

Problem 1

- (a) For $x = 0$, $P(X = x) = P(Z = 0) + P(Z = 1) \times P(Y = 0) = (1 - p) + pe^{-\lambda}$

$$\text{For } x = 1, 2, 3, \dots, P(X = x) = P(Z = 1) \times P(Y = x) = p \times \frac{e^{-\lambda}\lambda^x}{x!}$$

$$\text{Therefore, } P(X = x) = \begin{cases} 1 - p + pe^{-\lambda} & x = 0 \\ p \times \frac{e^{-\lambda}\lambda^x}{x!} & x \in \mathbb{N} \\ 0 & \text{otherwise} \end{cases}$$

- (b) For $x = 0$, $P(\tilde{X} = x) = P(1 - I = 0) + P(1 - I = 1) \times P(Y = 0) = P(I = 1) + P(I = 0) \times P(Y = 0) = (1 - p) + pe^{-\lambda}$

$$\text{For } x = 1, 2, 3, \dots, P(\tilde{X} = x) = P(1 - I = 1) \times P(Y = x) = P(I = 0) \times P(Y = x) = p \times \frac{e^{-\lambda}\lambda^x}{x!}$$

$$\text{Therefore, } P(\tilde{X} = x) = \begin{cases} 1 - p + pe^{-\lambda} & x = 0 \\ p \times \frac{e^{-\lambda}\lambda^x}{x!} & x \in \mathbb{N} \\ 0 & \text{otherwise} \end{cases}, \text{ which is the same as } P(X = x).$$

- (c) Let $p_U(u) = P(U = u)$, $p_V(v) = P(V = v)$. Since U and V are independent, $p_{UV}(u, v) = p_U(u) \times p_V(v)$. Therefore, $E[UV] = \sum_{u \in S_U} \sum_{v \in S_V} uv \times p_{UV}(u, v) = \sum_{u \in S_U} \sum_{v \in S_V} uv \times p_U(u) \times p_V(v) = \sum_{u \in S_U} u \times p_U(u) \times \sum_{v \in S_V} v \times p_V(v) = E[U] \times E[V]$.

Problem 2

- (a) The MGF of a Poisson random variable is $e^{\lambda(e^t - 1)}$, so we can know $M_{3X}(t) = M_X(3t) = e^{\lambda(e^{3t} - 1)}$, $M_{4Y}(t) = M_Y(4t) = e^{\lambda(e^{4t} - 1)}$. We also know that $M_{3X+4Y}(t) = M_{3X}(t) \times M_{4Y}(t) = e^{\lambda(e^{3t} - 1)} \times e^{\lambda(e^{4t} - 1)} = e^{\lambda(e^{3t} + e^{4t} - 2)}$, which is not the MGF of a Poisson random variable. Therefore, $3X + 4Y$ is not a Poisson random variable.

- (b) $M_Y(t) = \sum_{k=1}^{\infty} e^{tk} \cdot \frac{6}{\pi^2 k^2} = \frac{6}{\pi^2} \sum_{k=1}^{\infty} \frac{e^{tk}}{k^2}$. For $t > 0$, the term $\frac{e^{tk}}{k^2}$ grows exponentially, which makes the series $\sum_{k=1}^{\infty} \frac{e^{tk}}{k^2}$ diverges. Therefore, $M_Y(t)$ does not exist since it is not finite for any $t > 0$.

Problem 3

- (a) Marginal CDF of X : $F_X(t) = \lim_{u \rightarrow \infty} F_{XY}(t, u) = \lim_{u \rightarrow \infty} (1 - e^{-t} - e^{-u} + e^{-(t+u+\theta tu)}) = 1 - e^{-t}$
 Marginal CDF of Y : $F_Y(t) = \lim_{t \rightarrow \infty} F_{XY}(t, u) = \lim_{t \rightarrow \infty} (1 - e^{-t} - e^{-u} + e^{-(t+u+\theta tu)}) = 1 - e^{-u}$
 If X and Y are independent, $F_{XY}(t, u) = F_X(t) \times F_Y(u) = (1 - e^{-t}) \times (1 - e^{-u}) = 1 - e^{-t} - e^{-u} + e^{-(t+u)}$, which means $e^{-(t+u+\theta tu)} = e^{-(t+u)}$. Therefore, X and Y are independent only if $\theta = 0$.

- (b) $\frac{\partial F_{X,Y}(t,u)}{\partial t} = \frac{\partial}{\partial t} (1 - e^{-t} - e^{-u} + e^{-(t+u+\theta tu)}) = e^{-t} + (1 + \theta u)e^{-(t+u+\theta tu)}$

$$\text{Joint PDF of } X \text{ and } Y: f_{X,Y}(t, u) = \frac{\partial}{\partial u} (e^{-t} + (1 + \theta u)e^{-(t+u+\theta tu)}) = \theta e^{-(t+u+\theta tu)} + (1 + \theta u)(1 + \theta t)e^{-(t+u+\theta tu)} = [1 + \theta(1 + u + t) + \theta^2 ut]e^{-(t+u+\theta tu)}$$

Problem 4

- (a) Since $R(T_a) > R(T_b)$, we can know that each labeler votes for T_a with probability $p = \sigma(R(T_a) - R(T_b)) > 0.5$. We can define the indicator random variable X_i for the i -th labeler, where $X_i = 1$ if the labeler votes for T_a and $X_i = 0$ if the labeler votes for T_b . Therefore, $X_i \sim \text{Bernoulli}(p)$. Define the sample mean $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$, then the event E that T_a gets more votes than T_b is equivalent to $E = \{\bar{X} > \frac{1}{2}\}$. Using Hoeffding's inequality for bounded independent random variables, $P(|\bar{X} - \mu| \geq \epsilon) \leq 2e^{-\frac{2n\epsilon^2}{(b-a)^2}}$, where $a = 0$ and $b = 1$ in this case, so $P(E) = P(\bar{X} > \frac{1}{2}) = 1 - P(\bar{X} \leq \frac{1}{2}) = 1 - P(\bar{X} - \mu \leq -(\mu - 0.5)) \geq 1 - e^{-2n(\mu - 0.5)^2}$. Therefore, $P(E) \geq 1 - e^{-2n(p - \frac{1}{2})^2}$.
- (b) 1. We should ensure that $P(E) = P(\bar{X} > \frac{1}{2}) \geq 1 - \delta$, which means $P(\bar{X} \leq \frac{1}{2}) \leq \delta$. Applying Chebyshev's inequality, $P(\bar{X} \leq \frac{1}{2}) = P(|\bar{X} - \mu| \geq \mu - \frac{1}{2}) \leq \frac{p(1-p)}{n(\mu - \frac{1}{2})^2}$. Therefore, we require $\frac{p(1-p)}{n(\mu - \frac{1}{2})^2} \leq \delta$, which means $n \geq \frac{p(1-p)}{\delta(\mu - \frac{1}{2})^2}$.
2. $P(E) \geq 1 - e^{-2n(p - \frac{1}{2})^2} \geq 1 - \delta$. This requires $e^{-2n(p - \frac{1}{2})^2} \leq \delta$, which can be simplified to $2n(p - \frac{1}{2})^2 \geq \ln(\frac{1}{\delta})$. Therefore, $n \geq \frac{1}{2(p - \frac{1}{2})^2} \ln(\frac{1}{\delta})$.
- (c) We need to find an upper bound on $P(S > 90)$, where $S = \sum_{j=1}^{100} I_j$. For each I_j , $\mathbb{E}[e^{tI_j}] = (1 - p_j)e^{t \cdot 0} + p_j e^t = 1 + p_j(e^t - 1)$. Since I_j are independent, for any $t > 0$, we have $P(S \geq a) \leq e^{-ta} \cdot M_X(t) = e^{-ta} \prod_{j=2}^{100} (1 + p_j(e^t - 1))$, where $a = 91$ since $S > 90$. Using the inequality $1 + x \leq e^x$, we can simplify the expression to $e^{-ta} \prod_{j=2}^{100} e^{p_j(e^t - 1)} = e^{-ta} \cdot e^{\sum_{j=2}^{100} p_j(e^t - 1)}$. Now we have $P(S \geq a) \leq e^{-ta + \mu(e^t - 1)}$, where $\mu = \sum_{j=2}^{100} p_j$. To find the tightest bound, set $\phi(t) = -ta + \mu(e^t - 1)$, then $\phi'(t) = -a + \mu e^t$. Set $\phi'(t) = 0$, we can find the optimal $t = \ln \frac{a}{\mu}$. Therefore, $P(S \geq a) \leq e^{-a \ln \frac{a}{\mu} + a - \mu} = e^{-91 \ln \frac{91}{\mu} + 91 - \mu}$.

Problem 5

- (a)
1. Since N is the smallest integer such that $S_N > 1$, therefore $N = n$ occurs when $S_{n-1} < 1$ and $S_n > 1$. So $P(N = n) = P(S_{n-1} < 1 \text{ and } S_n > 1) = P(S_{n-1} < 1) - P(S_n \leq 1)$. Since $P(S_n = 1) = 0$, $P(N = n) = P(S_{n-1} < 1) - P(S_n < 1)$.
 2. Proof $P(S_k < v) = \frac{v^k}{k!}$ by induction:
 Base case: $P(S_1 < 1) = 1 = \frac{1^1}{1!}$
 Inductive step: Assume $n = k$, $P(S_k < 1) = \frac{v^k}{k!}$. Then for $n = k + 1$, $P(S_{k+1} < 1) = \int_{u_{k+1}=0}^1 P(S_k < 1 - u_{k+1}) du_{k+1}$. Let $v = 1 - u_{k+1}$, then $P(S_{k+1} < 1) = \int_{v=0}^1 P(S_k < v) dv = \int_{v=0}^1 \frac{v^k}{k!} dv = \frac{1}{k!} \int_0^1 v^k dv = \frac{1}{k!} \left[\frac{v^{k+1}}{k+1} \right]_{v=0}^1 = \frac{1}{k!} \cdot \frac{1}{k+1} = \frac{1}{(k+1)!}$.
 Therefore, $P(S_k < 1) = \frac{1^k}{k!} = \frac{1}{k!}$.
 3. $P(N = n) = P(S_{n-1} < 1) - P(S_n < 1) = \frac{1}{(n-1)!} - \frac{1}{n!} = \frac{n}{n!} - \frac{1}{n!} = \frac{n-1}{n!}$.
 $E[N] = \sum_{n=1}^{\infty} n \times P(N = n) = \sum_{n=1}^{\infty} \frac{n(n-1)}{n!} = \frac{1 \cdot 0}{1!} + \sum_{n=2}^{\infty} \frac{1}{(n-2)!} = \sum_{m=0}^{\infty} \frac{1}{m!} = e$

(b) Procedure of simulation:

1. Define the number of trials N_{trials} of each simulation run.
2. Generate a sequence of i.i.d. $Uniform(0, 1)$ random variables $U_1, U_2, \dots, U_{N_{trials}}$.
3. For each $i = 1, 2, \dots, N_{trials}$, record the value n such that $S_{n-1} < 1$ and $S_n > 1$.
4. After all trials, compute the average of all recorded N_i values. This average is an estimate of e .

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1 | All Estimates of Euler's Number e:
2 | Trials:      10, Estimated e: 2.8000000000
3 | Trials:     1000, Estimated e: 2.7240000000
4 | Trials:    100000, Estimated e: 2.7153000000
5 | Trials: 10000000, Estimated e: 2.7183091000

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Problem 6

(a) Observations:

1. For lower ϵ values ($\epsilon = 0.01$), the performance of Epsilon Greedy is closer to Empirical Means.
2. For moderate ϵ values ($\epsilon = 0.03$), a balance between exploration and exploitation is achieved.
3. For higher ϵ values ($\epsilon = 0.1$), Epsilon Greedy outperforms Empirical Means in environments with sparse reward distributions (e.g., Environment 2).
4. Larger ϵ values ($\epsilon = 0.3$) result in higher regrets due to excessive exploration.

	$\epsilon = 0.01$	$\epsilon = 0.03$	$\epsilon = 0.1$	$\epsilon = 0.3$
Environment 0	0.048430	0.041721	0.040679	0.040719
Environment 1	0.018111	0.008061	0.009311	0.007883
Environment 2	0.040201	0.039511	0.042640	0.042674

Mean Regrets for Empirical Means

	$\epsilon = 0.01$	$\epsilon = 0.03$	$\epsilon = 0.1$	$\epsilon = 0.3$
Environment 0	0.059363	0.030785	0.044694	0.121840
Environment 1	0.031996	0.022477	0.039259	0.103480
Environment 2	0.046880	0.027960	0.015047	0.022627

Mean Regrets for Epsilon Greedy

(b) Observations:

1. Smaller α values ($\alpha = 0.1$) result in slower decay of exploration, leading to excessive regret in some environments.
2. Moderate α values ($\alpha = 0.5$) achieve the best trade-off, minimizing regret effectively across all environments.
3. Larger α values ($\alpha = 2.0$) lead to insufficient exploration, causing suboptimal performance.
4. Sparse reward environments (e.g., Environment 2) are more sensitive to the choice of α , as insufficient exploration can quickly result in higher regret.

	$\alpha = 0.1$	$\alpha = 0.5$	$\alpha = 1.0$	$\alpha = 2.0$
Environment 0	0.044749	0.024617	0.048363	0.036975
Environment 1	0.010909	0.005492	0.009362	0.009503
Environment 2	0.043087	0.042800	0.046280	0.044781

Mean Regrets for Empirical Means

	$\alpha = 0.1$	$\alpha = 0.5$	$\alpha = 1.0$	$\alpha = 2.0$
Environment 0	0.177120	0.015667	0.113410	0.417050
Environment 1	0.149890	0.011907	0.030241	0.381130
Environment 2	0.031097	0.021433	0.078094	0.087898

Mean Regrets for Epsilon Greedy