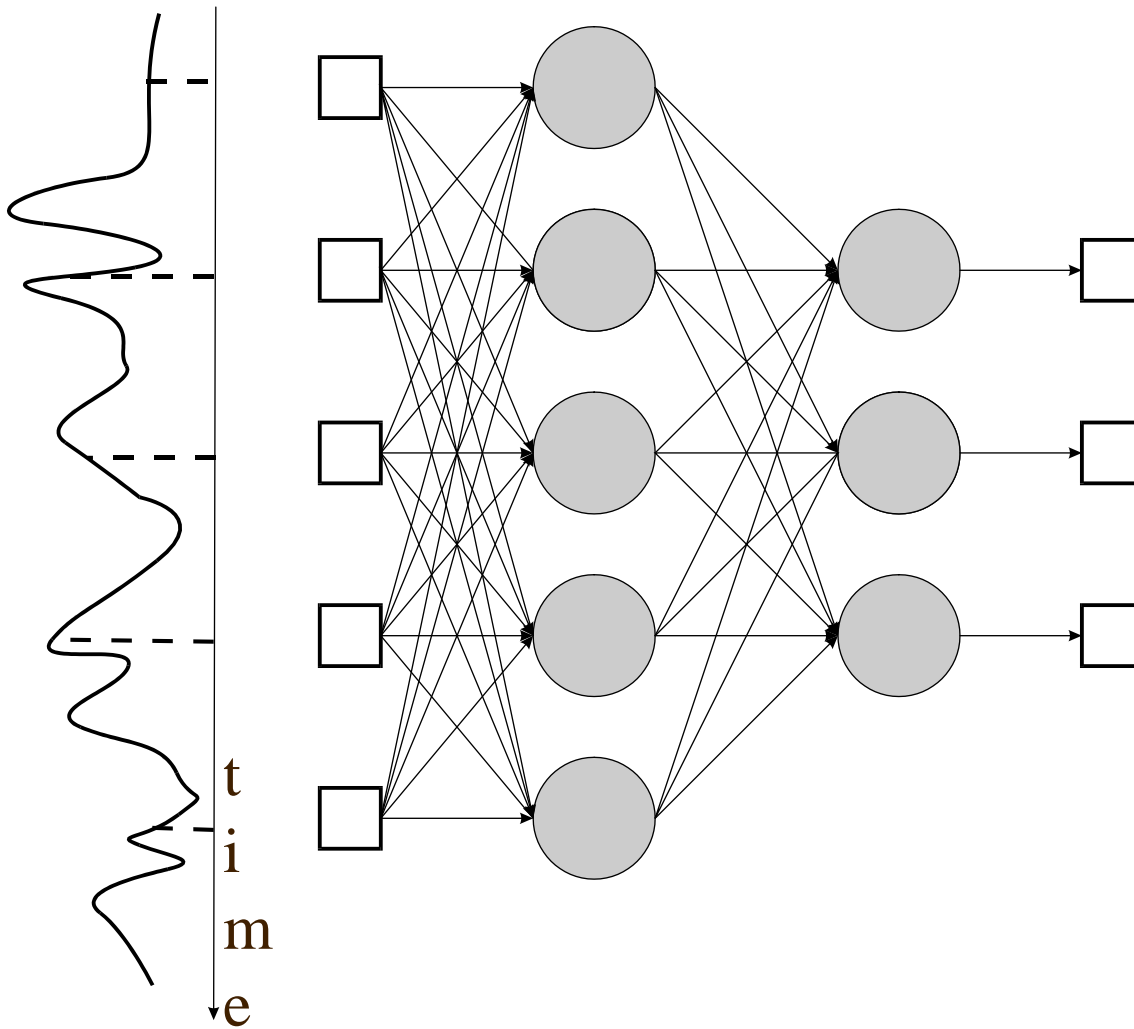


# Application of ANN to forecasting

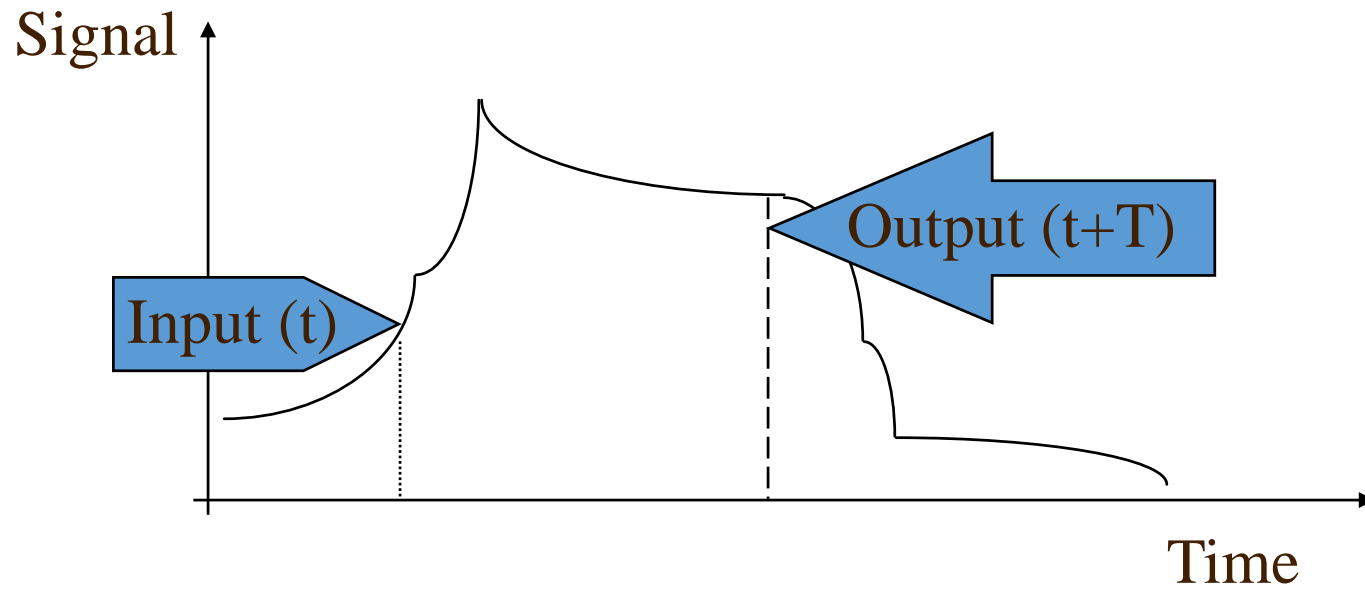
# Agenda

- Problems in applying ANN in time-domain
- Case-study: Current speed forecast in Oresund
- Drawbacks

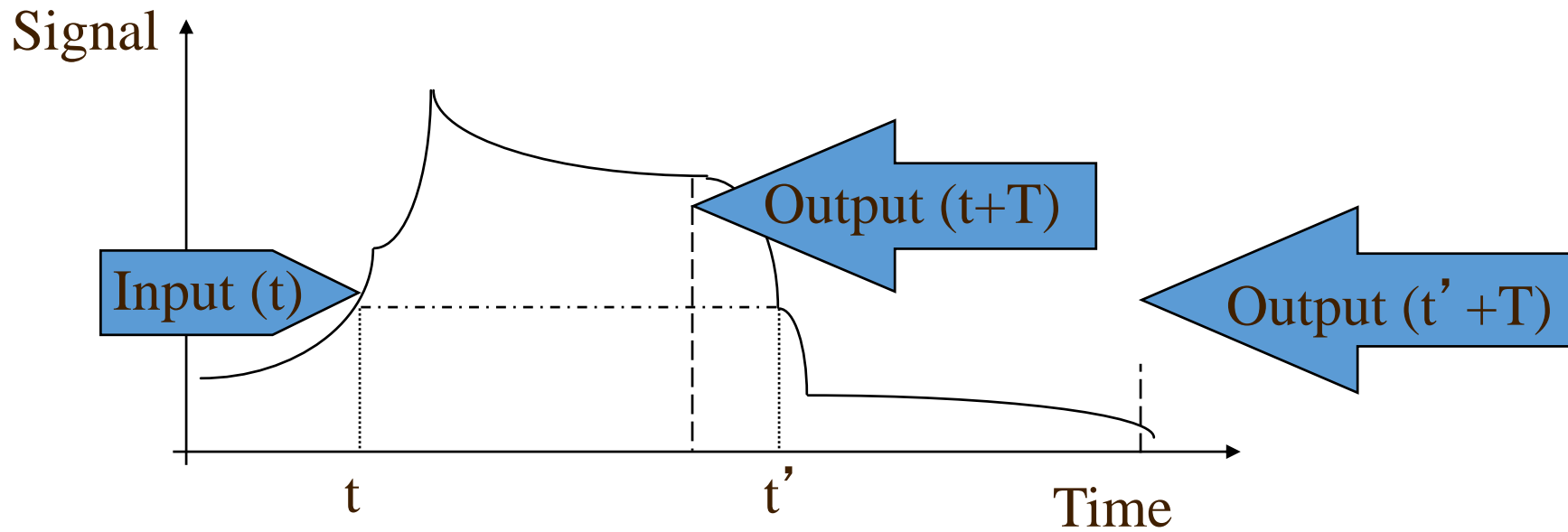
# Feedforward Network in Time



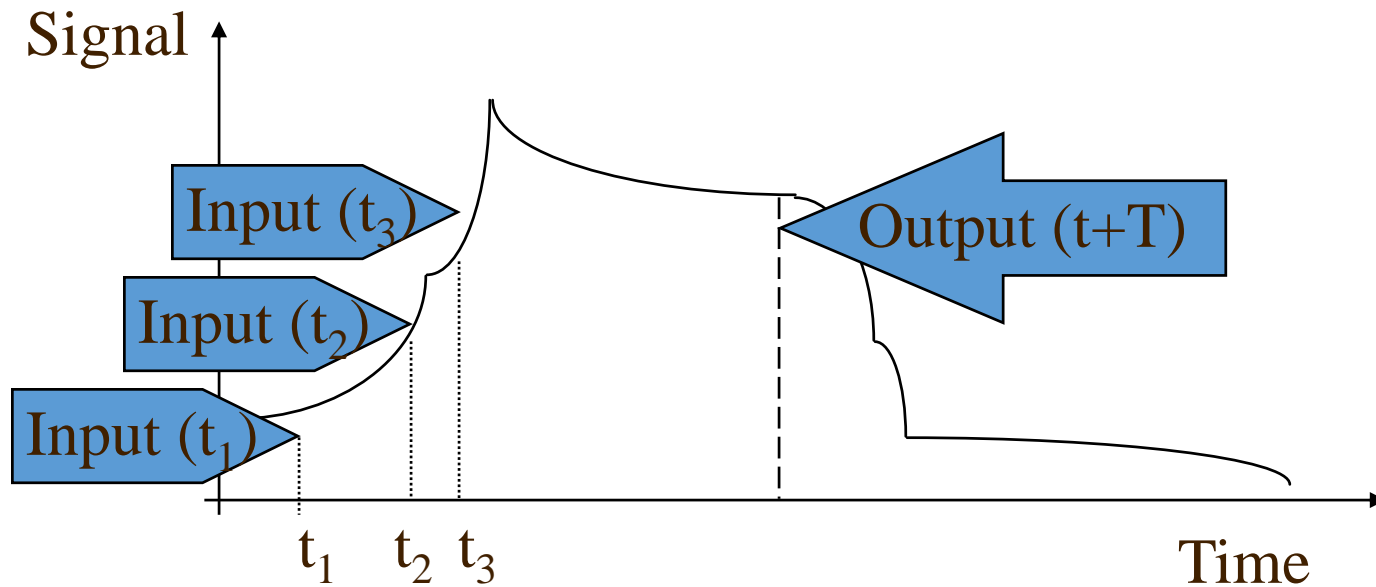
# Neural Network in Time



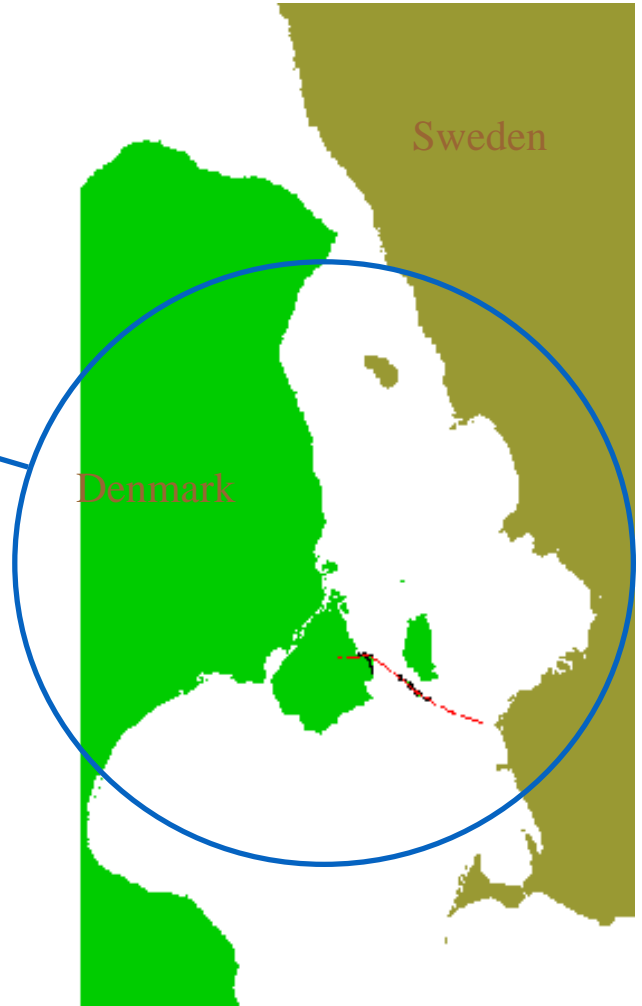
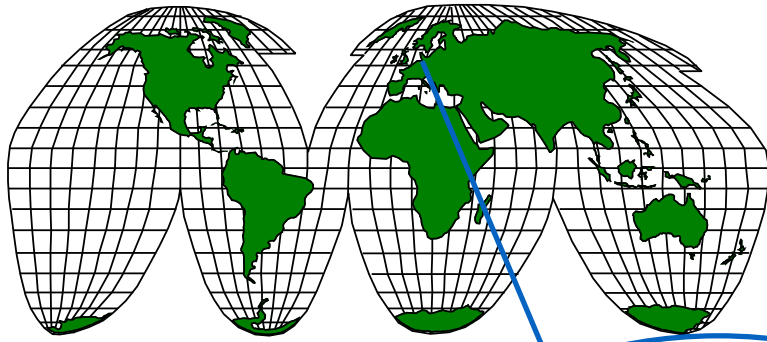
# Neural Network in Time



# Neural Network in Time



# Project Location



# The Project

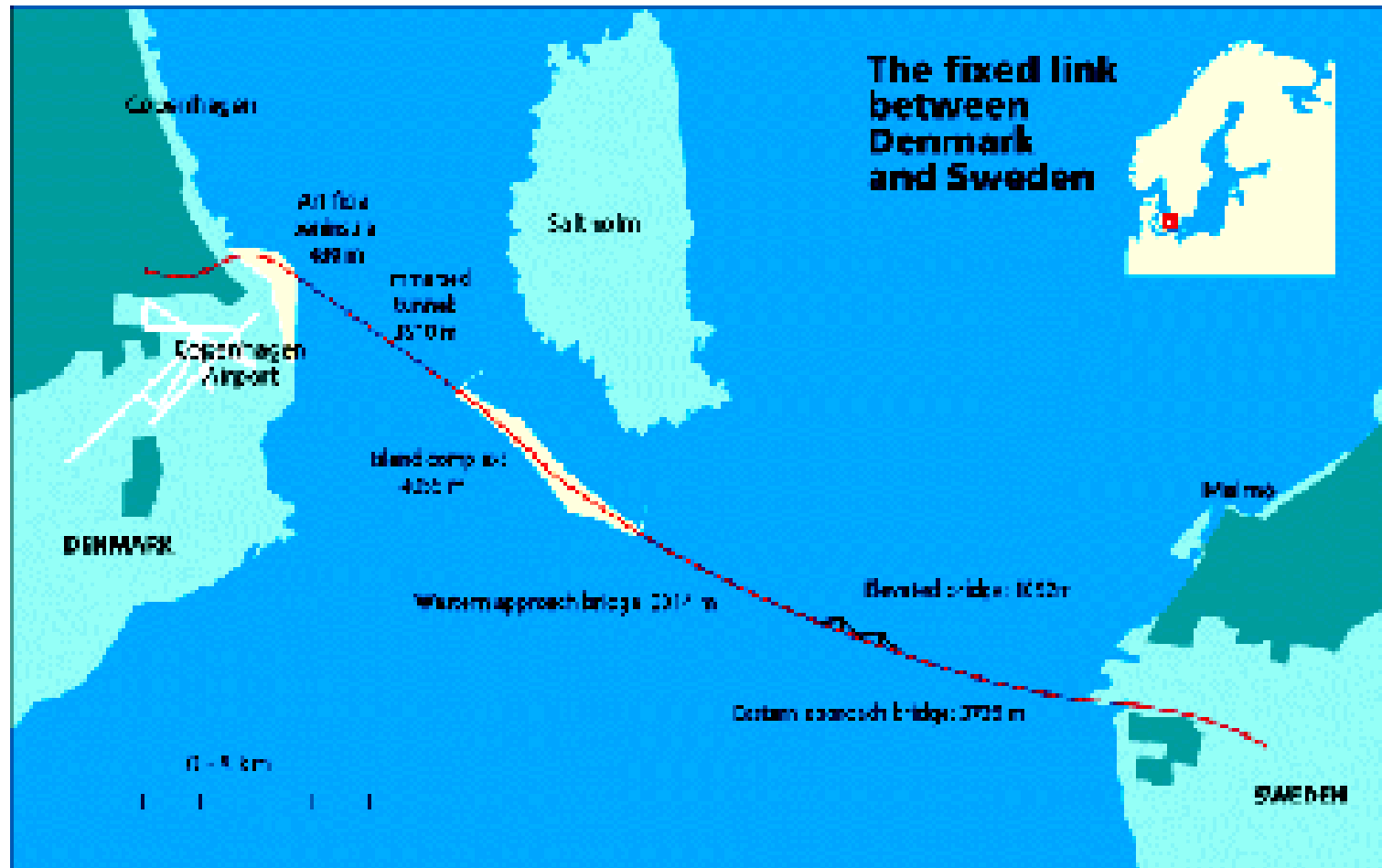


Total Span: 15.9 km

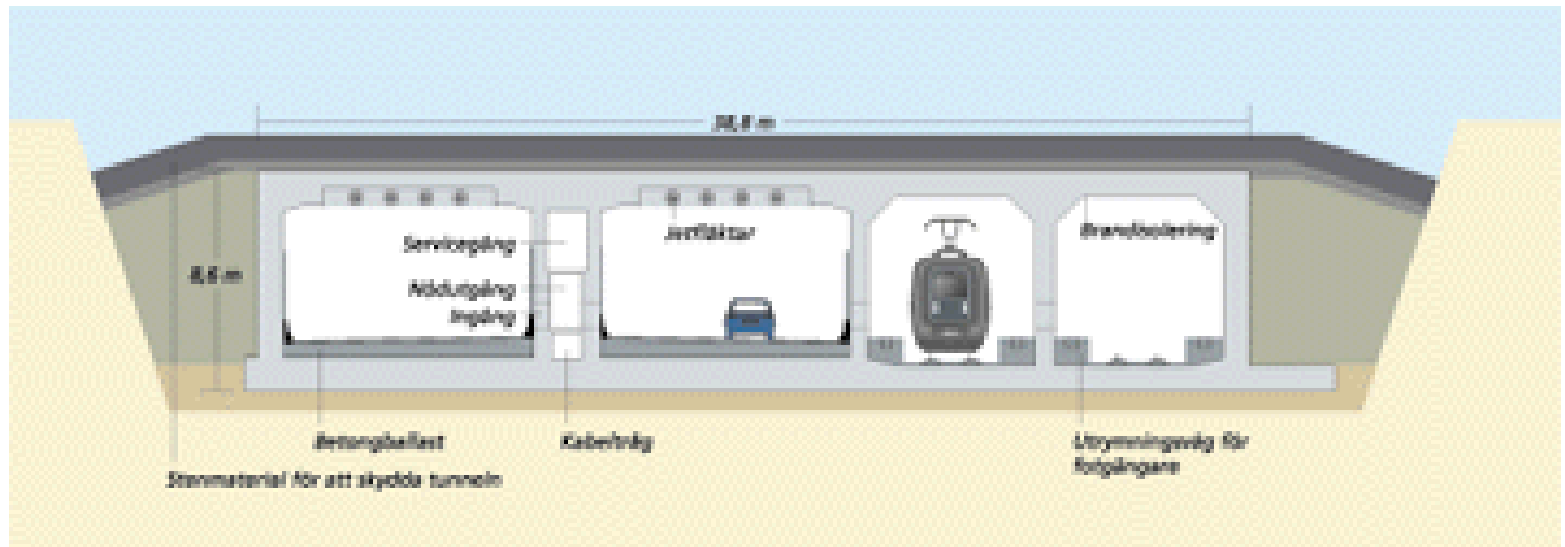
Total Cost: 3.7 billion US\$



# The Project



# Tunnel



# Bridge



# Tunnel Element Towing

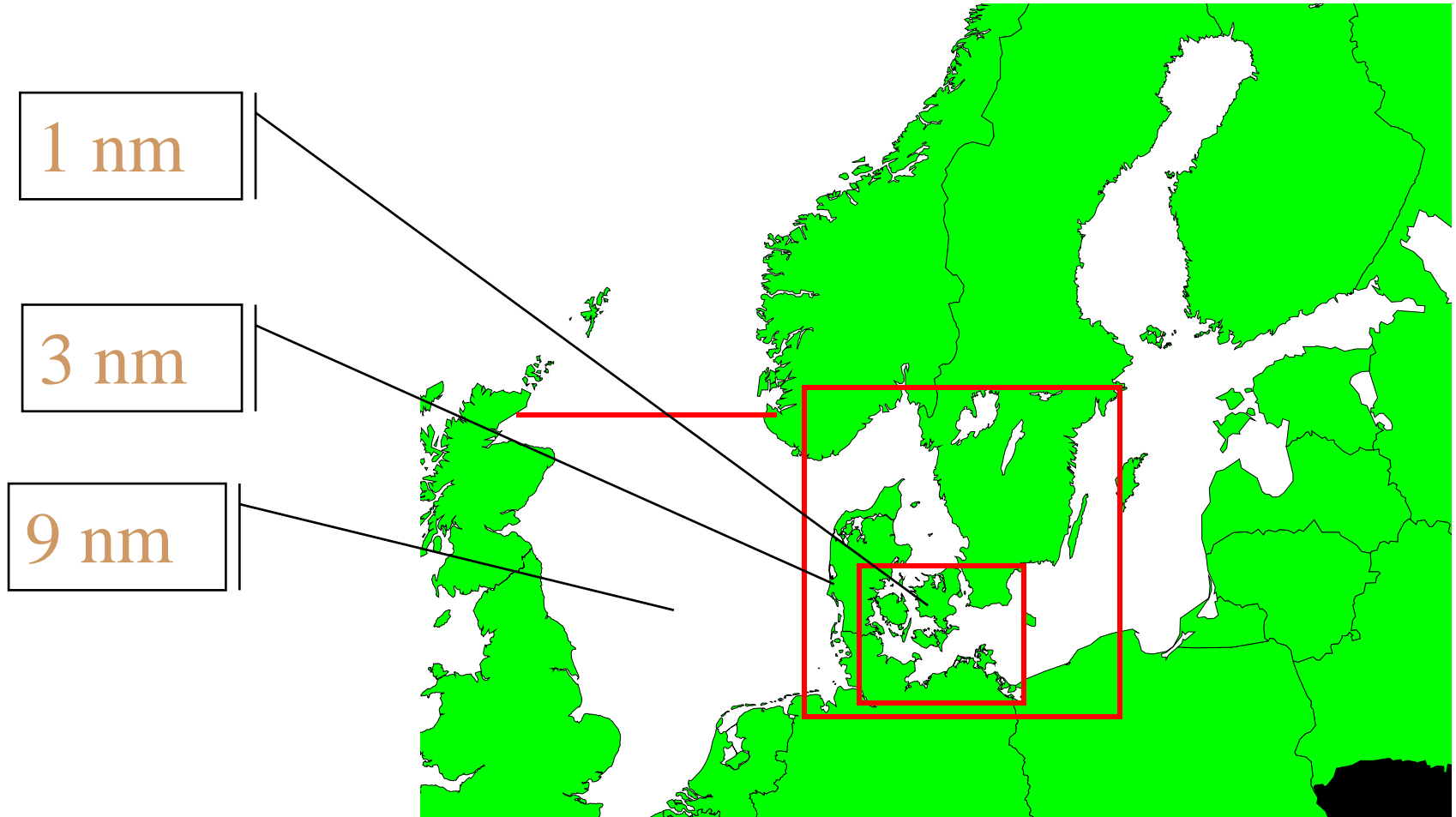
- 0.75 m/s  
(operational limit)
- 1.0 m/s (survival  
limit)
- 1.2 m/s (critical  
limit)

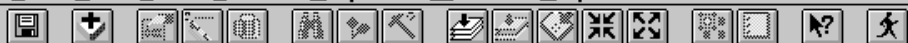


## 24 hour Weather Windows

|          | 0.75 m/s | 1.0 m/s | 1.25 m/s | 1.5 m/s |
|----------|----------|---------|----------|---------|
| February | 18.90%   | 49.90%  | 77.40%   | 93.70%  |
| August   | 50.70%   | 86.40%  | 96.80%   | 99.00%  |
| October  | 38.10%   | 68.00%  | 90.50%   | 98.30%  |

# Nested Deterministic Models



Scale 1: 469.28  
297.51

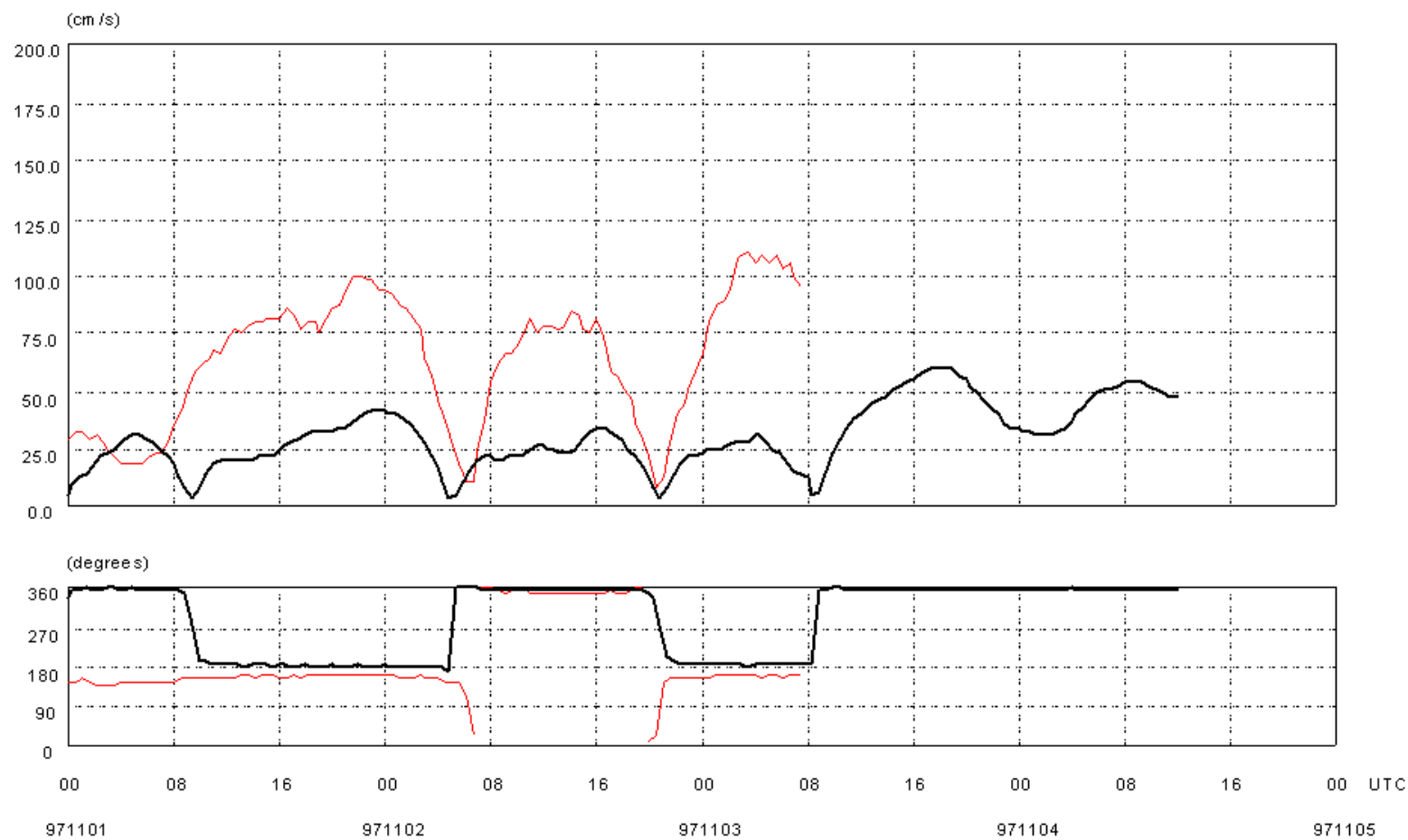
DMI Depth average (bins 1-17) Current - latest forecast - t0plot.odb

(C) DHI

Station 24 : Nordre Røse

971103 12:56

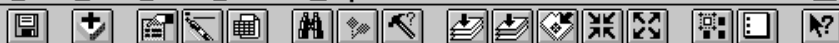
Average Current Speed and Direction, bin 1-17



# The Idea

- Use (local) observations (water levels, wind speed, current speed and direction)
- Use global information through models (pressure fields)
- Use ANNs as a data assimilation system



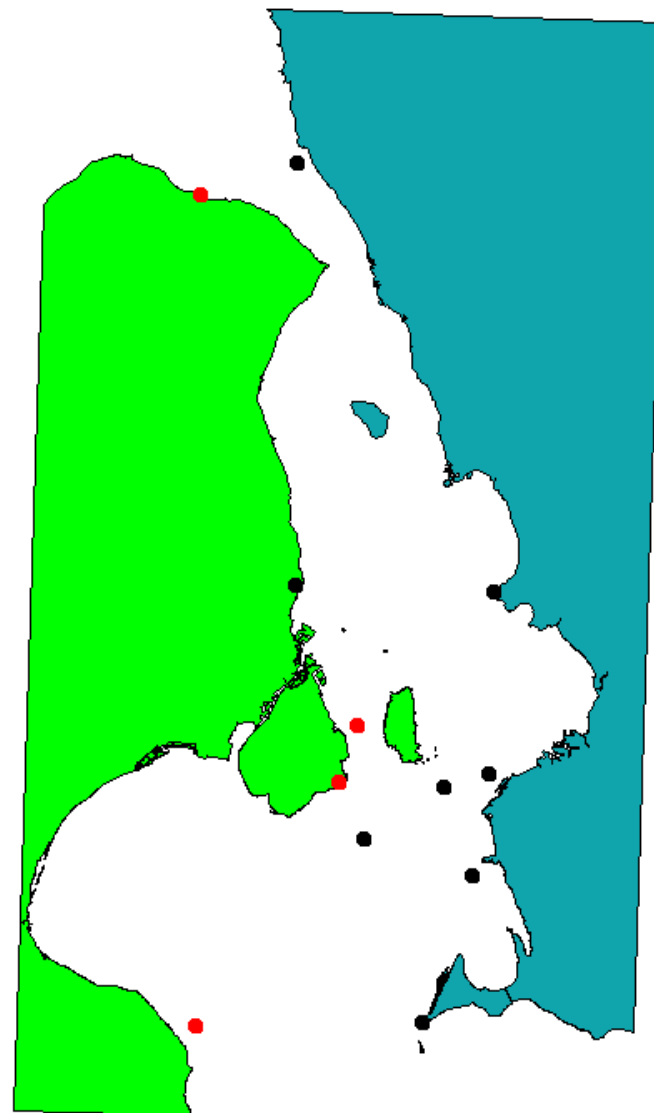


Scale 1: 616,086

421,817.35  
6,215,919.45

X-Disp

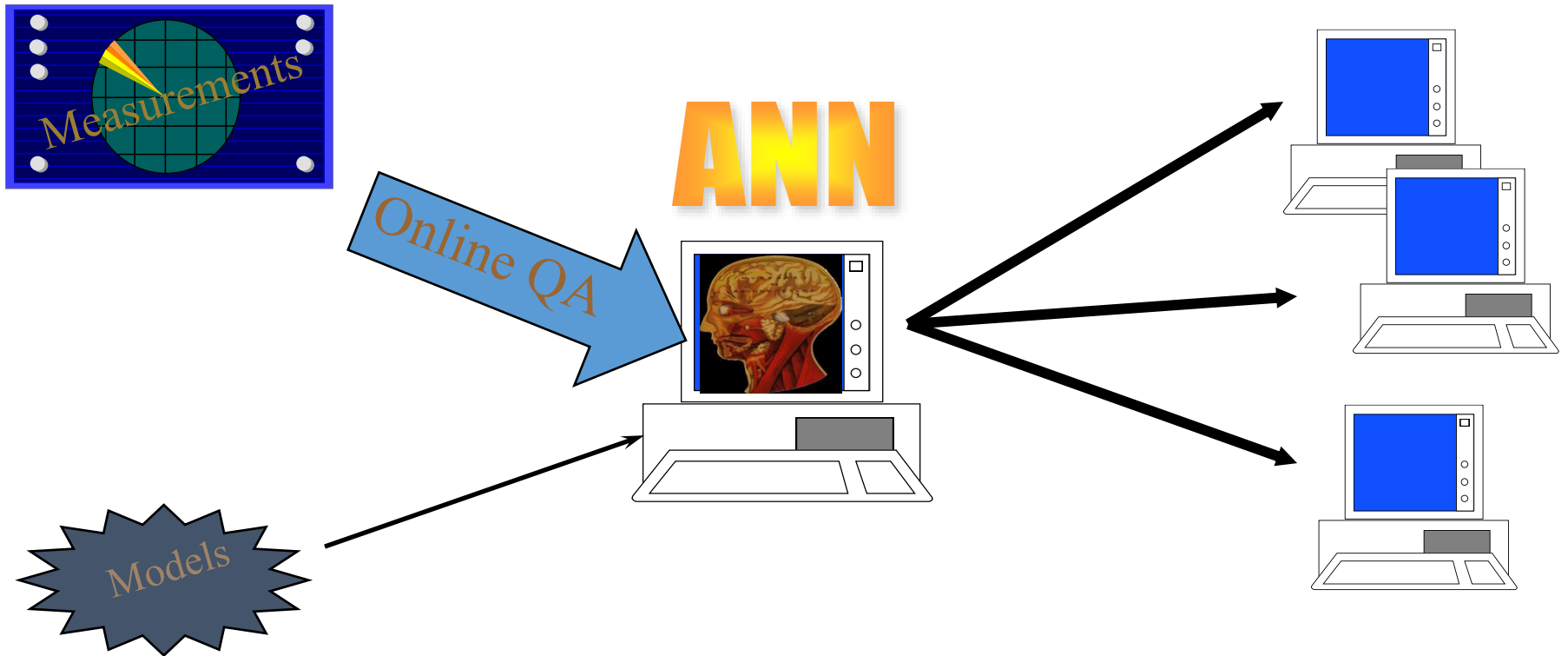
- ☐ ADCP
  - Acoustic Doppler Current Profiler
- ☐ Currentforecast
  - Currentforecast
- ☐ Meteorology
  - Meteorological Data - 10 Meter Wind
  - Meteorological data - Wind
- ☐ Temperature and Conductivity
  - TC(OT) Chain
- ☒ Water level
  - Acoustic Water Level Recorder
  - GMI Water Level Recorder
  - Mechanical Water Level Recorder
- ☒ Waterlevel forecast
  - Waterlevel forecast
- ☐ Wave recordings
  - Acoustic Wave Recorder
  - Wave Recorder
- ☒ Øresund

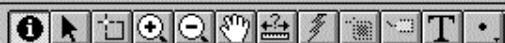
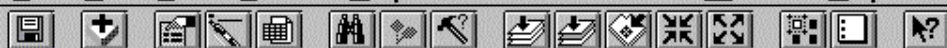


# Real-Time Current Forecast

- On-line observations
- Operational deterministic forecast (MIKE 21, HIRLAM)
- Artificial Neural Networks
- Forecast Window +36 hours
- Confidence limits (90%)

# System Architecture





Scale 1:

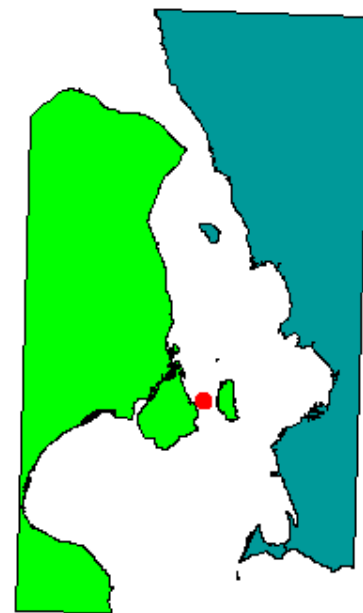
351,606.67  
6,127,541.88

Active sensors - 1 of 23 (1 selected)

| Station              | Sensor Type      |
|----------------------|------------------|
| Nordre Røse - DHI-24 | Current forecast |

X-Disp

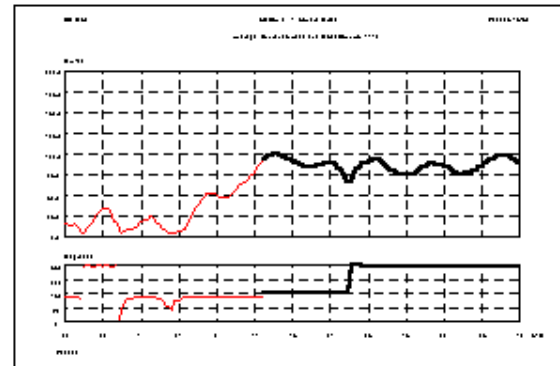
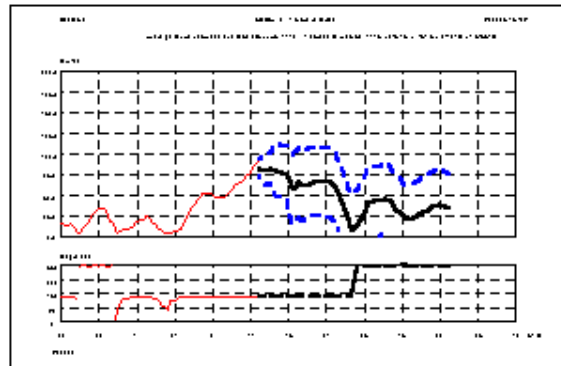
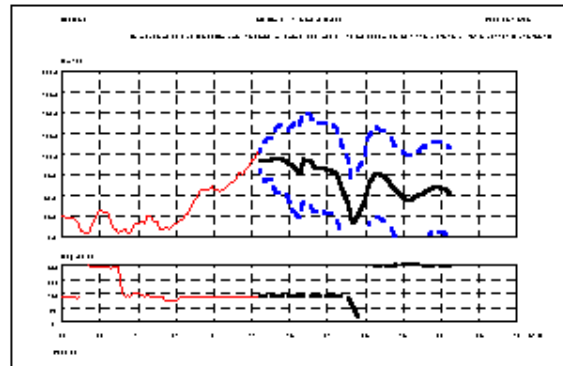
- ☐ ADCP
  - Acoustic Doppler Current Profiler
- ☒ Currentforecast
  - Currentforecast
- ☐ Meteorology
  - Meteorological Data - 10 Meter Wind
  - Meteorological data - Wind
- ☐ Temperature and Conductivity
  - TC(OT) Chain
- ☐ Water level
  - Acoustic Water Level Recorder
  - GMI Water Level Recorder
  - Mechanical Water Level Recorder
- ☐ Waterlevel forecast
  - Waterlevel forecast
- ☐ Wave recordings
  - Acoustic Wave Recorder
  - Wave Recorder
- ☒ Country



Nordre Røse - DHI-24 : Current forecast

Nordre Røse - DHI-24 : Current forecast - 2

Nordre Røse - DHI-24 : Current forecast - 3



Scale 1: 469.71  
306.50

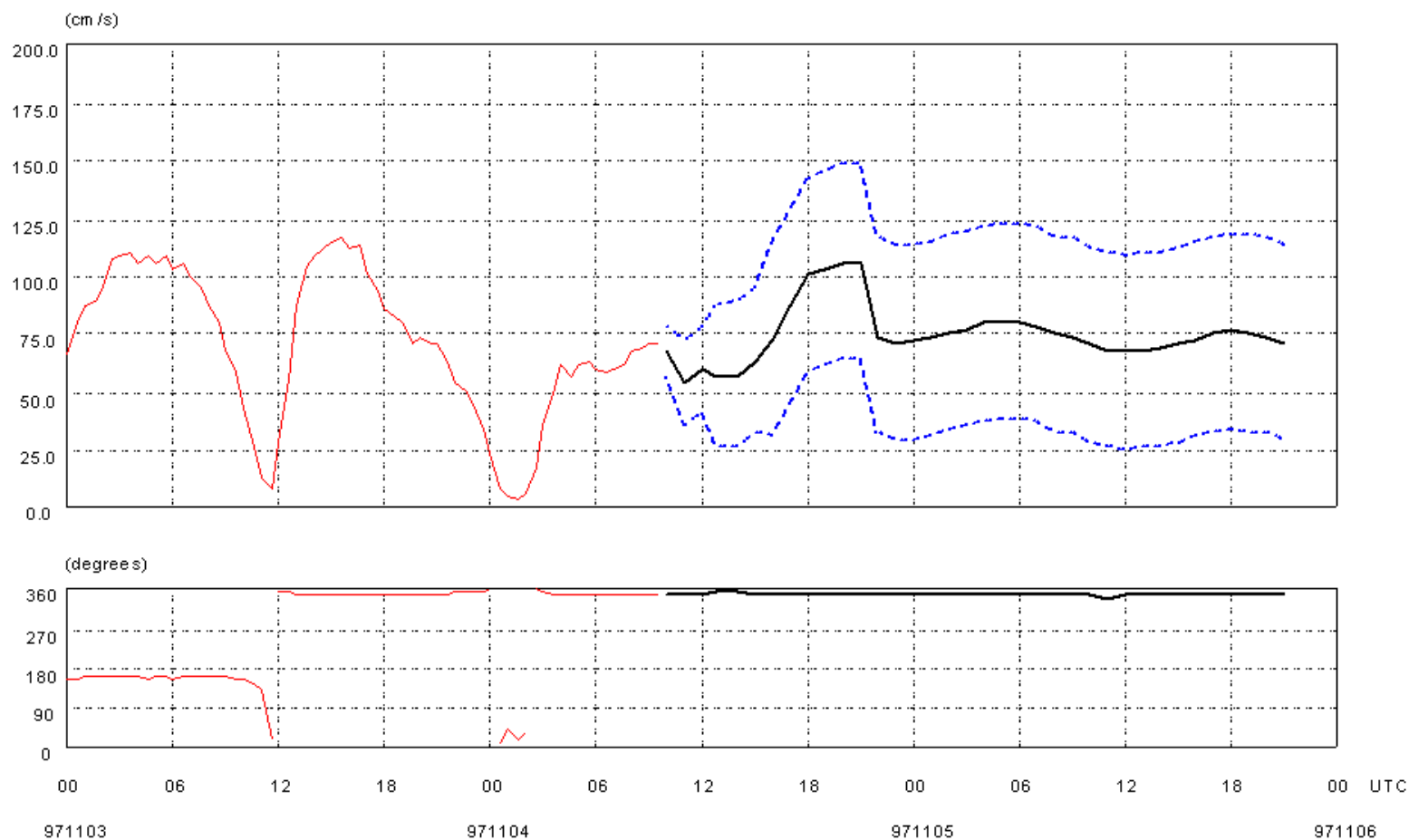
Nordre Røse - DHI-24 : Current forecast - 2

(C) DHI

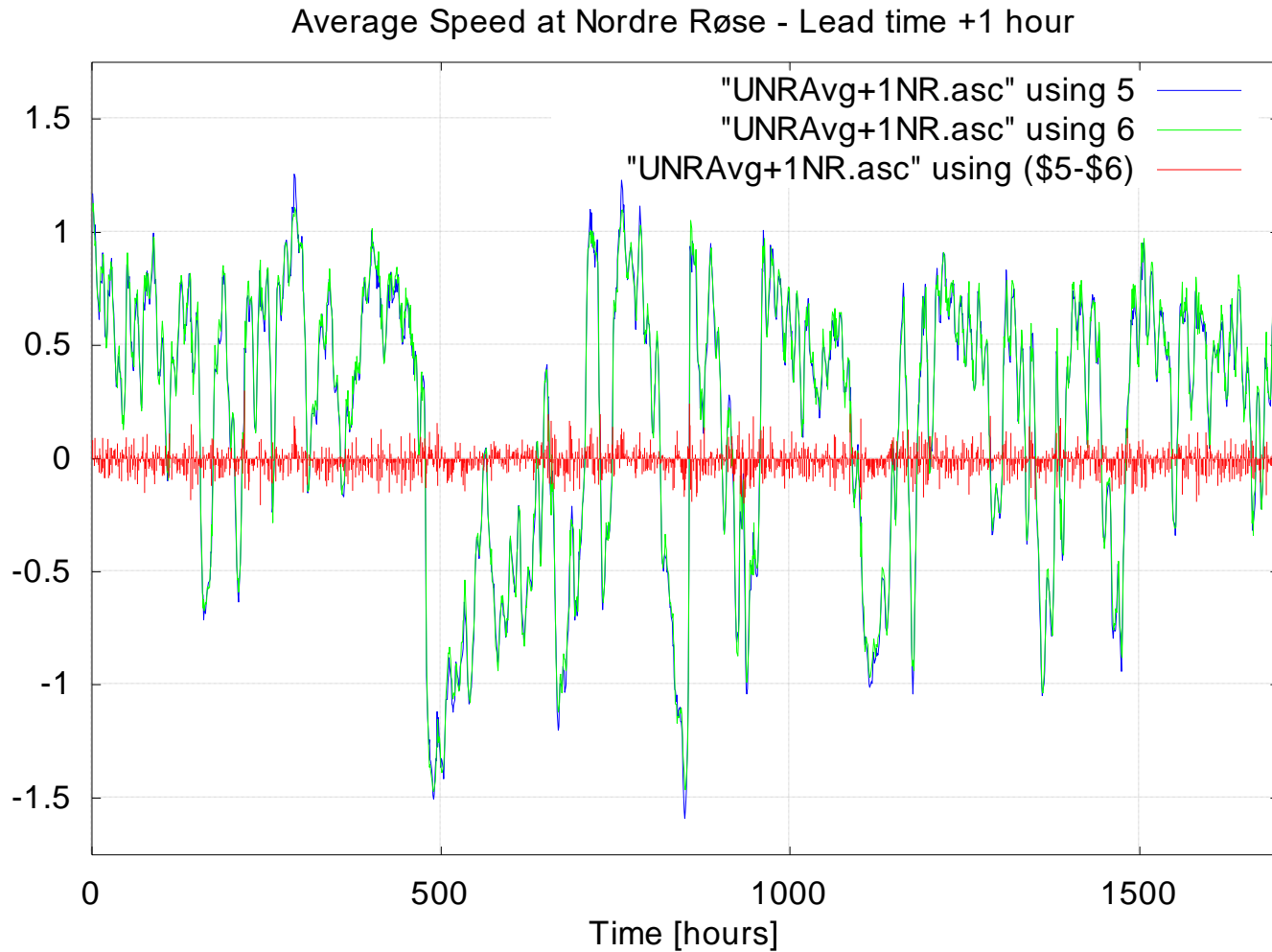
Station 24 : Nordre Røse

971104 10:28

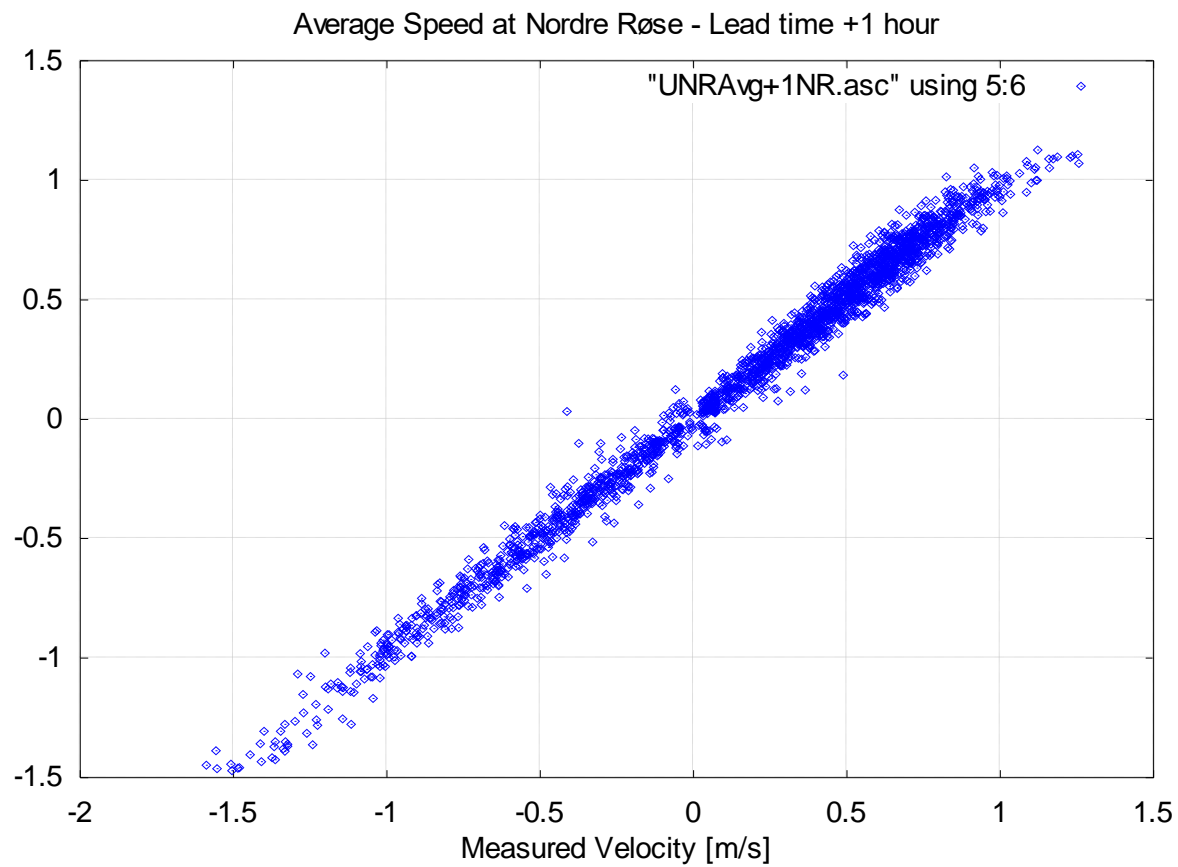
Average Current Speed and Direction, bin 1-17 - Forecast method : 1: H , 2-3: H , 4-6: H , 7-12: H , 13-36: D



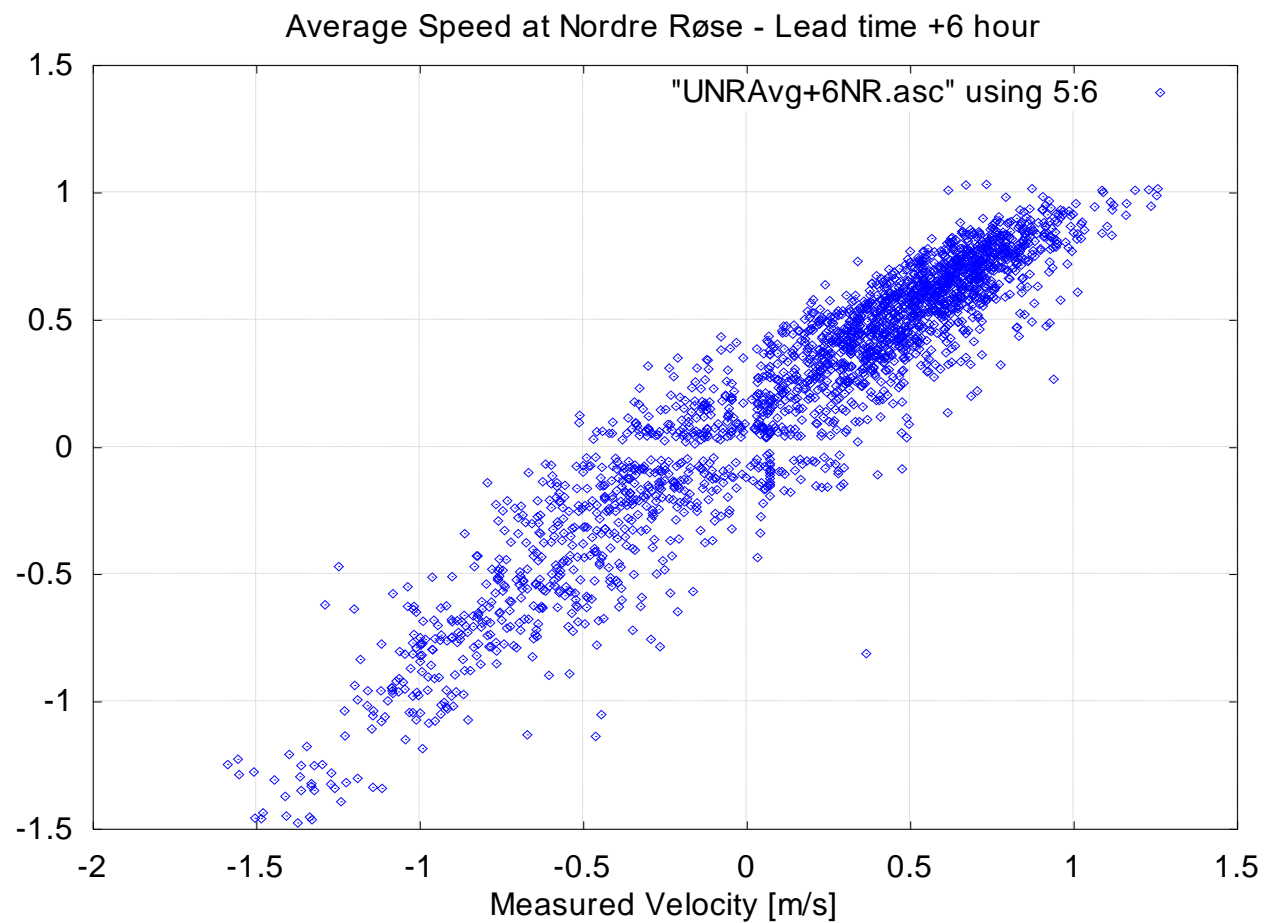
# Results +1 hour



# Results +1 hour

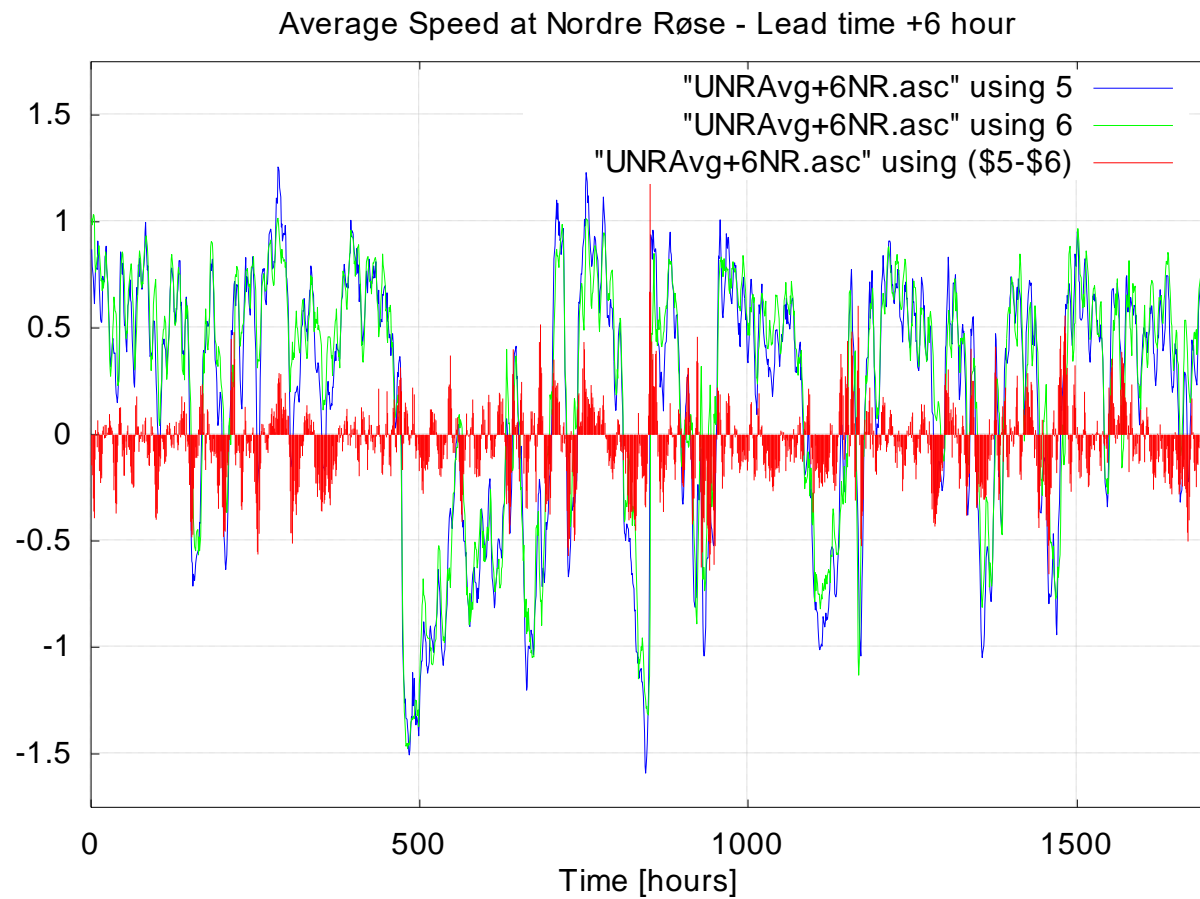


# Results +6 hours

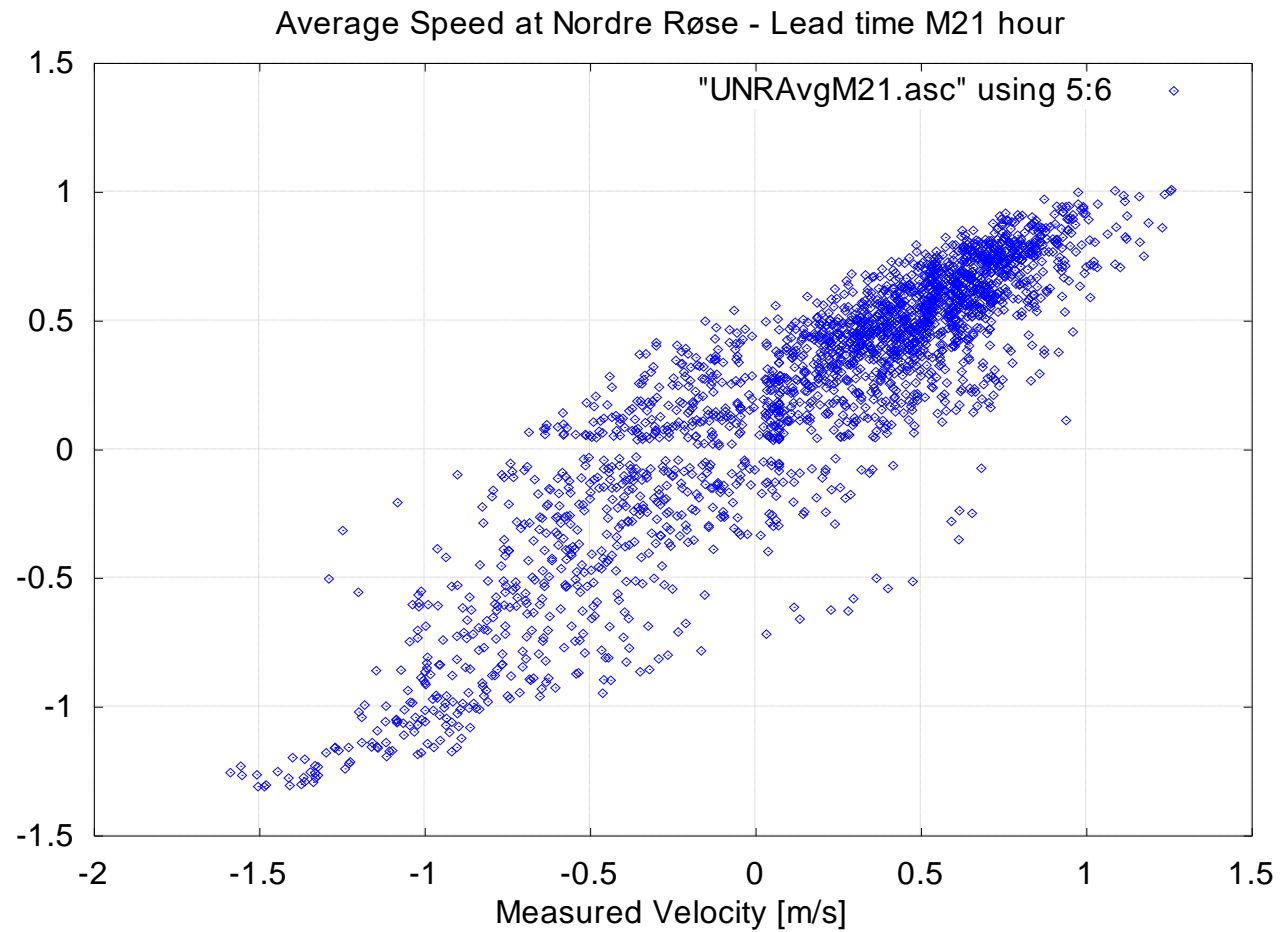




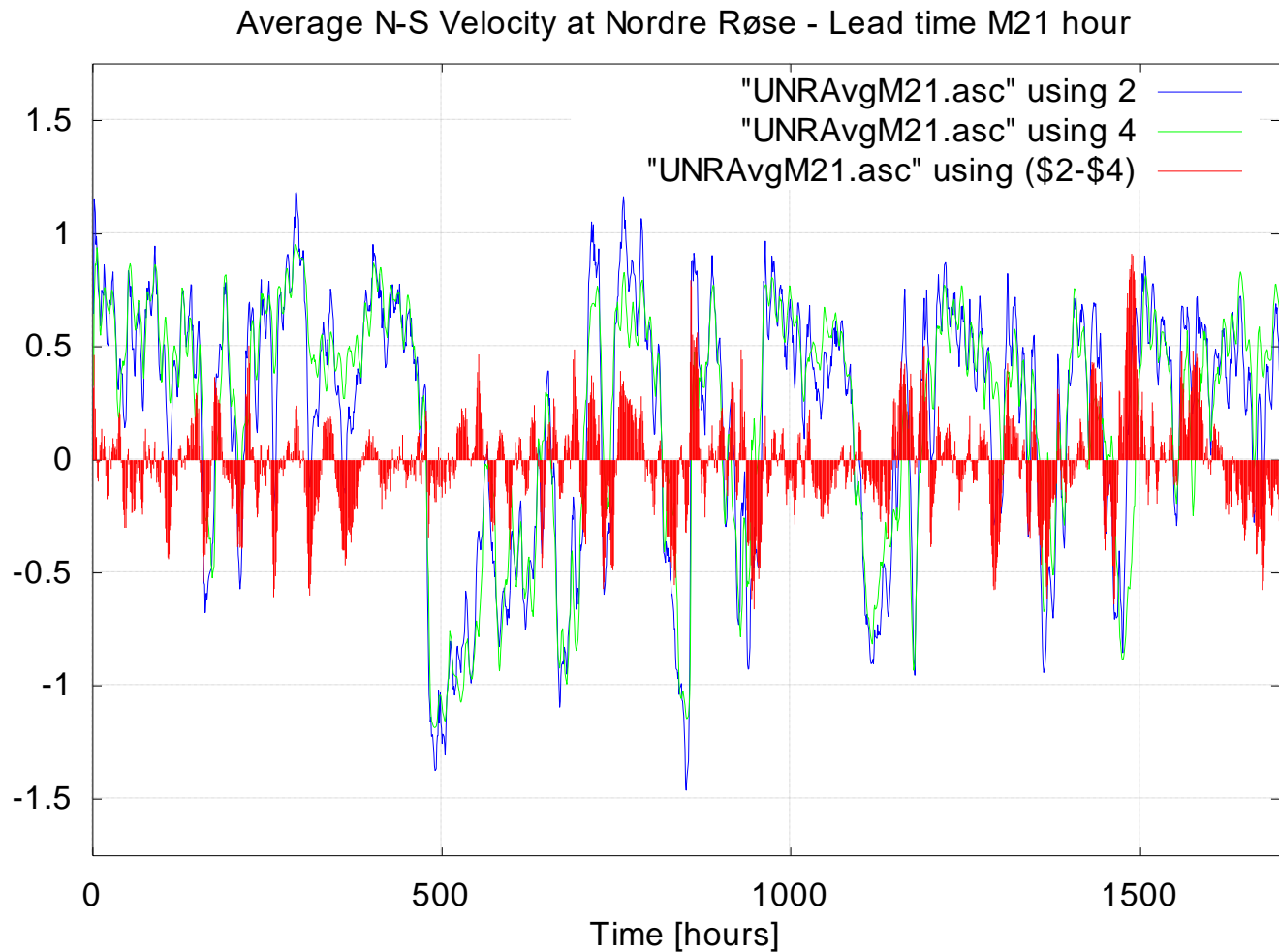
# Results +6 hours



# Results - up to 48 hours



# Results - up to 48 hours



## Results - Summary

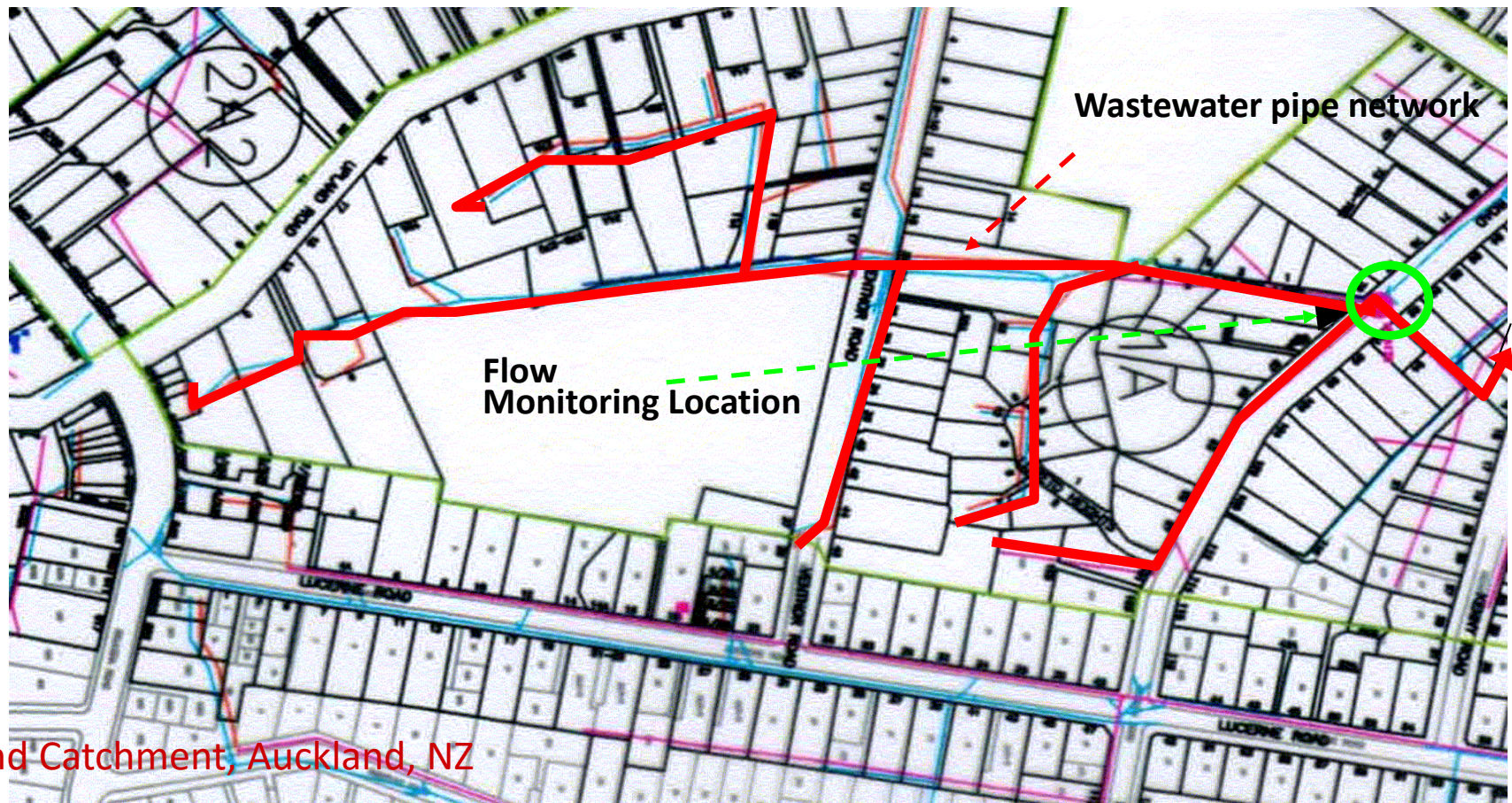
| Performance | 1      | 6      | 48     |
|-------------|--------|--------|--------|
| MSE (m/s)   | 0.0034 | 0.0311 | 0.0526 |
| NMSE        | 0.0125 | 0.116  | 0.1955 |
| MAE (m/s)   | 0.0439 | 0.1355 | 0.1718 |
| r           | 0.994  | 0.9466 | 0.9026 |
| R2          | 0.988  | 0.9002 | 0.8147 |

One more example from civil engineering field:

## Hybrid Approach for Modeling Wet Weather Response in Wastewater Systems

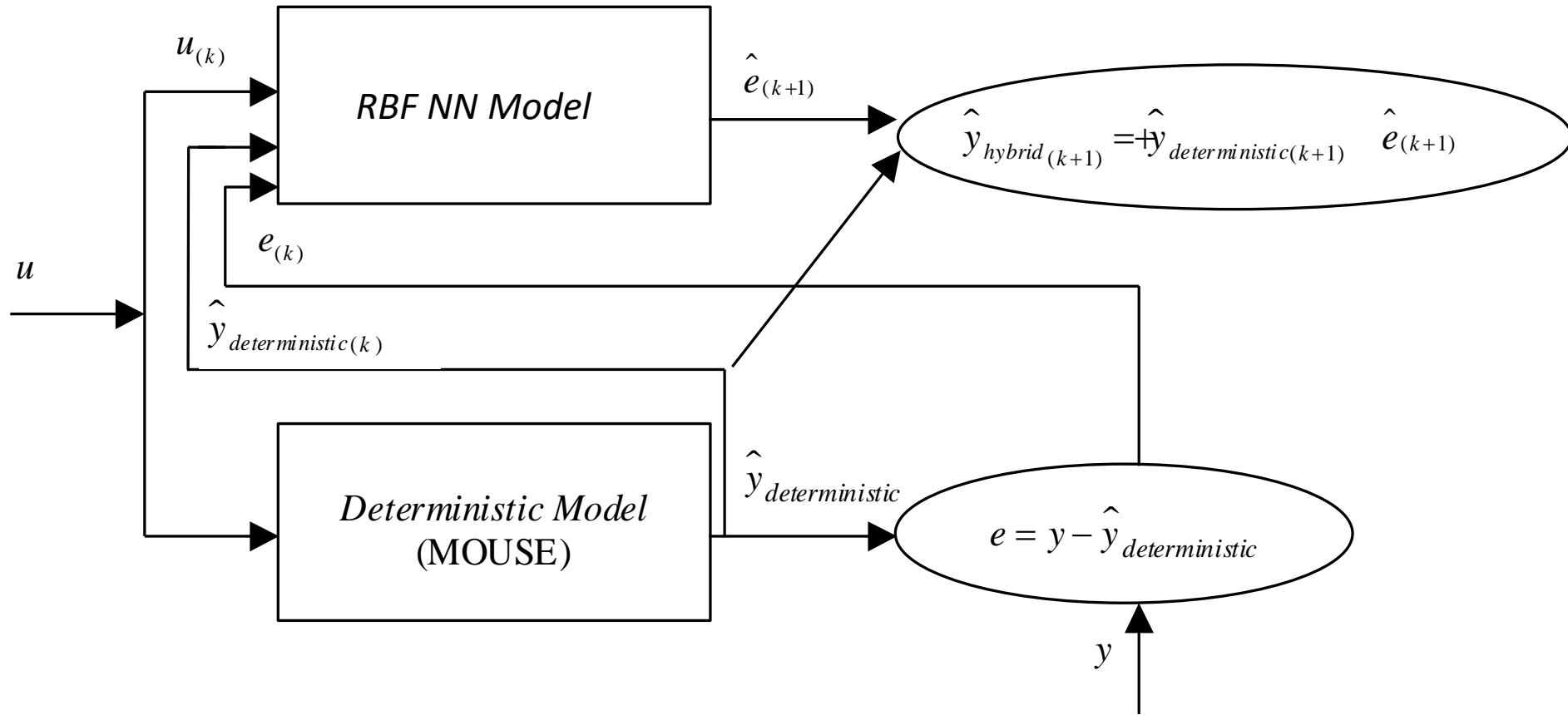
(Vojinovic, Kecman, Babovic, ASCE, J. OF WATER RESOURCES PLANNING AND MANAGEMENT, NOV/DEC 2003, 511-521)

Modeling by deterministic (first principle) models takes account of what we know, Modeling data (statistical models) takes account of uncertainty, or random phenomena.



Upland Catchment, Auckland, NZ

# Hybrid Model



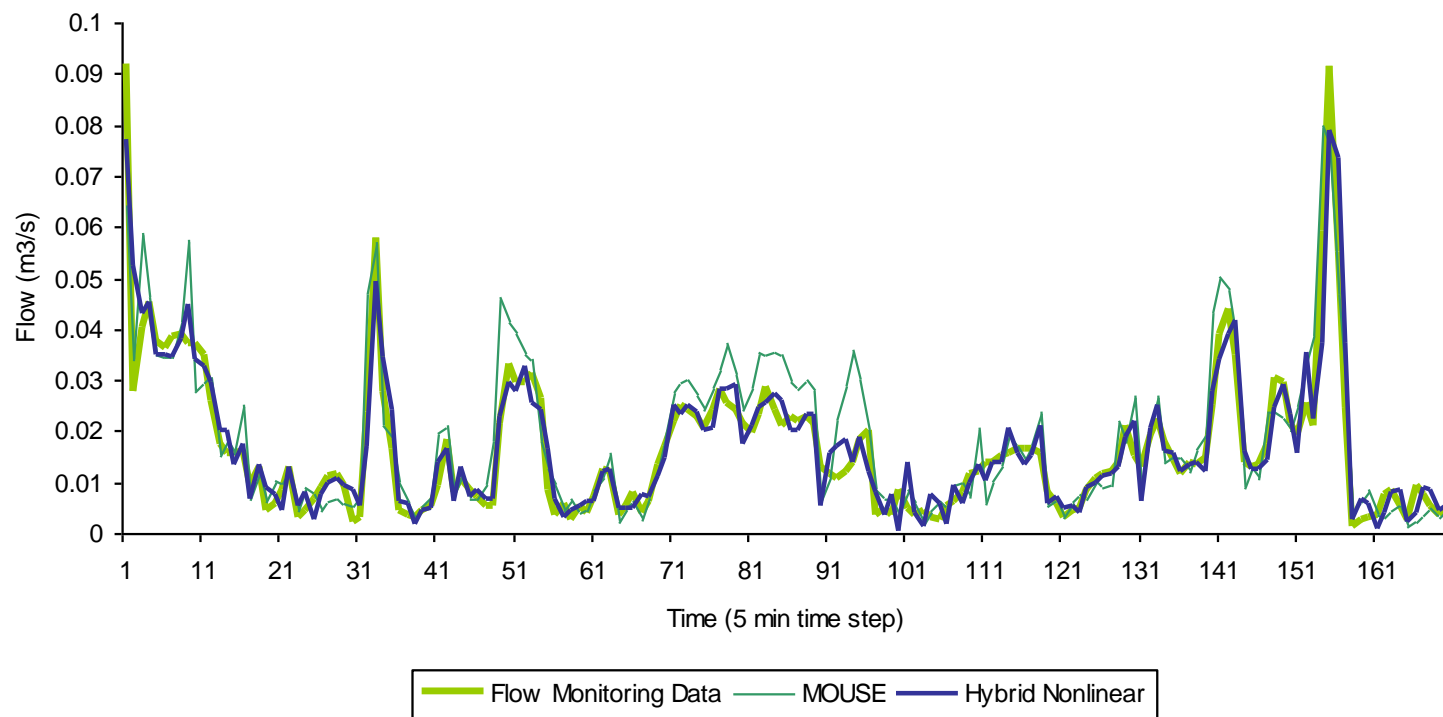
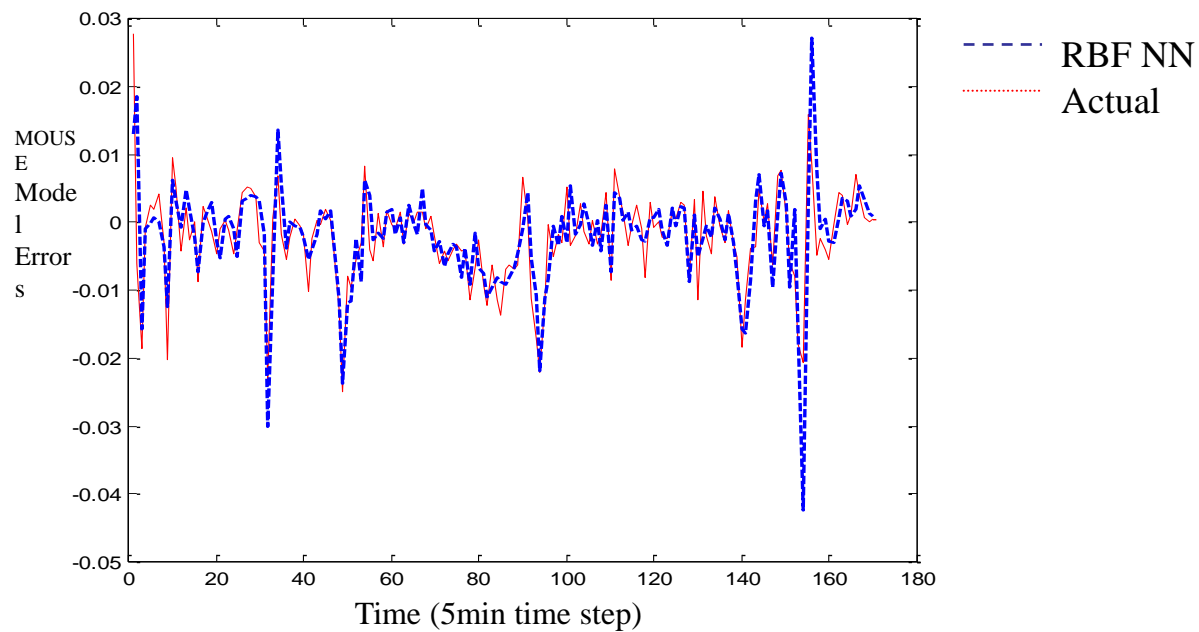
$u$  - rainfall

$e_{\wedge}$  - deterministic model error

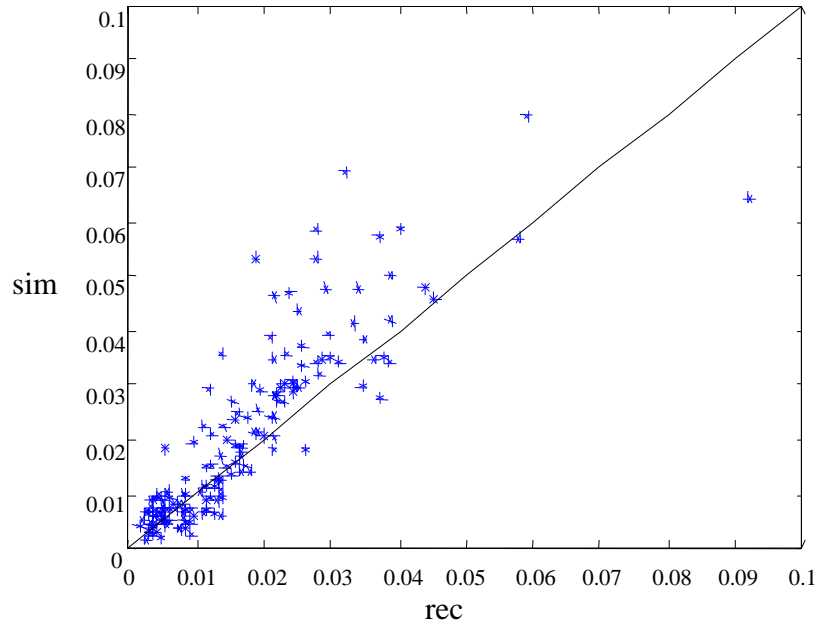
$y_{deterministic}$  - deterministic model output

Actual  
Measurements

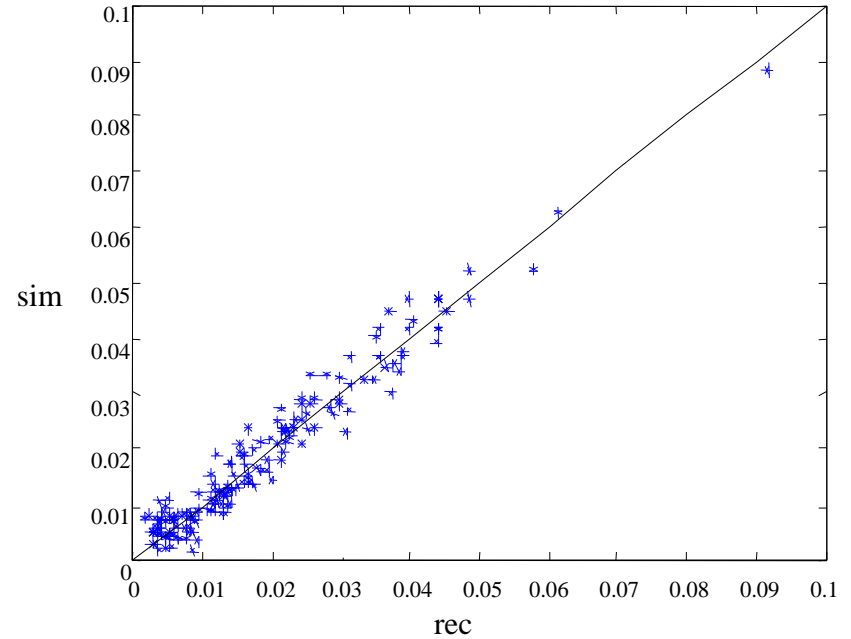




# MOUSE



# HYBRID



| FORECAST HORIZON | PERFORMANCE        |                |               |                |
|------------------|--------------------|----------------|---------------|----------------|
|                  | $E_{(expd\sigma)}$ | $R^2$          | $r$           | $MAE$          |
| 1                | 0.147<br>(28%)     | 0.910<br>(12%) | 0.955<br>(4%) | 0.003<br>(40%) |
| 2                | 0.174<br>(15%)     | 0.869<br>(6%)  | 0.935<br>(2%) | 0.004<br>(20%) |
| 3                | 0.175<br>(15%)     | 0.866<br>(6%)  | 0.936<br>(2%) | 0.004<br>(20%) |
| 4                | 0.173<br>(16%)     | 0.868<br>(6%)  | 0.936<br>(2%) | 0.004<br>(20%) |
| 5                | 0.175<br>(15%)     | 0.864<br>(6%)  | 0.934<br>(2%) | 0.004<br>(20%) |

Results: Improvements in respect to the deterministic model results