

Autonomous Fault Detection Using Artificial Intelligence Applied to CLAS12 Drift Chamber Data

August 13, 2018

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Motivation

- > Most crucial elements of a physical experiment?
 - > Methods of measurement, e.g. drift chamber at CLAS12
 - > Need to be highly precise
 - > Essential for success
- > Problem: Extreme conditions often lead to faults
 - > Distortions in measurement accuracy
 - > Have to be detected and filtered out during runtime
- > Too much data to be processed by a human
 - > An *autonomous* approach of fault detection is required

Motivation

- > Emerging field lending itself particularly well to the task:
 - > The domain of Artificial Intelligence (AI)
 - > Deep Learning, Convolutional Neural Networks (CNNs)
- > Goal: Apply methods of AI to the problem of fault detection
 - > Experimental context: CLAS12 drift chamber
- > Baseline software: deeplearning4j (DL4J) library
 - > Will be used to implement the fault detection system

The CLAS12 Drift Chamber

- > Subsystem of the CLAS12 particle detector
 - > Electron beam hits target inside the detector's center
 - > Drift Chamber (DC) is used to measure the results (particle momentum)
- > Hierarchical arrangement of multiple wires grouped together as wire chambers
 - > Wires are used to detect particle presence
 - > Particle hits wire → wire gets activated

The CLAS12 Drift Chamber

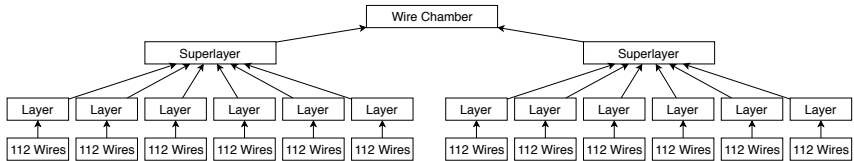
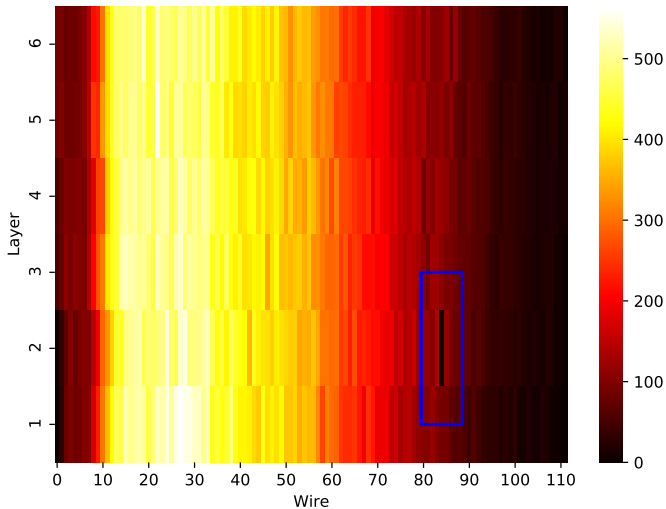


Figure: The hierarchical structure of a single wire chamber.

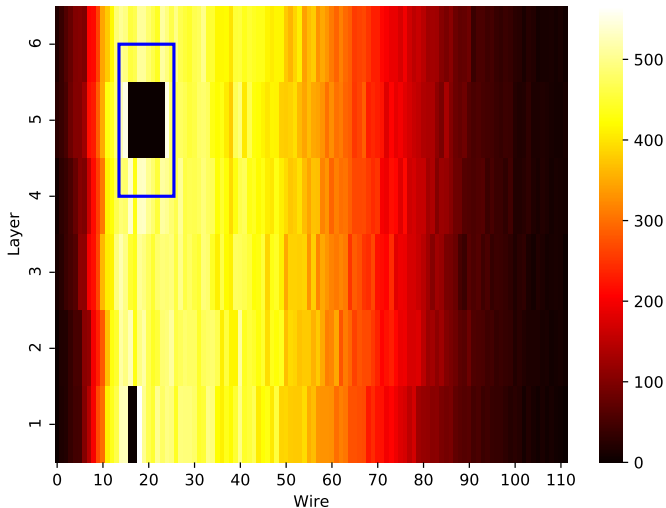
Drift Chamber Faults

- > Drift chamber operates under extreme conditions
 - > Huge amounts of radiation
 - > Components can get damaged during an experiment
 - > Single wires or collections thereof stop working
- > Wire activations can be visualized as heatmaps
 - > Easier to detect faults

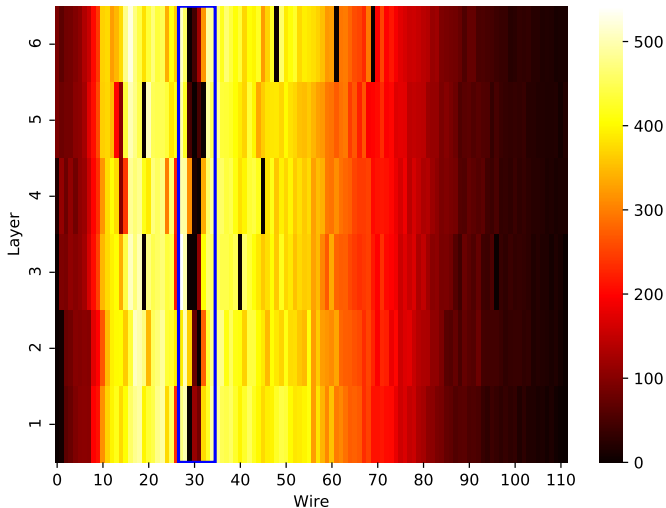
Dead Wire



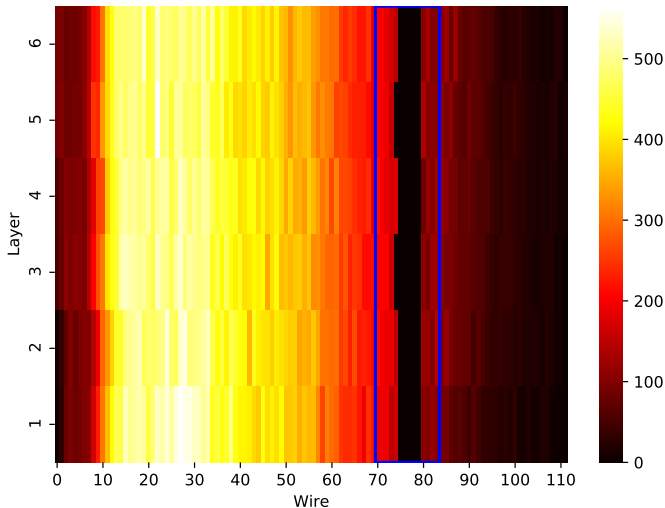
Dead Pin



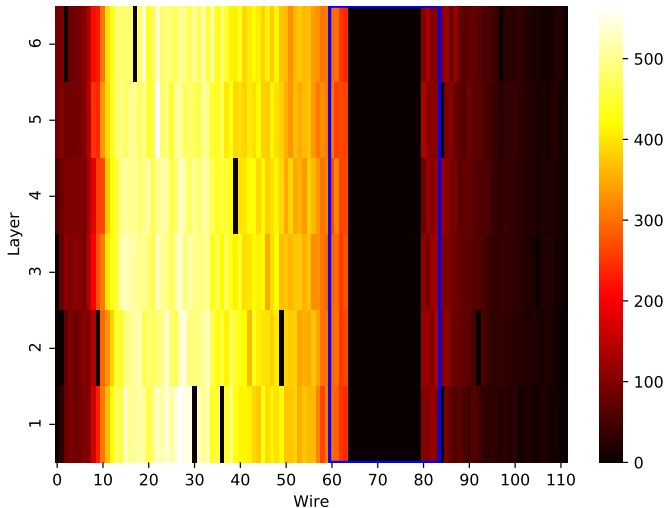
Dead Connector



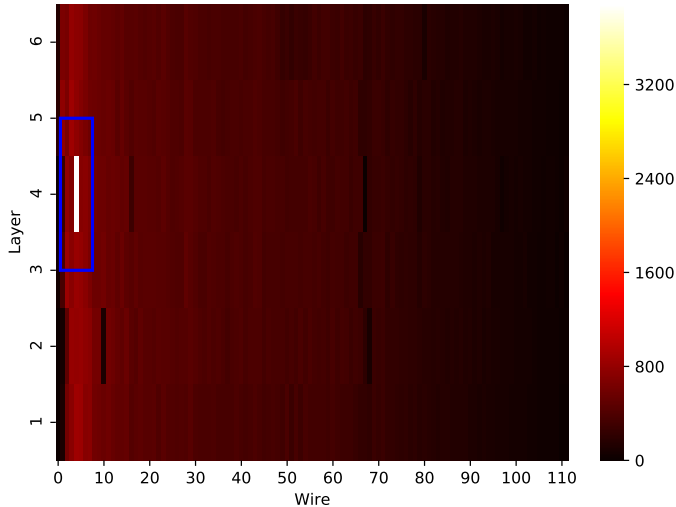
Dead Fuse



Dead Channel



Hot Wire



Artificial Neural Networks

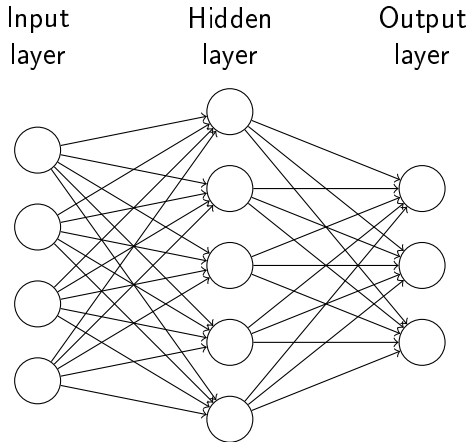


Figure: A common ANN-structure represented by a directed graph.

Artificial Neural Networks

- > Class of machine learning algorithms
 - > Loosely inspired by biological nervous systems
- > Collection of artificial neurons that are connected with each other
 - > Enables them to exchange signals along their connections
 - > Can be represented by a directed graph
- > Usually arranged in layers
 - > *Input Layer* collects input signals and passes them on
 - > *Hidden Layers* apply transformations to incoming signals and pass the outcomes further into the network
 - > *Output Layer* applies a final transformation representing the networks' result
- > Goal: Convert input into meaningful output by applying multiple transformations

Modeling Artificial Neurons

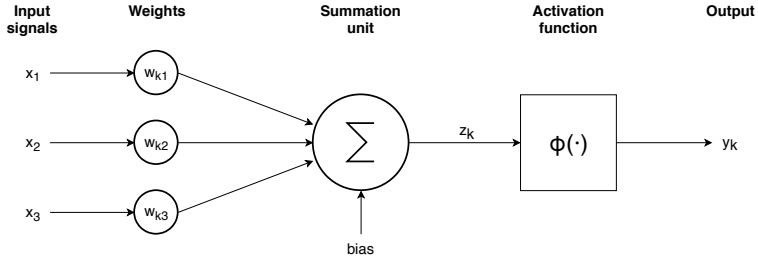


Figure: The components of a single artificial neuron k .

Components of the neural model

- > A set of weighted inputs
 - > Each input originating from neuron j and traveling into neuron k is first multiplied by a weight w_{kj}
- > A summation unit
 - > All the weighted inputs are summed and a constant value, the *bias*, is added to yield the result z_k
- > An activation function
 - > Applies a non-linear transformation $\phi(\cdot)$ to the output of the summation unit
 - > This result, called y_k , is propagated further into the network alongside the connections



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