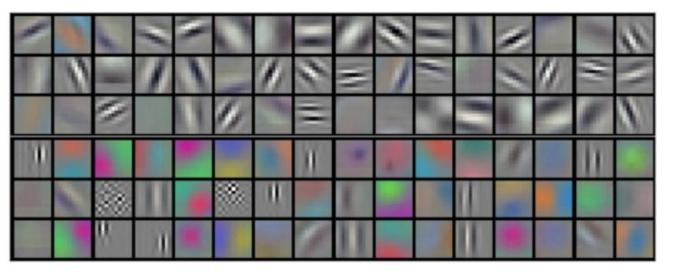


Alex net 구조

- GPU-1: color과 상관 없는 정보를 추출 하기 위 Kernel 이 학습
- GPU-2: 주로 color과 관련된 정보를 추출하기

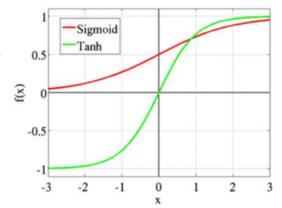
Kernel이 학습

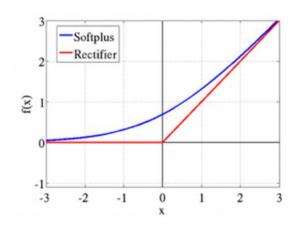




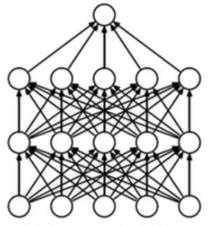


- Alex net 성능 향상
- (1) ReLU: x = 0에서 미분이 안되지만, Sigmoid나 Tanh보다 학습 속도 탁월, back propagation 결과도 단순

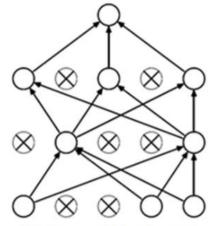




- (2) Max pooling : pooling란 convolution에서
 Feature map 영상의 크기를 줄이기 위한 용도이며, max pooling는
 Window에서 최대값을 갖는 픽셀을 선택
 (Alex net에서는 3 x 3)
- (3) Dropout: overfitting 해결 일정한 mini batch 구간 동안 생략된 망에 대한 학습을 끝내면 다시 무작위로 다른 뉴런들을 생략하면서 반복적인 학습 수행



(a) Standard Neural Net



(b) After applying dropout.

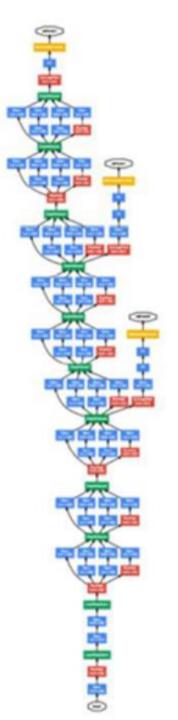


- Google net 이란?
- ILSVRC 2014 우승한 CNN 알고리즘
- 핵심: Networks are deeper and deeper!!!
- 2013년도 까지는 10 layers 미만 이었지만, Google net은 22 layers
- ** 망증가시 free parameter의 수, 연산 량증가 overfitting 문제 발생
- 따라서,문제 해결을 위한 Inception model 적용





C. Szegedy et al, "Going Deeper with Convolutions" (CVPR 2015)





INCEPTION MODEL

■ 같은 layer에 서로 다른 크기를 갖는 convolution filter을 적용하여, 다른 scale의 feature을 획득

■ l x l convolution을 사용하여 차원(dimension)을

• 적절히 줄이고(reduce), 망이 깊어 졌을 때, • 연산 량 증가 문제 해결 Filter concatenation Filter concatenation 3x3 convolutions 5x5 convolutions 1x1 convolutions 1x1 convolutions 1x1 convolutions 3x3 max pooling 1x1 convolutions 3x3 max pooling 1x1 convolutions 3x3 convolutions 5x5 convolutions Previous layer Previous layer



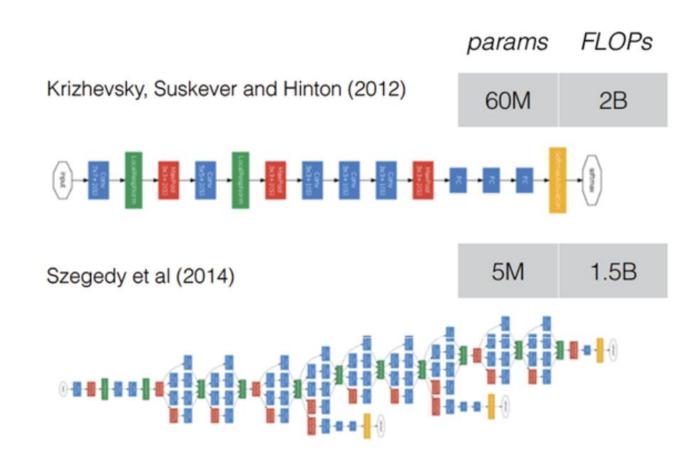
22 LAYER

type	patch size/ stride	output size	depth	#1×1	#3×3 reduce	#3×3	#5×5 reduce	#5×5	pool proj	params	ops
convolution	7×7/2	112×112×64	1							2.7K	34M
max pool	3×3/2	56×56×64	0								
convolution	3×3/1	$56 \times 56 \times 192$	2		64	192				112K	360M
max pool	3×3/2	28×28×192	0								
inception (3a)		28×28×256	2	64	96	128	16	32	32	159K	128M
inception (3b)		28×28×480	2	128	128	192	32	96	64	380K	304M
max pool	3×3/2	14×14×480	0								
inception (4a)		$14 \times 14 \times 512$	2	192	96	208	16	48	64	364K	73M
inception (4b)		$14 \times 14 \times 512$	2	160	112	224	24	64	64	437K	88M
inception (4c)		$14 \times 14 \times 512$	2	128	128	256	24	64	64	463K	100M
inception (4d)		$14 \times 14 \times 528$	2	112	144	288	32	64	64	580K	119M
inception (4e)		14×14×832	2	256	160	320	32	128	128	840K	170M
max pool	3×3/2	7×7×832	0								
inception (5a)		$7 \times 7 \times 832$	2	256	160	320	32	128	128	1072K	54M
inception (5b)		7×7×1024	2	384	192	384	48	128	128	1388K	71M
avg pool	7×7/1	$1 \times 1 \times 1024$	0								
dropout (40%)		$1\times1\times1024$	0								
linear		1×1×1000	1							1000K	1M
softmax		1×1×1000	0								

Table 1: GoogLeNet incarnation of the Inception architecture.



ALEX NET 과 GOOGLE NET의 파라미터(PARAMS)의 수와 연산량(FLOP'S) 비교





ALEX NET, GOOGLE NET APPLICATION

• Alex net 검증 (validation set : cats 976 images, dogs 976 images)

23x1 Layer array with layers:

1	'input'	lmage Input	227x227x3 images with 'zerocenter' normalization
2	'conv1'	Convolution	96 11x11x3 convolutions with stride [4 4] and padding [0 0 0 0]
3	'relu1'	ReLU F	ReLU
4	'norm1'	Cross Channel Normaliz	zation cross channel normalization with 5 channels per element
5	'pool1'	Max Pooling	3x3 max pooling with stride [2 2] and padding [0 0 0 0]
6	'conv2'	Convolution	256 5x5x48 convolutions with stride [1 1] and padding [2 2 2 2]
7	'relu2'	ReLU F	ReLU
8	'norm2'	Cross Channel Normaliz	zation cross channel normalization with 5 channels per element
9	'pool2'	Max Pooling	3x3 max pooling with stride [2 2] and padding [0 0 0 0]
10	'conv3'	Convolution	384 3x3x256 convolutions with stride [1 1] and padding [1 1 1 1]
11	'relu3'	ReLU	ReLU
12	'conv4'	Convolution	384 3x3x192 convolutions with stride [1 1] and padding [1 1 1 1]
13	'relu4'	ReLU	ReLU
14	'conv5'	Convolution	256 3x3x192 convolutions with stride [1 1] and padding [1 1 1 1]
15	'relu5'	ReLU	ReLU
16	'pool5'	Max Pooling	3x3 max pooling with stride [2 2] and padding [0 0 0 0]
17	'fc6'	Fully Connected	4096 fully connected layer
18	'relu6'	ReLU	ReLU
19	'fc7'	Fully Connected	4096 fully connected layer
20	'relu7'	ReLU	ReLU
21	'fc8'	Fully Connected	1000 fully connected layer
22	'prob'	Softmax	softmax
23	'classificationLay	er' Classification Output	crossentropyex with 'n01440764', 'n01443537', and 998 other classes

ans =								
2×2 table								
Label	Count							
cats	976							
dogs	976							

confMat =	
0.9268	0.0732
0.1098	0.8902

0/0	cats	dogs
cats	92.68	7.32
dogs	10.98	89.02

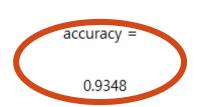


■ Google net 검증 (validation set : cats 77 images , dogs 77 images)

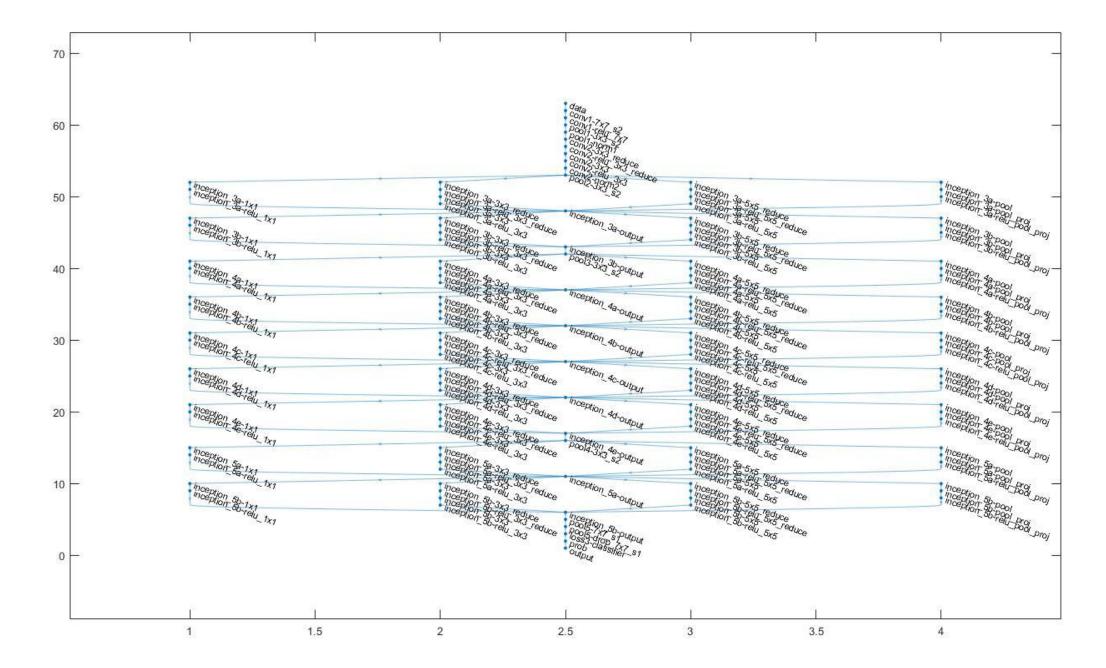
mini batch size : 10 cross validation : 3 validation split ; 0.7 , 0.3

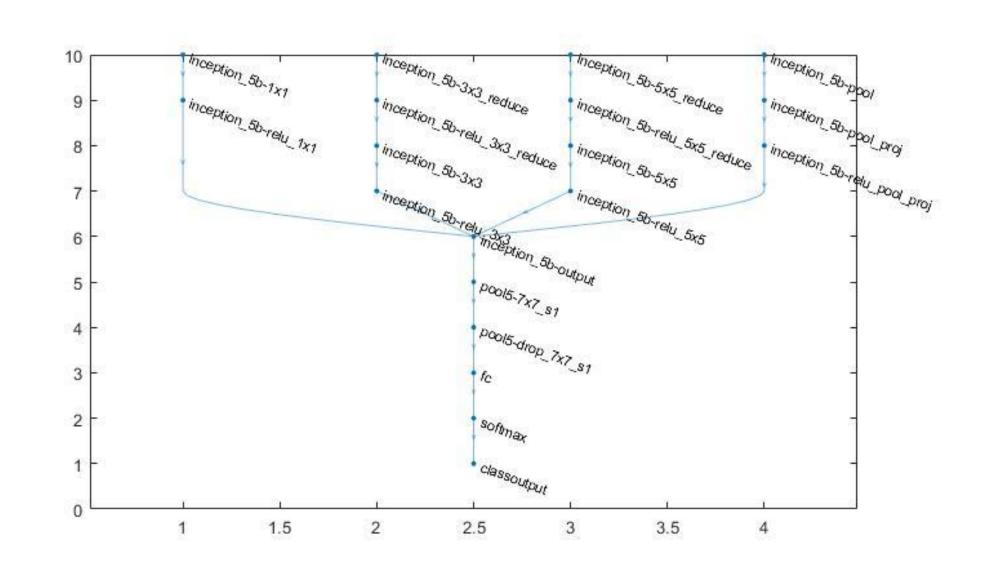
Layers: [144×1 nnet.cnn.layer.Layer] Connections: [170×2 table]

Training on single GPU. Initializing image normalization.



:h	Iteration	Time Elaps	ed Mini-b	atch Valid	dation Min	i-batch \	/alidation Ba	ase Learning
1	(se	conds)	Loss	Loss	Accuracy	Accuracy	Rate	
===== 1	1	0.43	0.6682	0.5906	60.00%	65.22%		
1	2	2.39	0.7177	0.5500	40.00%		1.00e-04	
1	3	3.08	0.4452	0.5106	80.00%		1.00e-04	
1	4	5.68	0.6661	1	60.00%		1.00e-04	
1	5	6.00	0.9095	i	60.00%		1.00e-04	
1	6	6.29	0.5651	0.2347	60.00%		1.00e-04	
1	7	8.09	0.2109		90.00%		1.00e-04	•
1	8	8.42	0.3843	i	80.00%		1.00e-04	
1	9	8.75	0.1850	0.2542	100.00%		1.00e-04	I
1	10	10.13	0.0413	ı'	100.00%	1	1.00e-04	•
2	11	10.43	0.3277	i	90.00%	i	1.00e-04	
2	12	10.72	0.2489	0.1380	90.00%	93.48%	1.00e-04	I
2	13	11.82	0.1378		90.00%		1.00e-04	
2	14	12.11	0.0070	İ	100.00%	i	1.00e-04	
2	15	12.39	0.1494	0.1026	90.00%	93.48%	1.00e-04	I
2	16	13.58	0.0633		100.00%		1.00e-04	
2	17	13.88	0.0345		100.00%		1.00e-04	
2	18	14.17	0.0098	0.0956	100.00%	93.48%	6 1.00e-04	H
2	19	15.08	0.0344		100.00%		1.00e-04	
2	20	15.41	0.0010		100.00%		1.00e-04	
3	21	15.71	0.0760	0.0925	100.00%	93.48%	6 1.00e-04	II
3	22	16.89	0.0149		100.00%		1.00e-04	
3	23	17.16	0.0557		100.00%		1.00e-04	
3	24	17.46	0.0047	0.0905	100.00%	93.48%	6 1.00e-04	H
3	25	18.46	0.1053		90.00%		1.00e-04	
3	26	18.74	0.0140		100.00%	1	1.00e-04	
3	27	19.03	0.0090	0.0889	100.00%	93.48%	6 1.00e-04	H
3	28	19.89	0.0048		100.00%	1	1.00e-04	
3	29	20.18	0.0342		100.00%	1	1.00e-04	
3	30	20.47	0.0009	0.0904	100.00%	93.48%	6 1.00e-04	·







DWT(DISCRETE WAVELET TRANSFORM) CATS ,DOGS)



165837_c1dd297 8e3_o_wav



1457998_eabdfea feb_o_wav



1553668_e1d6b1 6a77_o_wav



1583638_d514da a1ec_o_wav



1586840_2387a4 e79a_o_wav



1594113_4645f12 5b4_o_wav



14391096_a1552 4de66_o_wav



14603492_191be 47594_o_wav



14779422_9e72e 8b412_o_wav



15148909_df97bc d066_o_wav



15219412_b638a c1d30_o_wav



15243063_5b2cb c8c01_o_wav



15437110_a461d eeee6_o_wav



16202909_77d8e 9998b_o_wav



16382726_670ab 8f1aa_o_wav



16387910_ca14e1 7f7d_o_wav



16432573_2b183 be805 o way



16452635_94832 7d65c_o_wav



16560575_5ed29 382c5_o_wav



143564659_8202c fc638 o wav



145956022_bc85 42c182_o_wav



146221410_1d04 1638f4_o_wav



146369754_03ba 960a59_o_wav



146607644_ac2f0 9e533_o_wav



146685637_1cb3 08a7e0_o_wav



146916868_80d3 1b08ec_o_wav



146927634_700f8 84b1b_o_wav



147530354_0940 eed5f3_o_wav



147579697_708d 312551_o_wav



148061496_a301 6aa17a_o_wav



148771017_146d e656ce_o_wav



149154800_146b 4d4d12_o_wav





149894383_996a

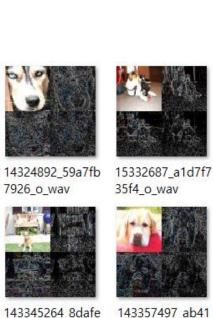
ade99a_o_wav

143345264 8dafe 641a3_o_wav 147686126_3403 4a5bd0_o_wav

7926_o_wav

149895119_64d9

7d08e2_o_wav



a83a73_o_wav

148013534_748c5

149964964_7df42

190db_o_wav

039c9_o_wav



148818579_e6f3f

150071395_6d7b

ebbd90_o_wav

86992_o_wav

15520587_dffd1c





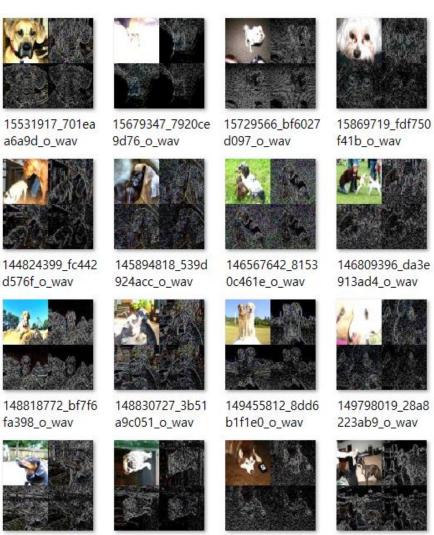
150135258_50d1

59b2a1_o_wav



2fa09c_o_wav

9b66a_o_wav



150367532_c5895

8bf99_o_wav

• DWT(Discrete Wavelet Transform) validation set(cats: 77 images, dogs: 77 images)

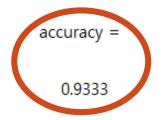
L.	(se	econds)	Loss	Loss /	Accuracy A	, ,	5.
1	1	3.75	0.6794	0.7729	60.00%	52.17% 1.00e-04	
1	2	6.18	0.7394		60.00%	1.00e-04	
1	3	6.88	0.8574	0.7031	30.00%	56.52% 1.00e-04	
1	4	9.55	0.8722		40.00%	1.00e-04	
1	5	9.92	0.9498		50.00%	1.00e-04	
1	6	10.22	0.4789	0.5751	70.00%	65.22% 1.00e-04	
1	7	11.79	0.4361		80.00%	1.00e-04	
1	8	12.10	0.8257		60.00%	1.00e-04	
1	9	12.41	0.5685	0.5274	80.00%	71.74% 1.00e-04	
1	10	13.66	0.5026	1	60.00%	1.00e-04	
2	11	13.96	0.1524	1	100.00%	1.00e-04	
2	12	14.25	0.3132	0.5333	80.00%	73.91% 1.00e-04	
2	13	15.41	0.3985	1	80.00%	1.00e-04	
2	14	15.70	0.4820	1	70.00%	1.00e-04	
2	15	16.01	0.4234	0.5384	80.00%	73.91% 1.00e-04	
2	16	17.25	0.5126	1	80.00%	1.00e-04	
2	17	17.55	0.0912	1	100.00%	1.00e-04	
2	18	17.88	0.7960	0.5496	80.00%	78.26% 1.00e-04	
2	19	19.06	0.4647	1	90.00%	1.00e-04	
2	20	19.37	0.2492	1	80.00%	1.00e-04	
3	21	19.66	0.0324	0.5252	100.00%	80.43% 1.00e-04	
3	22	20.49	0.2599	1	90.00%	1.00e-04	
3	23	20.79	0.2644	1	90.00%	1.00e-04	
3	24	21.09	0.2600	0.5385	90.00%	80.43% 1.00e-04	
3	25	22.19	0.2810	1	90.00%	1.00e-04	
3	26	22.48	0.2412	1	90.00%	1.00e-04	
3	27	22.76	0.1104	0.5378	100.00%	76.09% 1.00e-04	
3	28	23.84	0.2868	1	90.00%	1.00e-04	
3	29	24.12	0.4389	1	80.00%	1.00e-04	
3	30	24.41	0.1122	0.5462	100.00%	76.09% 1.00e-04	



GOOGLE NET 성능 향상을 위한 파라

mini batch size : 32 cross validation : 5 validation split ; 0.8 , 0.2

```
Iteration | Time Elapsed | Mini-batch | Validation | Mini-batch | Validation | Base Learning
Epoch
                                              Accuracy | Accuracy |
              (seconds)
                            Loss
                                      Loss
                     0.90
                             0.8037
                                        0.5993
                                                  53.13%
                                                             70.00%
                                                                       1.00e-04
                     2.30
                             0.6441
                                                 62.50%
                                                                    1.00e-04
                                                 84.38%
                     3.28
                             0.5509
                                                                   1.00e-04
                             0.3990
                                                                    1.00e-04
                     4.24
                                                 81.25%
                     5.23
                             0.3082
                                        0.2285
                                                  93.75%
                                                             90.00% | 1.00e-04 |
                             0.2100
                                                                    1.00e-04
                     6.86
                                                 96.88%
                    7.93
                             0.2087
                                                 90.63%
                                                                   1.00e-04
             8 |
                     9.08
                             0.1065
                                                100.00%
                                                                    1.00e-04 |
             9 |
                    10.11
                             0.1262
                                                 96.88%
                                                                    1.00e-04
```



mini batch size : 32 cross validation : 4

validation split ; 0.75 , 0.25

=	=======	======		======			=======================================	=
	Epoch	Iteration	Time Elaps	ed Mini-b	atch Valid	dation Min	ni-batch Validation Base Learning	
		(sec	conds)	Loss	Loss	Accuracy	Accuracy Rate	
=	=======	======		======		======		=
	1	1	1.08	0.7959	0.6687	43.75%	57.89% 1.00e-04	
	1	2	4.63	0.7294		56.25%	1.00e-04	
	1	3	5.63	0.5745		71.88%	1.00e-04	
	2	4	6.63	0.3609	0.2693	90.63%	94.74% 1.00e-04	
	2	5	8.26	0.2540		96.88%	1.00e-04	
	2	6	9.16	0.2788		90.63%	1.00e-04	
	3	7	10.09	0.1105		96.88%	1.00e-04	
	3	8	11.13	0.1820	0.1063	90.63%	94.74% 1.00e-04	
	3	9	12.62	0.2245		87.50%	1.00e-04	
=	======	======		======		======		=





Applied_Mathematics_Capstone_Design

- -Matlab : 응용수학캡스톤디자인 전공수업 (Alexnet , Googlenet) : cats vs dogs binary classification
 - CNN(Convolutional Neural Network) 사용

<프로젝트 진행 과정>

- (1) Python 으로 직접 모델링 (Contests 폴더 kaggle_cats_dogs 참조)
- (2) image augmentation , training image wavelet transform 하였으나 accuracy 가 평균 65%
- DWT_RGB.m : discrete wavelet transform code
- training set의 부족임을 알게되어 googlenet, alexnet 적용,
- At least, Matlab r2017b version, Using Computer Vision System Toolbox, Image Processing Toolbox, Neural Network Toolbox. Parallel Computing Toolbox, Statistics and Machine Learning Toolbox
- (3) Alexnet accuracy: cats: 87.04%, dogs: 83.33%, validation set: cats(77 images), dogs(77 images)
- accuracy: cats: 92.68%, dogs: 89.02%, validation set: cats(976 images), dogs(976 images)
- (4) Googlenet (I recommend using GPU better than CPU, because of time spending.)
- accuracy: 93.33%, validation set: cats(77 images), dogs(77 images) -cross validation: 5, minibatch size: 32, validation: 0.2
- accuracy: 93.48%, validation set: cats(77 images), dogs(77 images) -cross validation: 3, minibatch size: 10, validation: 0.3
- accuracy: 94.74%, validation set: cats(77 images), dogs(77 images) -cross validation: 4, minibatch size: 32, validation: 0.25
- mini batch size : 64 -> GPU out of memory
- accuracy: 76.09%, DWT(Discrete Wavelet Transform) validation set: cats(77 images), dogs(77 images)



RESULT

- (1) Python 과 Matlab 의 사용을 통한 Deep Learning 에서 알고리즘의 한 종류인 CNN 직접 모델링.
- (2) 검증된 알고리즘인 Alex net, Google net 을 이용한 적용.
- <추가적인 진행 방향>
- Google net 의 내부 알고리즘 구조를 완벽히 이해 한 후, binary classification 뿐만 아니라, 실생활에 더욱더
- 밀접한 문제 해결 능력 향상.
- < Github portfolio URL (MATLAB, PYTHON related code) >
- https://github.com/choiwb



참고문헌

- Batch Normalization: Accelerating Deep Network Training by

Reducing Internal Covariate Shift: ICML 2015

https://pdfs.semanticscholar.org/clba/ed4le4bc940lblb2ec8ef55ba45543f7ala3.pdf

- Classifying cats and dogs from images using deep learning

: university of Alberta

https://github.com/shrobon/Classifying-Dogs-and-Cats-using-CNN/blob/master/MM803_Project_Reportf.pdf

- https://www.slideshare.net/ssuser06e0c5/normalization-72539464



- Google net

https://www.cs.unc.edu/~wliu/papers/GoogLeNet.pdf

- Alex net

https://www.nvidia.cn/content/tesla/pdf/machine-learning/imagenet-classification-with-deep-convolutional-nn.pdf

- Discrete Fourier Transform

http://web.csulb.edu/~jchang9/m521/m695_sp10_FinalReport_Minh_Angela.pdf

