

Embedded System Lab

Final Report

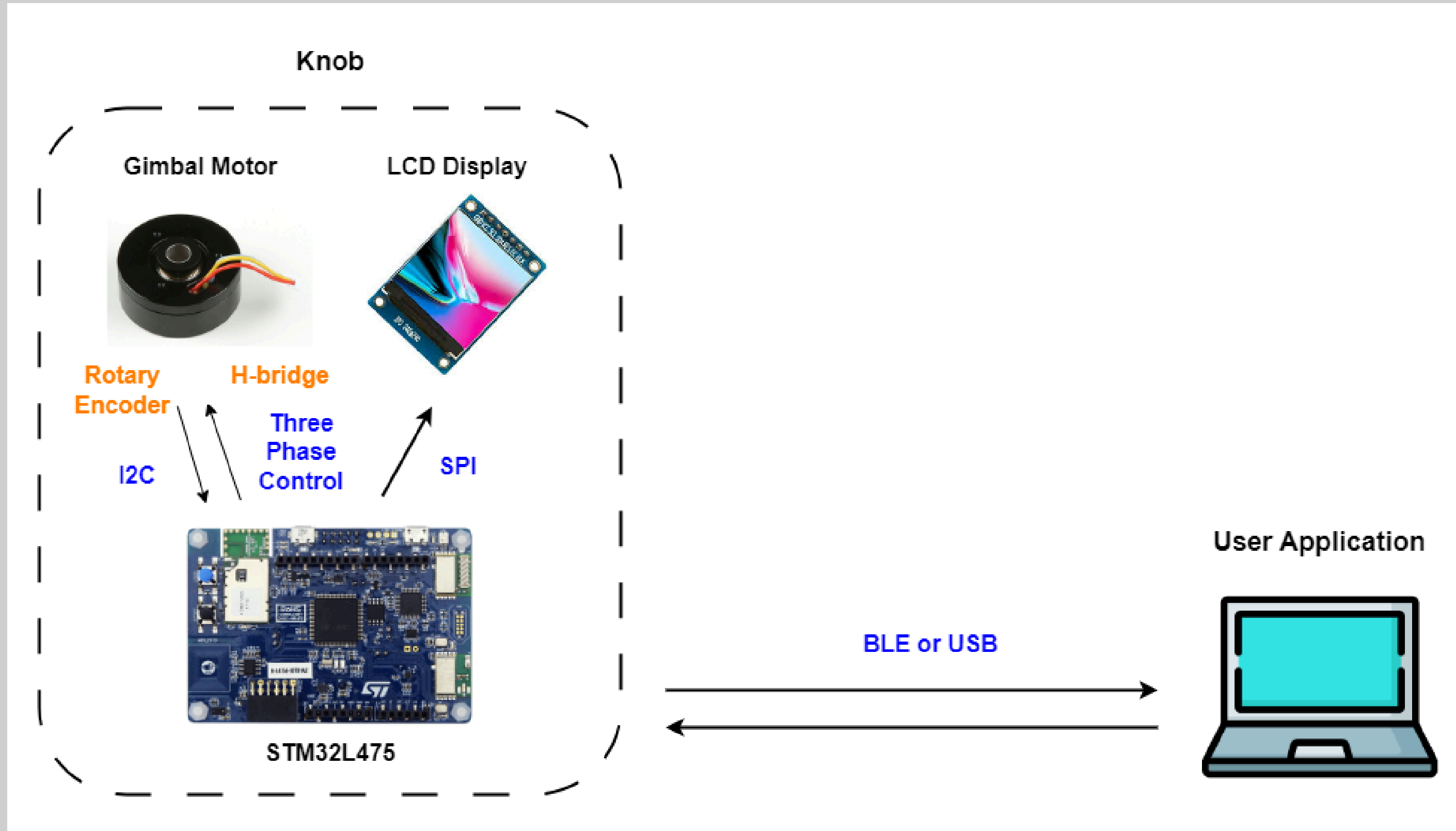
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Computer knob with FOC controlled gimbal motor



System diagram



Techniques used

- **Motor**

- FOC(Field Oriented Control)
- PID Controller
- I2C Communication

- **Device Connection**

- USB HID
- BLE / GATT

- **LCD Display**

- SPI Communication
- DMA

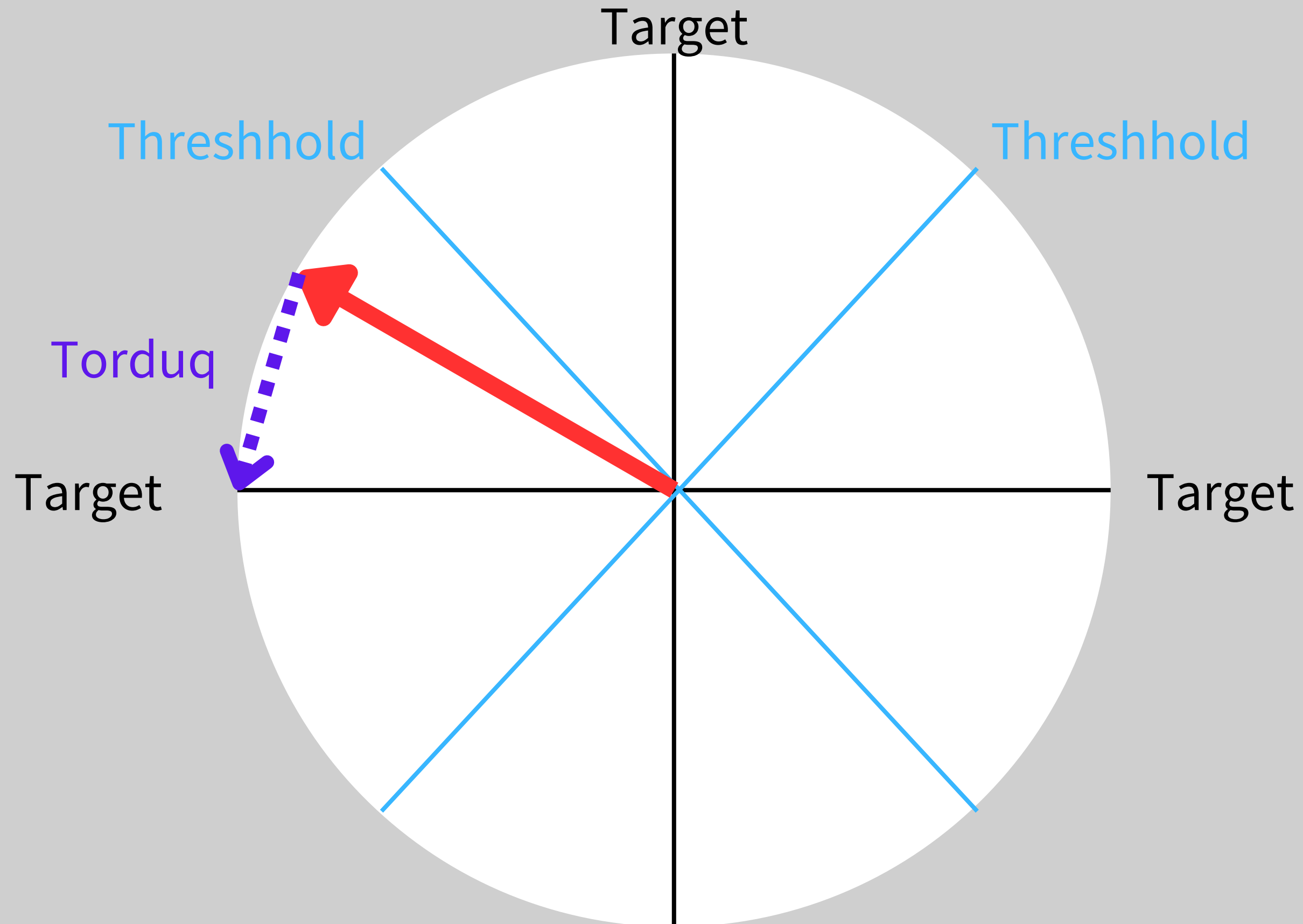
- **Project Stack**

- STM32 HAL driver
- CMake & Ninja build

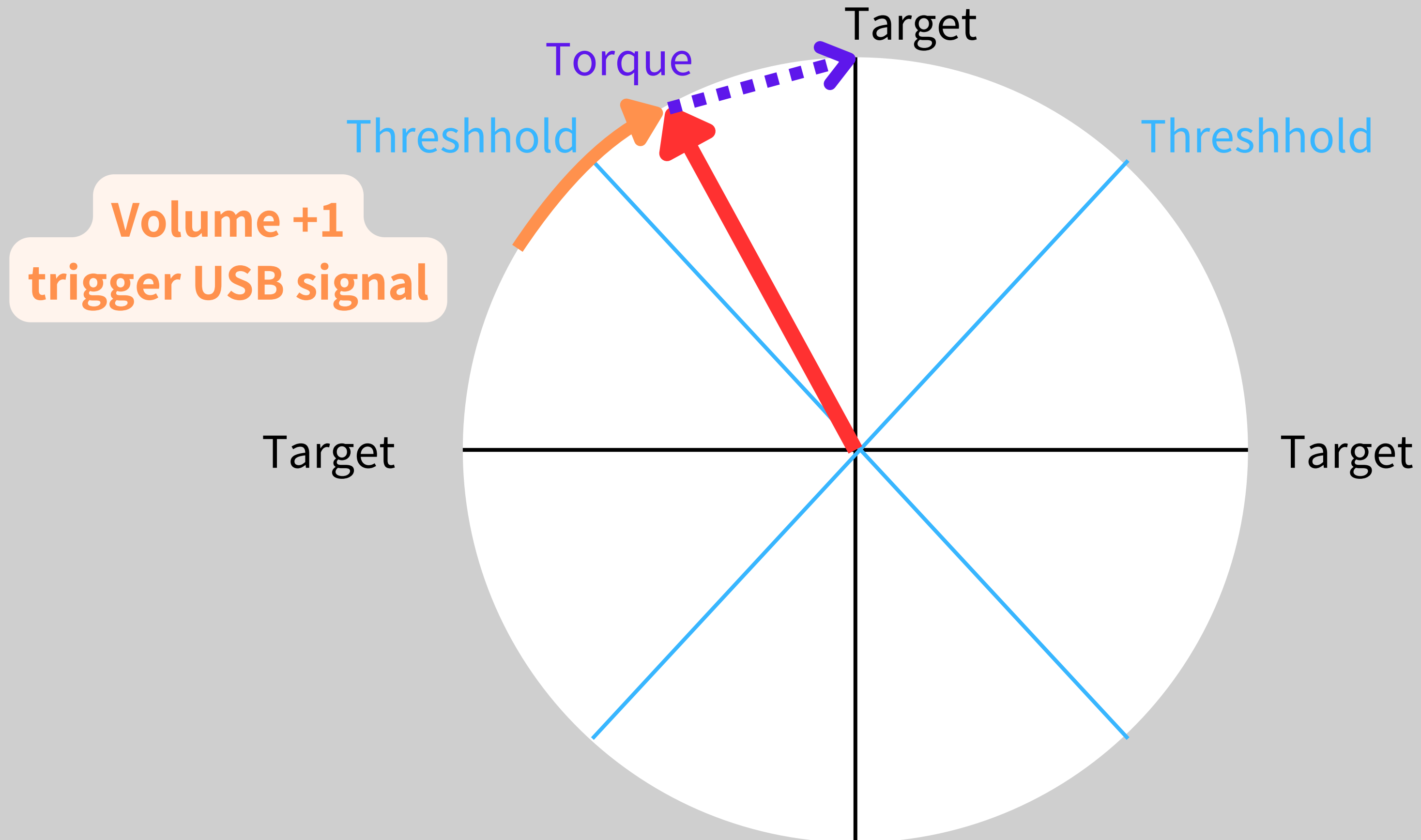
System integration

- **FOC motor control**
- **USB volume control**
- **TFT LCD control through SPI**
- **BLE task bridged with Windows application**

FOC with USB volume control



FOC with USB volume control



FOC with USB volume control

```
1  if (angle > ThresholdArray[Partition_Inx] && Partition_Inx < 10)
2  {
3      Partition_Inx++;
4      VOL_FLAG = 1;
5      target_angle = angleArray[Partition_Inx];
6  }
7  else if (angle < ThresholdArray[Partition_Inx - 1] && Partition_Inx > 0)
8  {
9      Partition_Inx--;
10     VOL_FLAG = -1;
11     target_angle = angleArray[Partition_Inx];
12 }
13
14
```

```
1  void volume_control(int flag)
2  {
3      hidbuffer2[0] = 0x00;
4      if (flag == 1)
5      {
6          HAL_Delay(2);
7          if (flag == 1)
8          {
9              hidbuffer2[0] = 0x01;
10             }
11         }
12     else if (flag == -1)
13     {
14         HAL_Delay(2);
15         if (flag == -1)
16         {
17             hidbuffer2[0] = 0x02;
18         }
19     }
20     USB_CUSTOM_HID_SendReport(&hUsbDeviceFS, hidbuffer2, 1);
21 }
```


TFT LCD control - SPI & DMA

Draw volume

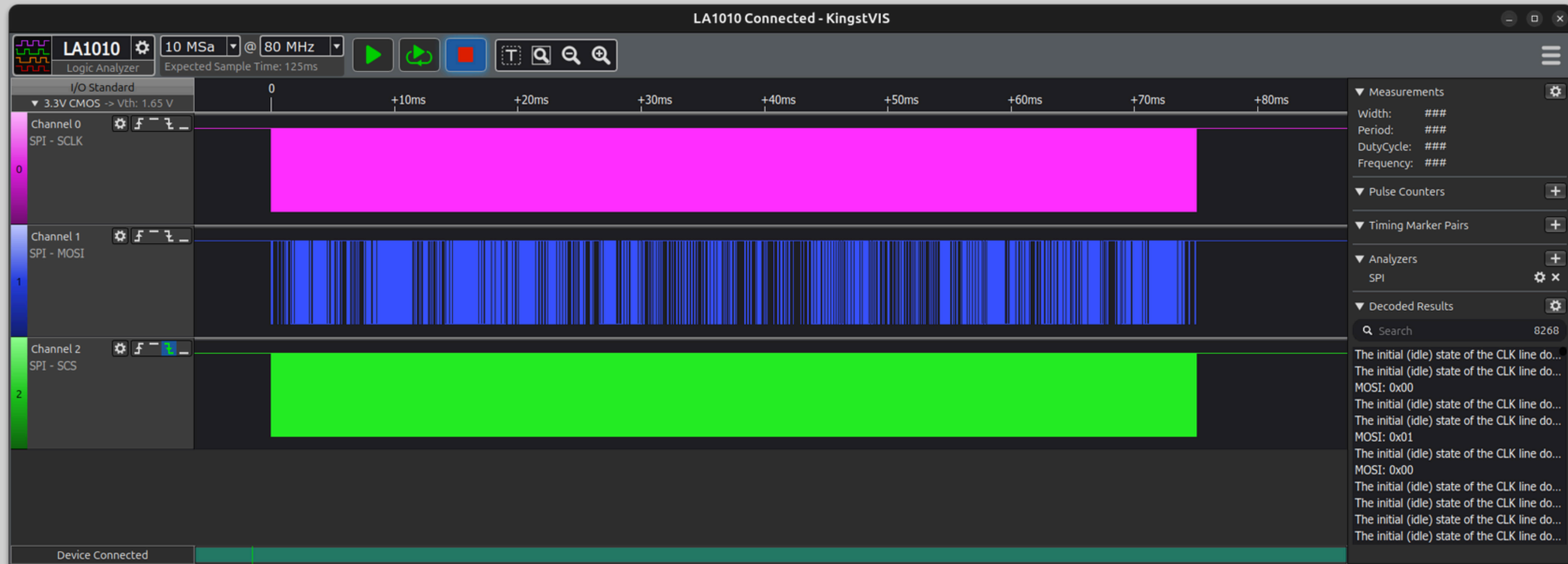
```
1  if (VOL_FLAG != 0)
2      {
3          sprintf(msg, "Vol: -", Partition_Inx);
4          ST7789_WriteString(10, 100, msg, Font_16x26, WHITE, BLACK);
5      }
```

Transfer data
through DMA

```
1  if (DMA_MIN_SIZE <= buff_size)
2      {
3          HAL_SPI_Transmit_DMA(&ST7789_SPI_PORT, buff, chunk_size);
4          while (ST7789_SPI_PORT.hdmatx->State != HAL_DMA_STATE_READY)
5              ;
6      }
```

SPI frame buffer time diagram

About 70 ms of data transfer handled my DMA



One frame data transfer

BLE integration with main task

```
1 void BLE_Task(void)
2 {
3     if (HAL_GPIO_ReadPin(BLE_INT_GPIO_Port, BLE_INT_Pin))
4     { // if an event occurs let's catch it
5         catchBLE();
6     }
7     updateSignedMillesimal(ANGLE_SERVICE_HANDLE, ENCODER_CHAR_HANDLE,
8                             ENCODER_VALUE, 10, Partition_Inx * 10);
9 }
```

According to the dial angular position (Partition index)
update the BLE service value

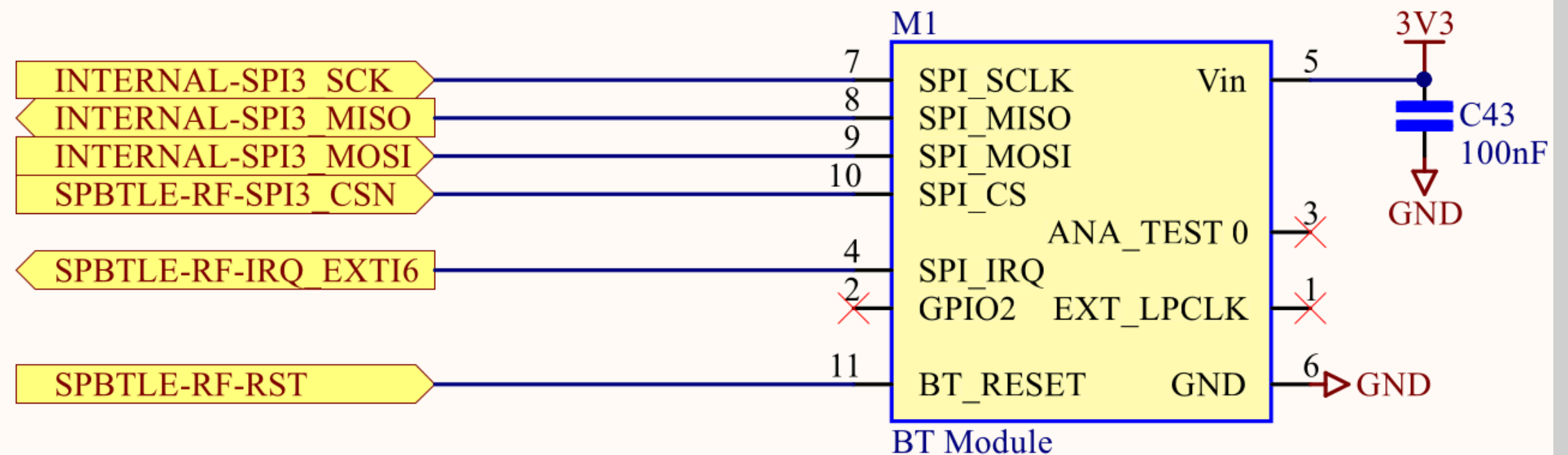
BLE: HCL & SPI

Using HCI command (legacy) interface with BLE on board module
For example: this command start the server advertisement



```
1  uint8_t ACI_GAP_SET_DISCOVERABLE[]={0x01,0x83,0xfc,0xff,0x00,0x40,0x06,0x40,0x06,0x01,0x00,0xff,0x09};
```

It is interfaced with SPI



Self-defined BLE Service on STM32

Self defined GATT characteristics

```
24 uint8_t UUID_ANGLE_SERVICE[] = {0x00,0x00,0x00,0x00,0x00,0x00,0x01,0x00,0x00,0x00,0x00,0x00,0x05,0x50,0x05,0x00};
25 uint8_t ANGLE_SERVICE_HANDLE[2];
26
27 // Characteristic
28 uint8_t UUID_CHAR_ENCODER[] = {0x01,0x00,0x00,0x00,0x00,0x00,0x03,0x00,0x00,0x00,0x00,0x00,0x00,0x50,0x05,0x00};
29 uint8_t ENCODER_CHAR_HANDLE[2];
30 uint8_t ENCODER_VALUE[]={ '{', '\'', 'A', 'n', 'g', 'l', 'e', '\'', ':', '\'', '+', '0', '0', '0', '0', '\'', '}' };
31
32 uint8_t UUID_CHAR_OUTPUT[] = {0x01,0x00,0x00,0x00,0x00,0x00,0x03,0x00,0x00,0x00,0x00,0x00,0x00,0x50,0x05,0x01};
33 uint8_t OUTPUT_CHAR_HANDLE[2];
34 uint8_t OUTPUT_VALUE[]={ '{', '\'', 'A', 'n', 'g', 'l', 'e', '\'', ':', '\'', '+', '0', '0', '0', '0', '\'', '}' };
```

```
// Add Service
addService(UUID_ANGLE_SERVICE, ANGLE_SERVICE_HANDLE, SET_ATTRIBUTES(1+2+3*2));
// Add Characteristic
addCharacteristic(UUID_CHAR_ENCODER, ENCODER_CHAR_HANDLE, ANGLE_SERVICE_HANDLE, SET_CONTENT_LENGTH(17), READABLE|NOTIFIABLE);
updateCharValue(ANGLE_SERVICE_HANDLE, ENCODER_CHAR_HANDLE, 0, SET_CONTENT_LENGTH(17), ENCODER_VALUE);

addCharacteristic(UUID_CHAR_OUTPUT, OUTPUT_CHAR_HANDLE, ANGLE_SERVICE_HANDLE, SET_CONTENT_LENGTH(17), WRITABLE);
updateCharValue(ANGLE_SERVICE_HANDLE, OUTPUT_CHAR_HANDLE, 0, SET_CONTENT_LENGTH(17), OUTPUT_VALUE);
```

```
// update encoder value
updateSignedMillesimal(ANGLE_SERVICE_HANDLE, ENCODER_CHAR_HANDLE, ENCODER_VALUE, 10, encoder_value);
```

Find GATT Characteristic on Win11

Find by UUID

(Note: services and characteristic need to be declared static)

```
private static GattDeviceService? gattService;  
2 references  
private static GattCharacteristic? gattCharacteristic;  
2 references
```

```
Guid serviceUuid = new Guid("00055005-0000-0000-0001-000000000000");  
Guid characteristicUuid = new Guid("00055000-0000-0000-0003-000000000001");
```

Subscribe to GATT Characteristic

Subscribe and add a handler

```
if (properties.HasFlag(GattCharacteristicProperties.Notify))
{
    GattCommunicationStatus status = await characteristic.WriteClientCharacteristicConfigurationDescriptorAsync(
        GattClientCharacteristicConfigurationDescriptorValue.Notify);
    if (status == GattCommunicationStatus.Success)
    {
        characteristic.ValueChanged += Characteristic_ValueChanged;
    }
}
```

Turn the bytes read into string and extract the values to set the volume of the PC

```
var reader = DataReader.FromBuffer(args.CharacteristicValue);
byte[] input = new byte[reader.UnconsumedBufferLength];
reader.ReadBytes(input);
string str = Encoding.ASCII.GetString(input);
Console.WriteLine($"receive: {str}");
int angleValue = ExtractValue(str);
Console.WriteLine($"Extracted value: {angleValue}");
VolumeController.SetVolume(angleValue);
```

Windows Side Extract Value read

Value format: {” <Angle>” :” +deg”}

```
private static int ExtractValue(string str)
{
    str = str.Trim(new char[] { '{', '}' });
    string[] split_str = str.Split(':');
    str = split_str[1].Trim(new char[] { '"', ' ' });
    str = str.TrimStart('+');
    return int.Parse(str);
}
```

Extract result: Angle

Set Volume with Windows API

Using CoreAudio API

```
1  using AudioSwitcher.AudioApi.CoreAudio;
2
3  namespace GATT_Client_Win11;
4
5  You, 2 days ago | 1 author (You) | 0 references
6  class VolumeController
7  {
8      1 reference
9      private static CoreAudioController audioController = new CoreAudioController();
10     1 reference
11     private static CoreAudioDevice playbackDevice = audioController.DefaultPlaybackDevice;
12
13     0 references
14     public static void SetVolume(int value)
15     {
16         playbackDevice.Volume = value;
17     }
18 }
```

You, 2 days ago • move windows GATT

Monitoring CPU Usage (WIP)

Using performance counter in System.Diagnostics API

```
PerformanceCounter cpuCounter = new PerformanceCounter("Processor", "% Processor Time", "_Total");
```

Calculate average CPU usage

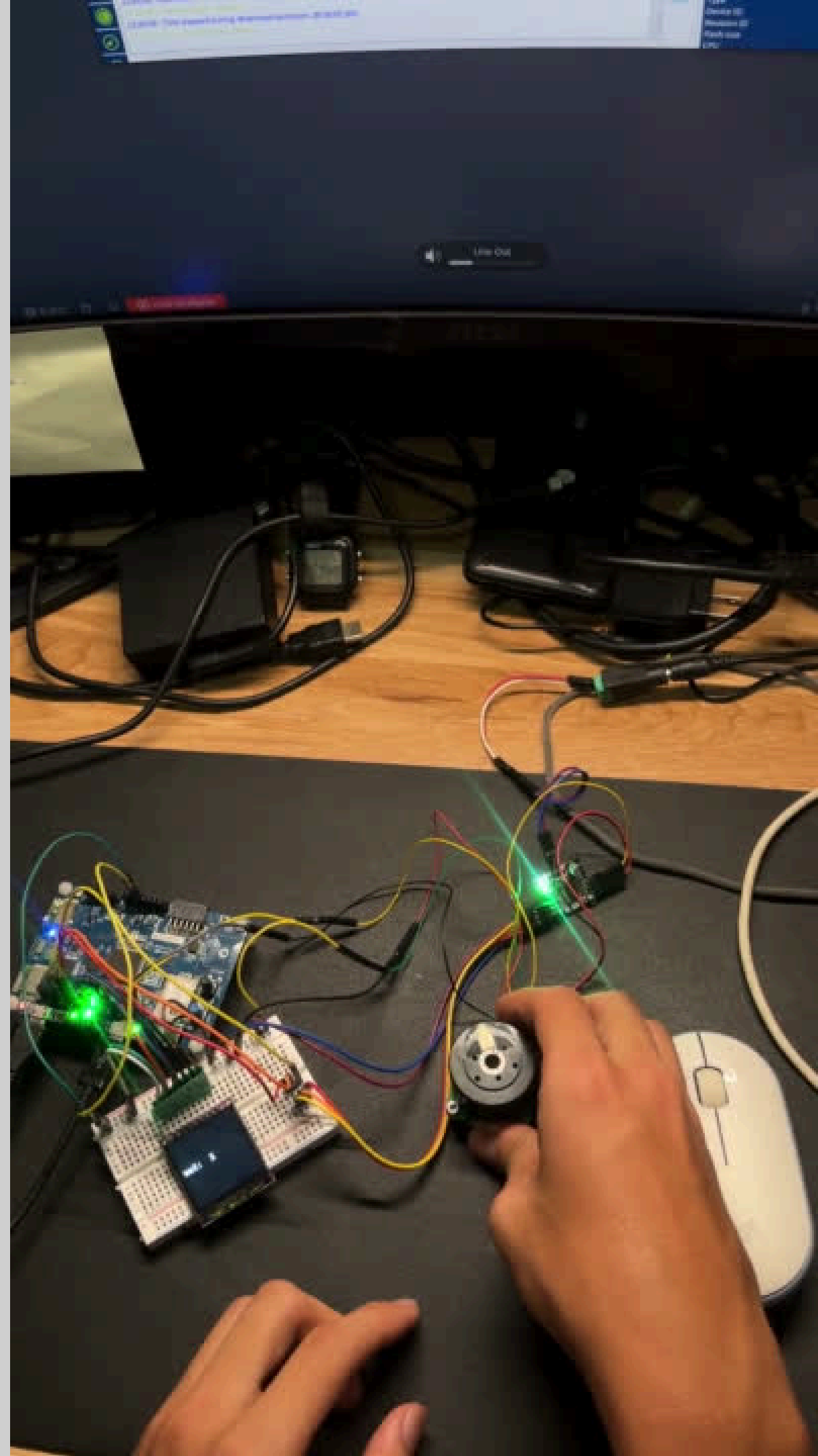
```
while (true)
{
    float[] samples = new float[5];
    for (int i = 0; i < samples.Length; i++)
    {
        samples[i] = cpuCounter.NextValue();
        Thread.Sleep(200); // Sample every 200ms for a total of 1 second
    }

    float averageCpuUsage = samples.Average();

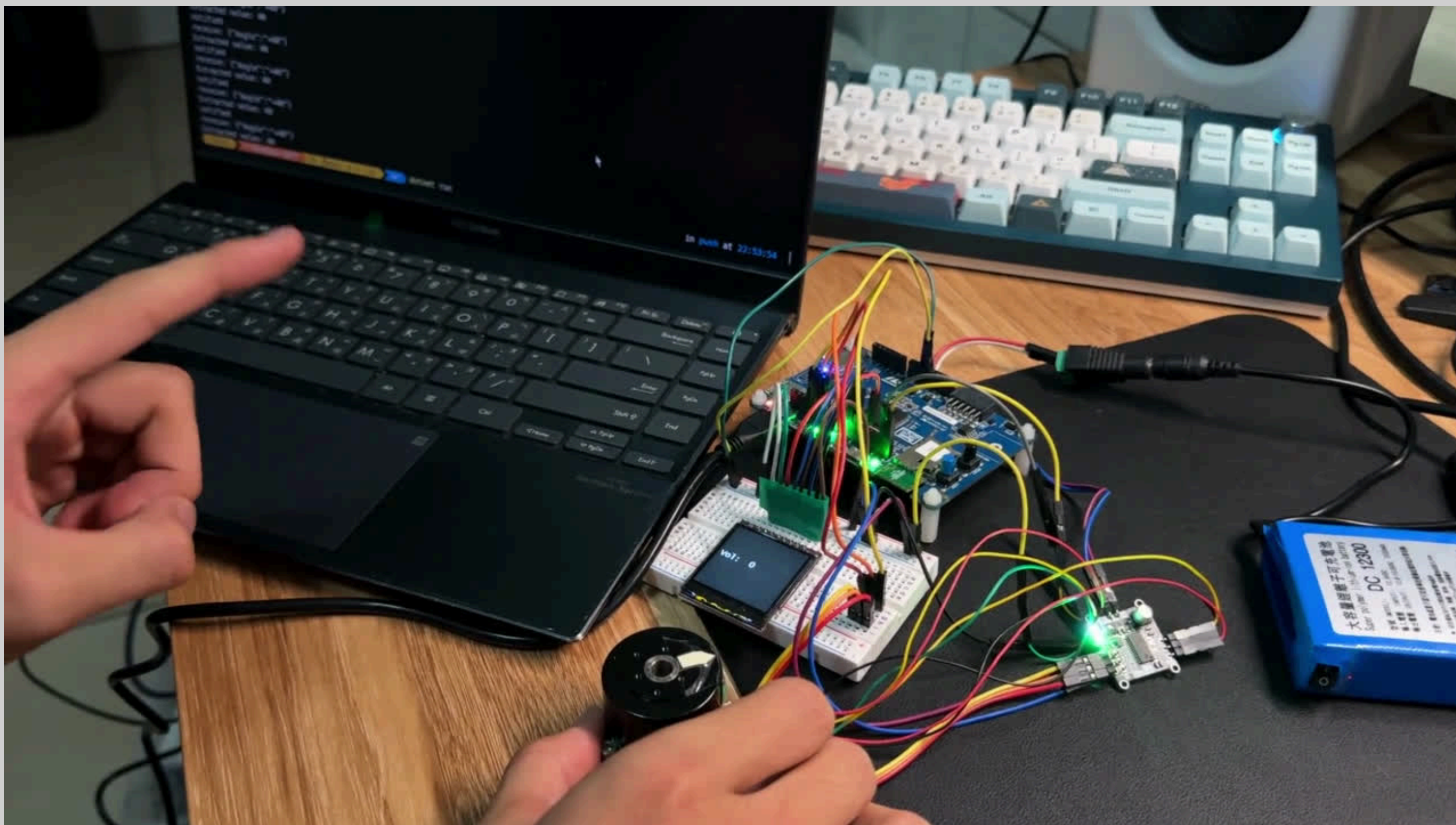
    // Print the average CPU usage percentage
    Console.WriteLine("Average CPU Usage: {0}%", averageCpuUsage);

    // Wait for a second before getting the next set of samples
    Thread.Sleep(1000);
}
```

Demo (USB)



Demo(BLE)



Reference

- <https://github.com/Floyd-Fish/ST7789-STM32>
- https://github.com/iot2tangle/STM32_B-L475E-IOT01A/tree/main/BLE-sender