

12C3 Last Day Basis & Dimension

A basis of a Vspace is a Linearly Independent & Spanning set of the space.

⇒ each basis of a Vspace gives a co-ordinate system in which vectors can be expressed uniquely

All bases of a given Vspace are same size
for a space V this is $\dim(V)$ the dimension
(can be a $\#$, can be ∞)

$$(\text{Size of LI sets}) \leq \dim V \leq (\text{Size of spans})$$

& if U is a subspace of V

$$\underline{\underline{\dim(U) \leq \dim(V)}}$$

$$U = V \\ \text{iff } \dim(U) = \dim(V)$$

Also last day showed if any two of

(1) spans, (2) LI (3) # vectors = $\dim(V)$

are true \Rightarrow all 3 are true \Rightarrow we have a basis

$$e.g. \left\{ \overset{\vec{u}_1}{\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}}, \overset{\vec{u}_2}{\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}}, \overset{\vec{u}_3}{\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}}, \overset{\vec{u}_4}{\begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}} \right\} = S$$

Is this a basis of M_{22} (2×2 matrices).

Solution (1) $\dim(M_{22}) = 4 = \underline{\# \text{ of vectors}}$ ✓
 $= n(S)$

Check L.I.

L.I. iff

$$a \vec{u}_1 + b \vec{u}_2 + c \vec{u}_3 + d \vec{u}_4 = 0$$

$$\text{iff } a = b = c = d = 0$$

that mean

$$a \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} + c \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + d \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

only for $a=b=c=d=0$

$$\left\{ \begin{array}{ll} a+c=0 & b+d=0 \\ b-d=0 & a-c=0 \end{array} \right\} \begin{array}{l} \text{could solve!} \\ \text{if } a=b=c=d=0 \\ \text{only } \Rightarrow \text{L.I.} \end{array}$$

or

as Lin. sys

$$\left\{ \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 1 & 0 & -1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right\} \begin{array}{l} \text{does this have} \\ \text{a } \underline{\text{unique soln?}} \end{array}$$

If \det of this \uparrow is $\neq 0 \Rightarrow$ invertible!
 \Rightarrow only 0 solution!

$$\begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & -1 \\ 1 & 0 & -1 & 0 \end{vmatrix} \begin{matrix} R_2 - R_1 \\ \\ R_3 - R_2 \\ \end{matrix} = \begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & -2 \\ 0 & 0 & -2 & 0 \end{vmatrix} \begin{matrix} \\ \text{Flip } R_3 \& R_4. \\ \\ \end{matrix}$$

$$= - \begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & -2 \end{vmatrix} \neq 0 \checkmark$$

\Rightarrow L.I. set!

The Wronskian

Detects L.I. functions

Wronskian of n functions is an $n \times n$ matrix determinant

$$\det \begin{pmatrix} f_1(x) & f_2(x) & f_3(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & \dots & f_n'(x) \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ f_1^{(n-1)}(x) & \dots & \dots & \dots & f_n^{(n-1)}(x) \end{pmatrix}$$

If Wron $\neq 0 \Rightarrow \{f_1(x), \dots, f_n(x)\}$ is L.I.

eg. Are $\sin(x)$ & $\cos(x)$ L.I.?

Solution

$$Wron = \det \begin{bmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{bmatrix}$$

$$= -\sin^2 x - \cos^2 x = -1 \neq 0 \quad \underline{\underline{L.I.}}$$



Orthogonality & Basis

We need to working in an "inner product space"

i.e. we need a real vspace & an inner product $\langle \vec{u}, \vec{v} \rangle$.

Remember

$\langle \vec{u}, \vec{v} \rangle$

input: 2 vectors in V

output: $\# \in \mathbb{R}$

Properties:

- 1) $\langle \vec{u}, \vec{v} \rangle = \langle \vec{v}, \vec{u} \rangle$
- 2) $\langle k\vec{u}, \vec{v} \rangle = k\langle \vec{u}, \vec{v} \rangle$
- 3) $\langle \vec{u} + \vec{w}, \vec{v} \rangle = \langle \vec{u}, \vec{v} \rangle + \langle \vec{w}, \vec{v} \rangle$
- 4) $\langle \vec{u}, \vec{u} \rangle \geq 0$ ($\|\vec{u}\|^2 = \langle \vec{u}, \vec{u} \rangle$)
- 5) $\langle \vec{u}, \vec{u} \rangle = 0 \iff \vec{u} = \vec{0}$

If $\vec{u}, \vec{v} \neq 0$ but $\langle \vec{u}, \vec{v} \rangle = 0 \Leftrightarrow$ orthogonal vectors

An orthogonal set is a set of non-zero vectors that
are pairwise orthogonal

ie. $\{ \vec{v}_1, \dots, \vec{v}_n \}$ such that $\vec{v}_i \cdot \vec{v}_j = 0$
iff $i \neq j$

An orthonormal set is a orthogonal set where all vectors
have length 1

ii. $\{ \vec{v}_1, \dots, \vec{v}_n \}$ such that $\vec{v}_i \cdot \vec{v}_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$

Note any orthogonal set is automatically L.I

Proof

Say $a_1 \vec{v}_1 + \dots + a_n \vec{v}_n = \vec{0}$

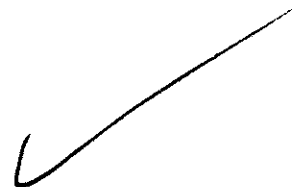
dot with any \vec{v}_i , say \vec{v}_1

$$a_1 \vec{v}_1 \cdot \vec{v}_1 + a_2 \cancel{\vec{v}_2 \cdot \vec{v}_1} + \dots + a_n \cancel{\vec{v}_n \cdot \vec{v}_1} = \vec{0} \cdot \vec{v}_1$$

$$\hookrightarrow a_1 \|\vec{v}_1\|^2 = 0$$

$$\|\vec{v}_1\| \neq 0 \Rightarrow a_1 = 0$$

by same logic, any $a_i = 0 \Rightarrow$ v_i L.I
(only!)



If I have an orthogonal basis, i.e. $n(\text{set}) = \dim V$

\Rightarrow very pretty co-ordinate calculation!

If $\vec{u} \in \text{Span}(\{\vec{v}_1, \dots, \vec{v}_n\})$

$$\Rightarrow \vec{u} = a_1 \vec{v}_1 + \dots + a_n \vec{v}_n$$

$$\langle \vec{u}, \vec{v}_i \rangle = a_1 \langle \cancel{\vec{v}_1}, \vec{v}_i \rangle + \dots + a_n \langle \cancel{\vec{v}_n}, \vec{v}_i \rangle$$

$$= a_i \cdot \|\vec{v}_i\|^2$$

$$a_i = \langle \vec{u}, \vec{v}_i \rangle / \|\vec{v}_i\|^2$$

& \vec{v} 's are orthonormal

$$a_i = \langle \vec{u}, \vec{v}_i \rangle$$