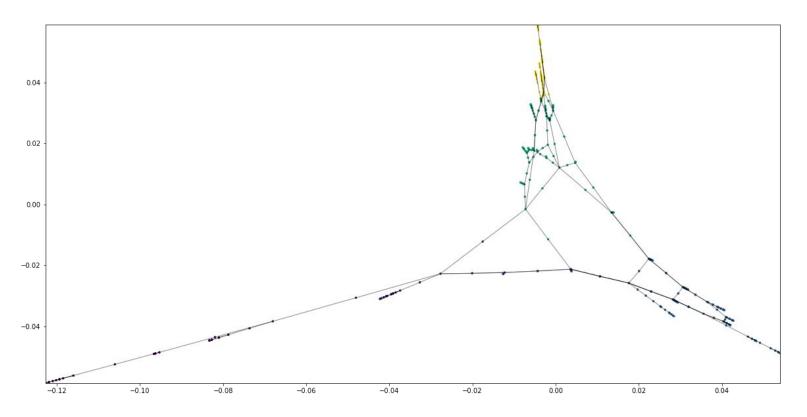
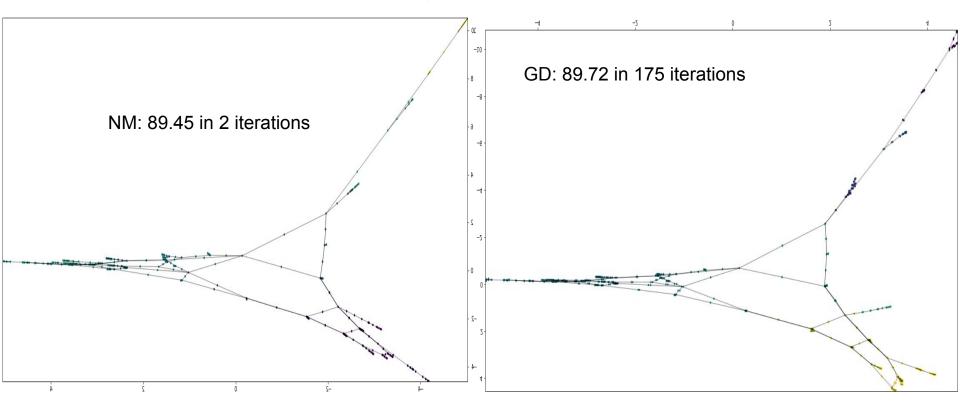
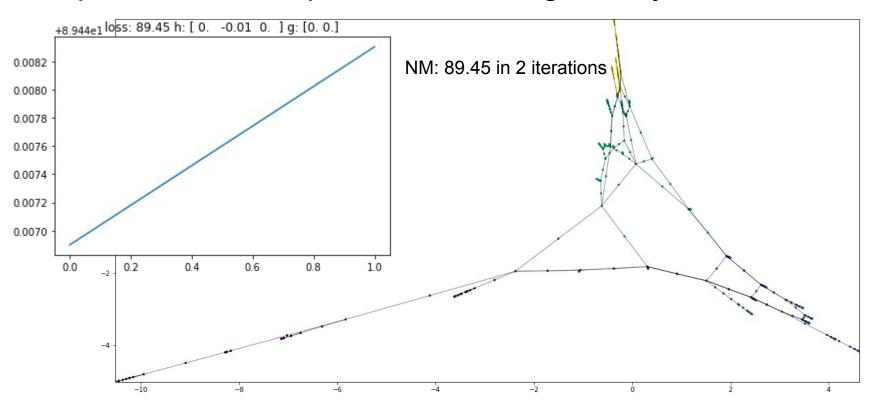
V1 v2 initialization



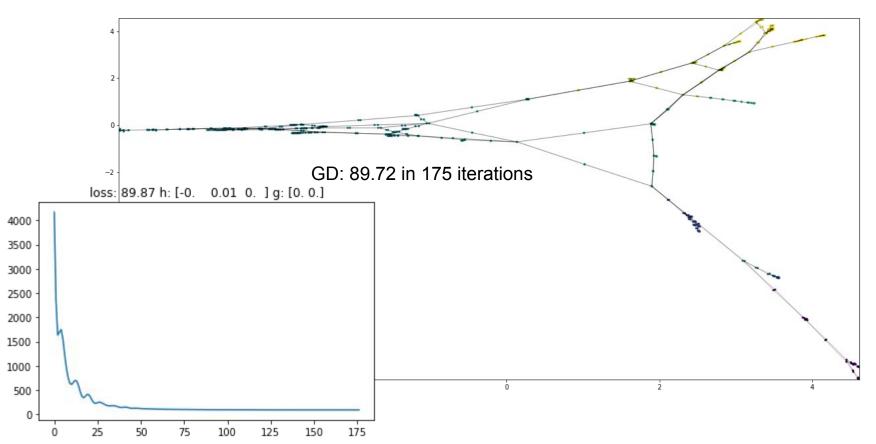
Top level placement, using x=v1 y=v2 as initial



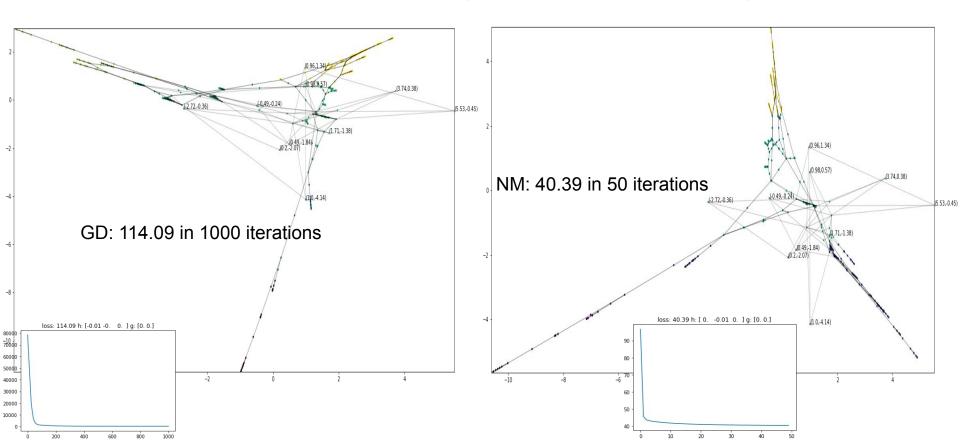
Top level Newton placement, using x=v1 y=v2 as initial



Top level gradient placement, using x=v1 y=v2 as initial

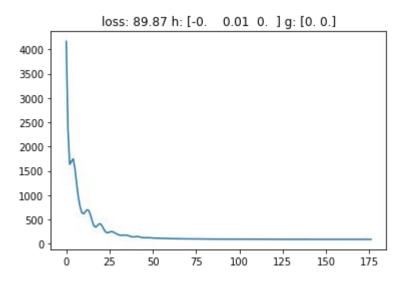


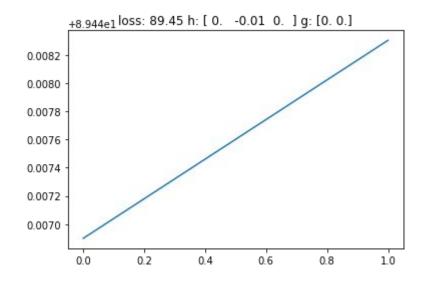
Placement with fixed nodes (+linear constraints)



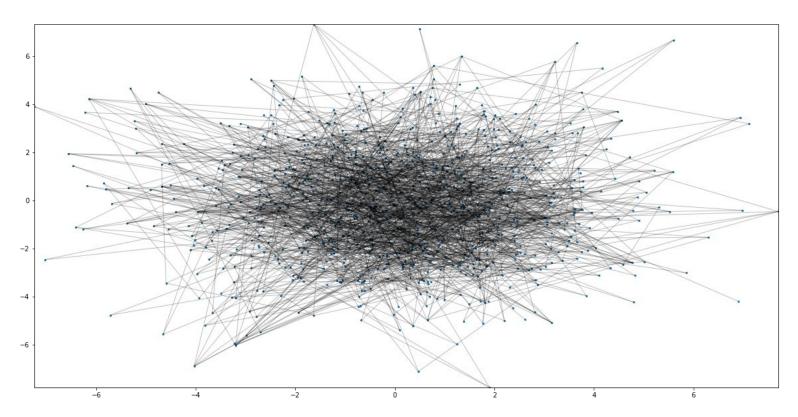
Convergence of Gradient & Newton Descent under v1, v2 initialization

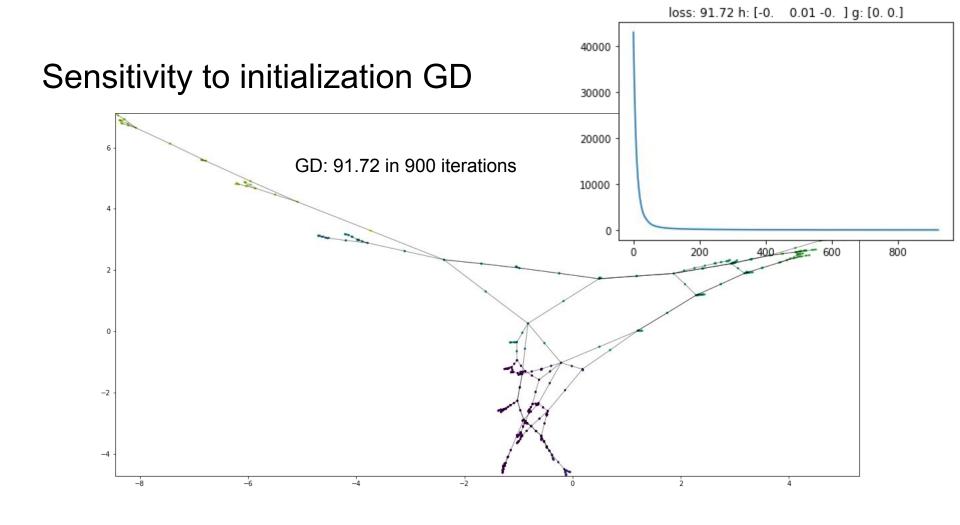
iterations to delta cost <= 1e-3

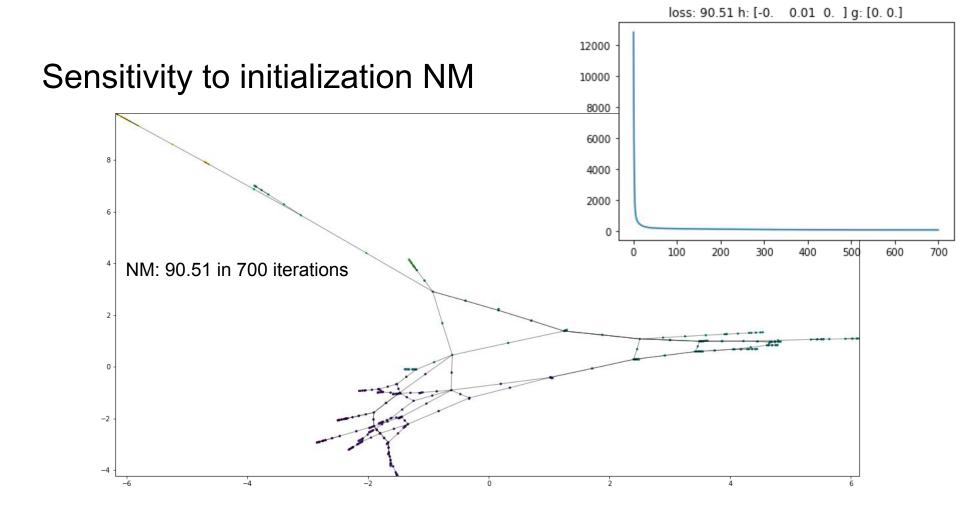




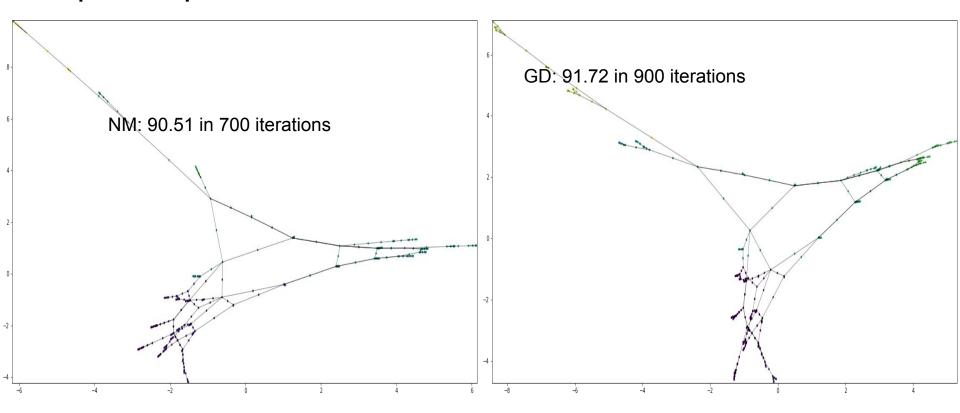
Random initialization







Top level placement



Initial Descent Directions (top) & Step Size (bottom) of Newton Method

