

1.1 A First Problem: Stable Matching

Matching Residents to Hospitals

Goal. Given a set of preferences among hospitals and medical students, design a **self-reinforcing** admissions process.

Unstable pair: applicant x and hospital y are **unstable** if:

- x prefers y to its assigned hospital.
- y prefers x to one of its admitted students.

Stable assignment. Assignment with no unstable pairs.

- Natural and desirable condition.
- Individual self-interest will prevent any applicant/hospital deal from being made.

Stable Matching Problem

Goal. Given n men and n women, find a "suitable" matching.

- Participants rate members of opposite sex.
- Each man lists women in order of preference from best to worst.
- Each woman lists men in order of preference from best to worst.

	favorite ↓ 1 st	2 nd	least favorite ↓ 3 rd
Xavier	Amy	Bertha	Clare
Yancey	Bertha	Amy	Clare
Zeus	Amy	Bertha	Clare

Men's Preference Profile

	favorite ↓ 1 st	2 nd	least favorite ↓ 3 rd
Amy	Yancey	Xavier	Zeus
Bertha	Xavier	Yancey	Zeus
Clare	Xavier	Yancey	Zeus

Women's Preference Profile

Stable Matching Problem

Perfect matching: everyone is matched monogamously.

- Each man gets exactly one woman.
- Each woman gets exactly one man.

Stability: no incentive for some pair of participants to undermine assignment by joint action.

- In matching M , an unmatched pair m - w is **unstable** if man m and woman w prefer each other to their current partner.
- Unstable pair m - w could each improve by eloping.

Stable matching: perfect matching with no unstable pairs.

Stable matching problem. Given the preference lists of n men and n women, find a stable matching if one exists.

Stable Roommate Problem

Q. Do stable matchings always exist?

A. Not obvious a priori.

Stable roommate problem.

- $2n$ people; each person ranks others from 1 to $2n-1$.
- Assign roommate pairs so that no unstable pairs.

	1 st	2 nd	3 rd
Adam	B	C	D
Bob	C	A	D
Chris	A	B	D
Doofus	A	B	C

A-B, C-D \Rightarrow B-C unstable

A-C, B-D \Rightarrow A-B unstable

A-D, B-C \Rightarrow A-C unstable

Observation. Stable matchings do not always exist for stable roommate problem.

Propose-And-Reject Algorithm

Propose-and-reject algorithm. [Gale-Shapley 1962] Intuitive method that guarantees to find a stable matching.

```
Initialize each person to be free.
while (some man is free and hasn't proposed to every woman) {
    Choose such a man m
    w = 1st woman on m's list to whom m has not yet proposed
    if (w is free)
        assign m and w to be engaged
    else if (w prefers m to her fiancé m')
        assign m and w to be engaged, and m' to be free
    else
        w rejects m
}
```

Proof of Correctness: Termination

Observation 1. Men propose to women in decreasing order of preference.

Observation 2. Once a woman is matched, she never becomes unmatched; she only "trades up."

Claim. Algorithm terminates after at most n^2 iterations of while loop.

Pf. Each time through the while loop a man proposes to a new woman. There are only n^2 possible proposals. ■

	1 st	2 nd	3 rd	4 th	5 th
Victor	A	B	C	D	E
Wyatt	B	C	D	A	E
Xavier	C	D	A	B	E
Yancey	D	A	B	C	E
Zeus	A	B	C	D	E

	1 st	2 nd	3 rd	4 th	5 th
Amy	W	X	Y	Z	V
Bertha	X	Y	Z	V	W
Clare	Y	Z	V	W	X
Diane	Z	V	W	X	Y
Erika	V	W	X	Y	Z

$n(n-1) + 1$ proposals required

Proof of Correctness: Perfection

Claim. All men and women get matched.

Pf. (by contradiction)

- Suppose, for sake of contradiction, that Zeus is not matched upon termination of algorithm.
- Then some woman, say Amy, is not matched upon termination.
- By Observation 2, Amy was never proposed to.
- But, Zeus proposes to everyone, since he ends up unmatched. ▪

Proof of Correctness: Stability

Claim. No unstable pairs.

Pf. (by contradiction)

- Suppose $A-Z$ is an unstable pair: each prefers each other to partner in Gale-Shapley matching S^* .

- Case 1: Z never proposed to A .
 - $\Rightarrow Z$ prefers his GS partner to A .
 - $\Rightarrow A-Z$ is stable.

men propose in decreasing
order of preference

- Case 2: Z proposed to A .
 - $\Rightarrow A$ rejected Z (right away or later)
 - $\Rightarrow A$ prefers her GS partner to Z .
 - $\Rightarrow A-Z$ is stable.

← women only trade up

- In either case $A-Z$ is stable, a contradiction. ■

S^*

Amy-Yancey

Bertha-Zeus

...

Summary

Stable matching problem. Given n men and n women, and their preferences, find a stable matching if one exists.

Gale-Shapley algorithm. Guarantees to find a stable matching for **any** problem instance.

Q. How to implement GS algorithm efficiently?

Q. If there are multiple stable matchings, which one does GS find?

Efficient Implementation

Efficient implementation. We describe $O(n^2)$ time implementation.

Representing men and women.

- Assume men are named $1, \dots, n$.
- Assume women are named $1', \dots, n'$.

Engagements.

- Maintain a list of free men, e.g., in a queue.
- Maintain two arrays `wife[m]`, and `husband[w]`.
 - set entry to 0 if unmatched
 - if m matched to w then `wife[m]=w` and `husband[w]=m`

Men proposing.

- For each man, maintain a list of women, ordered by preference.
- Maintain an array `count[m]` that counts the number of proposals made by man m .

Efficient Implementation

Women rejecting/accepting.

- Does woman w prefer man m to man m' ?
- For each woman, create **inverse** of preference list of men.
- Constant time access for each query after $O(n)$ preprocessing.

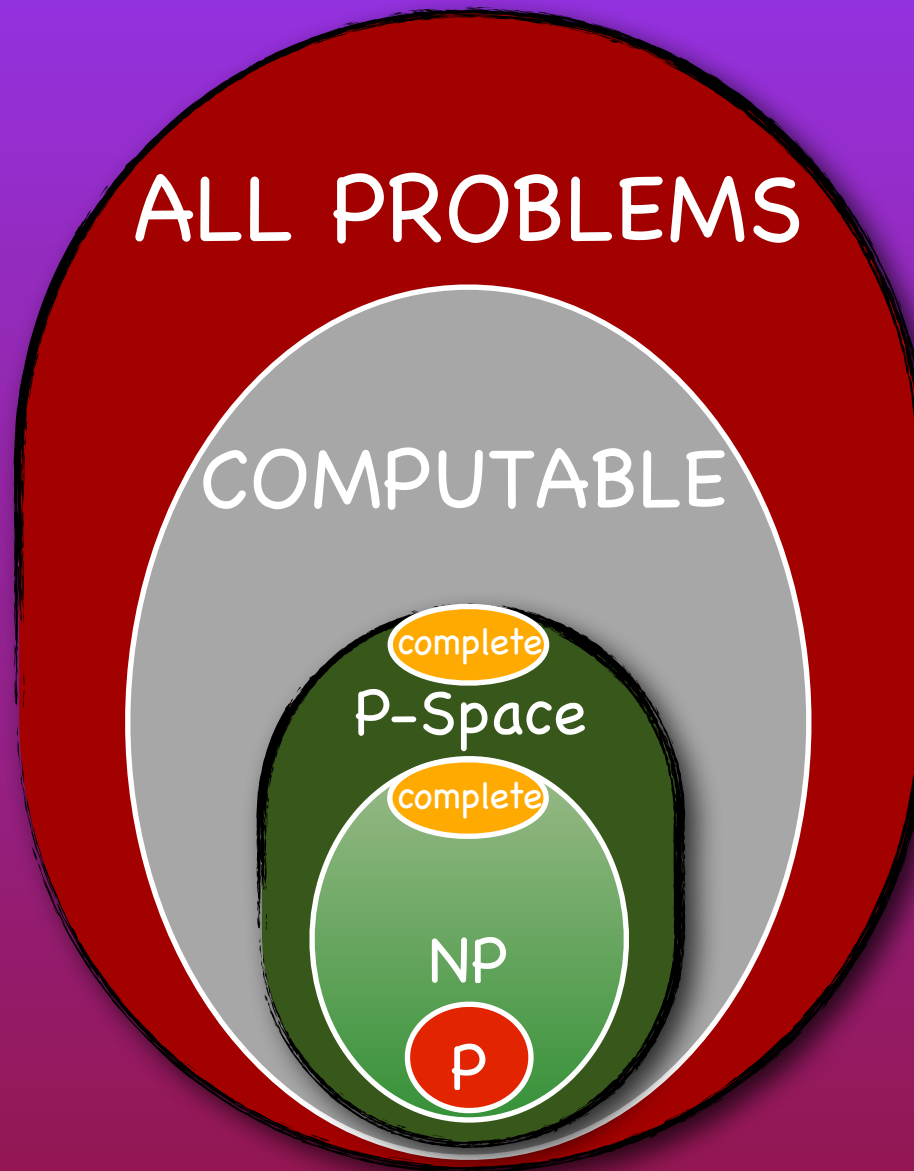
Amy	1 st	2 nd	3 rd	4 th	5 th	6 th	7 th	8 th
Pref	8	3	7	1	4	5	6	2

Amy	1	2	3	4	5	6	7	8
Inverse	4 th	8 th	2 nd	5 th	6 th	7 th	3 rd	1 st

```
for i = 1 to n
    inverse[pref[i]] = i
```

Amy prefers man 3 to 6
since $\text{inverse}[3] < \text{inverse}[6]$
2 7

A few Computability Classes



Polynomial-Time

Brute force. For many non-trivial problems, there is a natural brute force search algorithm that checks every possible solution.

- Typically takes 2^N time or worse for inputs of size N .
- Unacceptable in practice.

↖
 $N!$ for stable matching
with N men and N women

Desirable scaling property. When the input size doubles, the algorithm should only slow down by some constant factor C .

There exists constants $a > 0$ and $d > 0$ such that on every input of size N , its running time is bounded by $a \cdot N^d$ steps.

Def. An algorithm is **poly-time** if the above scaling property holds.

↖
choose $C = 2^d$

Property: poly-time is invariant over **all** computer models.

Average/Worst-Case Analysis

Worst case running time. Obtain bound on **largest possible** running time of algorithm on any input of a given size N.

- Generally captures efficiency in practice.
- Draconian view, but hard to find effective alternative.
- For probabilistic algorithms, we take the worst average running time.

Average case running time. Obtain bound on running time of algorithm on random input as a function of input size N.

- Hard (or impossible) to accurately model real instances by random distributions.
- Algorithm tuned for a certain distribution may perform poorly on other input distributions.

Worst-Case Polynomial-Time

Def. An algorithm is **efficient** if its running time is polynomial.

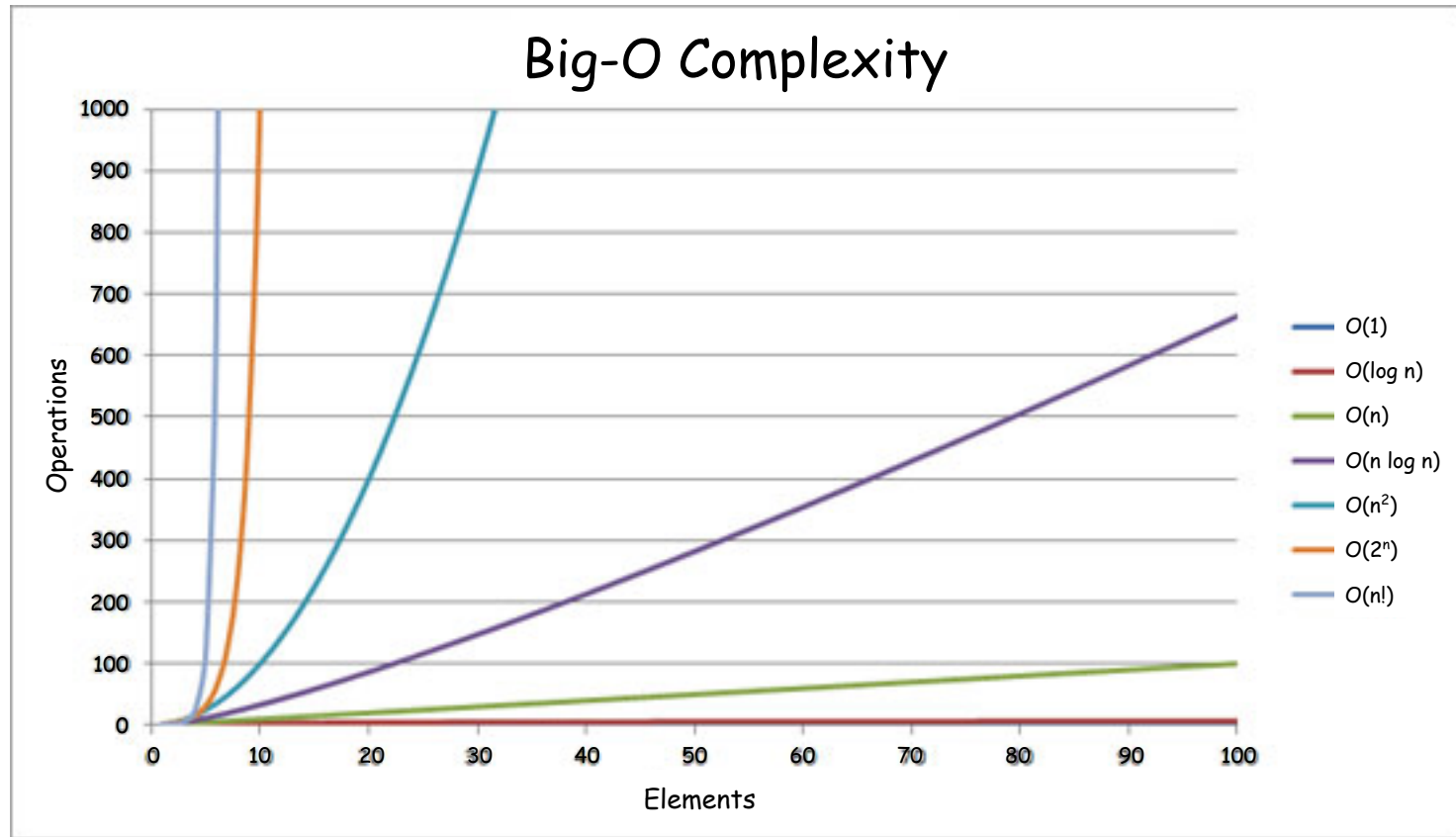
Justification: **It really works in practice!**

- Although $6.02 \times 10^{23} \times N^{20}$ is technically poly-time, it would be useless in practice.
- In practice, the poly-time algorithms that people develop **almost always** have low constants and low exponents.
- Breaking through the exponential barrier of brute force typically exposes some crucial structure of the problem.

Exceptions.

- Some poly-time algorithms do have high constants and/or exponents, and are useless in practice.
 - Some exponential-time (or worse) algorithms are widely used because the worst-case instances seem to be rare.
- Primality testing
- simplex method
Unix grep

Why It Matters



2.2 Asymptotic Order of Growth

Asymptotic Order of Growth

Let $f:\mathbb{N}\rightarrow\mathbb{R}^+$ be a function, we define

Upper bounds.

$$O(f) = \{ g:\mathbb{N}\rightarrow\mathbb{R}^+ \mid \exists c\in\mathbb{R}^+, n_0\in\mathbb{N} \text{ s.t. } \forall n\geq n_0 [g(n)\leq c\cdot f(n)] \}.$$

Lower bounds.

$$\Omega(f) = \{ g:\mathbb{N}\rightarrow\mathbb{R}^+ \mid \exists c\in\mathbb{R}^+, n_0\in\mathbb{N} \text{ s.t. } \forall n\geq n_0 [g(n)\geq c\cdot f(n)] \}.$$

Tight bounds.

$$\Theta(f) = O(f) \cap \Omega(f).$$

Ex: $T(n) = 32n^2 + 17n + 32$.

$T(n) \in O(n^2), O(n^3), \Omega(n^2), \Omega(n)$, and $\Theta(n^2)$.

$T(n) \notin O(n), \Omega(n^3), \Theta(n)$, or $\Theta(n^3)$.

Notation

Abuse of notation. $T(n) = O(f(n))$.

- Not transitive:
 - $f(n) = 5n^3$; $g(n) = 3n^2$
 - $f(n) = O(n^3)$ and $g(n) = O(n^3)$ but $f(n) \neq g(n)$.
- Better notation: $T(n) \in O(f(n))$.
- Acceptable notation: $T(n) \text{ is } O(f(n))$. (if scared by \in !)

Meaningless statement. Any comparison-based sorting algorithm requires at least $O(n \log n)$ comparisons.

- Statement doesn't "type-check".
- Precisely, $f(n)=1 \in O(n \log n)$, therefore "at least one comparison".
- Use Ω for lower bounds: "at least $\Omega(n \log n)$ comparisons".
- "requires at least $cn \log n$ comparisons for $c>0$ and all large enough n ".

Limit theorems.

Let $f, g: \mathbb{N} \rightarrow \mathbb{R}^+$ be functions, such that

$$\lim_{n \rightarrow \infty} f(n)/g(n) = c \in \mathbb{R}^+,$$

then $f \in \Theta(g)$, $g \in \Theta(f)$, $\Theta(f) = \Theta(g)$

$$\lim_{n \rightarrow \infty} f(n)/g(n) = 0,$$

then $f \in O(g)$, $f \notin \Omega(g)$,
 $O(f) \subsetneq O(g)$, $\Omega(g) \subsetneq \Omega(f)$

Properties

Let $f, g: \mathbb{N} \rightarrow \mathbb{R}^+$ be functions

Transitivity.

- If $f \in O(g)$ and $g \in O(h)$ then $f \in O(h)$ since $O(f) \subset O(g) \subset O(h)$.
- If $f \in \Omega(g)$ and $g \in \Omega(h)$ then $f \in \Omega(h)$ since $\Omega(f) \subset \Omega(g) \subset \Omega(h)$.
- If $f \in \Theta(g)$ and $g \in \Theta(h)$ then $f \in \Theta(h)$ since $\Theta(f) \subset \Theta(g) \subset \Theta(h)$.

Additivity.

- If $f \in O(h)$ and $g \in O(h)$ then $f + g \in O(h)$
since $f(n) < c_f h(n)$, $g(n) < c_g h(n) \Rightarrow f(n) + g(n) < (c_f + c_g) h(n)$.
- If $f \in \Omega(h)$ and $g \in \Omega(h)$ then $f + g \in \Omega(h)$.
- If $f \in \Theta(h)$ and $g \in O(h)$ then $f + g \in \Theta(h)$.

Consequence:

- $f + g \in O(\max\{f, g\})$ since $f + g \leq 2 \max\{f, g\}$.
- $f + g \in \Omega(\max\{f, g\})$ since $f + g \geq \max\{f, g\}$.
- $f + g \in \Theta(\max\{f, g\})$ since $\max\{f, g\} \leq f + g \leq 2 \max\{f, g\}$.

Asymptotic Bounds for Some Common Functions

Polynomials. $a_0 + a_1n + \dots + a_dn^d \in \Theta(n^d)$ if $a_d > 0$.

Polynomial time. Running time $\in O(n^d)$ for some constant d independent of the input size n .

Logarithms. $O(\log_a n) \in O(\log_b n)$ for any constants $a, b > 0$.
↑
can avoid specifying the base

Logarithms. For every $x > 0$, $\log n \in O(n^x)$.
↑
log grows slower than every polynomial

Exponentials. For every $r > 1$ and every $d > 0$, $n^d \in O(r^n)$.
↑
every exponential grows faster than every polynomial

2.4 A Survey of Common Running Times

Linear Time: $O(n)$

Linear time. Running time is proportional to input size.

Computing the maximum. Compute minimum of n numbers a_1, \dots, a_n .

```
min ← a1
for i = 2 to n {
    if (ai < min)
        min ← ai
}
```

$O(n \log n)$ Time

$O(n \log n)$ time. Arises in divide-and-conquer algorithms.



also referred to as linearithmic time

Sorting. **Mergesort** and **Heapsort** are sorting algorithms that perform $O(n \log n)$ comparisons.

Closest Points on a line. Given n numbers x_1, \dots, x_n , what is the smallest distance $x_i - x_j$ between any two points?

$O(n \log n)$ solution. Sort the n numbers. Scan the sorted list in order, identifying the minimum gap between successive points.

Quadratic Time: $O(n^2)$

Quadratic time. Enumerate all pairs of elements.

Closest pair of points. Given a list of n points in the plane
 $(x_1, y_1), \dots, (x_n, y_n)$, find the pair that is closest.

$O(n^2)$ solution. Try all pairs of points.

```
min ←  $(x_1 - x_2)^2 + (y_1 - y_2)^2$ 
for i = 1 to n {
  for j = i+1 to n {
    d ←  $(x_i - x_j)^2 + (y_i - y_j)^2$ 
    if (d < min)
      min ← d
  }
}
```

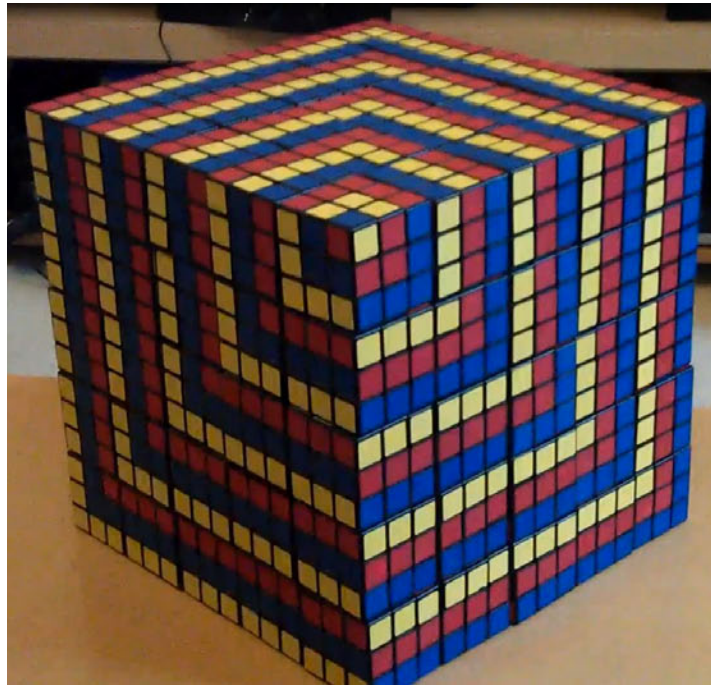
← don't need to
take square roots

Remark. This algorithm is $\Omega(n^2)$ and it seems inevitable in general,
but this is just an illusion: $\Theta(n \log n)$ is actually possible and optimal... ← see chapter 5

Quadratic Time: $O(n^2)$

Quadratic time. Solve $O(n^2)$ independent sub-puzzles each in constant-time.

$n \times n \times n$ Rubik's cube. Given a scrambled $n \times n \times n$ cube, put it in solved configuration.



Remark. This algorithm is $\Omega(n^2)$ and it seems inevitable in general, but this is just an illusion: $\Theta(n^2/\log n)$ is actually possible and optimal...

Cubic Time: $O(n^3)$

Cubic time. Enumerate all triples of elements.

Matrix multiplication. Given two $n \times n$ matrices of numbers A, B , what is their matrix product C ?

$$\begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1n} \\ c_{21} & c_{22} & \cdots & c_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ c_{n1} & c_{n2} & \cdots & c_{nn} \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{nn} \end{bmatrix}$$

$O(n^3)$ solution. For each entry c_{ij} compute as below.

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

Polynomial Time: $O(n^k)$ Time

Independent set of size k . Given a graph, are there k nodes such that no two are joined by an edge?

↖
 k is a constant

$O(n^k)$ solution. Enumerate all subsets of k nodes.

```
foreach subset S of k nodes {  
    if (S is an independent set)  
        report S  
}
```

- Check whether S is an independent set = $O(k^2)$.

- Number of k element subsets = $\binom{n}{k} = \frac{n(n-1)(n-2)\cdots(n-k+1)}{k(k-1)(k-2)\cdots(2)(1)} \leq \frac{n^k}{k!}$
- $O(k^2 n^k / k!) = O(n^k)$.

↖
poly-time for $k=17$,
but not practical

Exponential Time

Independent set. Given a graph, what is the maximum size of an independent set?

$O(n^2 2^n)$ solution. Enumerate all subsets.

```
S* ← ∅  
foreach subset S of nodes {  
    if (S is an independent set and |S| > |S*|)  
        update S* ← S  
}  
}
```