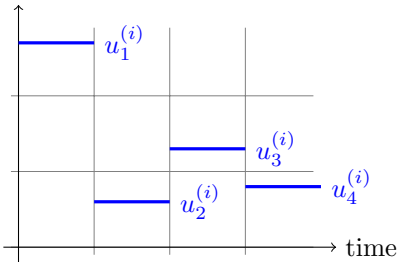


$i$ -th sampling

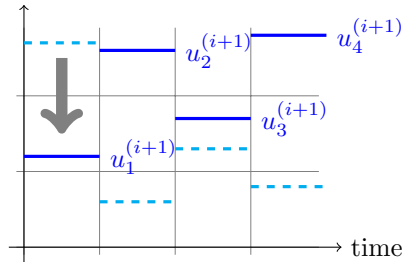
throttle



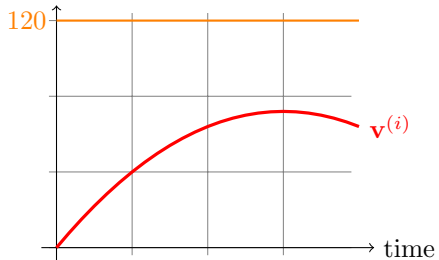
Choosing  
 $u_1^{(i+1)}, \dots, u_K^{(i+1)}$   
by optimization

$(i+1)$ -th sampling

throttle



vehicle speed



vehicle speed

