FYS3150 Project 4 -

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Abstract

In this project, we want to implement the Ising model, in the case of a two-dimensional squared lattice, with periodic boundary conditions, by using the object-oriented programming. In this lattice, we have $L \times L$ particles characterized by their spin (up or down). The starting point of the program will be a random lattice or a lattice with all the spins-up. The Metropolis algorithm will be run in a lattice 20×20 and then bigger. We will study the properties of the system: the mean energy E, the mean magnetization |M|, the specific heat and the susceptibility χ as function of the temperature. The purpose is then to study the phase transitions. We will again study these properties near the critical temperature (Curie point).

Quelques résultats...

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Introduction

Chapter 1

Theory

1.1 The Ising model

1.1.1 The general model

The Ising model is a mathematical model used in statistical mechanics. It consists of discrete variables, which represent the magnetic moment of the spin, which can take only two values (here +1 or -1). The spins will only interact with their direct neighbors. With this model, we can study the phase transitions at finite temperature for magnetic systems. We can expressed the energy as

$$E = -J \sum_{\langle kl \rangle}^{N} s_k s_l - B \sum_{k}^{N} s_k \tag{1}$$

with J a constant expressing the strength of the interaction between the neighboring spins, $\langle kl \rangle$ indicating the fact that we only sum the nearest neighbors, N the number of spins, $s_{k,l}=\pm 1$ and B an external magnetic field interacting with the magnetic moment set up by the spins. This is the general expression of the Ising model. For our use, we will only focus on the case where B=0.

Then, we will be able to calculate expectation values of the mean energy $\langle E \rangle$ and magnetization $\langle M \rangle$ at a given temperature. To do this, we will use a Boltzmann distribution

$$P_i(\beta) = \frac{e^{-\beta E_i}}{Z} \tag{2}$$

where P_i is the probability of finding the system in the state i, $\beta = \frac{1}{kT}$, T being the temperature and k the Boltzmann constant, E_i is the energy of a state i and Z is the partition function defined by $Z = \sum_{i=1}^{M} e^{-\beta E_i}$ with M the number of configurations. E_i , which is the energy in the state i, is given by, for k, l the spins of the state i:

$$E_i = -J \sum_{\langle kl \rangle}^N s_k s_l \tag{3}$$

A simple particular case of the Ising model, the two-dimensional square lattice model, allows us to have an analytical solution, which will be compared to the numerical results.

1.1.2 Two-dimensional square lattice model

This particular case is one of the simplest models to show a phase transition. It is defined by the following conditions: a null external magnetic field B=0, this is a two-dimensional lattice with $N=L\times L$ sites with L the number of spins in each dimension, with periodic boundary conditions.

Let's take the case with $N=2\times 2$ spins. We have $2^4=16$ different possible states with those conditions. We reuse the equation (3) to find the energy of each configuration i with the spins-up \uparrow taking the value +1 and the spins-down \downarrow taking the value -1. Let's take for example the case where three spins are pointing up (and so one is pointing down) numbered

from 1 to 4:
$$\downarrow^{(1)}$$
 $\uparrow^{(2)}$ $\uparrow^{(4)}$.

$$\begin{split} E &= -J \sum_{\langle kl \rangle}^4 s_k s_l \\ &= -J (s_1 s_2 + s_2 s_1 + s_1 s_3 + s_3 s_1 + s_2 s_4 + s_4 s_2 + s_3 s_4 + s_4 s_3) \\ &= -J \left[(-1) + (-1) + (-1) + (-1) + 1 + 1 + 1 + 1 \right] \\ &= -J \times 0 \\ E &= 0 \end{split}$$

The magnetization formula is the simple sum of all spin of the state $M = \sum_{k=0}^{N} s_k$ with k each spin of the configuration. So in our example, we have

$$M = s_1 + s_2 + s_3 + s_4$$
$$= (-1) + 1 + 1 + 1$$
$$M = 2$$

The following table sums up the possible states of a two-dimensional square lattice model.

Number of spins-up	Possible configurations		Degeneracy	Energy	Magnetization
4	<u></u>	†	1	-8J	4
3	↓ ↑ ↑ ↓ ↑ ↑ ↑ ↑	$\begin{array}{c cccc} \uparrow & \uparrow & \uparrow & \uparrow \\ \downarrow & \uparrow & \uparrow & \downarrow \\ \end{array}$	4	0	2
2	$\left \begin{array}{c c} \uparrow & \uparrow & \downarrow & \downarrow \\ \downarrow & \downarrow & \uparrow & \uparrow \end{array}\right $		4	0	0
2	↑ ↓ ↓ ↑	→ →	2	8J	0
1	\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	↓ ↑ ↑ ↓ ↓ ↓	4	0	-2
0	+	+ + +	1	-8J	-4

Table 1.1: Energy and magnetization for a $N=2\times 2$ spins Ising model with periodic boundary conditions.

The 16 configurations known, we can calculate the partition function in its analytic form.

$$Z = \sum_{i=1}^{16} e^{-\beta E_i}$$

$$Z = (1 \times e^{-\beta \times (-8J)}) + (4 \times e^{-\beta \times 0}) + (4 \times e^{-\beta \times 0}) + (2 \times e^{-\beta \times 8J}) + (4 \times e^{-\beta \times 0}) + (1 \times e^{-\beta \times (-8J)})$$

$$Z = 2(e^{8J\beta} + e^{-8J\beta} + 6)$$

$$Z = 4[\cosh(8J\beta) + 3]$$
(4)

$$Z = 4[\cosh(8J\beta) + 3] \tag{4'}$$

Let's now compute the expectation value of the energy, defined by

$$\langle E \rangle = \sum_{i=1}^{M} E_i P_i(\beta)$$

From (2), we can write:

$$\langle E \rangle = \frac{1}{Z} \sum_{i=1}^{M} E_{i} e^{-\beta E_{i}}$$

$$= \frac{1}{Z} \left(2 \times (-8J) e^{8J\beta} + 2 \times 8J e^{-8J\beta} \right)$$

$$\langle E \rangle = -\frac{J}{Z} \left(16 e^{8J\beta} - 16 e^{-8J\beta} \right)$$

$$\langle E \rangle = -8J \frac{e^{8J\beta} - e^{-8J\beta}}{e^{8J\beta} + e^{-8J\beta} + 6}$$

$$\langle E \rangle = -8J \frac{\sinh(8J\beta)}{\cosh(8J\beta) + 3}$$
(5')

(5')

Similarly, we compute the mean value of the magnetic moment (or mean magnetization) in its absolute value $\langle |M| \rangle$:

$$\langle |M| \rangle = \sum_{i=1}^{M} |M_i| P_i(\beta) = \frac{1}{Z} \sum_{i=1}^{M} |M_i| e^{-\beta E_i}$$

$$\langle |M| \rangle = \frac{1}{Z} \left(4e^{8J\beta} + 4 \times 2e^0 + 4 \times 2e^0 + 4e^{8J\beta} \right)$$

$$\left| \langle |M| \rangle = \frac{8e^{8J\beta} + 16}{Z} \right|$$

$$\langle |M| \rangle = \frac{4e^{8J\beta} + 8}{e^{8J\beta} + e^{-8J\beta} + 6}$$
(6)

which match with the fact that we have taken the external magnetic field B=0.

We can use the expression of the expectation value of the energy to find the specific heat C_V which is defined by

 $C_V = \frac{\langle E^2 \rangle - \langle E \rangle^2}{kT^2}$

The specific heat capacity represents the amount of energy requiered to raise the temperature of a unit of mass by a unit of temperature.

We need to compute $\langle E^2 \rangle$:

$$\langle E^{2} \rangle = \sum_{i=1}^{M} E_{i}^{2} P_{i}(\beta) = \frac{1}{Z} \sum_{i=1}^{M} E_{i}^{2} e^{-\beta E_{i}}$$

$$= \frac{1}{Z} \left(2 \times (-8J)^{2} e^{8J\beta} + 2 \times (8J)^{2} e^{-8J\beta} \right)$$

$$\langle E^{2} \rangle = \frac{J^{2}}{Z} \left(128 e^{8J\beta} + 128 e^{-8J\beta} \right)$$

$$\langle E^{2} \rangle = 64J^{2} \frac{e^{8J\beta} + e^{-8J\beta}}{e^{8J\beta} + e^{-8J\beta} + 6}$$

$$\langle E^{2} \rangle = 64J^{2} \frac{\cosh(8J\beta)}{\cosh(8J\beta) + 3}$$
(7')

Then, with (5), we have

$$C_{V} = \frac{J^{2}}{ZkT^{2}} \left[\left[128 \left(e^{8J\beta} + e^{-8J\beta} \right) \right] - \frac{1}{Z} \left[16 \left(e^{8J\beta} - e^{-8J\beta} \right) \right]^{2} \right]$$

$$C_{V} = \frac{256J^{2}}{ZkT^{2}} \left[\cosh(8J\beta) - \frac{4}{Z} \sinh^{2}(8J\beta) \right]$$
(8)

Similarly, to have the susceptibility χ , which is its capacity to be attracted or not into a magnetic field, defined by

$$\chi = \frac{\langle |M|^2 \rangle - \langle |M| \rangle^2}{kT},$$

we start by computing $\langle |M|^2 \rangle$:

$$\langle |M|^{2} \rangle = \sum_{i=1}^{M} |M_{i}|^{2} P_{i}(\beta) = \frac{1}{Z} \sum_{i=1}^{M} |M_{i}|^{2} e^{-\beta E_{i}}$$

$$= \frac{1}{Z} \left(4^{2} e^{8J\beta} + 4 \times 2^{2} e^{0} + 4 \times 2^{2} e^{0} + 4^{2} e^{8J\beta} \right)$$

$$\left[\langle |M|^{2} \rangle = \frac{1}{Z} \left(32 e^{8J\beta} + 32 \right) \right]$$

$$\langle |M|^{2} \rangle = 16 \frac{e^{8J\beta} + 1}{e^{8J\beta} + e^{-8J\beta} + 6}$$
(9)

Using (6), we can write

$$\chi = \frac{1}{ZkT} \left[\left(32e^{8J\beta} + 32 \right) - \left(\frac{(8e^{8J\beta} + 16)^2}{Z} \right) \right]$$

$$\chi = \frac{16}{kT} \left[\frac{3e^{8J\beta} + e^{-8J\beta} + 3}{(e^{8J\beta} + e^{-8J\beta} + 6)^2} \right]$$
(10)

1.2 Phase transition

A phase transition is a transformation of a system due to a variation of an external parameter (such as the temperature). It exists a critical point where the transition takes place.

1.2.1 The critical temperature

To study the phase transitions, we consider a critical temperature. The Ising model with our conditions (in two dimensions and with an null-external magnetic field B=0) undergoes a phase transition of second-order, called like this because of the fact that there is a discontinuity in the second derivative of the free energy. That means that the new states grows continuously from the previous one and when $T \to T_C$, these two states are quantatively the same.

Near this temperature, a power-law applies to many physical quantities : one quantity varies as the power of another. In the Ising model, we can express the mean magnetization as

$$\langle M(T) \rangle \sim (T - T_C)^{\beta}$$

with $\beta = \frac{1}{8}$ one of the Ising critical exponents (in two dimensions). We have similar expression for the heat capacity and the susceptibility:

$$C_V(T) \sim |T_C - T|^{-\alpha}$$

$$\chi(T) \sim |T_C - T|^{-\gamma}$$

with $\alpha = 0$ and $\gamma = \frac{7}{4}$ two other critical exponents.

We also defined the correlation length which is a quantity which represents how two spins are correlated. When the temperature T gets closer to T_C , the correlation length between two spins increases. This quantity is given by

$$\xi(T) \sim |T_C - T|^{-\nu}$$

defining the constant ν .

1.2.2 Around the critical temperature

When the correlation length spans the whole system, we say that we have a second-order (or continuous) phase transition. ξ is proportional to the size of the lattice L at the critical point $(\xi \propto L)$, as it is always finite. With the finite size scaling relations, we can relate the temperature for a finite lattice and the one for an infinite lattice:

$$T_C(L) - T_C(L = \infty) = aL^{-\frac{1}{\nu}}$$

with a a constant.

With the last equation, we can write:

$$\langle M(T) \rangle \sim (T - T_C)^{\beta} \to L^{-\frac{\beta}{\nu}}$$

$$C_V(T) \sim |T_C - T|^{-\alpha} \to L^{\frac{\alpha}{\nu}}$$

$$\chi(T) \sim |T_C - T|^{-\gamma} \to L^{\frac{\gamma}{\nu}}$$

for T near T_C .

To find the critical temperature of our case, we will plot the values of the physical properties we study from the beginning (namely the expectation values for the energy E and the magnetic moment |M|, the specific heat C_V and the susceptibility ξ as function of the temperature T. The discontinuity in the graph would tell us an approximation of the critical temperature. We have a theorical value of the critical temperature which is

$$\frac{kT_C}{J} = \frac{2}{\ln(1+\sqrt{2})} \approx 2.269$$
 (11)

according to the work of Lars Onsager exposed in the Physical Review 65, 116 in 1944.

1.3 The Metropolis algorithm

1.3.1 Introduction to the algorithm

The Metropolis algorithm is a Markov Chain Monte Carlo method (MCMC).

A Markov Chain is a Markov process, which is a stochastic process that satisfies the Markov property. This property says that to know the next state, we only need the current state. There is no need to remember the past ones. We obtain a sequence of random samples from a probability distribution, here the Boltzmann distribution.

Every Monte Carlo cycle is based on a Markov process to get a new random state. The point is to run it enough time to reach the most likely state of the system, starting with a random configuration. To reach this most likely state, and so an equilibrium distribution, we need either to accept or reject the new random state.

Our Monte Carlo sampling function will be the probability of finding the system in the state i given in (2):

$$P_i = \frac{e^{-\beta E_i}}{Z}$$

The partition function Z is hard to compute as we need to have the energies of all states E_i : in two dimensions, we have 2^N configurations with $N = L \times L$ the number of spins. The Metropolis algorithm does not require us to compute this partition function. Indeed, we only need the difference between the energy of a configuration and the previous one.

1.3.2 The algorithm

```
Algorithm 1: Monte Carlo method using the Metropolis algorithm
 Input: E_b the energy of the initial random configuration.
 Input: E_t the energy of the configuration obtained by flipping one spin.
 E_t - E_b \to \Delta E;
 E_t \to E_b;
 Compute expectation values for the state with the energy E_b;
 for each new configuration do
     energy of the new configuration \rightarrow E_t;
     E_t - E_b \rightarrow \Delta E;
     if \Delta E \leq 0 then
         E_t \to E_b;
         e^{-\beta\Delta E} \to w;
         pick a random number r \in [0, 1];
         if r \leq w then
             The new configuration is accepted, E_t \to E_b;
             Keep the old configuration.;
         end
     \mathbf{end}
     update expectation values.;
 end
```

In this algorithm, we go through the lattice to calculate the energy of the actual configuration of the system. This is a Monte Carlo cycle. The choice of accepting or not a configuration is made by comparing the actual energy of the system with the energy of the previous one. If the energy of the actual configuration is lower than the previous one, we accept the configuration as we try to have the lowest energy at a given temperature.

The strength of this method is that we do not have to compute the total energy of each configuration but only the difference between the actual configuration and the previous one. Then we do not have to compute the exponential $e^{-\beta\Delta E}$ each time we go through the loop but we can pre-calculate its possible values. When we flip the spins only one by one we are

able to know all the ΔE which are possibles. For the Ising model in two dimensions, we have a total of five possible values of ΔE . We take a random spin in the lattice, surrounded by four other spins, which will be flipped. The direction of the four surronding spins determines the energy of the mini-system composed of the five spins. We only need to know how the energy is modified by the flip of the spin chosen to compute ΔE .

In the following array, we sum up all the different possible values of ΔE according to the number of spins-up around the chosen spin.

Number of surr.	Energy of the	Flipped	Energy of the	Difference of energy ΔE
spins-up	initial state	configurations	resulting state	between the two states
$4: \uparrow \uparrow \uparrow \uparrow \uparrow \uparrow$	$E_b = -4J$	↑ ↑ ↓ ↑ ↑	$E_t = 4J$	$\Delta E = 8J$
3: \ \ \ \ \ \ \ \	$E_b = -2J$	↑ ↓ ↓ ↑ ↑	$E_t = 2J$	$\Delta E = 4J$
$2:\downarrow\uparrow\uparrow$	$E_b = 0$	↓ ↓ ↑ ↑	$E_t = 0$	$\Delta E = 0$
$\begin{array}{ c c c }\hline & \downarrow \\ 1: & \uparrow & \uparrow \\ & \downarrow \\ \end{array}$	$E_b = 2J$	↓ ↓ ↑ ↓ ↓ ↑	$E_t = -2J$	$\Delta E = -4J$
$0: \downarrow \uparrow \downarrow$	$E_b = 4J$	\	$E_t = -4J$	$\Delta E = -8J$

Table 1.2: Possible values of ΔE for a two-dimensional Ising model

We will implement this algorithm in a little bit different way. We will not have to do the calculations of ΔE to save time and FLOPs.

Chapter 2

Implementation

For the programs of this project, we will use a object-oriented programing instead of standard programing with a lot of functions and variables. The program will then be closer to how we conceptualize the model.

2.1 The Ising model

_emptyness_test()	with	without	inline
	0.767089	0.724986	0.727917
	0.820451	0.733801	0.724200
Execution time (s)	0.818652	0.735491	0.731647
	0.764639	0.726894	0.740837
	0.803291	0.738665	0.788194
Total (s)	3.974122	3.659837	3.712795

Table 2.1: Comparison of time of execution with, without or inline the function _emptyness_text() for a 20 × 20 lattice and 100000 itérations in five different cases for the function lattice::change_random_spin(void)

with/without	7.9083%
inline/without	1.4470%
with/inline	6.5757%

Table 2.2: Ratio

	inline	non-inline	
	0.00214803	0.00197528	
	0.00193242	0.00196044	
Execution time (s)	0.00193351	0.00231188	
	0.00223604	0.00200409	
	0.00194202	0.00209086	
Total (s)	0.01019202	0.01034255	
Ratio inline/non-inline	1.45544%		

Table 2.3: Comparison of time of execution inline or not the function lattice::energies(const int row, const int col) for a 100×100 lattice in five different cases.

	inline	non-inline	
	0.00151482	0.00152923	
	0.00212926	0.00154181	
Execution time (s)	0.00159991	0.00151376	
	0.00187490	0.00225723	
	0.00189646	0.00153893	
Total (s)	0.00901535	0.00838096	
Ratio inline/non-inline	-7.56942%		

Table 2.4: Comparison of time of execution inline or not the function lattice::neighbors_spin_sum(const int row, const int col) for a 100×100 lattice in five different cases.

2.2 The Metropolis algorithm

2.3 Critical temperature

Chapter 3

Results

3.1 Two-dimensional squared lattice

3.1.1 2×2 case

This very simple case allows us to test the algorithm. We just have to compare the numerical results with the theorical ones.

3.1.2 20×20 case

The most likely state

Two cases: ordered and random

The probability distribution of a given energy

3.2 Phase transitions

- 3.2.1 The Ising model near the critical temperature
- 3.2.2 The critical temperature

Conclusion

Bibliography

 \bullet Lars Onsager Phys. Rev. 65, 117 (1944)

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