Efficient Low Diameter Clustering

with strong diameter in the CONGEST model

Christian Micheletti



About this Presentation



- 1. Distributed Algorithms
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- 3. Network Decomposition
- 4. Computing a Clustering
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Distributed Algorithms



- We want to solve graph problems on **networks**
 - Computers are like nodes in a graph

Distribution ⇒ Multiple processors



- We want to solve graph problems on **networks**
 - Computers are like nodes in a graph

Distribution ⇒ Multiple processors



Each node gives a partial solution

At the end they are all combined altogether

Distributed Algorithms



...how can we combine those partial solutions?



Distribution ⇒ Collaboration

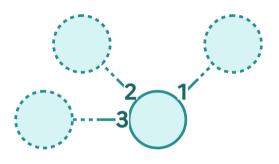
- Arcs are direct links between computers
 - Computers have to exchange messages

A First Simple Model

Distributed Algorithms



- In the PN-Network a node only knows some Numbered Ports
 - Connected with a different nodes
 - Such nodes are called "neighbours"
- There are no self loops





A node can't see the whole topology





All nodes appear identical

- The only difference could be in the total number of ports
 - Not enough!
- We must break this symmetry





We add unique identifiers to the nodes

 $id:V\to\mathbb{N}$

where $\forall v \in V : id(v) \le n^c$ for some $c \ge 1$

We choose n^c so that we need $O(\log n)$ bits to represent an identifier, i.e. identifiers are reasonably "small"

Communication (Intuition)

Distributed Algorithms



- Collaborating requires exchanging messages
 - ...on a medium that is slow and unreliable



- ⇒ Communication is the main pitfall
- We are intersted in quantifying the number of messages that algorithms need
 - An "efficient" algorithm will need few messages

Communication Model

Distributed Algorithms



W.l.o.g.¹ we adopt a model of "synchronous communication"

Each round, a node $v \in V$ performs this actions:

- 1. v "sends" a message $msg \in \mathbb{N}$ to its neighbours;
- 2. v "receives" messages from its neighbours;
- 3. ...
- (1.) and (2.) establish a "communication round"
 - Main measure of complexity

¹Without loss of generality.

Communication Model

Distributed Algorithms



- 3. v "executes locally" some algorithm (same for each node).
 - A node can "stop" in this phase
 - (3.) doesn't affect the algorithm's complexity
- When all nodes stopped the algorithm terminates

A First Example (WAVE)

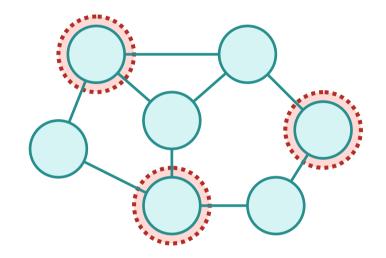
Distributed Algorithms



- The node with id(v) = 1 "waves hello" to neighbours
 - ...sending them a message
- When a node receives the message, forwards it to its neighbours
 - And then stops
- The running time of this algorithm on a graph G is O(diam(G))



Example: Maximal Independent Set (MIS)



- Solving it "centralized" is easy
- How can we solve it "distributed"?

A Second Example (Naive-MIS)

Distributed Algorithms





Let's leverage id(v) to select the next MIS node

- At round #i, node v : id(v) = i executes
 - If no neighbour is in the MIS, add the node
 - And inform the neighbours
 - Otherwise, the node is outside the MIS
- It is correct since no node has the same id
- This algorithm runs in $O(n^c)$ (the maximum id)
 - Very bad

Distributed Algorithms



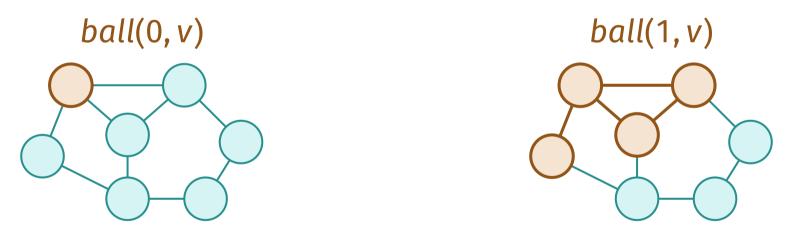


Running a centralized algorithm on a single node would take O(1) rounds

- We'd like to run a MIS algorithm on each node
 - ► Each must have a **local copy** of the **entire** graph
 - The algorithm must be deterministic
 - When a node stops it checks if it is included in MIS



- The algorithm Gather-All makes all nodes build a local copy of the whole graph
 - At round i, each node v knows ball(i, v)



All nodes will know the whole graph after O(diam(G)) rounds

Critique to LOCAL

Distributed Algorithms



• Gather-All assumes that messages size is unbounded



Requires to send the whole graph in one message

- It is not always possible to send arbitrary large messages
 - Heavy ones may be "sharded"
- We provide an upper bound for message size
 - Messages need to be reasonably "small"
 - Large messages will require more rounds to be sent



In the CONGEST model, messages size has to be $O(\log n)$

- Sending k identifiers takes O(1) rounds
- Sending a set of identifiers can take up to O(n)
- Sending the whole graph requires $O(n^2)$ rounds:
 - ► The adjacency matrix suffices...



⇒ We can't use Gather-All in the CONGEST model

We've established our computation model

Now we'll see how to solve problems in CONGEST

MIS in CONGEST

Censor-Hillel et al. provided an algorithm that solves MIS in O(diam(G) log² n) in CONGEST [1]



The diameter can be very large Worst case: diam(G) = n

Network Decomposition



- A <u>Network Decomposition</u> groups nodes in <u>colored</u> clusters
 - Clusters with the same color are not adjacent
 - We say it to <u>"have diameter"</u> d if all of its clusters have diameter at most d
 - ► It has c colors



Solving MIS in a color will give a correct partial solution

- We can iterate this action with [1] for all colors
 - (dropping neighbours of different colors)
- This algorithm has complexity $O(c \cdot d \log^2 n)$
 - ▶ If $c = O(\log n) = d$ then we would have a MIS algorithm in polylogarithmic time

How to compute one?





Each color induces a low diameter clustering

<u>def:</u> A <u>low diameter clustering</u> $\mathscr{C} \subseteq 2^V$ for a graph G with diameter d is such:

- 1. $\forall C_1 \neq C_2 \in \mathscr{C} : dist_G(C_1, C_2) \geq 2$
 - ""There are no adjacent clusters""
- 2. $\forall C \in \mathscr{C} : diam(G[C]) \leq d$
 - ""Any cluster has diameter at most"" d

How to compute one?





A clustering "can not be a partitioning": some nodes have to be left out

Main iteration:

- 1. Find a low diameter clustering
- 2. Assign a free color to its nodes
- 3. Repeat to discarded nodes until there are no more left

How to compute one?







To get a $O(\log n)$ -colors decomposition, each color has to cluster **at least half** of the uncolored nodes

Definitions

Our previous definition of diamter is also called <u>strong</u> diameter

<u>def:</u> We say a clustering has <u>weak</u> diameter when:

- 1. (unchanged) "There are no adjacent clusters"
- 2. "Any cluster has diameter "in G" at most" d

Introduction



- The main accomplishment of [2] is to provide a straightforward algorithm that:
 - ▶ Terminates in $O(\log^6 n)$ rounds in the CONGEST model
 - Outputs a clustering with $O(\log^3 n)$ colors
 - The clustering has strong diameter
- Previously [3] provided an algorithm for low diameter clustering with "weak" diameter
 - $O(\log^7 n)$ rounds with $O(\log^3 n)$ colors
 - It's possible to turn it into strong diameter

- [4] provided strong diameter in $O(\log^4 n)$ rounds with $O(\log^3 n)$ colors
 - Still has to pass by a weak diameter intermediate solution

"Phases"

- There are $b = \log(\max i) = O(\log n)$ "phases"
- "One phase for each bit in index"
 - ▶ Phase $i \in [0, b-1]$ computes ""terminals" set" Q_i

"Notation"

- Q_i is the terminals set built before phase i
- Q_b is the terminals set built after phase b-1

"Objective 1:" Creating connected components with low diameters

- Eventually, each connected component will contain exactly one terminal
 - Keep terminals <u>close</u> to active nodes
 - This ensures polylogarithmic diameter
 - Removing nodes is allowed
- Q_{i+1} is "closer" than Q_i to any node
 - Q_b is <u>close</u> to any node

Algorithm Outline (informal)





"Objective 2:"

- The algorithm must cluster at least $\frac{n}{2}$ nodes
 - Each phase **removes** at most $\frac{n}{2b}$ nodes

"Further notation:"

- V_i is the set of **living nodes** at the beginning of phase i $(V_0 = V)$
- V' is the set of living nodes after the last phase;

Phase Invariants $\forall i \in [0..b]$





- 1. Q_i is R_i -ruling, i.e. $dist_G(Q_i, v) \le R_i$ for all $v \in V$
 - We set $R_i = i * O(\log^2 n)$
 - Q_0 is 0-ruling, trivially true with $Q_0 = V$
 - Q_b is $O(\log^3 n)$ -ruling

Each node has polylogarithmic distance from $Q_b \Rightarrow$ each connected component has "at least one" terminal

- 2. let $q_1, q_2 \in Q_i$ s.t. they are in the same connected component in $G[V_i]$. Then $id(q_1)[0..i] = id(q_2)[0..i]$
 - for i = 0 it's trivially true
 - for i = b there is ≤ 1 terminal in each c.c.

Along with invariant (1.), it means that each c.c. has polylogarithmic diameter!

Phase Invariants $\forall i \in [0..b]$



3.
$$|V_i| \ge \left(1 - \frac{i}{2b}\right) |V|$$

- $V_0 \ge V$
- $V' \geq \frac{1}{2} |V|$

"The algorithm doesn't discard too much vertexes from the graph" "Objective:" Keeping only terminals from which is possible to build a forest whose trees have polylogarithmic diameter

Leaves of the trees may be connected in G

"Outline:"

- 2b² "steps", each computing a forest
- resulting into a sequence of forests $F_0..F_{2b^2}$

"Inductive definition:"

- F_0 is a BFS forest with roots in Q_i
- let T be any tree in F_i and r its root
 - if id(r)[i] = 0 the whole tree is red, if not blue
 - red vertexes stay red
 - some blue nodes stay blue
 - some others "propose" to join red trees

"Proposal:"

$$v \in V_j^{propose} \Leftrightarrow v \text{ is `blue'}$$

 $\land v$ is the only one in path(v, root(v)) that neighbours a `red` node

Define T_v the (blue) subtree rooted at v



v is the only node in T_v that is also in $V_j^{propose}$

"Proposal:"

- Each node in $V_j^{propose}$ proposes to an arbitrary red neighbour
- Each red tree decides to grow or not
 - If it grows, it accepts all proposing trees
 - If not, all proposing subtrees are frozen
- "Criteria:" it decides to grow if it would gain at least $\frac{|V(T)|}{2b}$ nodes





If the red tree doesn't decide to grow, it will neighbour red nodes only

- This means it will be able to delete nodes only once in the whole phase

 - ⇒ At most $\frac{|V|}{2b}$ nodes are lost in each phase ⇒ After the *b* phases at most $\frac{|V|}{2}$ nodes are removed

High Level Pseudocode

Computing a Clustering

1:
$$V_0 \leftarrow V$$

2: $Q_0 \leftarrow V$
3: **for** $i \in 0...b - 1$ **do**
4: INIT F_0
5: **for** $j \in 0...2b^2 - 1$ **do**
6: BUILD $V_j^{propose}$
7: $F_{j+1} \leftarrow \text{STEP}$ $O(diam(T_v))$ $b = O(\log n)$
8: $V_{i+1} \leftarrow V(F_{2b^2})$
9: $Q_{i+1} \leftarrow roots(F_{2b^2})$

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Step Complexity



- Recall invariant (1.)
 - ► $\forall v \in V : dist_G(Q_i, v) = O(\log^3 n)$, for all $i \in 0...b$
 - ► Hence, $diam(T_v) = O(\log^3 n)$, for all $v \in V$
- Complexity is #steps × #phases × $O(diam(T_v))$
 - $= O(\log n) \times O(\log^2 n) \times O(\log^3 n)$

The algorithm runs in $O(\log^6 n)$ communication steps

- We've seen how to build a **low diameter clustering** $(O(\log^6 n))$
 - It clusters at least $\frac{n}{2}$ nodes
- We can apply that until all nodes have a color
 - ► O(log n) steps and therefore O(log n) colors
- For each color, we solve MIS [1]
 - ▶ In parallel in the clusters $(O(\log^3 n \times \log^2 n))$
- \Rightarrow We end up solving MIS in $O(\log^6 n)$ rounds

Bibliography

- [1] K. Censor-Hillel, M. Parter, and G. Schwartzman, "Derandomizing Local Distributed Algorithms under Bandwidth Restrictions." [Online]. Available: https://arxiv.org/abs/1608.01689
- [2] V. Rozhoň, B. Haeupler, and C. Grunau, "A Simple Deterministic Distributed Low-Diameter Clustering." [Online]. Available: https://arxiv.org/abs/2210.11784

- [3] V. Rozhoň and M. Ghaffari, "Polylogarithmic-Time Deterministic Network Decomposition and Distributed Derandomization." [Online]. Available: https://arxiv.org/abs/1907.10937
- [4] V. Rozhoň, M. Elkin, C. Grunau, and B. Haeupler, "Deterministic Low-Diameter Decompositions for Weighted Graphs and Distributed and Parallel Applications." [Online]. Available: https://arxiv.org/abs/2204.08254

About this presentation

This presentation is supposed to briefly showcase what you can do with this package.

For a full documentation, read the online book.

Let's explore what we have here.

On the top of this slide, you can see the slide title.

We used the title argument of the #slide function for that:

```
#slide(title: "First slide")[
    ...
]
```

(This works because we utilise the clean theme; more on that later.)

Titles are not mandatory, this slide doesn't have one.

But did you notice that the current section name is displayed above that top line?

We defined it using #new-section-slide("Introduction").

This helps our audience with not getting lost after a microsleep.

You can also spot a short title above that.

The bottom of the slide



Now, look down!

There we have some general info for the audience about what talk they are actually attending right now.

You can also see the slide number there.

Dynamic content



Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magnam aliquam quaerat voluptatem. Ut enim aeque doleamus animo, cum corpore dolemus, fieri tamen permagna accessio potest, si aliquod aeternum et infinitum impendere malum nobis opinemur. Quod idem licet transferre in voluptatem, ut postea variari voluptas distinguique possit, augeri amplificarique non possit. At etiam Athenis, ut e.

A dynamic slide with pauses

Dynamic content



Sometimes we don't want to display everything at once.

A dynamic slide with pauses

Dynamic content



Sometimes we don't want to display everything at once.

That's what the #pause function is there for!



Sometimes we don't want to display everything at once.

That's what the #pause function is there for!

It makes everything after it appear at the next subslide.

(Also note that the slide number does not change while we are here.)

Fine-grained control

Dynamic content



When #pause does not suffice, you can use more advanced commands to show or hide content.

These are some of your options: - #uncover

- #only
- #alternatives
- #one-by-one
- #line-by-line

Let's explore them in more detail!

Dynamic content



With #uncover, content still occupies space, even when it is not displayed.

For example, are only visible on the second "subslide".

In () behind #uncover, you specify when to show the content, and in [] you then say what to show:

#uncover(3)[Only visible on the third "subslide"]



With #uncover, content still occupies space, even when it is not displayed.

For example, these words are only visible on the second "subslide".

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#uncover(3)[Only visible on the third "subslide"]

Only visible on the third"subslide"

Dynamic content



So far, we only used single subslide indices to define when to show something.

We can also use arrays of numbers ...

```
\#uncover((1, 3, 4))[Visible on subslides 1, 3, and 4]
```

Visible on subslides 1, 3, and 4

...or a dictionary with beginning and/or until keys:





```
#uncover((beginning: 2, until: 4))[Visible on subslides 2, 3,
and 4]
```



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Dynamic content



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Dynamic content



```
#uncover((beginning: 2, until: 4))[Visible on subslides 2, 3,
and 4]
Visible on subslides 2, 3, and 4
```

Convenient rules as strings

Dynamic content



As as short hand option, you can also specify rules as strings in a special syntax.

Comma separated, you can use rules of the form

- 1-3 from subslide 1 to 3 (inclusive)
 - -4 all the time until subslide 4 (inclusive)
 - 2- from subslide 2 onwards
 - 3 only on subslide 3

Dynamic content



Everything that works with #uncover also works with #only.

However, content is completely gone when it is not displayed.

For example, the rest of this sentence moves.

Again, you can use complex string rules, if you want.

#only("2-4, 6")[Visible on subslides 2, 3, 4, and 6]



Everything that works with #uncover also works with #only.

However, content is completely gone when it is not displayed.

For example, see how the rest of this sentence moves.

Again, you can use complex string rules, if you want.

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Visible on subslides 2, 3, 4, and 6

You might be tempted to try

```
#only(1)[Ann] #only(2)[Bob] #only(3)[Christopher] likes #only(1)
[chocolate] #only(2)[strawberry] #only(3)[vanilla] ice cream.

Ann
likes chocolate
ice cream.
```

But it is hard to see what piece of text actually changes because everything moves around. Better:

#alternatives: Substituting content





```
#alternatives[Ann][Bob][Christopher] likes
#alternatives[chocolate][strawberry][vanilla] ice cream.
```

Ann likes chocolate ice cream.



You might be tempted to try

```
#only(1)[Ann] #only(2)[Bob] #only(3)[Christopher] likes #only(1)
[chocolate] #only(2)[strawberry] #only(3)[vanilla] ice cream.

Bob
likes strawberry
ice cream.
```

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#alternatives: Substituting content

Dynamic content



```
#alternatives[Ann][Bob][Christopher] likes
#alternatives[chocolate][strawberry][vanilla] ice cream.
Bob likes strawberry ice cream.
```

You might be tempted to try

```
#only(1)[Ann] #only(2)[Bob] #only(3)[Christopher] likes #only(1)
[chocolate] #only(2)[strawberry] #only(3)[vanilla] ice cream.
Christopher
likes vanilla
ice cream.
```

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```
#alternatives[Ann][Bob][Christopher] likes
#alternatives[chocolate][strawberry][vanilla] ice cream.
```

Christopher likes vanilla ice cream.



#alternatives is to #only what #one-by-one is to #uncover.

#one-by-one behaves similar to using #pause but you can additionally state when uncovering should start.

```
#one-by-one(start: 2)[one ][by ][one]
```

start can also be omitted, then it starts with the first subside:



```
#one-by-one[one ][by ][one]
```

one



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one
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```
#one-by-one[one ][by ][one]
oneby
```



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oneby
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onebyone



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#one-by-one[one][by][one]
onebyone



Sometimes it is convenient to write the different contents to uncover one at a time in subsequent lines.

This comes in especially handy for bullet lists, enumerations, and term lists.

```
#line-by-line(start: 2)[
   - first
   - second
   - third
]
```



start is again optional and defaults to 1.



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#line-by-line(start: 2)[
    - first
    - second
    - third
]
```

- first
- second
- third



start is again optional and defaults to 1.



While #line-by-line is very convenient syntax-wise, it fails to produce more sophisticated bullet lists, enumerations or term lists. For example, non-tight lists are out of reach.

For that reason, there are #list-one-by-one, #enum-one-by-one, and #terms-one-by-one, respectively.



Note that, for technical reasons, the bullet points, numbers, or terms are never covered.

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How a slide looks...



... is defined by the *theme* of the presentation.

This demo uses the unipd theme.

Because of it, the title slide and the decoration on each slide (with section name, short title, slide number etc.) look the way they do.

Themes can also provide variants, for example ...

... this one!

It's very minimalist and helps the audience focus on an important point.

Your own theme?



If you want to create your own design for slides, you can define custom themes!

The book explains how to do so.

The utils module



Polylux ships a utils module with solutions for common tasks in slide building.

Fit to height



You can scale content such that it has a certain height using #fit-to-height(height, content):

Fill remaining space



This function also allows you to fill the remaining space by using fractions as heights, i.e. fit-to-height(1fr)[...]:

Side by side content



Often you want to put different content next to each other. We have the function #side-by-side for that:

Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do.

Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore.

Lorem ipsum dolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor.

Outline



Why not include an outline?

- 1. Distributed Algorithms
- 2. Distributed Algorithms
- 3. Network Decomposition
- 4. Computing a Clustering
- 5. Computing a Clustering
- 6. Introduction

Outline



- 7. Dynamic content
- 8. Themes
- 9. Utilities
- 10. Typst features
- 11. Conclusion



Typst gives us so many cool things². Use them!

²For example footnotes!

Hopefully you now have some kind of idea what you can do with this template.

Consider giving it a GitHub star or open an issue if you run into bugs or have feature requests.