

Lecture 34: Distance Matrices, Procrustes Problem

Triangle inequality

Suppose 11x,-x2112=1 11x2-x3112=1 11x,-x3112=6

 $D = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 6 \\ 1 & 60 \end{bmatrix}$   $X^{T}X = G = positive semidefinite$   $G_{ij} = (x_{ij} \times x_{j})$ 

Gnelusion: G will not come out positive semidefinite if triangle inequality fails.

Procrustes problem - optimal rotation from basis to basis 2

 $\min_{Q^TQ=I} \left\| YQ - X \right\|_F^2$ 

Facts:

(i) Frobenius  $\|A\|_F^2 = \frac{a_1^2 + a_2^2 + \dots + a_m^2}{4 a_m^2 + \dots + a_m^2} = \text{trace of } A^TA = \begin{bmatrix} A \end{bmatrix}^T \begin{bmatrix} A \end{bmatrix}$ 

(ii) 
$$\|QA\|_F^2 = \|A\|_F^2$$

because  $\|QV\|^2 = \|V\|^2$ 
 $\Rightarrow columns of A$ 

Singular values unchanged by  $Q$ 

(iii) trace  $(A^TB) = \text{trace } (B^TA) = \text{trace } cf (BA^T)$ 

with the operate of each others

sums down the degenal does

ref change

trace  $(CD) = \text{trace } (DC)$ 

Same nonzero experialnes

Back to min  $\|YQ - X\|_F^2$ 
 $QTD = I$ 

part 18 in notes