

Ensemble Sensitivity Analysis

A Practical Introduction

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StuMeTa 2021

Overview

- 3 Hours
- 3 Parts:
 1. Introduction (theory) and sensitivity pattern quiz
 2. Practical considerations and normalization (hands-on)
 3. Example from the literature (hands-on)

You can **interrupt me at any time**, please ask questions!

Part I

- Sensitivity Analysis
- From Ensemble Regression to ESA
- Sensitivity Maps: Construction, Interpretation
- Quiz

Sensitivity Analysis

(How (much)) does T change when S changes?

Sensitivity Analysis

(How (much)) does T change when S changes?

Examples:

- How do initial condition errors affect forecast performance?
- Where should I add observations to improve a forecast?
- Where and when did an error in the forecast first develop?
- Which region should I pay attention to in the next forecast?
- How are different state variables related?

Sensitivity Analysis: Techniques

- **Climatological analysis** (e.g. composites)

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- **Deterministic modelling**
 - Data denial
 - Relaxation
 - Adjoint sensitivities

Sensitivity Analysis: Techniques

- **Climatological analysis** (e.g. composites)
- **Deterministic modelling**
 - Data denial
 - Relaxation
 - Adjoint sensitivities
- **Probabilistic modelling**
 - Ensemble Sensitivity Analysis
 - Clustering

Ensemble Synoptic Analysis

- Introduced as general term (Hakim and Torn 2008)
- **Regression techniques**
- Extract information from ensemble forecasts

Idea:

- Apply regression “**along**” the ensemble/**member dimension**
- In ML terms: the **ensemble** provides the **training dataset**

Ensemble Regression

Multivariate Regression

- Each ensemble member provides one data point for “training”

Steps:

1. Pick a **target** / forecast metric(s) / predictand(s): T
2. Pick a **source** / analysis field(s) / predictors: S
3. Train a **regression model** with ensemble: $T = f(S)$
4. Analyse model or use it for perturbation experiments

Ensemble Regression: Linear Model

Perturbations: $\hat{\mathbf{S}} = \mathbf{S} - \bar{\mathbf{S}}$ and $\hat{\mathbf{T}} = \mathbf{T} - \bar{\mathbf{T}}$

Linear Model: $\hat{\mathbf{T}} = \mathbf{L} \hat{\mathbf{S}}$

Ensemble Regression: Linear Model

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Linear Model: $\hat{\mathbf{T}} = \mathbf{L} \hat{\mathbf{S}}$ (right multiply by $\hat{\mathbf{S}}^T$)

$$\Leftrightarrow \hat{\mathbf{T}} \hat{\mathbf{S}}^T = \mathbf{L} \hat{\mathbf{S}} \hat{\mathbf{S}}^T$$

Ensemble Regression: Linear Model

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$$\Leftrightarrow \hat{\mathbf{T}} \hat{\mathbf{S}}^T = \mathbf{L} \hat{\mathbf{S}} \hat{\mathbf{S}}^T$$

$$\Leftrightarrow \text{cov}(\mathbf{T}, \mathbf{S}) = \mathbf{L} \text{cov}(\mathbf{S}, \mathbf{S})$$

Ensemble Regression: Linear Model

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$$\Leftrightarrow \hat{\mathbf{T}} \hat{\mathbf{S}}^T = \mathbf{L} \hat{\mathbf{S}} \hat{\mathbf{S}}^T$$

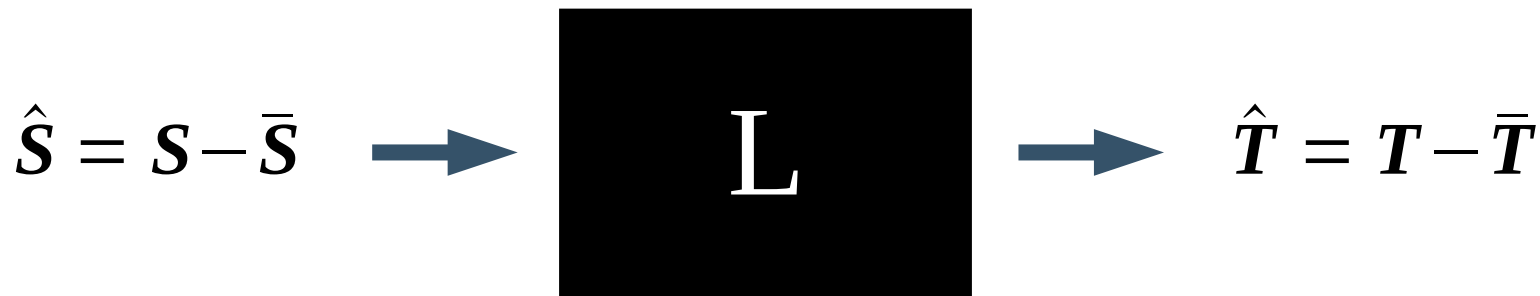
$$\Leftrightarrow \text{cov}(\mathbf{T}, \mathbf{S}) = \mathbf{L} \text{cov}(\mathbf{S}, \mathbf{S})$$

$$\Rightarrow \mathbf{L} = \text{cov}(\mathbf{T}, \mathbf{S}) \text{cov}(\mathbf{S}, \mathbf{S})^{-1}$$

Ensemble Regression: Sensitivity

Perturbation-based workflow:

1. Select source and target variables
2. Determine L for \hat{S} , \hat{T} relationship with ensemble
3. Prescribe a perturbation \hat{S}
4. Examine the target response $\hat{T} = L\hat{S}$



Ensemble Regression: Issues

- **Ill conditioned** (large state space, small ensemble)
- Perturbation-based workflow **doesn't scale** well
 - Trial-and-error approach difficult to automate
 - Hard to visualize effectively

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Is it possible to **visualize L directly**?

→ **ESA: yes**, but we have to simplify

Ensemble Sensitivity Analysis

Reminder: $L = \text{cov}(\mathbf{T}, \mathbf{S}) \text{cov}(\mathbf{S}, \mathbf{S})^{-1}$

Simplifications:

1. Restriction to scalar target: $\mathbf{T} \rightarrow t$

Ensemble Sensitivity Analysis

Reminder: $L = \text{cov}(\mathbf{T}, \mathbf{S}) \text{cov}(\mathbf{S}, \mathbf{S})^{-1}$

Simplifications:

1. Restriction to scalar target: $\mathbf{T} \rightarrow t$
2. Ignore off-diagonal elements in $\text{cov}(\mathbf{S}, \mathbf{S})$

$$\text{cov}(\mathbf{S}, \mathbf{S})^{-1} \rightarrow \begin{pmatrix} \sigma_{s_1}^{-2} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_{s_m}^{-2} \end{pmatrix}$$

Ensemble Sensitivity Analysis

Simplifications:

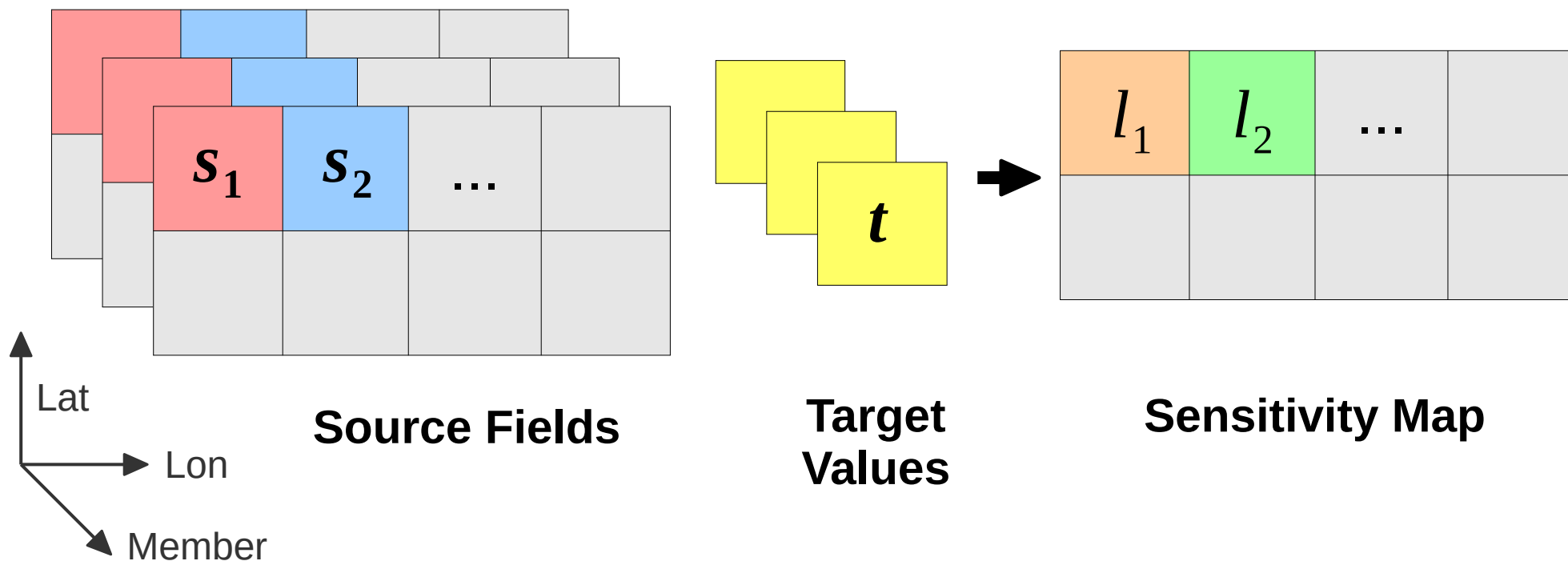
1. Restriction to scalar target: $T \rightarrow t$
 2. Ignore off-diagonal elements in $\text{cov}(\mathbf{S}, \mathbf{S})$
- **independent univariate regression** for every s_i :

$$\mathbf{L} = \underbrace{\begin{pmatrix} l_1 & \cdots & l_m \end{pmatrix}}_{\text{Same size as source!}} \quad \text{where} \quad l_i = \frac{\text{cov}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2} = \frac{\partial t}{\partial s_i}$$

Sensitivity Map: Construction

Plot the slope at every gridpoint!

$$l_i = \frac{\text{cov}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2} = \frac{\partial t}{\partial s_i}$$



Sensitivity Map: Interpretation

Plot the slope at every gridpoint!

$$l_i = \frac{\text{cov}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2} = \frac{\partial t}{\partial s_i}$$

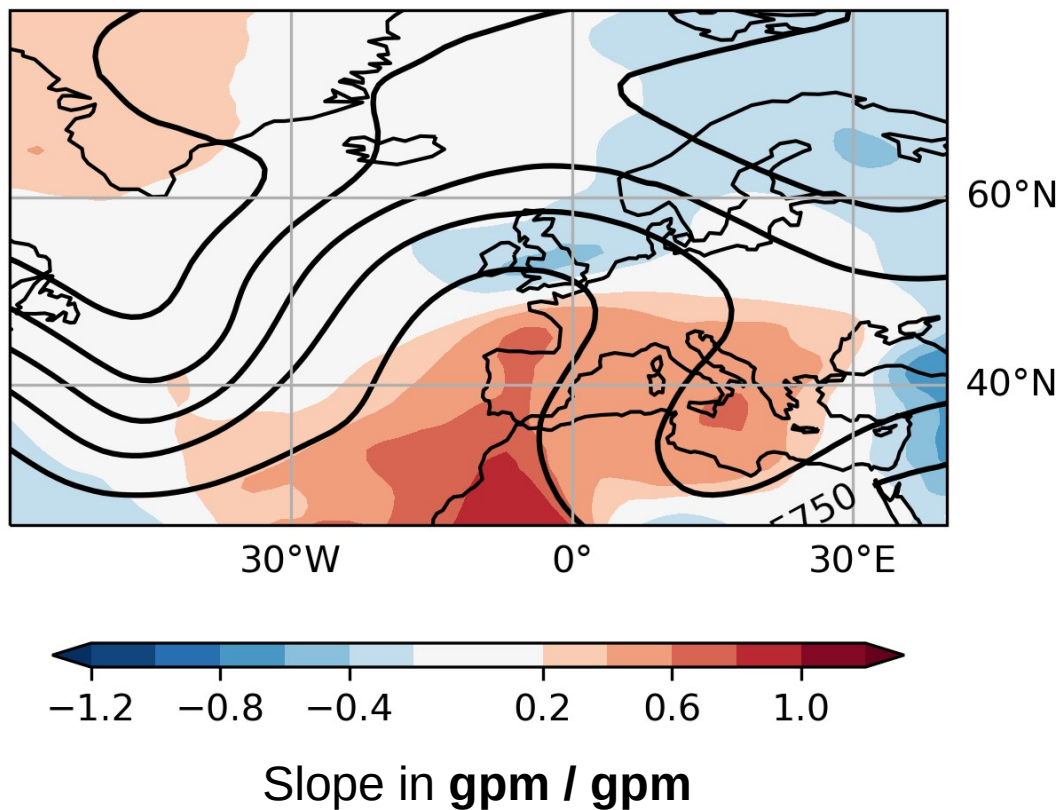
How (much) does T change when S changes?

- **Slope > 0**: larger $s_i \rightarrow$ larger t
- **Slope < 0**: larger $s_i \rightarrow$ smaller t

Visualization as map: spatial localization

- Directly read off response of t at every gridpoint

Sensitivity Map: Example

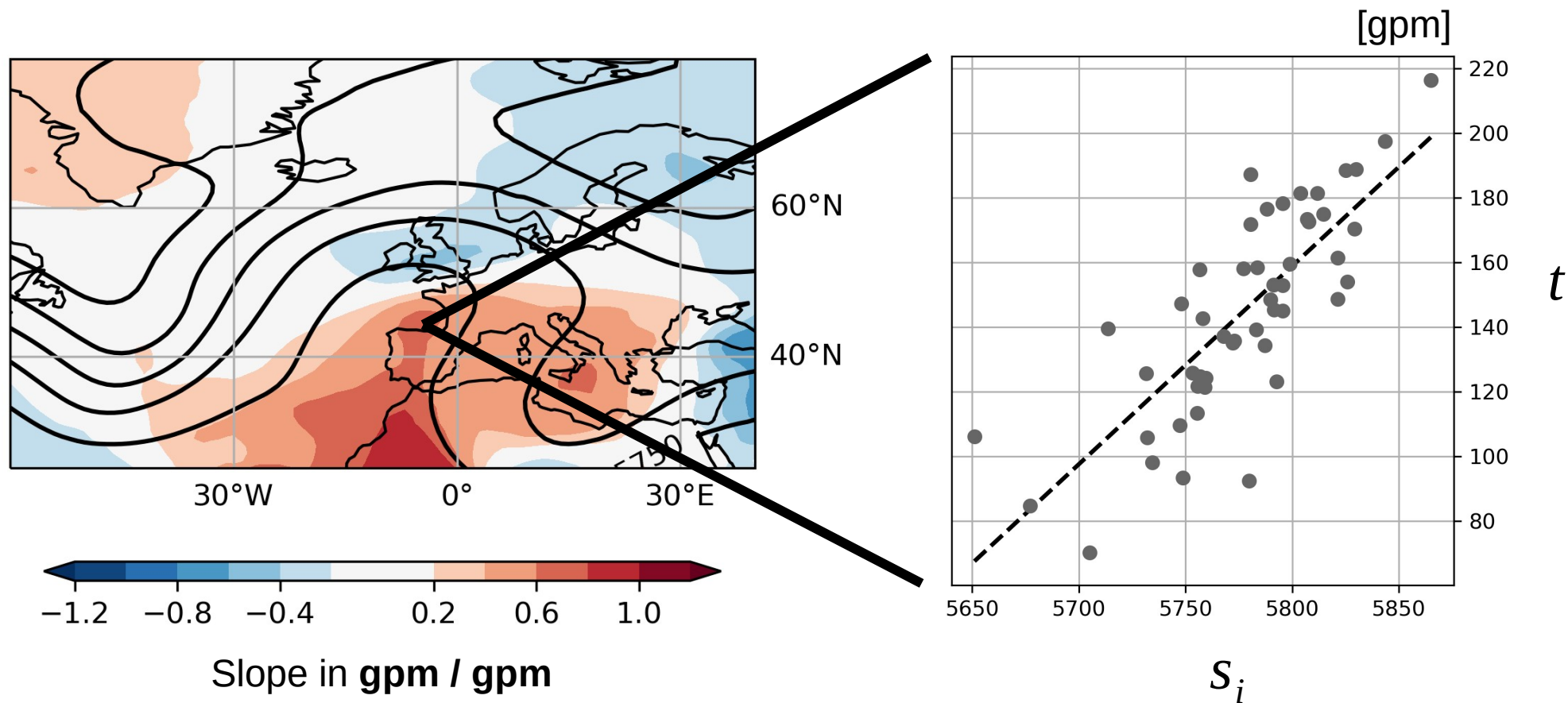


- **Slope > 0**
larger $s_i \rightarrow$ larger t
- **Slope < 0**
larger $s_i \rightarrow$ smaller t

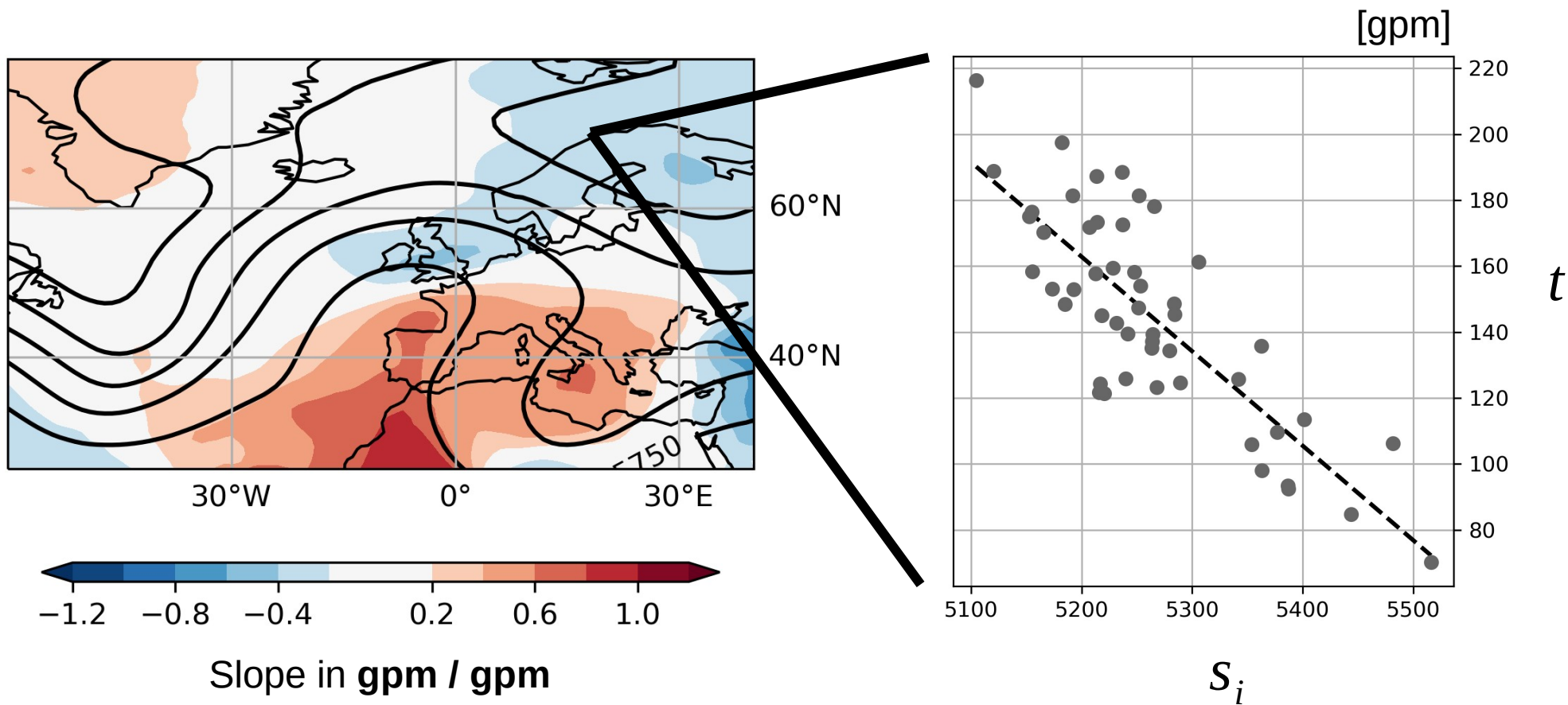
Here:

- t = forecast error
- s_i = 500 hPa Geopot.

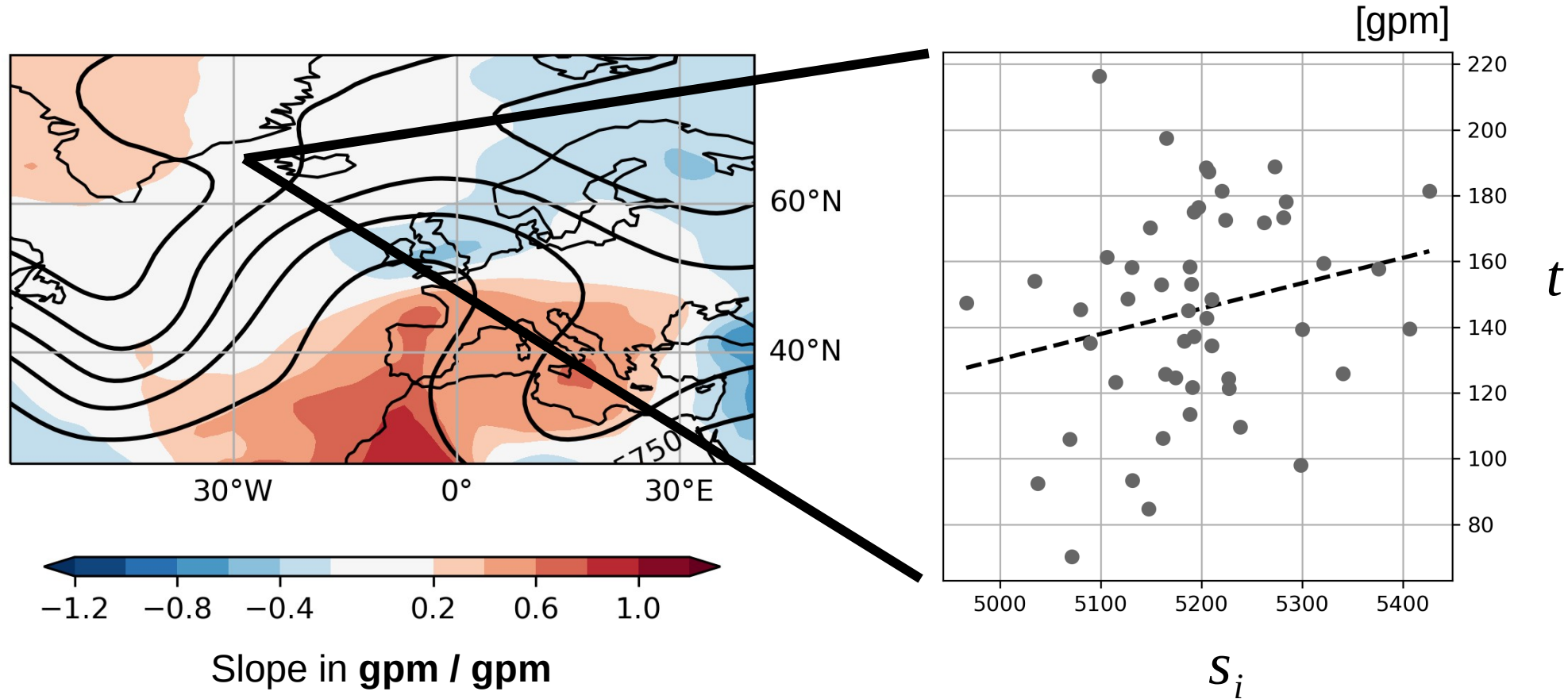
Sensitivity Map: Example



Sensitivity Map: Example



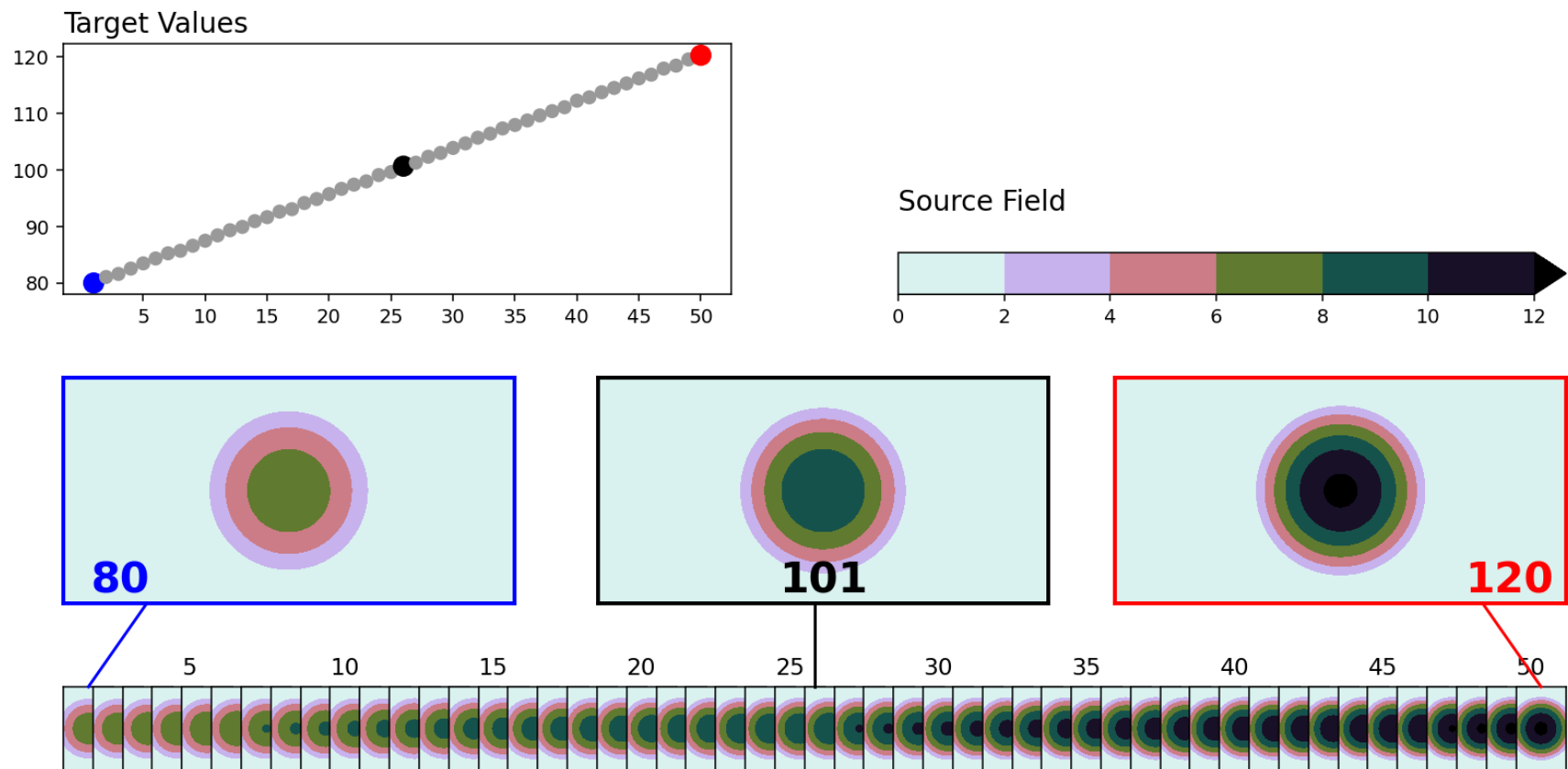
Sensitivity Map: Example



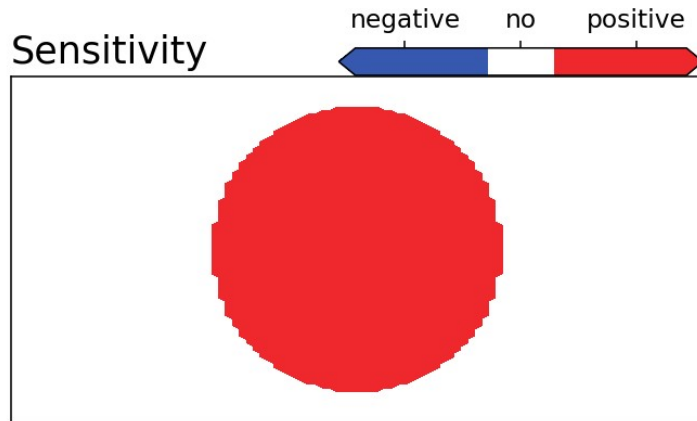
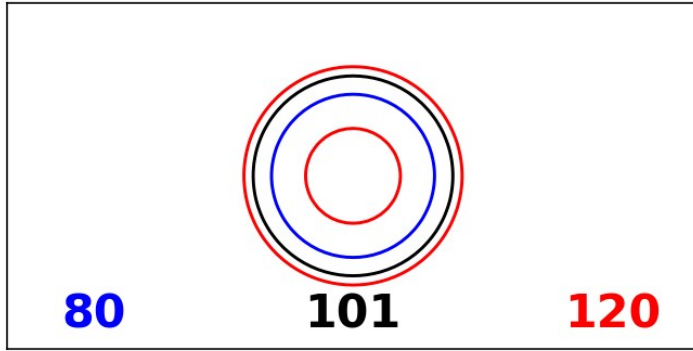
Hands-on

Sensitivity Pattern Quiz

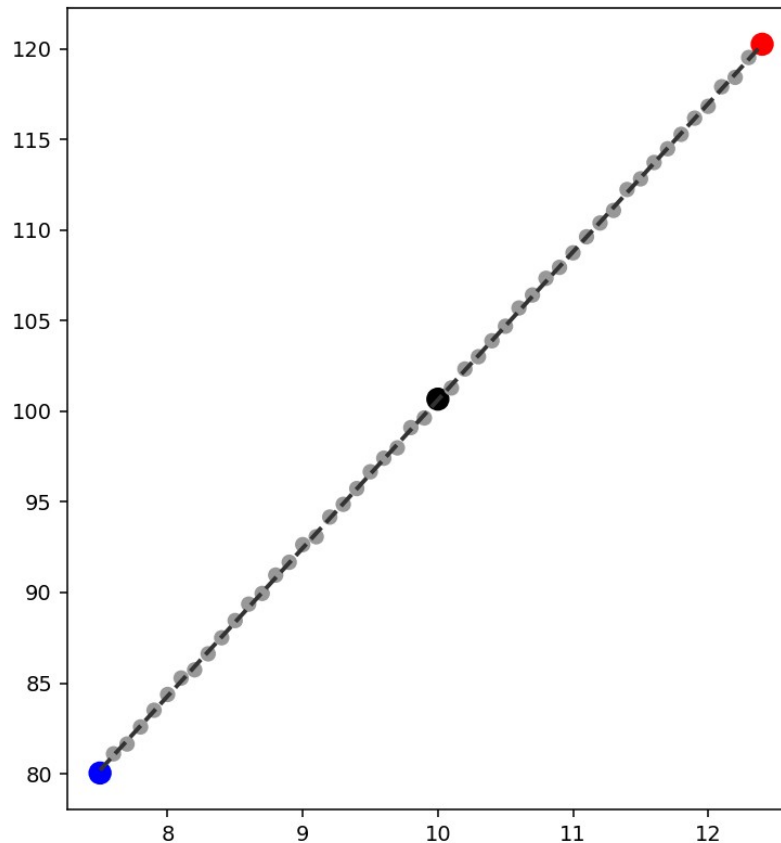
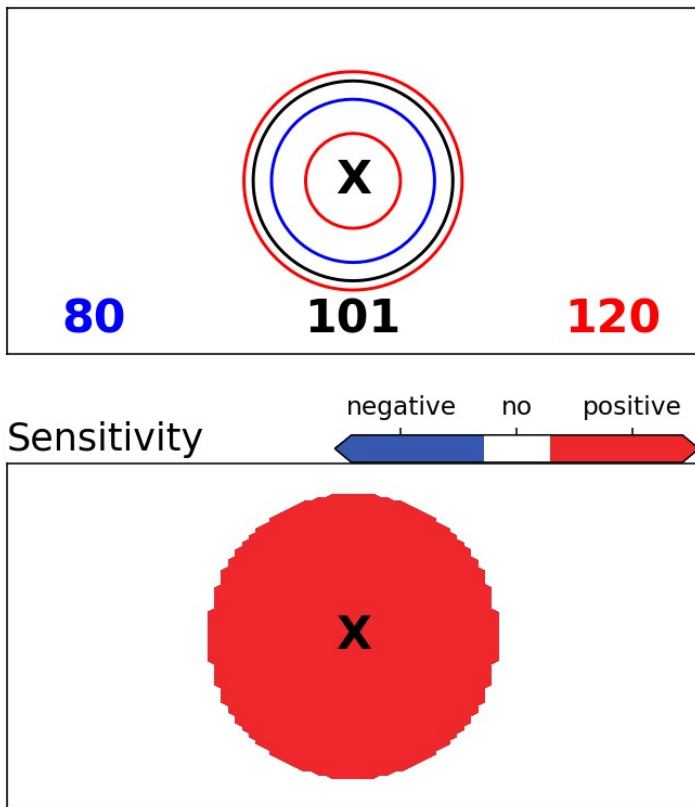
A: Blob Amplitude Uncertainty



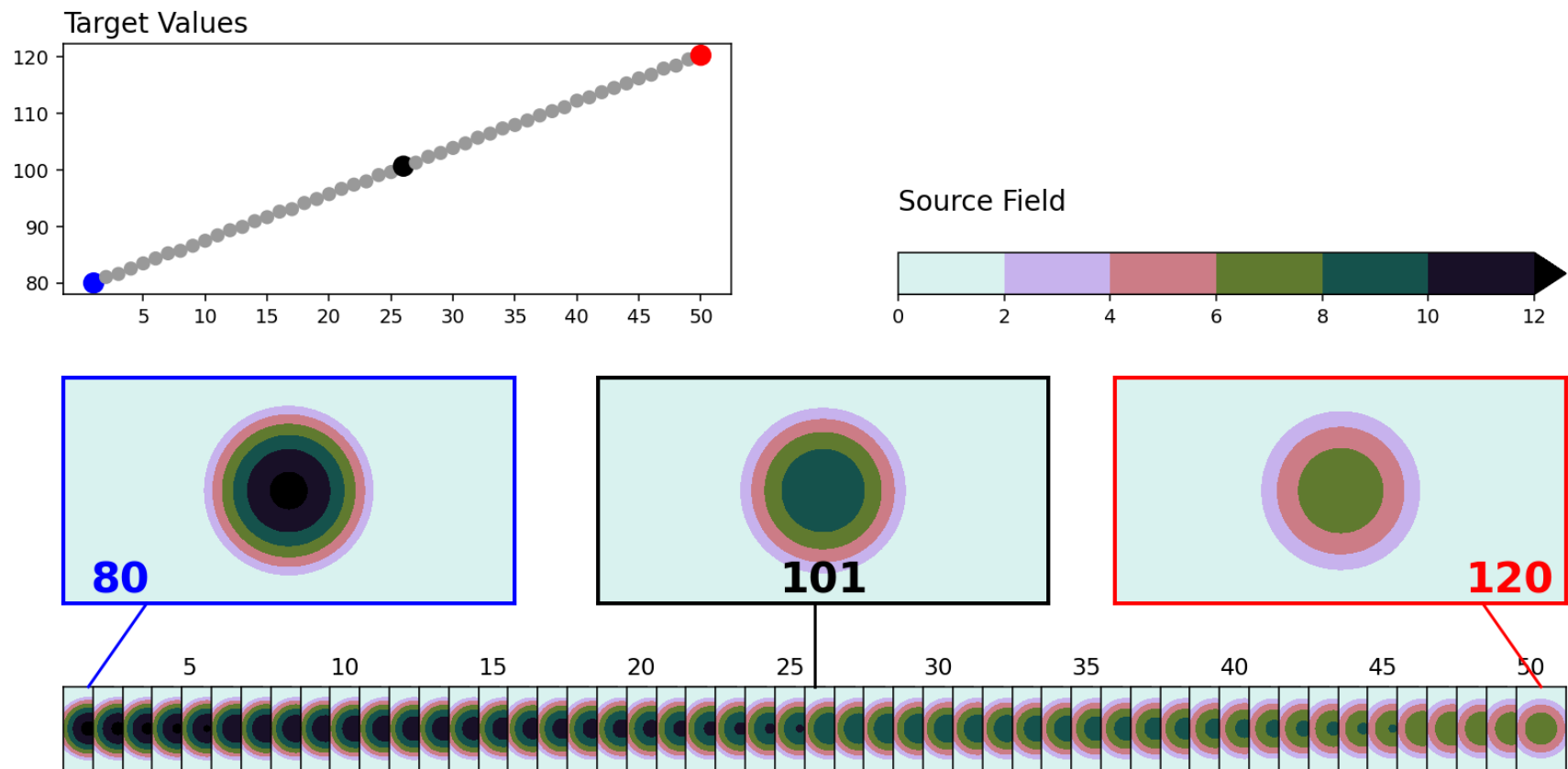
A: Blob Amplitude Uncertainty



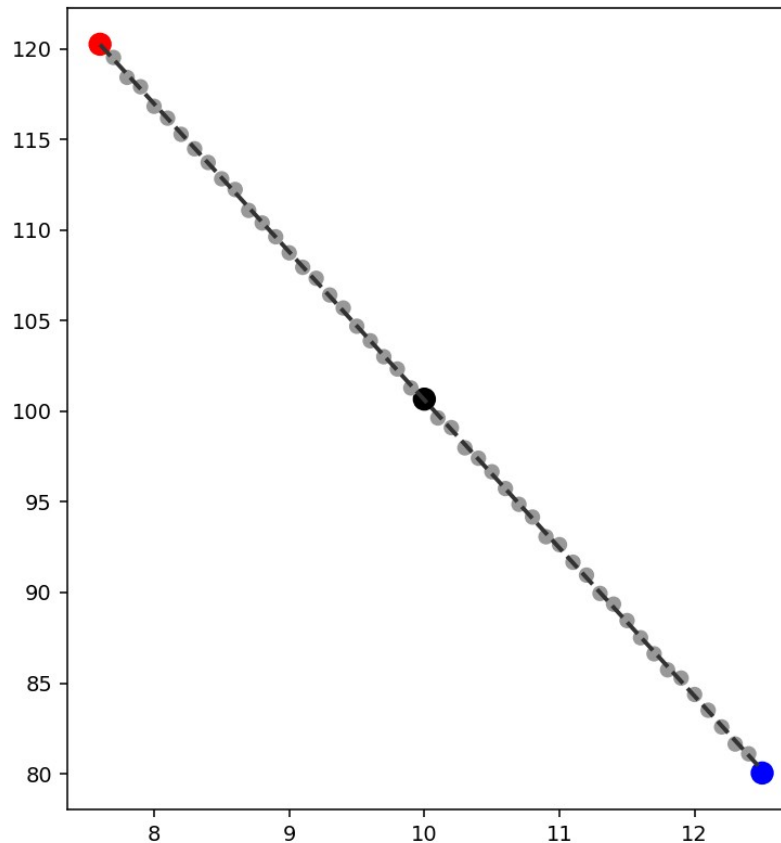
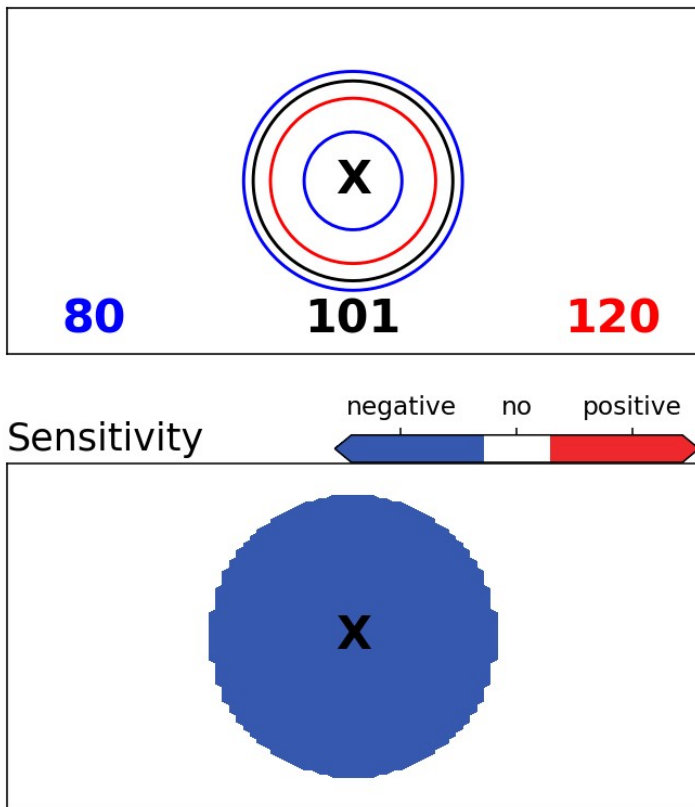
A: Blob Amplitude Uncertainty



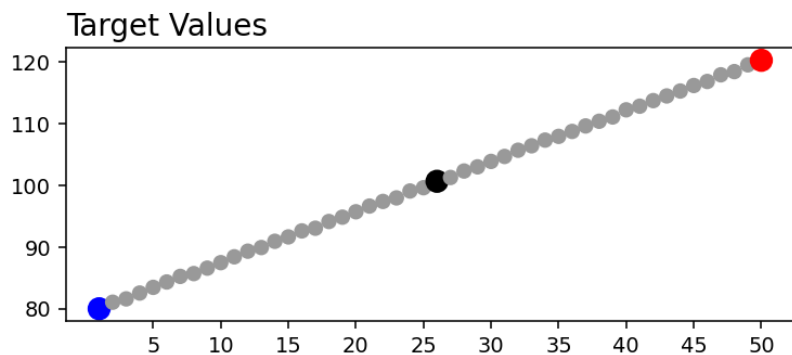
B: Blob Amplitude Uncertainty



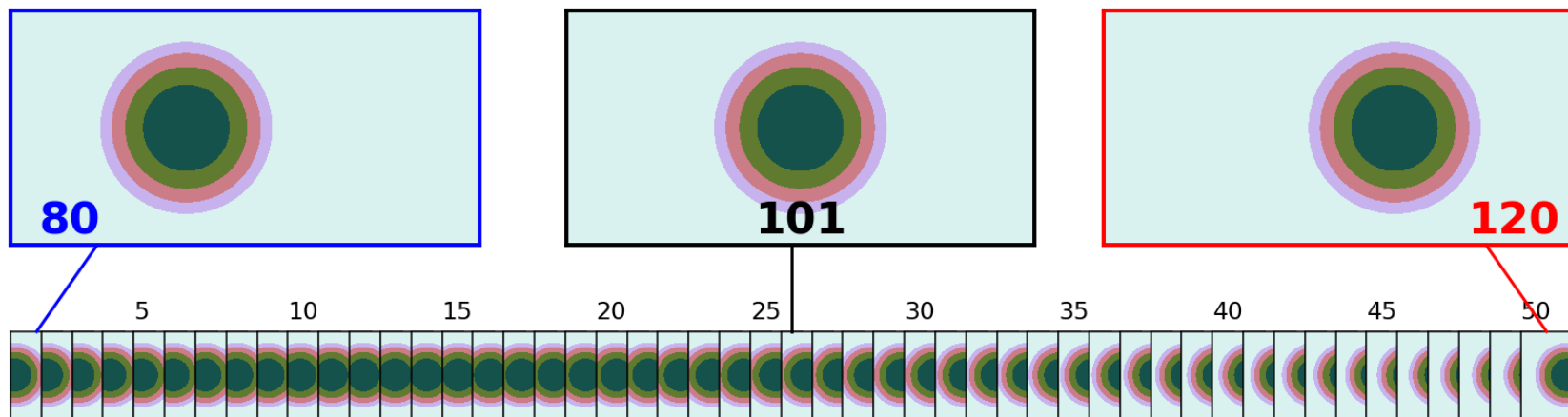
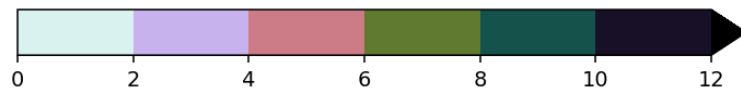
B: Blob Amplitude Uncertainty



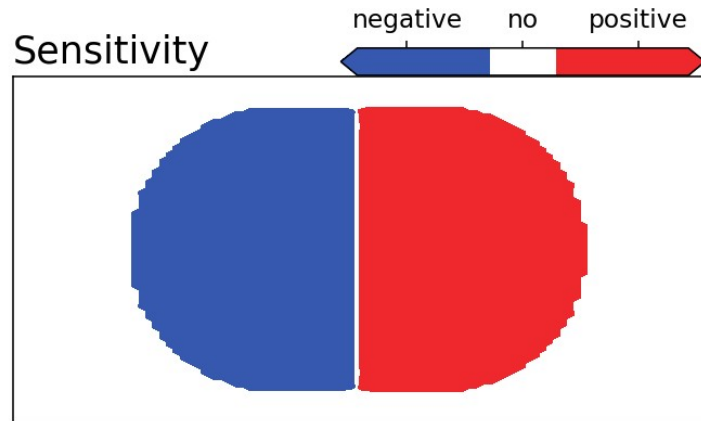
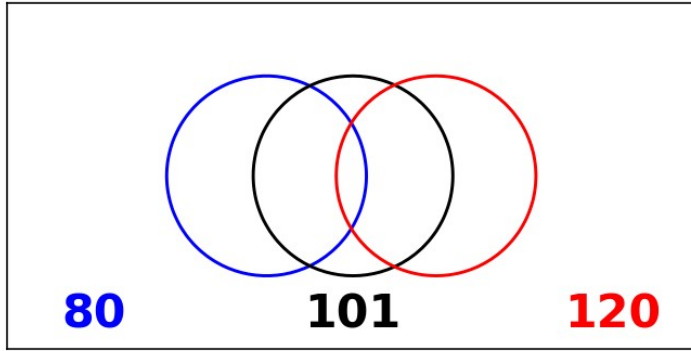
C: Blob Location Uncertainty



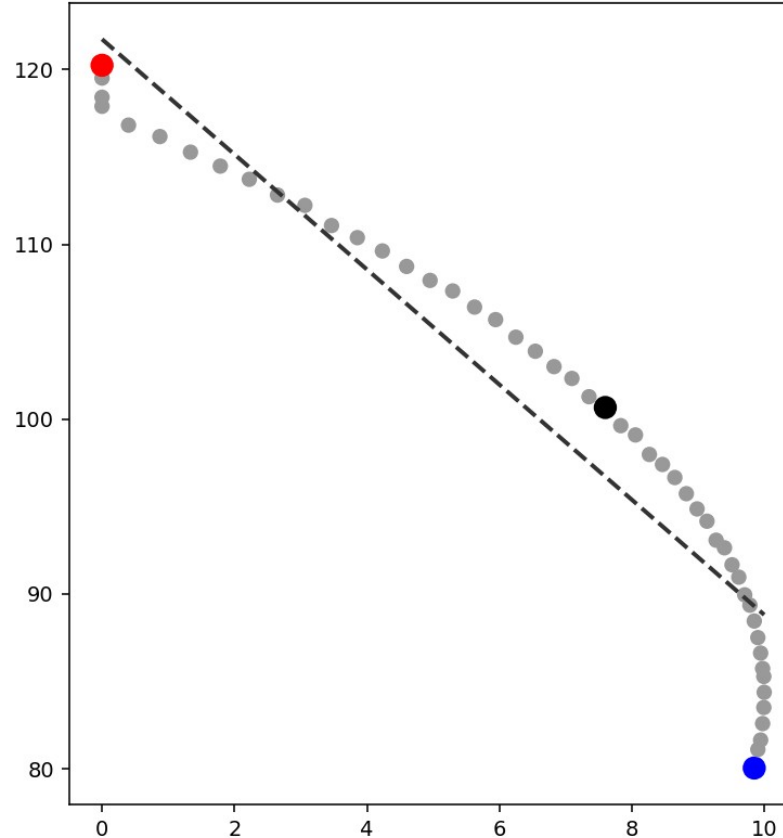
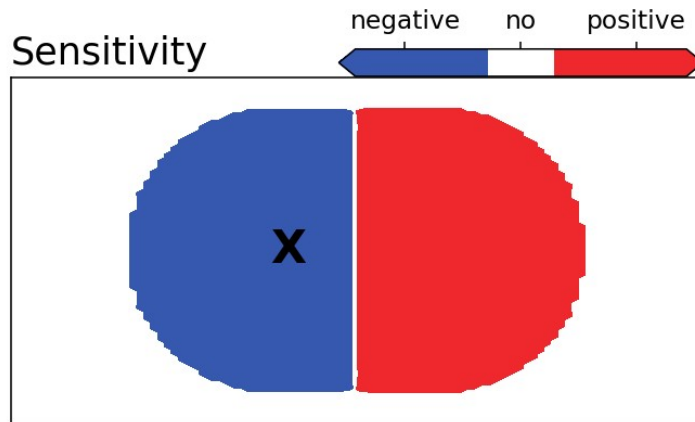
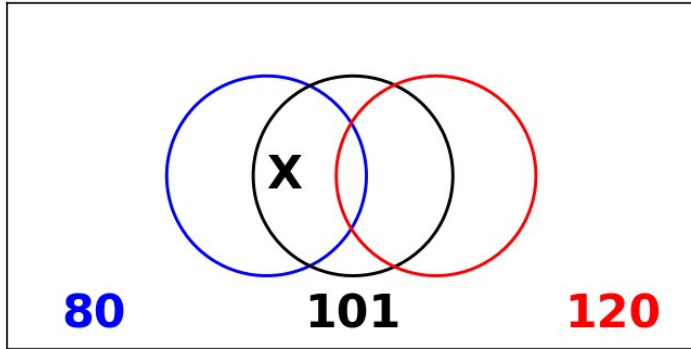
Source Field



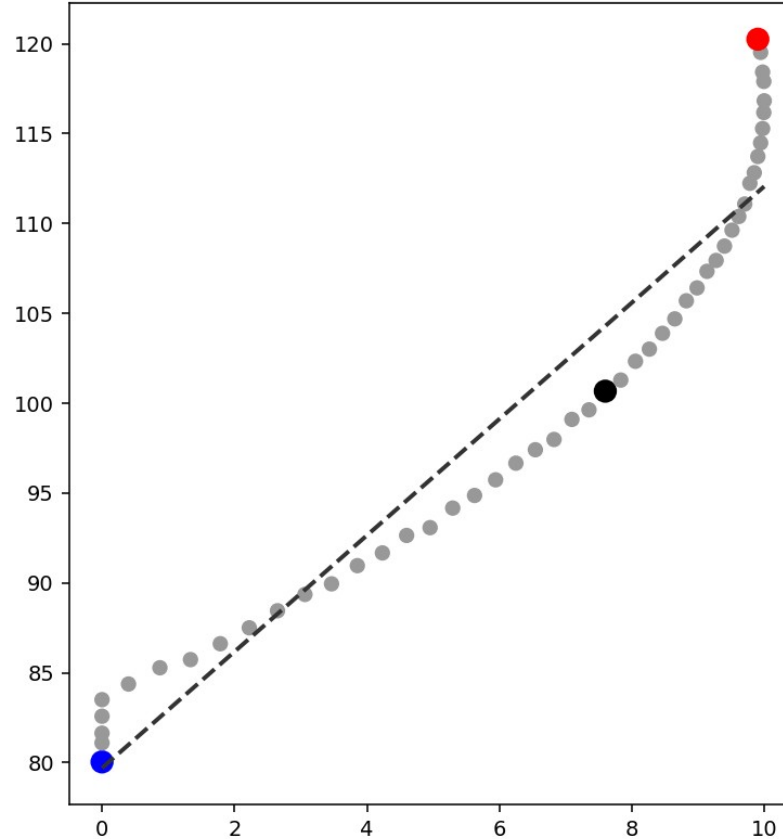
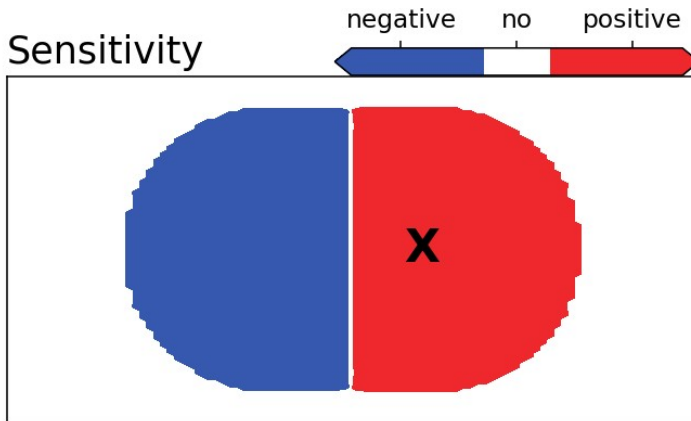
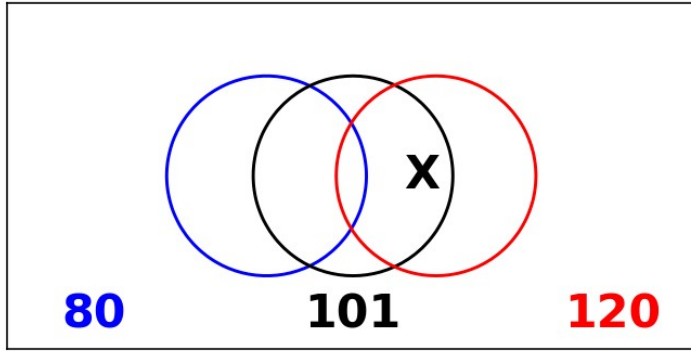
C: Blob Location Uncertainty



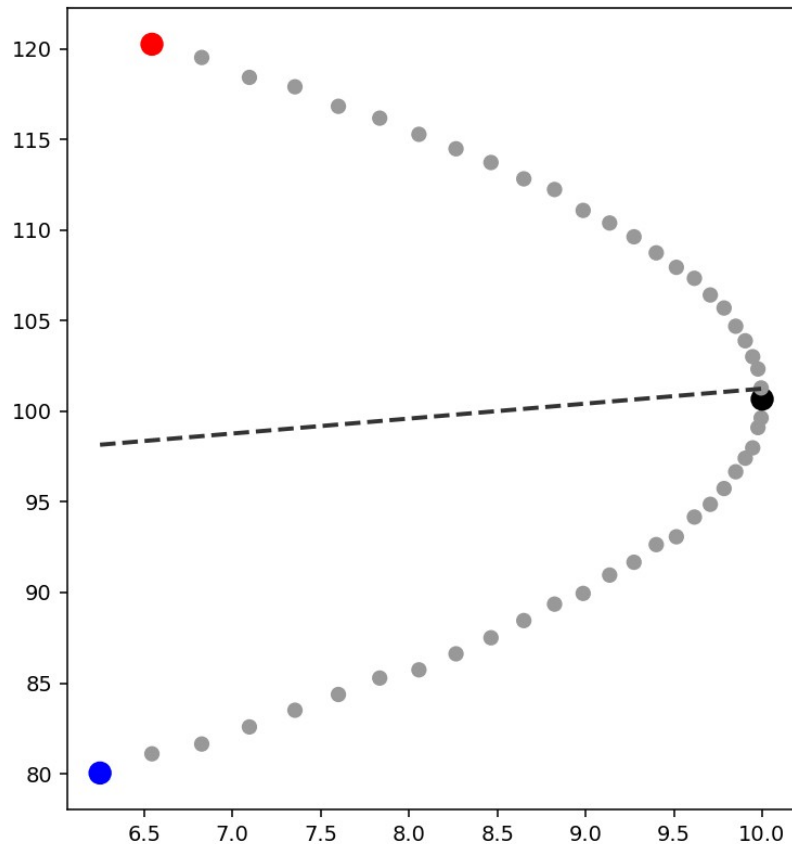
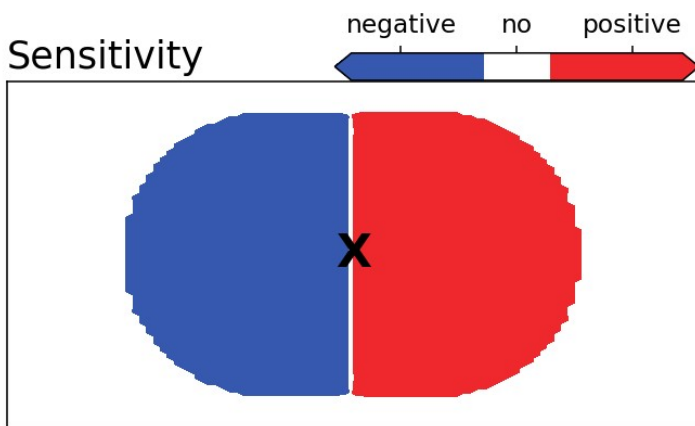
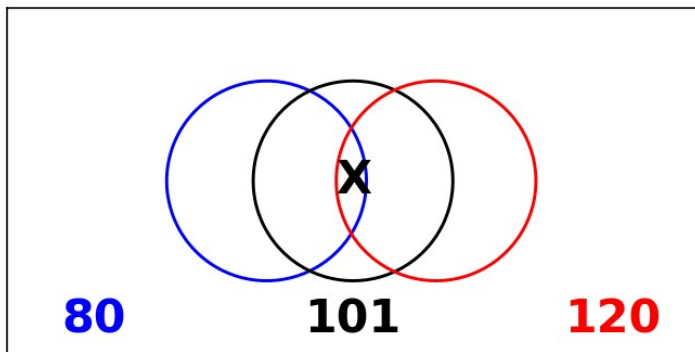
C: Blob Location Uncertainty



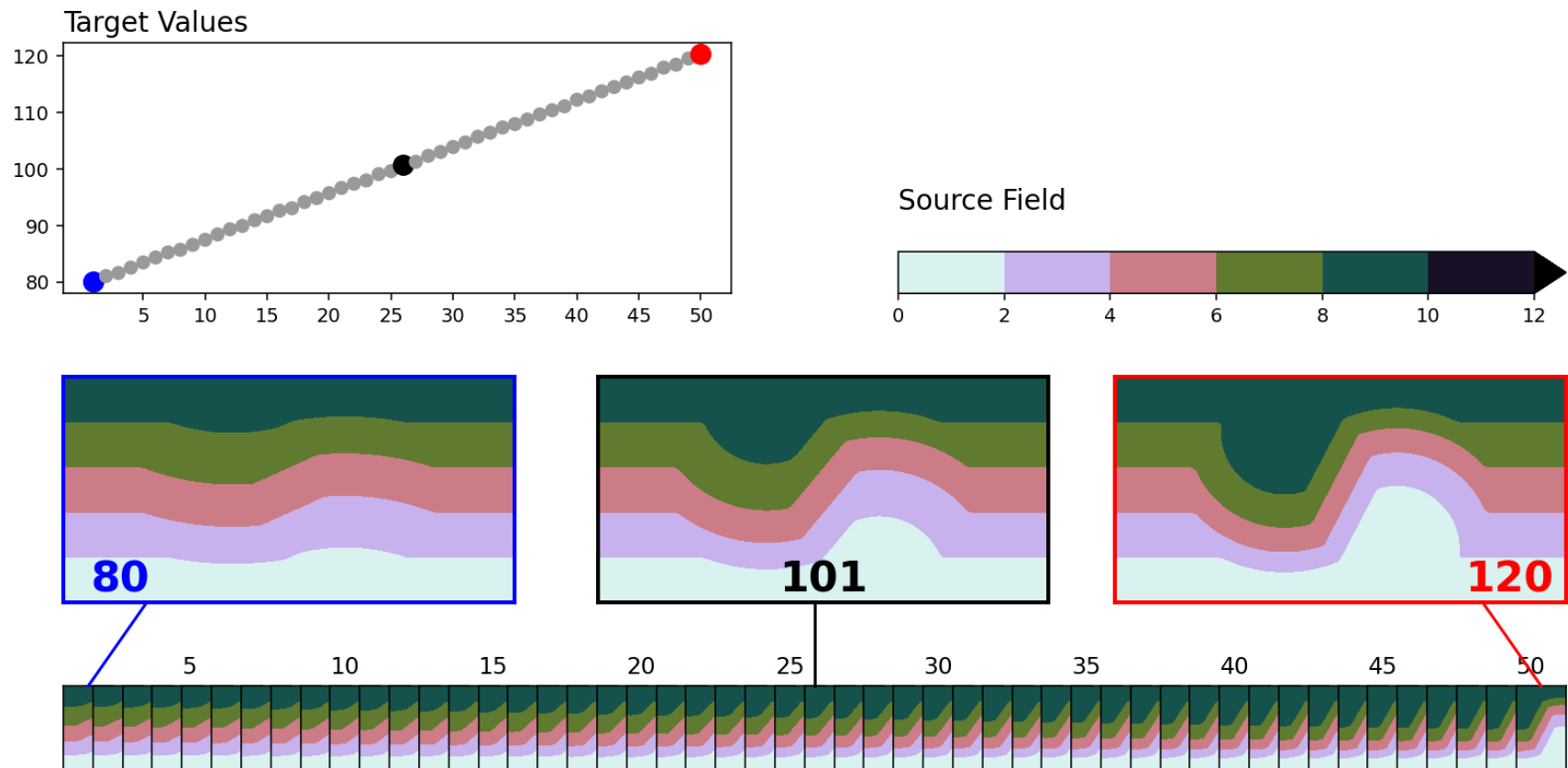
C: Blob Location Uncertainty



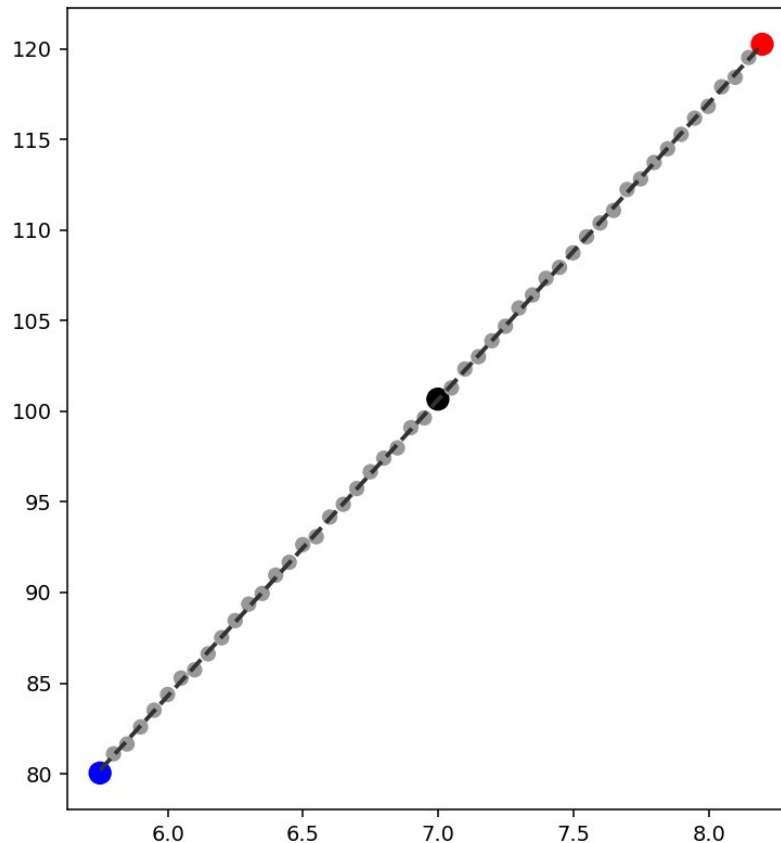
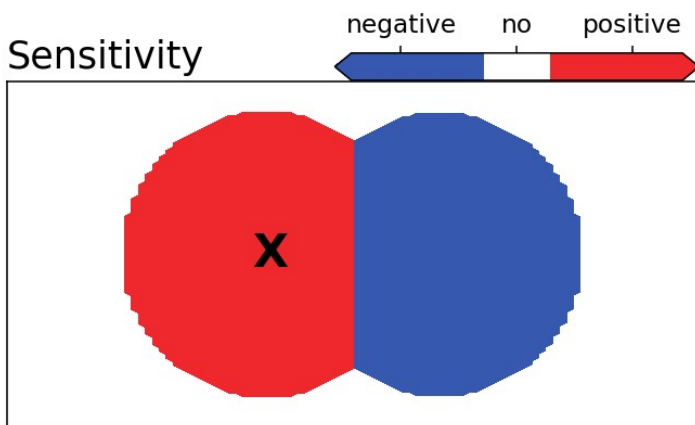
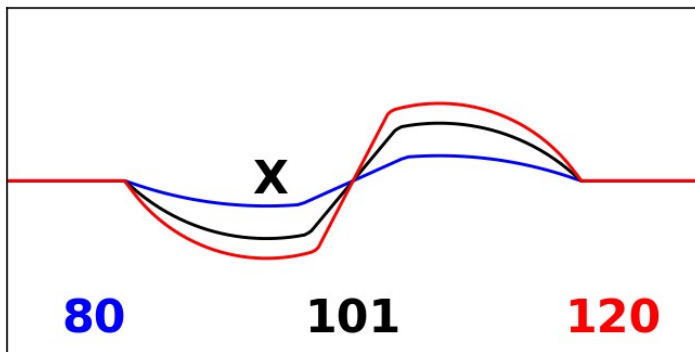
C: Blob Location Uncertainty



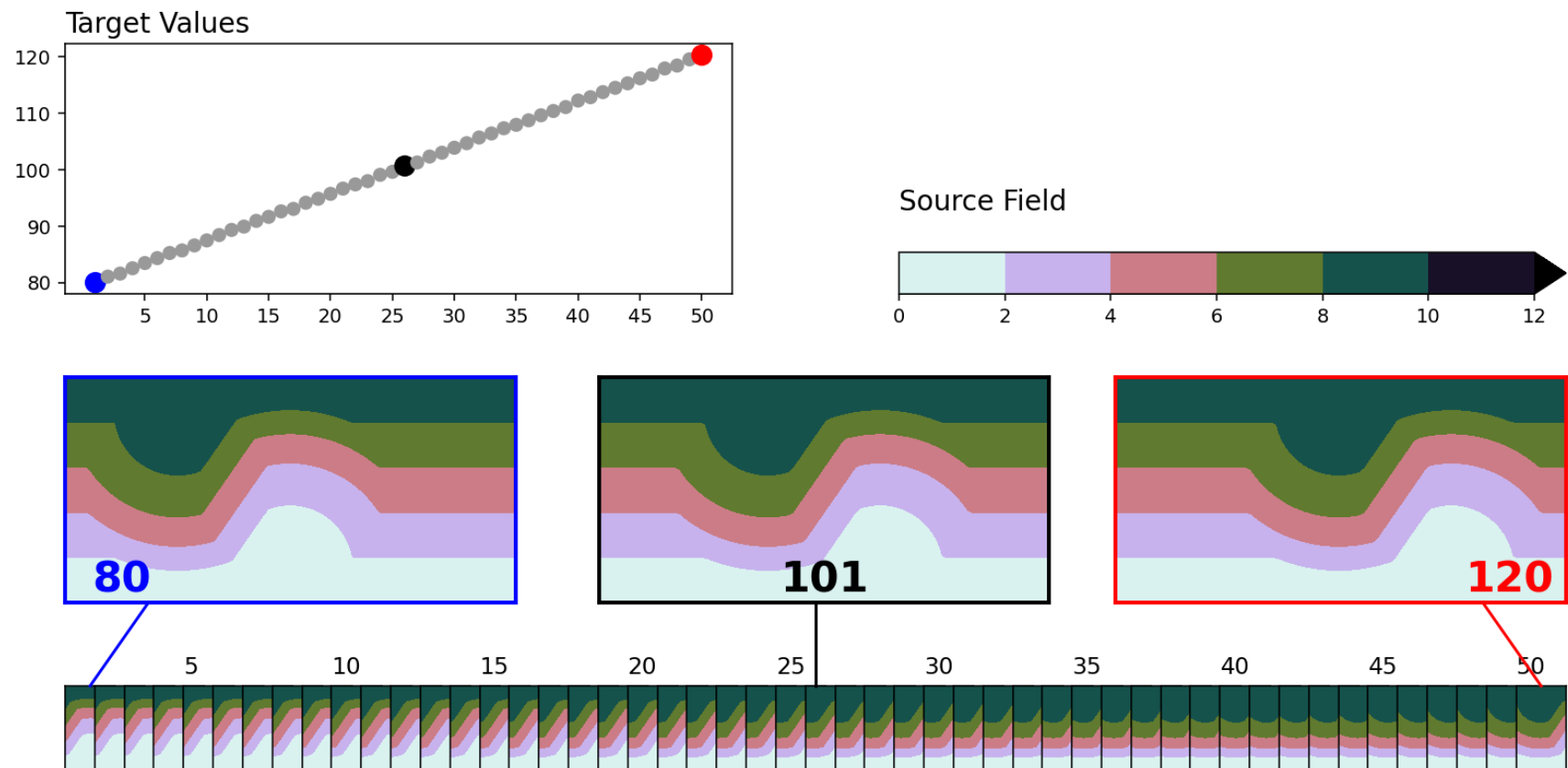
D: Wave Amplitude Uncertainty



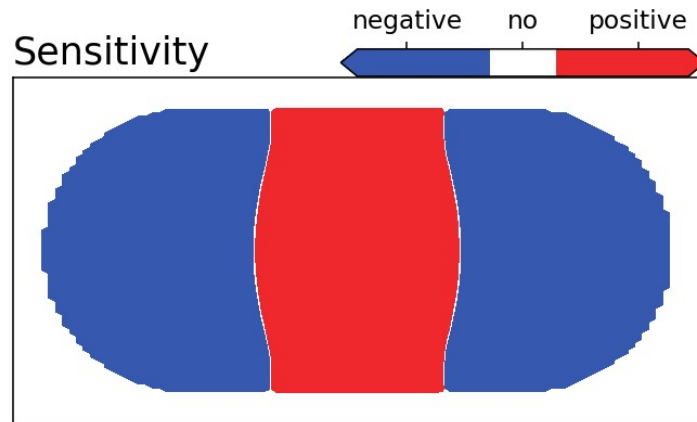
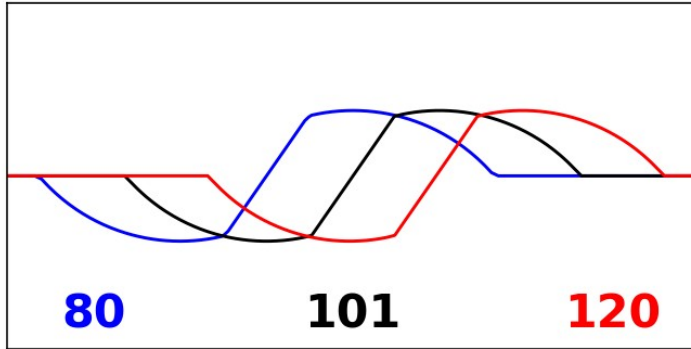
D: Wave Amplitude Uncertainty



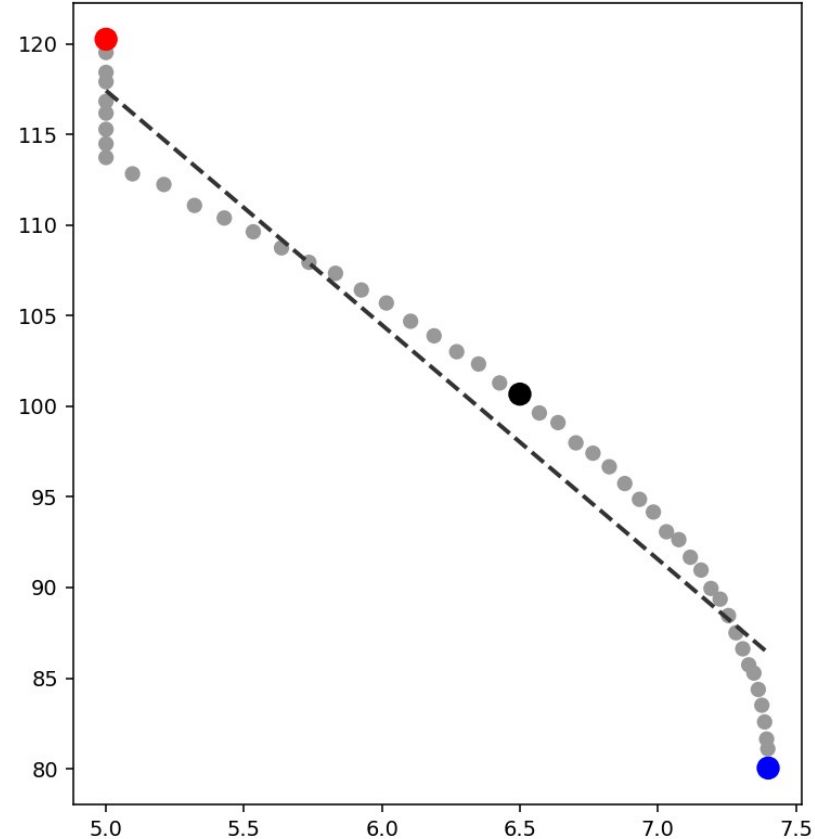
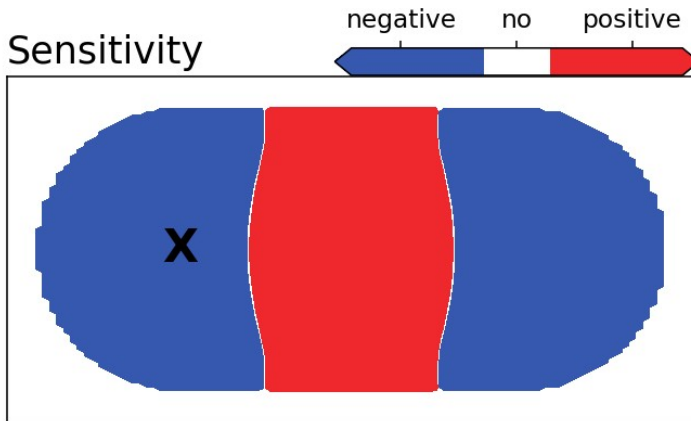
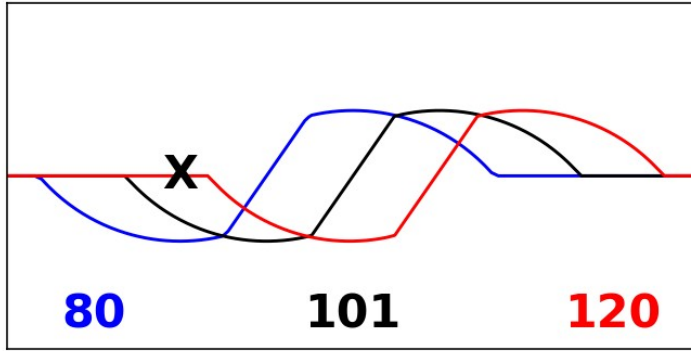
E: Wave Phase Uncertainty



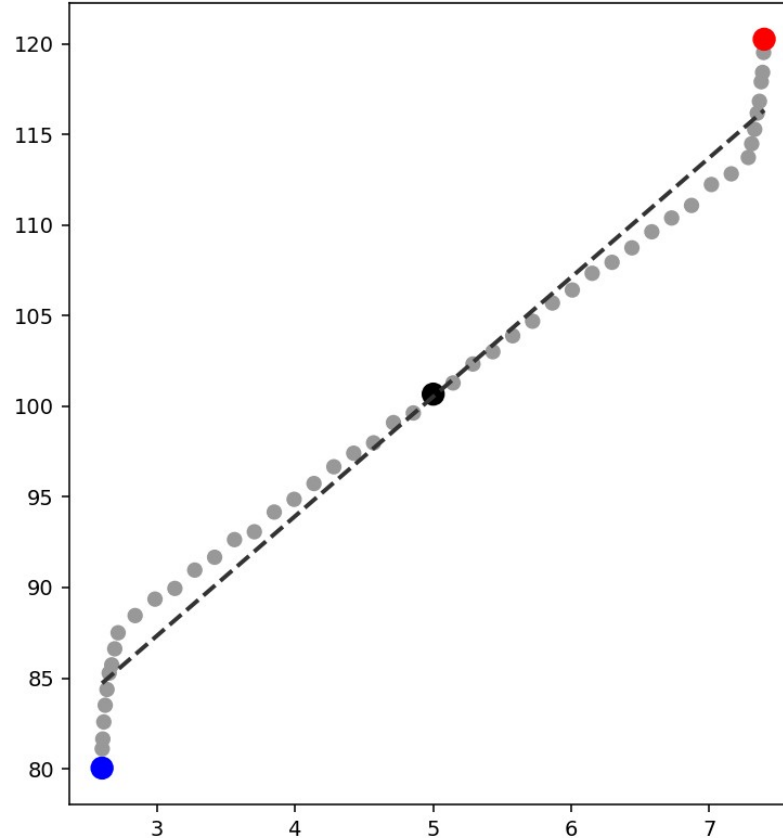
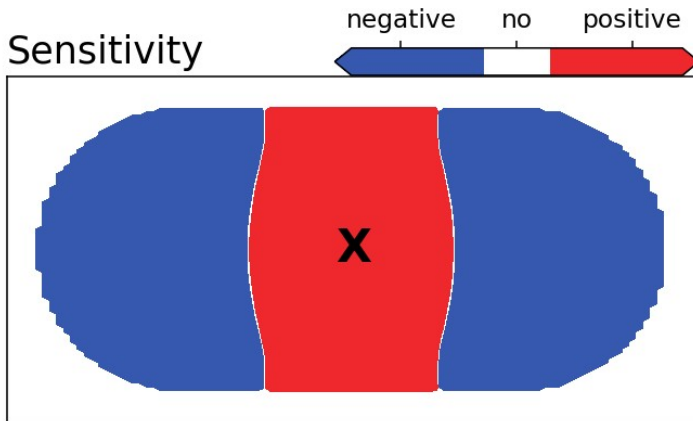
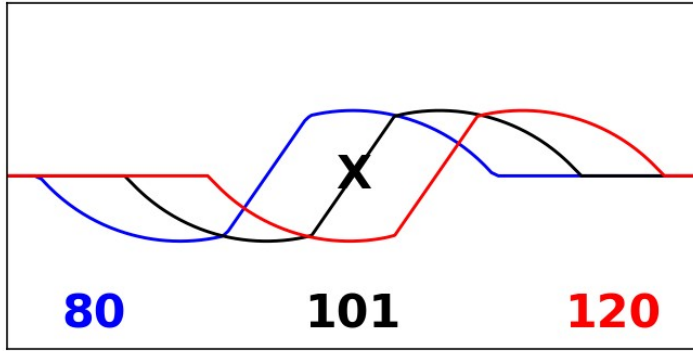
E: Wave Phase Uncertainty



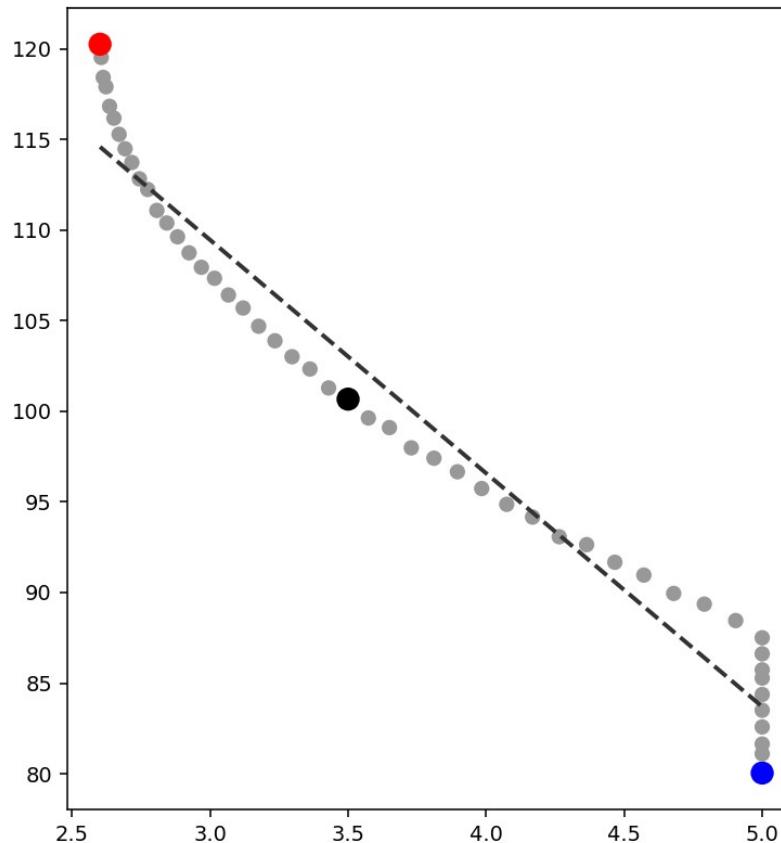
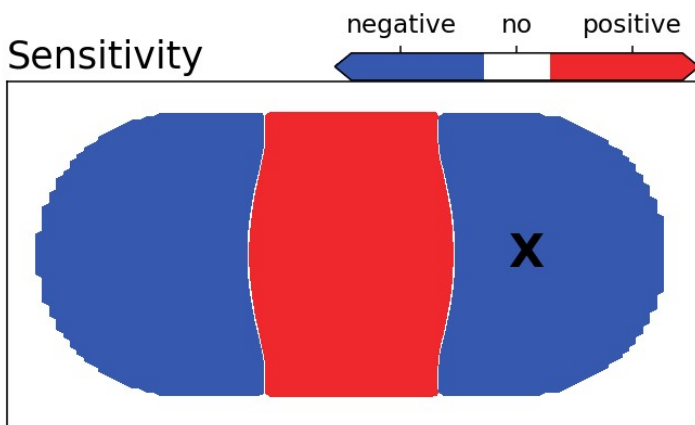
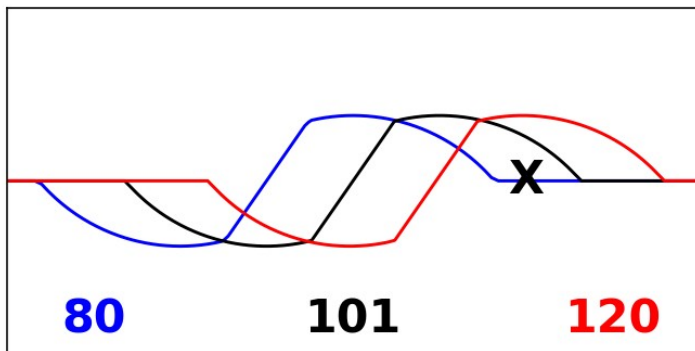
E: Wave Phase Uncertainty



E: Wave Phase Uncertainty



E: Wave Phase Uncertainty



Part II

- Source fields and target metrics
- Tracking in space and time
- Causality, Limitations, Normalization
- Hands-on: ESA, Normalization

Source Fields and Target Metrics

(How (much)) does T change when S changes?

Source Field Examples:

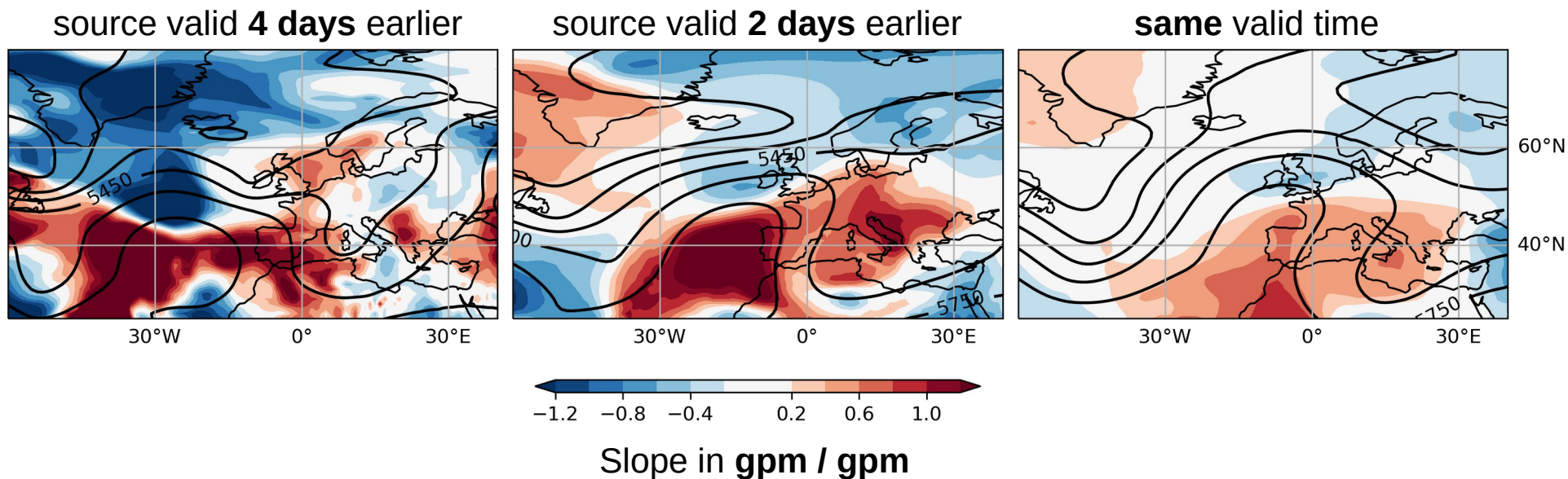
- Geopotential
- Temperature
- Moisture
- Precipitation
- Potential vorticity

Target Metric Examples:

- Forecast/Analysis Error
 - Regional RMSE, ACC, ...
- 3h-Precipitation at a location
- Cyclone central pressure
- Wind power production

Tracking in Space and Time

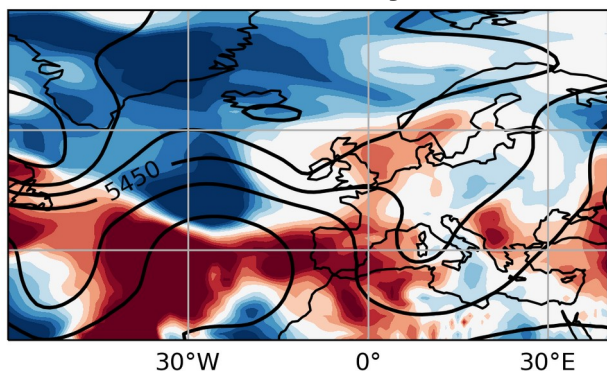
Consider source and target at **different valid times**:



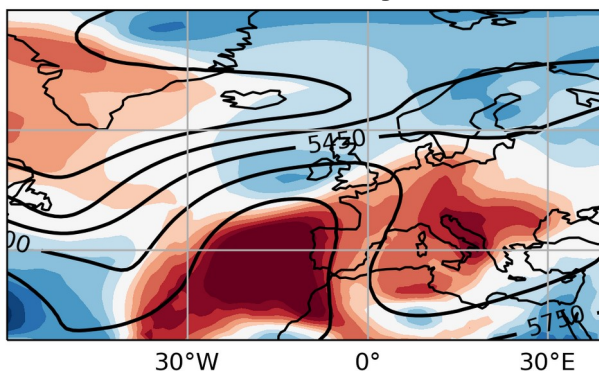
Tracking in Space and Time

Consider source and target at **different valid times**:

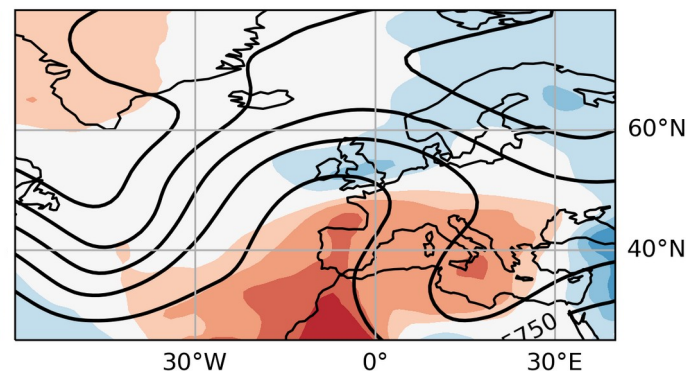
source valid **4 days** earlier



source valid **2 days** earlier



same valid time



Fields are connected through evolution in model, **but**:
ESA is statistical and does not diagnose causality directly!

Limitations

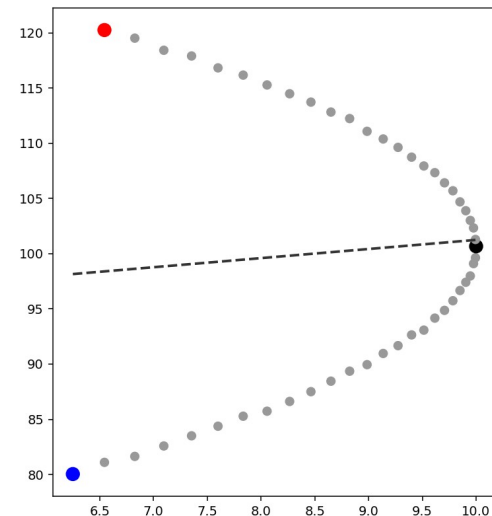
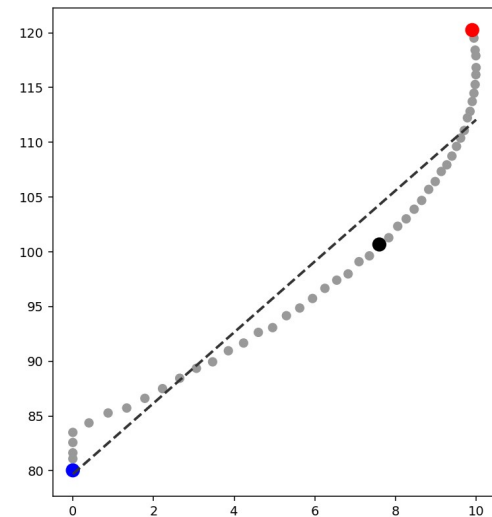
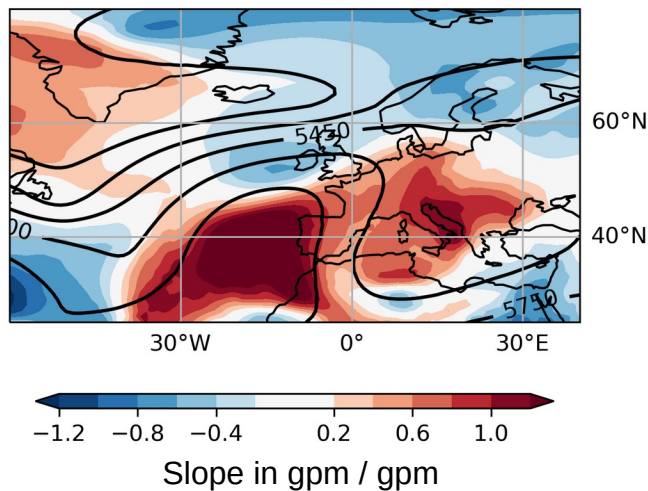
- **Results only as good as the ensemble**
 - Garbage in, garbage out
 - Generally: bigger is better
- Not all assimilation systems sample probability distribution of analysis properly
 - Throw away first timesteps to eliminate “**memory of the initial conditions**” (Hakim and Torn 2008)

Limitations

- Only “**linear**” sensitivity is measured
- **Gridpoint-wise** sensitivity, must not aggregate response

$$\text{cov}(\mathbf{S}, \mathbf{S})^{-1}$$

$$\rightarrow \begin{pmatrix} \sigma_{s_1}^{-2} & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & \sigma_{s_m}^{-2} \end{pmatrix}$$



Normalization

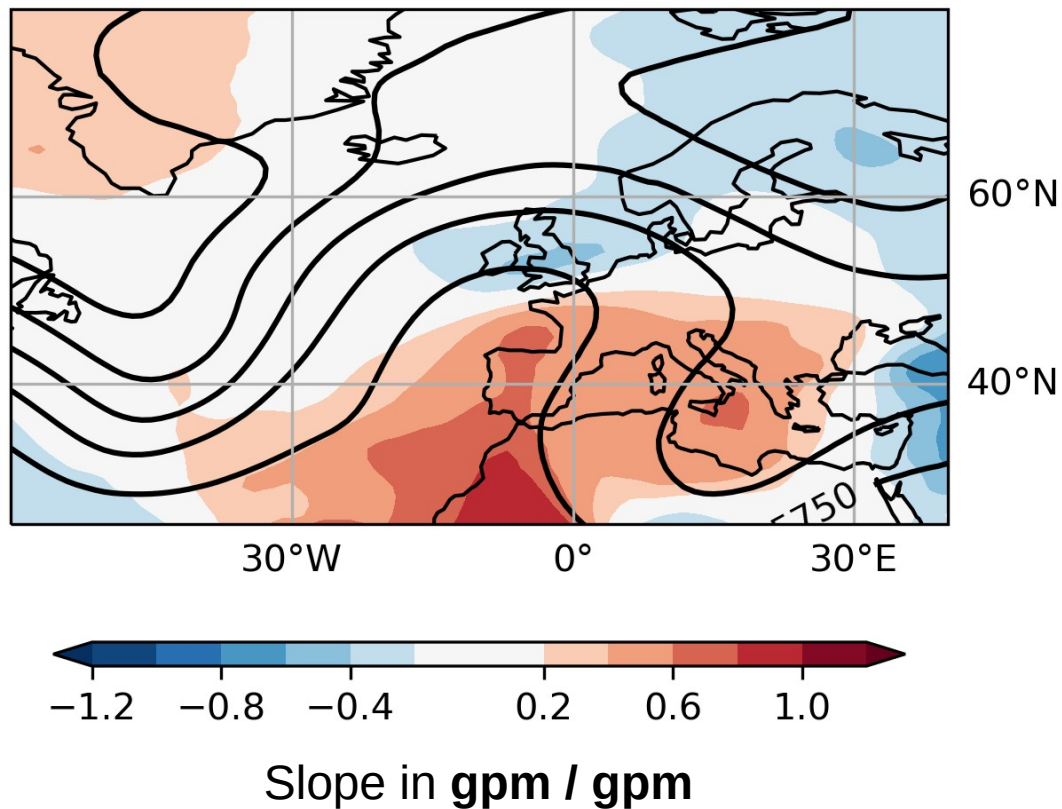
How to compare sensitivity quantitatively?

Z500 vs. Z500 Error

→ Slope in gpm / **gpm**

T850 vs. Z500 Error

→ Slope in gpm / **K**



Normalization

No normalization
of source

No normalization
of target

$$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2}$$

slope of regression

Normalization

	No normalization of source	Normalize source: multiply by σ_{s_i}
No normalization of target	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2}$ <p>slope of regression</p>	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}}$ <p>compare sources</p>

Normalization

	No normalization of source	Normalize source: multiply by σ_{s_i}
No normalization of target	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2}$ <p>slope of regression</p>	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}}$ <p>compare sources</p>
Normalize target: divide by σ_t	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2 \sigma_t}$ <p>compare targets</p>	

Normalization

	No normalization of source	Normalize source: multiply by σ_{s_i}
No normalization of target	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}^2}$ <p>slope of regression</p>	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i}}$ <p>compare sources</p>
Normalize target: divide by σ_t	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i} \sigma_t}$ <p>compare targets</p>	$\frac{\text{COV}(\mathbf{t}, \mathbf{s}_i)}{\sigma_{s_i} \sigma_t}$ <p>correlation coefficient</p>

Hands-on

Implement ESA
Compare Normalizations

Access to the Hands-on Material

Clone repository and run Jupyter locally:

- <https://github.com/chpolste/ESA-Workshop>
- Python 3 with numpy, xarray, netcdf4*, matplotlib, cartopy

Use mybinder.org and run online:

- <https://mybinder.org/v2/gh/chpolste/ESA-Workshop/main>
- Be aware of the 10 min inactivity timeout!

Part III

- Magnusson (2017): “Diagnostic methods ...”
- Hands-on: Tracking with ESA Maps
- Hands-on: Cluster-based Sensitivity

Magnusson (2017) Paper

Diagnostic methods for understanding the origin of forecast errors

- Investigation of 3 “forecast bust” cases
- Error tracking and confirmation with relaxation experiments

Get a copy:

- <https://doi.org/10.1002/qj.3072>
- <https://www.ecmwf.int/en/elibrary/17097-diagnostic-methods-understanding-origin-forecast-errors>

Hands-on

Tracking with ESA Maps
Cluster-based Sensitivity

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- Be aware of the 10 min inactivity timeout!

References

Data

- Ensemble forecast data: ECMWF (TIGGE)
<https://apps.ecmwf.int/datasets/licences/tigge/>
- Reanalysis data (verification): ERA5 (CDS)
<https://dx.doi.org/10.24381/cds.bd0915c6>

Sensitivity pattern quiz inspired by Fig. 1 of Maddison et al. (2019)

Literature

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