## Deep-Q Learning

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## 1 Decision Problems

In finance, optimization and associated techniques play a central role. Finance is nothing but the systemic application of optimization techniques to problems of a financial context. Here are the different optimization problems:

- Discrete vs Continuous Action Space: the quantites or action to be chosen through optimization can be from a set of finite, discrete options (optimal choice) or from a set of inifnite, continuous options (optimal control)
- Static vs Dynamic Problems: static problems are one-off optimization problems, dynamic problems are characterized by a typically large number of sequential and connected optimization problems
- Finite vs Infinite Horizon: dynamic optimization problems have a finite or infinite horizon. Playing a game of chess has a finite horizon. Climate policy is a descision problem with infinite horizons.
- Discrete vs Continuous Time: some dynamic problems only require discrete decisions and optimizations at different points in time, such as chess. Other dynamic problems require continuous decisions and optimizations. For example, driving a car.

## 2 Q-Learning

QL is based on an agent interacting with the environment and learning from the ensuing experiences through rewards and penalties. A QL agent takes actions based on two principles:

- Exploitation: refers to the actions taken by the QL agent under the current optimal policy QL
- Exploration: refers to actions taken by a Ql agent that are random. The purpose is to explore random actions and their associated values beyond what the current optimal policy would dictate

A QL agent usually follows a  $\epsilon$ -greedy strategy, where  $\epsilon$  is defined as the ratio with which the agent relies on exploration as compared to exploitation. During training, it is assumed that the  $\epsilon$  decreases with a increasing number of training units.

## 2.1 Deep Q-Learning

In DQL, the policy Q is regularly updated through *replay*. For replay, the agent stores passed experiences such as (state, actions, rewards and next states and etc.) and use small batches from the memorized experiences to retrain the DNN.