

12C3

Remember extra "C" chapter 10.1, 10.2, 10.3  
Online only

Linked with textbook practice problems!

Last Day  $z$  in better polar form!

$$z = r e^{i\theta}$$

$$\underline{e^{i\theta} = \cos\theta + i\sin\theta = \underline{\underline{cis\theta}}}$$

$r = \text{modulus of } z = \sqrt{a^2 + b^2} = |z|$

$\theta = \arg(z) \Rightarrow \underline{\underline{\tan\theta = b/a}}$

$$e^{i\pi} = \cos\pi + i\sin\pi$$

$$\Rightarrow \underline{\underline{e^{i\pi} = -1}}$$

$$\underline{\underline{\text{choose } \theta \in (-\pi, \pi]}}$$

(or in some texts:  $\in [0, 2\pi)$ )

Roots in  $\mathbb{C}$  Find all 4th roots of  $16i$

Solution

4th root is  $z \Rightarrow z^4 = 16i$

In polar

$$z = r e^{i\theta}$$

$$16i \Rightarrow |16i| = 16$$

$$\arg(16i) = \pi/2$$

(by inspection!)

$$(r e^{i\theta})^4 = 16 e^{i\pi/2}$$

$$r^4 e^{i4\theta} = 16 e^{i\pi/2}$$

$$\Rightarrow \text{modulus equal} \Rightarrow r^4 = 16 \Rightarrow r = 16^{1/4} = \underline{\underline{2}} \quad (r > 0)$$

$$\Rightarrow \text{equivalent arguments} \Rightarrow 4\theta = \pi/2 + 2n\pi$$

$$\theta = \pi/8 + \frac{2n\pi}{4} \rightarrow n\pi/2$$

$$\underline{n=0}$$

$$\theta = \pi/8$$

$$\underline{n=1}$$

$$\theta = \pi/8 + \pi/2 = 5\pi/8$$

$$\underline{n=2}$$

$$\theta = \pi/8 + \cancel{2\pi/2}^{+\pi} = 9\pi/8$$

$$\underline{n=3}$$

$$\theta = \pi/8 + 3\pi/2 = 13\pi/8$$

$$\underline{n=4}$$

$$\theta = \pi/8 + \cancel{4\pi/2}^{2\pi}$$

Solution

$$\therefore z^4 = 16i \Rightarrow z = 2 \cdot e^{i\pi/8} \quad (1)$$

$$\text{or } 2 \cdot e^{i5\pi/8} \quad (2)$$

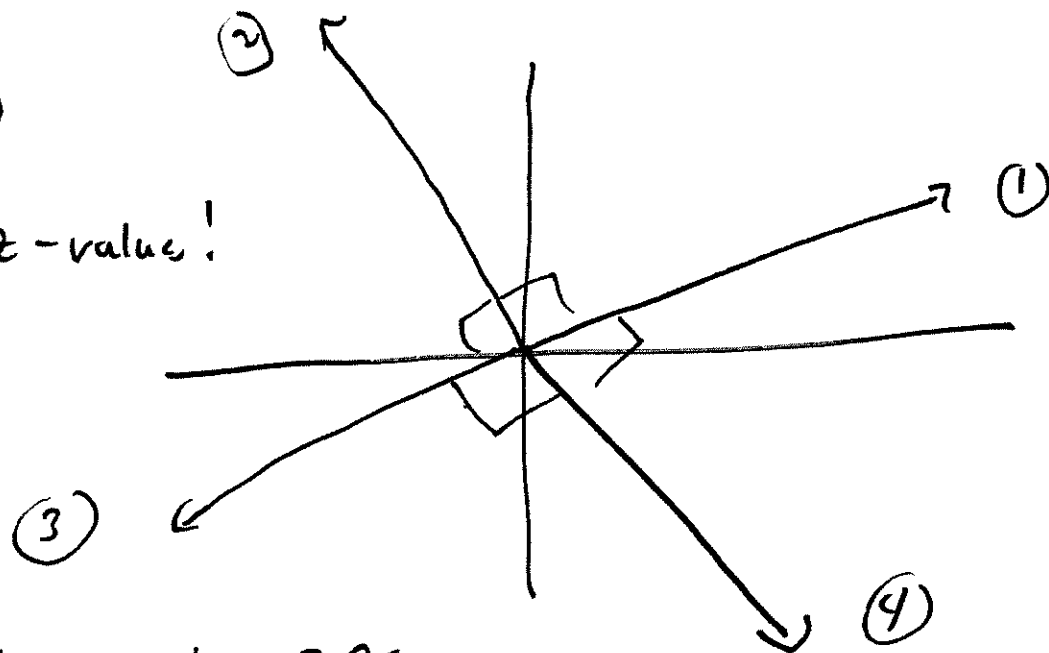
$$\text{or } 2 \cdot e^{i9\pi/8} \quad (3)$$

$$\text{or } 2 \cdot e^{i13\pi/8} \quad (4)$$

If  $z^n = w$

$n$  possible  $z$ -values!

$|z| = |w|^{1/n}$



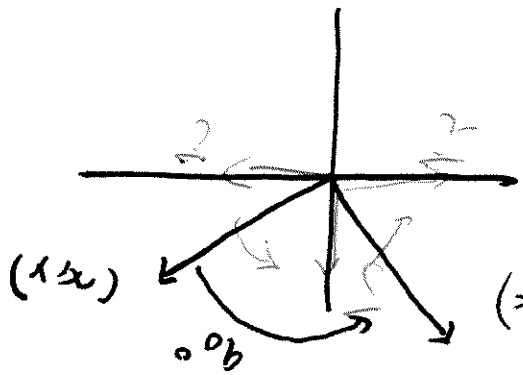
4th root  
 $\Rightarrow$  4 roots!

arguments differ by  $\frac{2\pi}{n}$ .

Now we can have Complex matrices!

eg  $A = \begin{bmatrix} 2i & 6-i \\ 7i & +2-3i \end{bmatrix}$

Complex  $\lambda$   
Complex  $\det(A)$ !



$$B \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ x \end{bmatrix}$$

$$B \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$B \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

nohu

$$\lambda^2 + 1 = 0 \Rightarrow \lambda = \pm i$$

$$\lambda^2 + 1 = \begin{vmatrix} \lambda - 1 & 1 \\ 1 & \lambda - 1 \end{vmatrix} =$$

$$C_B(\lambda) = |\lambda I - B|$$

$$B = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

Turns out it was the all along!

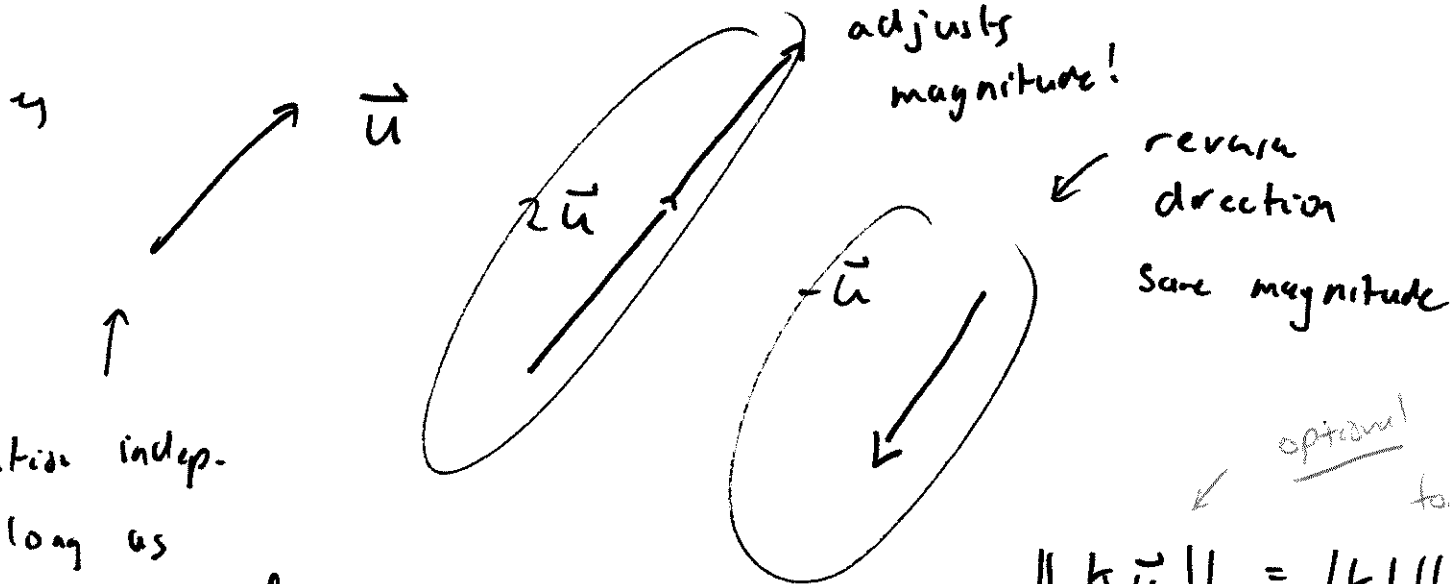
# Vectors



old definition

"a vector is a quantity with direction & magnitude"

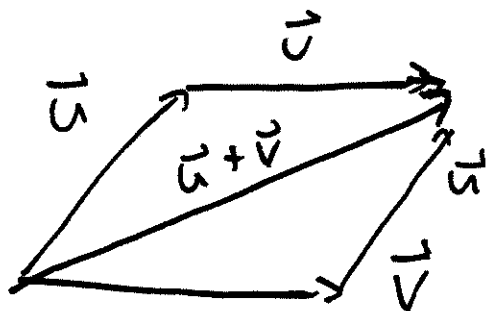
e.g. velocity, force, displacement,  $\vec{E}$  etc.



optional double bars for vector magnitude!

$$\|k\vec{u}\| = |k|\|\vec{u}\|$$

location indep.  
"=" as long as  
same direction &  
magnitude

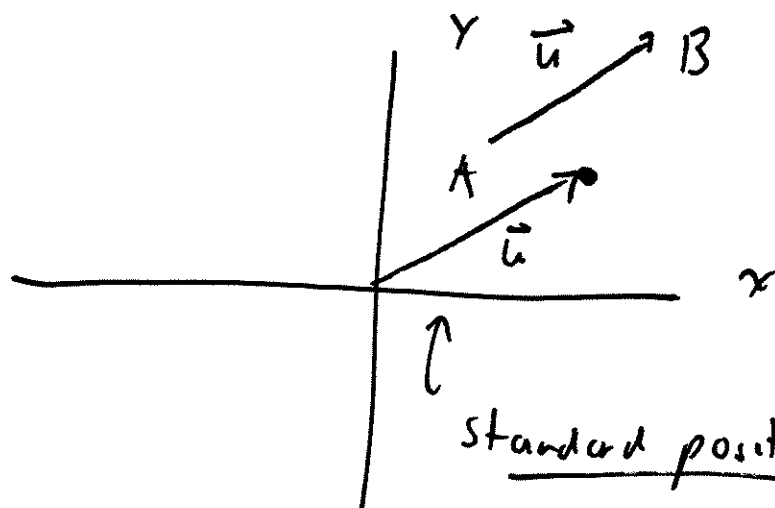


$$\vec{u} + \vec{v} = \vec{v} + \vec{u}$$

parallelogram law

or "triangle" law

Descartes!



$$A = (a_1, a_2)$$

$$B = (b_1, b_2)$$

$$\vec{u} = \overrightarrow{AB}$$

standard position! ("start" at  $(0, 0)$ )

$$\vec{u} \text{ related to } \underline{\text{position of tip}} = (b_1 - a_1, b_2 - a_2)$$

$$= \underline{(u_1, u_2)}$$

$$\|\vec{u}\| = \sqrt{u_1^2 + u_2^2} \quad \left. \vphantom{\|\vec{u}\|} \right\} \text{ by } \underline{\text{Pythagoras!}}$$

"Euclidean norm"

$$k\vec{u} = (ku_1, ku_2) \Rightarrow \|k\vec{u}\| = |k| \|\vec{u}\|.$$

$$-\vec{u} = (-u_1, -u_2) \Rightarrow \text{opposite direction!}$$

$$\begin{aligned} \vec{u} + \vec{v} &= (u_1, u_2) + (v_1, v_2) = (u_1 + v_1, u_2 + v_2) \\ &= \vec{v} + \vec{u}, \quad \text{just like } \underline{\underline{\text{group law}}} \end{aligned}$$

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$$\text{eg. } (2, 7) + (1, 1) = (3, 8)$$

$$3(-6, 1) = (-18, 3)$$

note addn follows:

$$\vec{u} + \vec{v} = \vec{v} + \vec{u}$$

$$k(\vec{u} + \vec{v}) = k\vec{u} + k\vec{v}$$

$$\vec{u} + (\vec{v} + \vec{w}) = (\vec{u} + \vec{v}) + \vec{w} = \underline{\underline{\vec{u} + \vec{v} + \vec{w}}}$$