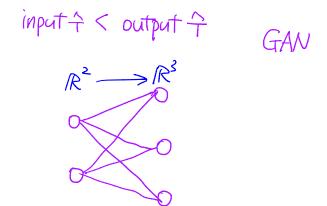
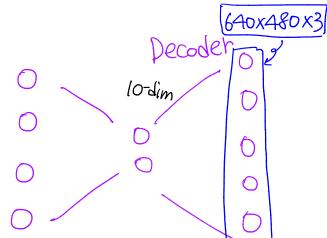
## Linear Algebra



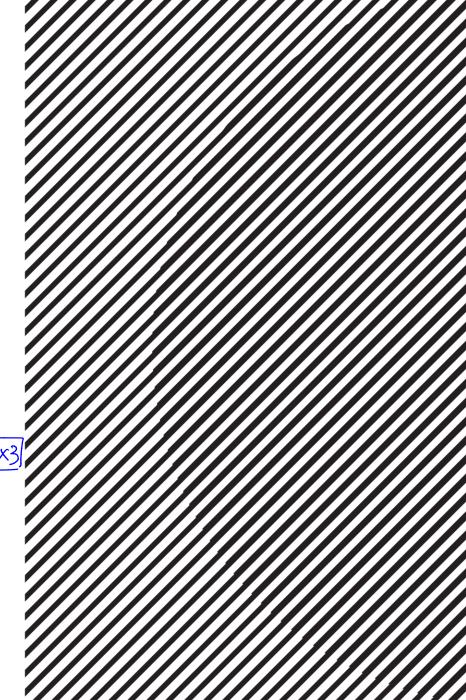
주재걸 고려대학교 컴퓨터학과

onto \$1





manifold

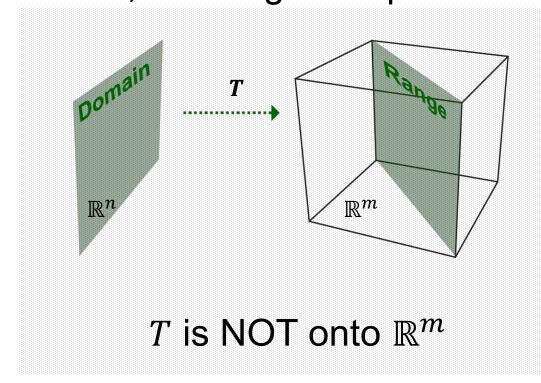


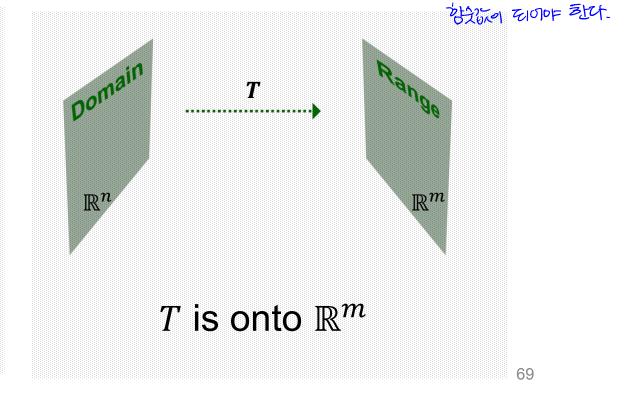




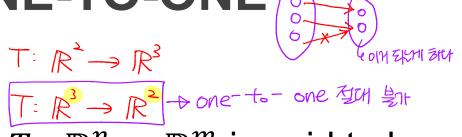
र्विष्टिः भाहि र्विष्टिं। मिन् विष्टिं। मिन् विष्टिं। भाहि रिविष्टे। मिन्

• **Definition:** A mapping  $T: \mathbb{R}^n \to \mathbb{R}^m$  is said to be onto  $\mathbb{R}^m$  if each  $\mathbf{b} \in \mathbb{R}^m$  is the image of at least one  $\mathbf{x} \in \mathbb{R}^n$ .





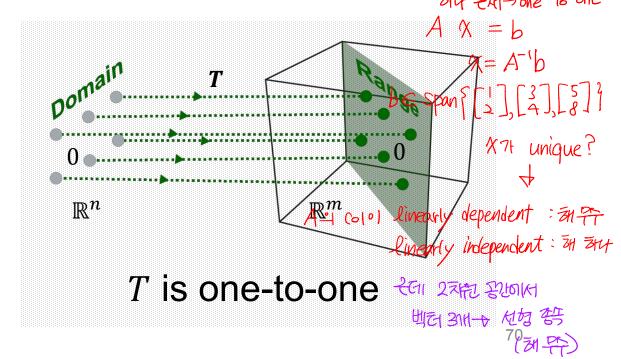




 $T(\begin{bmatrix} 0 \\ 0 \end{bmatrix}) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$   $T(\begin{bmatrix} 0 \\ 0 \end{bmatrix}) = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$   $T(\begin{bmatrix} 0 \\ 0 \end{bmatrix}) = \begin{bmatrix} 5 \\ 8 \end{bmatrix}$   $T: y = Ax = \begin{bmatrix} 1 & 3 & 5 \\ 2 & 4 & 8 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ 

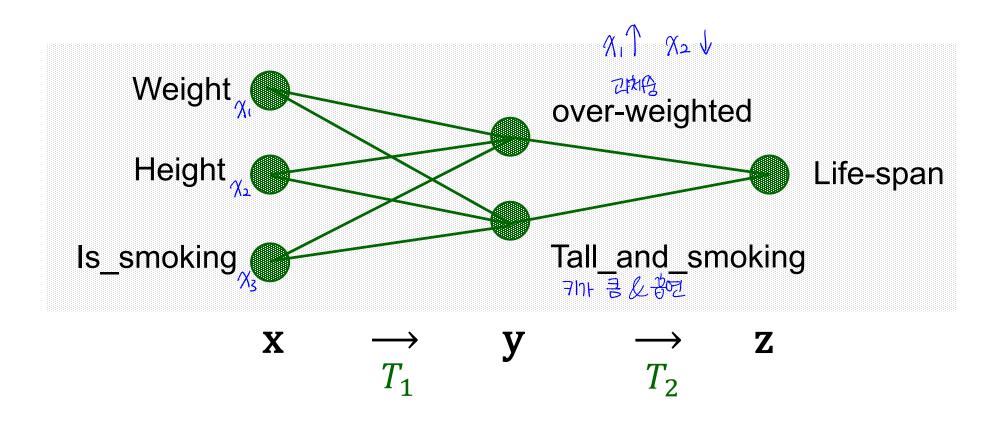
• **Definition:** A mapping  $T: \mathbb{R}^n \to \mathbb{R}^m$  is said to be **one-to-one** if each  $b \in \mathbb{R}^m$  is the image of at most one  $x \in \mathbb{R}^n$ . That is, each output vector in the range is mapped by only one input vector, no more than that.

T is NOT one-to-one



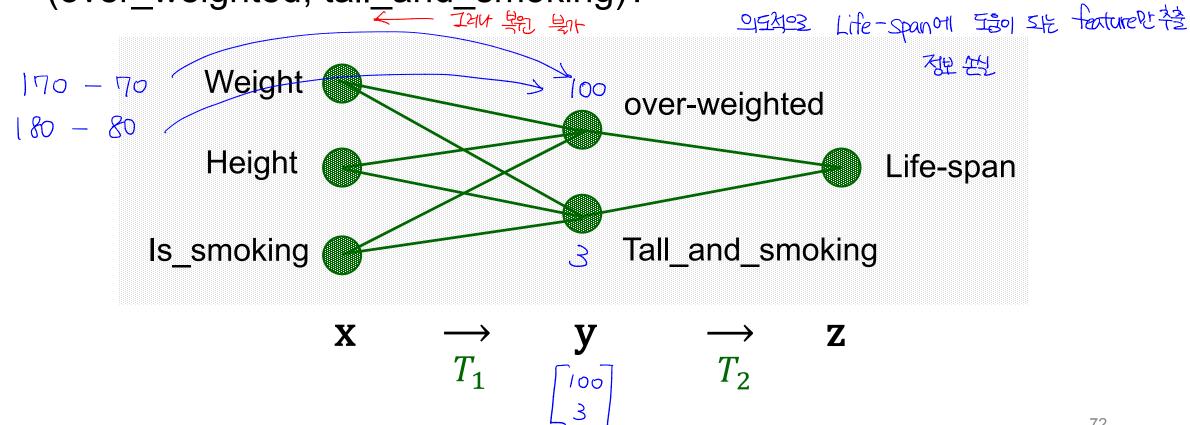
## **Neural Network Example**

Fully-connected layers



## **Neural Network Example: ONE-TO-ONE**

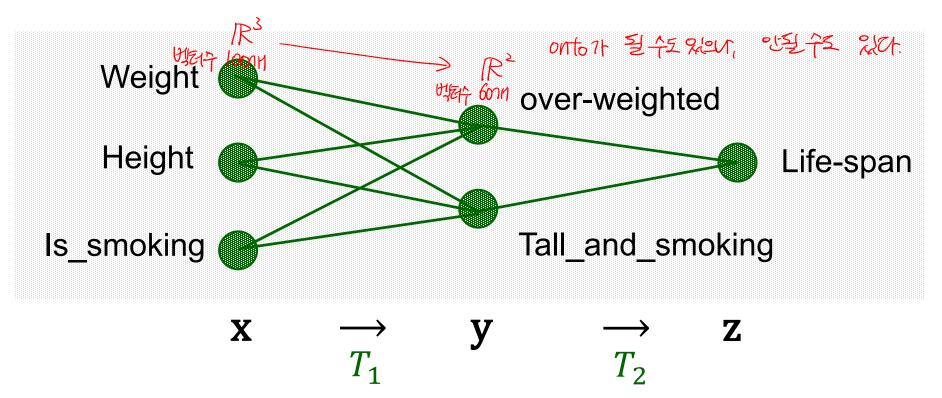
 Will there be many (or unique) people mapped to the same (over\_weighted, tall\_and\_smoking)?





## **Neural Network Example: ONTO**

• Is there any (over\_weighted, tall\_and\_smoking) that () (2) (2) (3) (3) does not exist at all?



老地

### **ONTO and ONE-TO-ONE**

• Let  $T: \mathbb{R}^n \to \mathbb{R}^m$  be a linear transformation, i.e.,

$$T(\mathbf{x}) = A\mathbf{x}$$
 for all  $\mathbf{x} \in \mathbb{R}^n$ .

# T is one-to-one if and only if the columns of A are linearly independent.

• T maps  $\mathbb{R}^n$  onto  $\mathbb{R}^m$  if and only if the columns of A span  $\mathbb{R}^m$ .



## **ONTO and ONE-TO-ONE**

Example:

Let 
$$T(\mathbf{x}) = A\mathbf{x} = \begin{bmatrix} 2 & 0 \\ -1 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

- Is *T* one-to-one?
- Does T map  $\mathbb{R}^2$  onto  $\mathbb{R}^3$ ?



## **ONTO and ONE-TO-ONE**

Example:

Let 
$$T(\mathbf{x}) = A\mathbf{x} = \begin{bmatrix} 1 & 4 & 5 \\ 2 & 3 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

- Is T one-to-one?
- Does T map  $\mathbb{R}^3$  onto  $\mathbb{R}^2$ ?

# **Further Study**

- Gaussian elimination, row reduction, echelon form
  - Lay Ch1.2,

- LU factorization: efficiently solving linear systems
  - Lay Ch2.5
- Computing invertible matrices
  - Lay Ch2.2

- Invertible matrix theorem for square matrices
  - Lay Ch2.3, Ch2.9