

17C3

Last Day adj & det

If  $A$  is invertible, then

$$A^{-1} = \text{adj } A \cdot \frac{1}{\det A}$$

& remember:  $\text{adj } A = (\text{transpose of matrix of cofactors of } A)$   
 $= [C_{ji}]$

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eg. If  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ , use above  $\uparrow$  to find  $A^{-1}$  (if exists!)

Solution

$$\det(A) = ad - bc$$

$$\text{adj } A = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}^T = \begin{bmatrix} C_{11} & C_{21} \\ C_{12} & C_{22} \end{bmatrix}$$

$$= \begin{bmatrix} (+1)M_{11} & (-1)M_{21} \\ (-1)M_{12} & (+1)M_{22} \end{bmatrix} = \begin{bmatrix} M_{11} & -M_{21} \\ -M_{12} & M_{22} \end{bmatrix} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\text{so } A^{-1} = \text{adj } A \cdot \frac{1}{\det A} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \cdot \frac{1}{ad-bc}$$

Megatheorem Recap (The Theorem so far!)

If  $A$  is an  $n \times n$  matrix, the following are all equivalent

- 1)  $A$  invertible
- 2)  $A$  row-equivalent to  $I$  (RREF form)
- 3)  $A$  is a product of elementary matrices.
- 4)  $A\vec{x} = \vec{b}$  has a unique solution.
- 5)  $A\vec{x} = \vec{b}$  always has a solution.
- 6)  $A\vec{x} = \vec{0}$  has only  $\vec{x} = \vec{0}$  (trivial) solution

New!

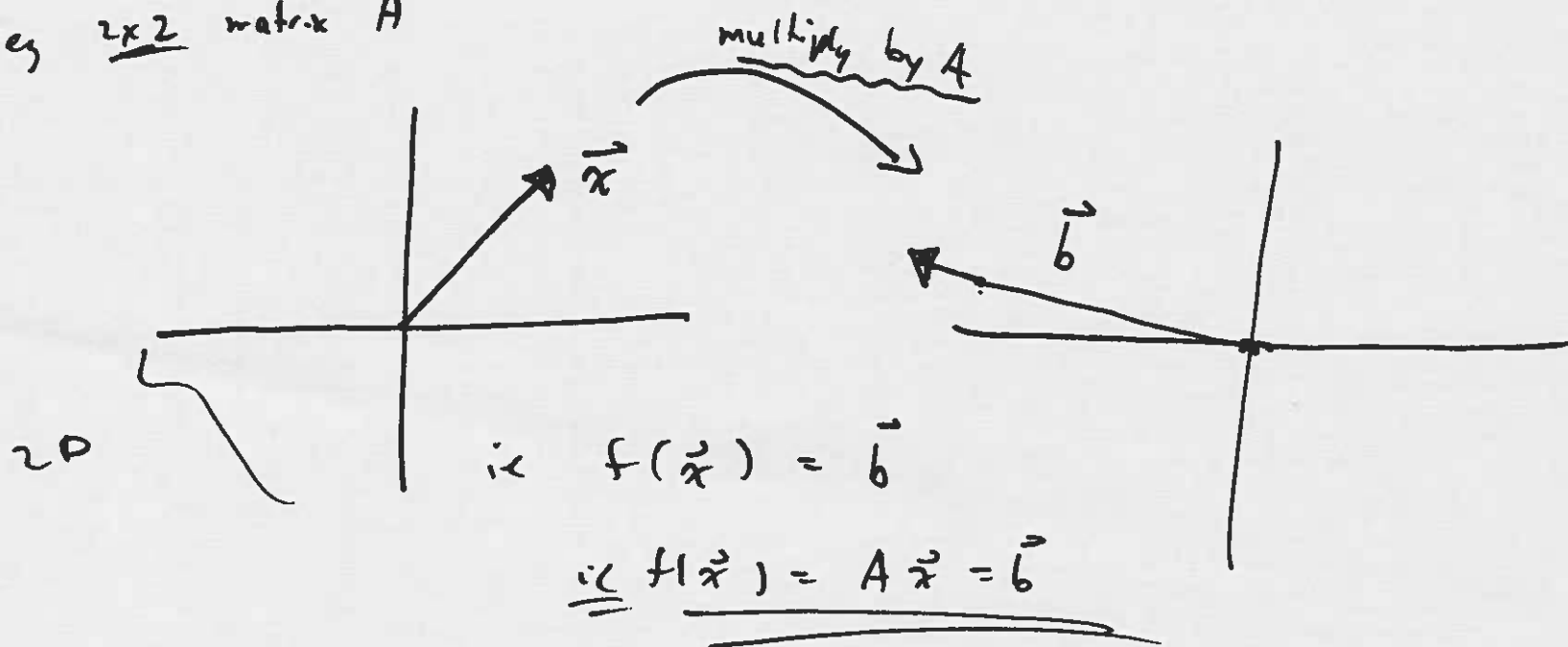
$$7) \underline{\underline{\det A \neq 0}}$$

# Eigenvectors & Eigenvalues

We've seen linear systems expressed as

$$\begin{array}{c} \text{coeff} \quad \text{variables} \\ \swarrow \quad \searrow \\ A \vec{x} = \vec{b} \end{array} \quad \begin{array}{c} \text{const.} \\ \nwarrow \quad \nearrow \end{array} \quad \left. \vphantom{\begin{array}{c} A \vec{x} = \vec{b} \end{array}} \right\} \begin{array}{l} \text{system as} \\ \text{a matrix} \\ \text{product} \end{array}$$

eg 2x2 matrix  $A$



In words: An eigenvector of a square matrix  $A$  is a vector for which mult. by  $A$  acts like mult. by

a real number

single

This real number is the eigenvalue

In symbols  $\vec{x}$  is a  $\lambda$ -eigenvector of a square matrix  $A$

means

$$\boxed{A \vec{x} = \lambda \vec{x}}$$

$\lambda \neq 0$

$\lambda$  is our eigenvalue!

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eg. If I tell you that  $\begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix}$  is the  $\lambda = 3$  eigenvector of a matrix  $A$  then!

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -6 \\ 3 \\ 9 \end{bmatrix}$$

$A \quad \vec{x} = \lambda \vec{x}$

$$\lambda = 3$$

Notice

Say  $A \vec{x} = \lambda \vec{x}$  for some  $\lambda$ ,  $\vec{x} \neq 0$

$$\underline{A(k \vec{x})} = k A \vec{x} = k \cdot \lambda \vec{x} = \lambda \cdot (k \vec{x})$$

If  $\vec{x}$  is an eigenvector, any non-zero multiple is an eigenvector.

Also

Say  $\vec{x}, \vec{y} \neq 0$  &  $A \vec{x} = \lambda \vec{x}$ ,  $A \vec{y} = \lambda \vec{y}$  for

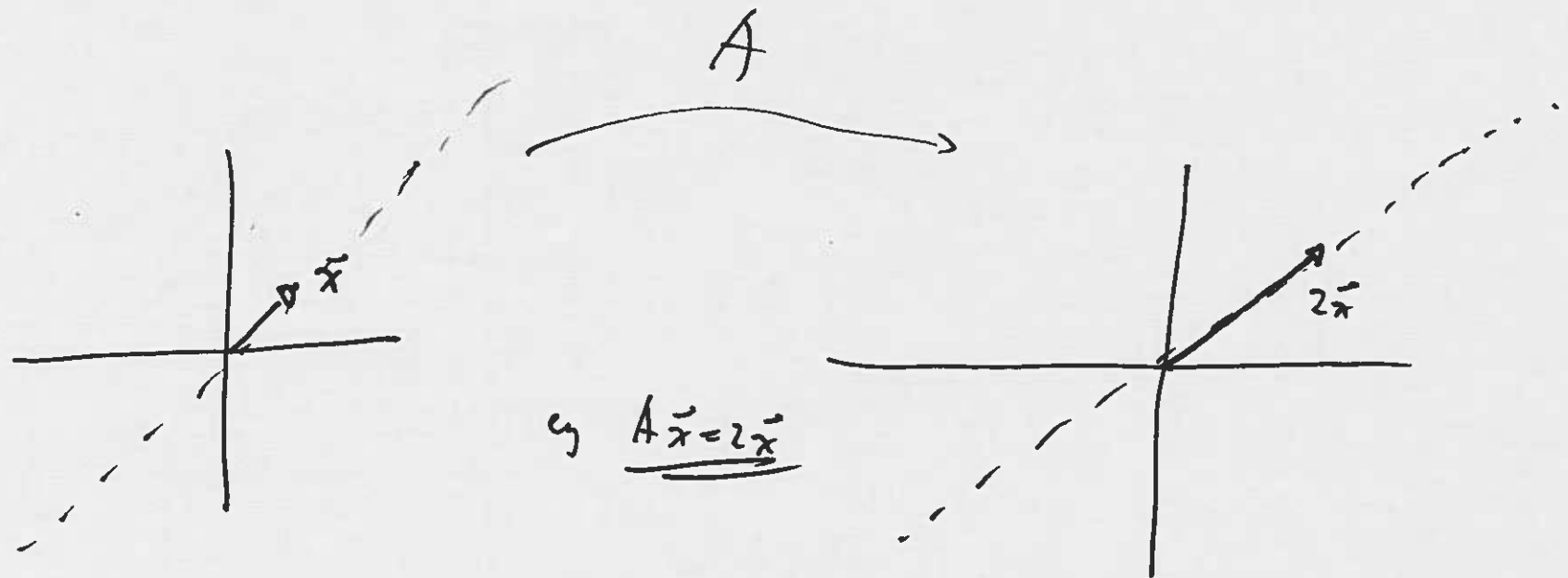
the same  $\lambda$

$$\Rightarrow A(\vec{x} + \vec{y}) = A(\vec{x}) + A(\vec{y})$$

$$= \lambda \vec{x} + \lambda \vec{y}$$

$$= \lambda(\vec{x} + \vec{y})$$

So, if  $\vec{x} \neq -\vec{y}$ ,  $\vec{x} + \vec{y}$  is still a  $\lambda$ -eigenvector!



(all  $\lambda$ -eigenvectors &  $\vec{0}$ )

The set of all  $\vec{x}$  such that  $A\vec{x} = \lambda\vec{x}$  is called

our  $\lambda$ -eigenspace & is preserved by action of  $A$ .

## Hunting Eigenvectors & Eigenvalues

If  $\vec{x} \neq 0$  &  $A\vec{x} = \lambda\vec{x}$  &  $A$  square

then  $A\vec{x} - \lambda\vec{x} = \vec{0}$   $\Leftrightarrow$

$$(A - \lambda I)\vec{x} = \vec{0} \quad \text{for } \underline{\underline{\vec{x} \neq 0}}$$

$(A - \lambda I)\vec{x} = \vec{0}$  has non-trivial soln!

$\Leftrightarrow A - \lambda I$  is non-invertible!

$$\Leftrightarrow \det(A - \lambda I) = 0$$

Reversible argument!

so IF  $\det(A - \lambda I) = 0$   $\Rightarrow$

$\lambda$  is an eigenvalue of  $A$   
&  $\vec{x}$  eigenvector exist

$$C_A(\lambda) = |A - \lambda I| = \text{characteristic polynomial}$$

roots of  $C_A(\lambda)$  are eigenvalues of  $A$

eg. Let  $A = \begin{bmatrix} 2 & 1 \\ 6 & 1 \end{bmatrix}$

$$C_A(\lambda) = |A - \lambda I| = \left| \begin{bmatrix} 2 & 1 \\ 6 & 1 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} \right|$$

$$= \begin{vmatrix} 2-\lambda & 1 \\ 6 & 1-\lambda \end{vmatrix}$$

$$= (2-\lambda)(1-\lambda) - 6$$

$$= \lambda^2 - 3\lambda - 4$$

$$(\lambda - 4)(\lambda + 1) = 0$$

$$\lambda = 4, -1$$