



UNIVERSITY<sup>AT</sup>ALBANY  
STATE UNIVERSITY OF NEW YORK

CSI 401 (Fall 2025)

# Numerical Methods

Lecture 1: Course Introduction & Numerical Errors

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# About myself



- Education:
  - PhD in Computer Science, UC Santa Barbara, 2018-2023
  - Data Science Institute Postdoc, University of Chicago, 2023-2024
- Research areas:
  - Machine Learning: Bayesian optimization, bandits, generative models
  - AI for Drug Discovery: experimental design, drug screening, binding affinity prediction
- Past courses:
  - CSI 436/536 Machine Learning (Fall 2024, Spring 2025)
- Contact:
  - Homepage: <https://chong-l.github.io/>
  - Email: cliu24@albany.edu

# Meet your TA!

- Charles DeGennaro
  - CS PhD student at UAlbany
  - [cdegennaro@albany.edu](mailto:cdegennaro@albany.edu)



# Agenda

- Course Information
- Self-evaluation
  - Don't worry – it doesn't count towards your final grades!
  - For me to get to know your math backgrounds
- Why numerical methods?
- First technical part: Numerical errors

# Course information

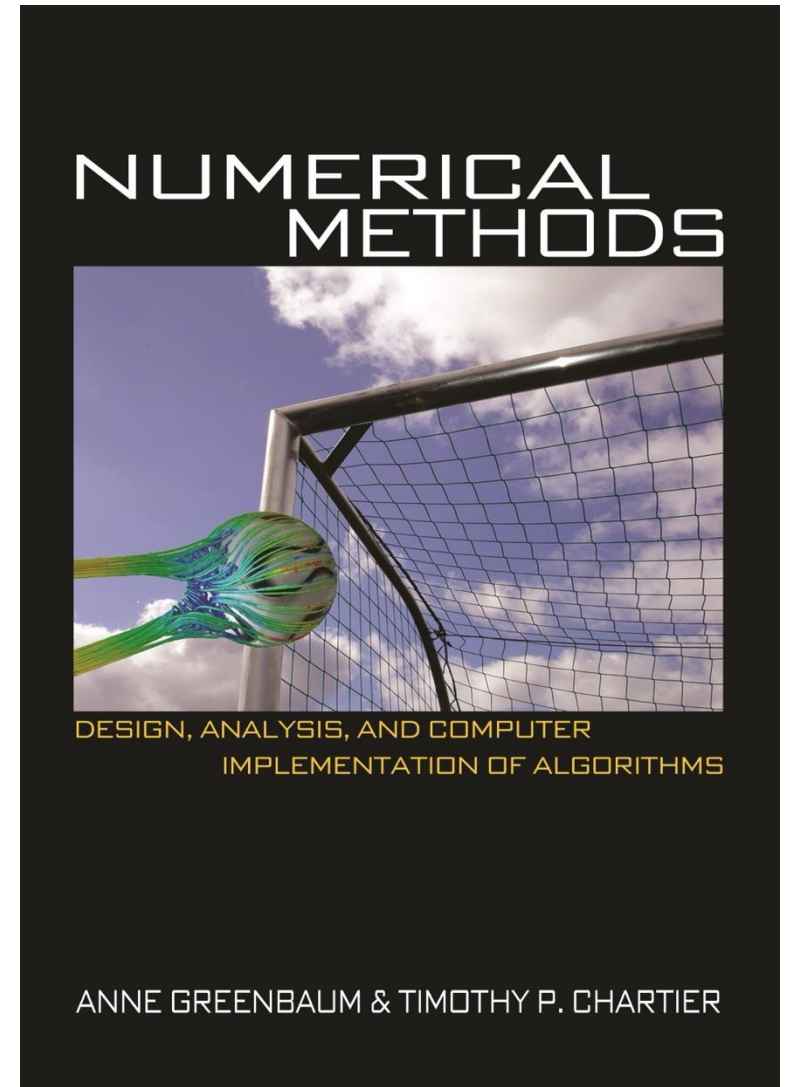
- Class webpages:
  - Syllabus: [https://chong-l.github.io/CSI\\_401\\_25F.html](https://chong-l.github.io/CSI_401_25F.html)
    - Your primary information source of this course, updated **regularly**
    - Lecture slides, deadlines
  - Brightspace
    - Posting grades, discussion
  - Gradescope
    - Homework assignments/submissions, course projects/report submissions
    - <https://www.gradescope.com/courses/1093542>
    - Use **7XJ4N5** to enroll ASAP using your albany.edu email
- Office hours (starting next week):
  - Instructor: Monday 3-4pm at UAB 426
  - TA: Wednesday 1:30-2:30pm at UAB 412E

# Course information - Requirements

- Data structure, linear algebra
- Programming:
  - Python
    - A very nice tutorial:  
<https://colab.research.google.com/github/cs231n/cs231n.github.io/blob/master/python-colab.ipynb>
  - Matlab
    - Official tutorials: <https://www.mathworks.com/support/learn-with-matlab-tutorials.html>
- Document editing:
  - LaTeX
    - A Tutorial by Overleaf:  
[https://www.overleaf.com/learn/latex/Learn\\_LaTeX\\_in\\_30\\_minutes](https://www.overleaf.com/learn/latex/Learn_LaTeX_in_30_minutes)
- We will review Python/Matlab/LaTeX on Sep 8 (Week 3)!

# Course information

- Reference book
  - Numerical Methods: Design, Analysis, and Computer Implementation of Algorithms
    - Anne Greenbaum and Timothy P. Chartier.
    - Princeton University Press, 2012.
  - Just for your reference. Lecture slides are your best source!



# Course information

- Scale

- A: 95-100 points
- A-: 90-94 points
- B+: 85-89 points
- B: 80-84 points
- B-: 75-79 points
- C+: 70-74 points
- C: 65-69 points
- C-: 60-64 points
- D+: 55-59 points
- D: 50-54 points
- E: 0-50 points

- Grading:

- Homework: 24%
- Course project: 21%
- Midterm exam: 20%
- Final exam: 30%
- Participation: 5%
- I reserve the right to curve up the points.



# Course information

- Study group
  - All homework assignments and course project are completed **in groups**.
  - A group consists of **3-5** students.
  - All students in the same group receive the same credits.

# Course information

- Group homework (24%)
  - 4 homework assignments, each 6%
  - No handwritten homework: LaTeX -> PDF submissions
  - Due at 11:59 pm (midnight) in Eastern Time on due dates
  - Late homework **within** 24 hr period receives **half** credits
  - Late homework **beyond** 24 hr period receives **0** credits

# Course information

- Group course project (21%)
  - Each group chooses to work on one project from project list
    - Group may work on a project beyond the list, subject to my approval.
  - Outcomes:
    - Midterm presentation practice (0%)
    - Midterm project one-pager (2%)
    - Final presentation (15%)
    - Final project report (4%)
    - Submit project code (0%)
      - **Lose all 21 credits** if your code is copied from somewhere or doesn't work!
  - Due at 11:59 pm Eastern Time on the due date, no late submission

# Group course project list

- Has been released on Gradescope!
- Data Compression via Singular Value Decomposition (SVD)
- Data Fitting Kaggle Competition
- Nonlinear System Solvers
- Function Optimization
- PDEs in Engineering Applications

# Course information

- Exams (50%)
  - Midterm exam (20%) – all topics before midterm exam
  - Final exam (30%) – all topics throughout this semester
  - Given **individually**
  - Tip: Try to understand all solutions to your homework!

# Course information

- Participation (5%)
  - How to earn?
    - Starting Week 4, ask questions in class or voluntarily show/explain your solutions to in-class exercise problems.
    - Register your name to me after each class meeting.
    - Up to 3 points can be given to each student.
  - 2 points are reserved for all students if the percent of submitted course evaluation goes above 60%.

# Course information

- A few remarks:
  - Some topics might be **very technical**, but the lectures will be self-contained.
  - Attending the lectures is required as we have many helpful in-class exercise questions that we will work together!
  - Do homework on time. Never hesitate to answer questions!

# Why learn Numerical Methods?

- Motivated by
  - most real-world problems in science, engineering, and data science **cannot** be solved exactly using **closed-form solutions**.
  - For example,
    - Many equations, such as nonlinear systems, high-dimensional integrals, and differential equations, either lack analytical solutions or are too complex to solve by hand.
- Advantages:
  - Providing systematic algorithms to approximate these solutions with controllable accuracy and efficiency
  - Bridging the gap between mathematical theory and computer implementation
  - Enabling the simulation and prediction of complex problems—such as climate modeling, structural design, or machine learning
  - Ensuring stability, convergence, and error control!



# Topics of Numerical Methods covered

- Source of numerical errors
- Asymptotic notations and floating point arithmetic
- Review:
  - Linear algebra, Python, Matlab, LaTeX
- Linear systems:
  - Direct linear equations solvers
  - Eigenvalues and eigenvectors
  - Iterative linear equations solvers
  - Conditioning of linear equations
- Numerical interpolation
  - Data fitting and regression problems
- Nonlinear equations solvers
- Optimization methods
- Numerical integration and differentiation

# Expected outcomes

- Understanding the foundation, major techniques, applications, and challenges of numerical methods
- The ability to apply numerical methods for solving real-world problems
- Familiarize the tools for more in-depth computer science / data science / engineering studies
- You will **not** be:
  - An expert in numerical methods - **yet**
  - Knowing all the subareas of numerical methods - **yet**

# Self-evaluation (0% towards grades)

- Q1. Given  $A = \begin{bmatrix} 2 & 7 & 3 \\ 1 & 0 & 9 \\ -1 & 2 & 10 \end{bmatrix}$ ,  $B = \begin{bmatrix} -2 & 0 & 3 \\ 2 & -1 & 7 \\ 6 & 4 & -3 \end{bmatrix}$ . Is  $AB = BA$ ?
- Q2. Given the function  $f(x, y) = e^{x+y} + e^{3xy} + e^{y^4}$ , find the partial derivatives  $\frac{\partial f}{\partial x}$  and  $\frac{\partial f}{\partial y}$ .

# Solutions to self-evaluation

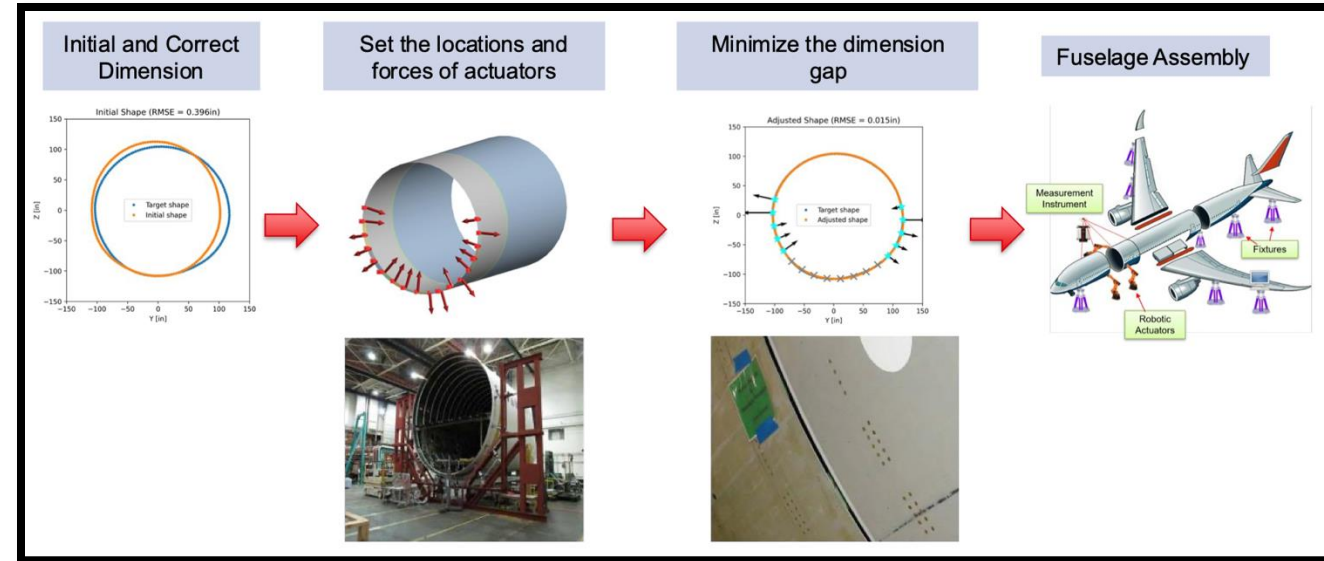
- A1.
- $AB \neq BA$  since  $(AB)_{11} = 2 * (-2) + 7 * 2 + 3 * 6 = 28$ ,  $(BA)_{11} = (-2) * 2 + 0 + 3 * (-1) = -7$ .
- A2.
- $\frac{\partial f}{\partial x} = e^{x+y} + 3ye^{3xy}$ ,  $\frac{\partial f}{\partial y} = e^{x+y} + 3xe^{3xy} + 4y^3e^{y^4}$ .

# This course heavily uses mathematics

- Points:
  - 2 points: you are ready for this course!
  - 0-1 points: we will have review sessions in Week 3, but you need to catch all technical details.
- Why math is so important in numerical methods?
  - This is the only language that we talk with data and computers
    - define a root finding problem == define a math problem
    - Solving high-dimensional problems == applying linear algebra
    - ...
  - This course aims at helping you **understand** numerical methods, rather than teach you to use tools

# Sources of numerical errors

- Data are always noisy
  - Discussion: Any example in your mind?
  - Aircraft fuselage design
- Computers can only handle discrete data
  - Think about data structure: string, array, tree, ...
- No measuring device is perfect
  - Discussion: Any example in your mind?
  - Exact rainfall of Albany, NY in July 2025? No way!



# Types of errors

- Discretization error: we can only deal with values of a function at finitely many points. For example, a very simple way to do numerical differentiation for a function  $f$  is to use a finite difference formula:

$$\hat{f}(x) = \frac{f(x+h) - f(x)}{h}. \quad (2.1)$$

Here, the parameter  $h$  is some small number. It cannot be 0, so this introduces discretization error. Recall that the definition of the derivative of a function at a point  $x$  is

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}. \quad (2.2)$$

Later in the course, we'll consider better methods than this.

- Convergence error: in which we, say, truncate a power series expansion, stop an iterative algorithm after finitely many iterations, etc.
- Rounding error: This arises because computers have only finite precision. We can only store a finite amount of data in any given machine. Interestingly, in numerical differentiation, there is a tradeoff between discretization error and rounding error (since we cannot make  $h$  infinitely small), and this leads to some optimal choice of  $h$ ! So multiple types of error can play an important role simultaneously in some problems.

# Example of error tolerance



**Example 2.1** (Figuring out error tolerance from a problem specification). *Suppose that we are observing an asteroid and would like to know whether or not it will collide with Earth. We can boil this down to numerically solving a differential equation for  $X(t)$ , the position of the asteroid at time  $t$  with respect to the center of the Earth (it is a three-dimensional vector of real numbers, measured in kilometers). The radius of Earth is approximately 6378.1km, so if we use a numerical method to solve the differential equation and find that the asteroid will at time  $t$  be in position*

$$X(t) = \begin{pmatrix} 6380 \\ 0 \\ 0 \end{pmatrix}, \quad (2.3)$$

*then we only know for certain that it will not collide with Earth at time  $t$  if we can guarantee that the amount of numerical error is small enough so that  $X(t) + \text{error}$  is not within the ball of radius 6378.1 km.*



# How do we measure error?

- Unknown true number is  $u$
- We are approximating  $u$  using our number  $v$
- Discussion: how can we measure error?

# One way is to take the absolute difference

- Definition of **absolute error**:
- $|u - v|$
- It's so simple, but it has some problems:
  - Suppose we try to figure out how much air passes through a Boeing 737 engine per minute during the flight.
  - The true answer is 120,000 pounds.
  - Your solution shows 119,000 pounds, so absolute error is 1,000 pounds.
  - Discussion: You missed 1,000 pounds? Are you doing a good job?



# Another way to measure error

- Definition of relative error:
- $\left| \frac{u-v}{u} \right|$ 
  - note  $u$  is the true number
- Discussion: What's the relative error in previous example?
  - Suppose we try to figure out how much air passes through a Boeing 737 engine per minute during the flight.
  - The true answer is 120,000 pounds.
  - Your solution shows 119,000 pounds.