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RNN 기초

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[1]

```
1 import numpy as np
2 import tensorflow as tf
3 from tensorflow import keras
4 from tensorflow.keras import layers
```

[2]

```
1 train_X = [[1,2,3,4,5],
2            [2,4,6,8,10],
3            [1,3,5,7,9],
4            [0,2,4,6,8]]
5 print(np.shape(train_X))
```

```
(4, 5)
```

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[3]

```
1 train_X = np.array(train_X, dtype=np.float32)
2 print(train_X.shape)
```

```
(4, 5)
```

RNN의 경우 2차원이 아닌 3차원 tensor로 값을 입력받기 때문에 3차원으로 변환해준다

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[4]

```
1 train_X = np.array([train_X], dtype=np.float32)
2 print(train_X.shape)
```

```
(1, 4, 5)
```

RNN에서 중요한 파라미터인 return\_sequences와 return\_state에 대해 알아보자

- 두 파라미터의 default 값은 False이다

1) return\_sequence = False 일때는 마지막 시점의 hidden state만 출력됨

[5]

```
1 # 우선 hidden_size는 임의로 3으로 정한다.
2 hidden_size = 3 # hidden state 차원수
3 cell = layers.SimpleRNNCell(units = hidden_size)
4 rnn = layers.RNN(cell, return_sequences=True, return_state=False)
5 hidden_state = rnn(train_X)
6
7 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
8 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
9 # tensor (1,3) 출력
10 # 마지막 시점의 hidden state이다.
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]]      shape : (1, 4, 5)
hidden_state : [[0.9416828  0.9945396  0.28762573]
 [0.99016666 0.99995726 0.9173503 ]
 [0.9287556  0.9996489  0.6515412 ]
 [0.87805897 0.99850094 0.39047372]]]      shape : (1, 4, 3)
```



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return\_sequence = True라면?

- 모든 시점의 hidden state가 출력됨

```
[6] 1 cell = layers.SimpleRNNCell(units = hidden_size)
2 rnn = layers.RNN(cell, return_sequences=True, return_state=False)
3 hidden_state = rnn(train_X)
4
5 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
6 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
7 # tensor (1,4,3) 출력
8 # 입력(x_data)의 크기는 (1,4,5)였고, 모든 시점의 hidden state값을 출력하기 때문에 (1,4,3)가 됨 (시점을 의미하는 값 4)
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]] shape : (1, 4, 5)
hidden_state : [[[ -0.9994465  -0.9996233  -0.37031716]
 [-1.          -1.          -0.90804714]
 [-1.          -1.          -0.8969634 ]
 [-0.99999756 -0.9999984  -0.84814155]]] shape : (1, 4, 3)
```

return\_state = True라면?

- return\_sequence의 값이 True/False인지 관계없이 마지막 시점의 은닉상태를 출력

```
[7] 1 cell = layers.SimpleRNNCell(units = hidden_size)
2 rnn = layers.RNN(cell, return_sequences=True, return_state=True)
3 hidden_state, last_state = rnn(train_X)
4
5 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
6 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
7 print('last_state : {} \t shape : {}'.format(last_state, last_state.shape))
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]] shape : (1, 4, 5)
hidden_state : [[[ -0.99792796 -0.95558643 -0.9975007 ]
 [-1.          -0.993731  -0.99999946]
 [-0.99999946 -0.9938855  -0.9999858 ]
 [-0.9999985  -0.9938856  -0.9996284 ]]] shape : (1, 4, 3)
last_state : [[ -0.9999985  -0.9938856  -0.9996284 ]] shape : (1, 3)
```

return\_sequence = False인데 return\_state = True인 경우는?

- 마지막 시점의 hidden state 출력

```
1 cell = layers.SimpleRNNCell(units = hidden_size)
2 rnn = layers.RNN(cell, return_sequences=False, return_state=True)
3 hidden_state, last_state = rnn(train_X)
4
5 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
6 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
7 print('last_state : {} \t shape : {}'.format(last_state, last_state.shape))
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]] shape : (1, 4, 5)
hidden_state : [[ 0.9999937 -0.9999158  0.9999802]] shape : (1, 3)
last_state : [[ 0.9999937 -0.9999158  0.9999802]] shape : (1, 3)
```



# 🔍 LSTM

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RNN에서 중요한 파라미터인 return\_sequences와 return\_state에 대해 알아본것 처럼 LSTM의 경우에도 한번 확인해보자

- 두 파라미터의 default 값은 False이다

- return\_sequences=False, return\_state=True 인경우

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```
[9] 1 from keras.layers import LSTM
    2
    3 # 우선 hidden_size는 임의로 3으로 정한다.
    4 hidden_size = 3 # hidden state 차원수
    5 lstm = LSTM(units=hidden_size, return_sequences=False, return_state=True)
    6 hidden_state, last_state, last_cell_state = lstm(train_X)
    7
    8 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
    9 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
   10 print('last_state : {} \t shape : {}'.format(last_state, last_state.shape))
   11 print('last_cell_state : {} \t shape : {}'.format(last_cell_state, last_cell_state.shape))
   12 # return_sequence가 False일때는 마지막 hidden_state가 출력되므로 hidden_state = last_cell_state의 결과값이 같다
   13 # RNN과 LSTM의 차이점은 LSTM의 경우 return_state = True인 경우 last_cell_state까지 출력해준다는 것이 다르다
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]]      shape : (1, 4, 5)
hidden_state : [[ 0.20272215 -0.0699851 -0.5315128 ]]      shape : (1, 3)
last_state : [[ 0.20272215 -0.0699851 -0.5315128 ]]      shape : (1, 3)
last_cell_state : [[ 3.3949492 -1.0960821 -0.9628552]]      shape : (1, 3)
```

- return\_sequences=True, return\_state=True 인경우

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```
[10] 1 # 우선 hidden_size는 임의로 3으로 정한다.
    2 hidden_size = 3 # hidden state 차원수
    3 lstm = LSTM(units=hidden_size, return_sequences=True, return_state=True)
    4 hidden_state, last_state, last_cell_state = lstm(train_X)
    5
    6 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
    7 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
    8 print('last_state : {} \t shape : {}'.format(last_state, last_state.shape))
    9 print('last_cell_state : {} \t shape : {}'.format(last_cell_state, last_cell_state.shape))
   10 # return_sequence가 True인 경우 모든 hidden_state값이 출력되므로 4개 값에대한 hidden_state가 모두 출력되었다.
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]]      shape : (1, 4, 5)
hidden_state : [[[-9.0078515e-04 -5.3682184e-01  1.3619630e-01]
 [-1.8837634e-05 -8.1220323e-01  3.7216518e-02]
 [-3.3685516e-05 -7.8859210e-01  4.6560906e-02]
 [-1.3770610e-04 -7.3374641e-01  5.8478165e-02]]]      shape : (1, 4, 3)
last_state : [[-1.3770610e-04 -7.3374641e-01  5.8478165e-02]]      shape : (1, 3)
last_cell_state : [[-0.00638166 -2.6925592  1.0004491 ]]      shape : (1, 3)
```



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```
[12] 1 gru = GRU(units=hidden_size, return_sequences=True, return_state=True)
      2 hidden_state, last_state, last_cell_state = lstm(train_X)
      3
      4 print('train_X : {} \t shape : {}'.format(train_X, train_X.shape))
      5 print('hidden_state : {} \t shape : {}'.format(hidden_state, hidden_state.shape))
      6 print('last_state : {} \t shape : {}'.format(last_state, last_state.shape))
      7 print('last_cell_state : {} \t shape : {}'.format(last_cell_state, last_cell_state.shape))
```

```
train_X : [[[ 1.  2.  3.  4.  5.]
 [ 2.  4.  6.  8. 10.]
 [ 1.  3.  5.  7.  9.]
 [ 0.  2.  4.  6.  8.]]] shape : (1, 4, 5)
hidden_state : [[[-9.0078515e-04 -5.3682184e-01  1.3619630e-01]
 [-1.8837634e-05 -8.1220323e-01  3.7216518e-02]
 [-3.3685516e-05 -7.8859210e-01  4.6560906e-02]
 [-1.3770610e-04 -7.3374641e-01  5.8478165e-02]]] shape : (1, 4, 3)
last_state : [[-1.3770610e-04 -7.3374641e-01  5.8478165e-02]] shape : (1, 3)
last cell state : [[-0.00638166 -2.6925592  1.0004491 ]] shape : (1, 3)
```