

Nested Loop Join Methods: Recap

```
T(R) = \# of tuples in R
P(R) = \# of pages in R
```

Nested Loop Join (NLJ)

Compute $R \bowtie S$ on A:

for r in R:

for s in S:

if r[A] == s[A]:

yield (r,s)

$$P(R) + T(R)*P(S) + OUT$$

Block Nested Loop Join (BNLJ)

Compute $R \bowtie S \ on \ A$:

for each B-1 pages pr of R:

for page ps of S:

for each tuple r in pr:

for each tuple s in ps:

if r[A] == s[A]:

yield (r,s)

$$P(R) + \frac{P(R)}{B-1}P(S) + \mathsf{OUT}$$

Index Nested Loop Join (INLJ)

Compute $R \bowtie S \ on \ A$:

Given index idx on S.A:

for r in R:

s in idx(r[A]):

yield r,s

$$P(R) + T(R)*L + OUT$$

Sort Merge Join (SMJ): Basic Procedure

To compute $R \bowtie S \ on \ A$:

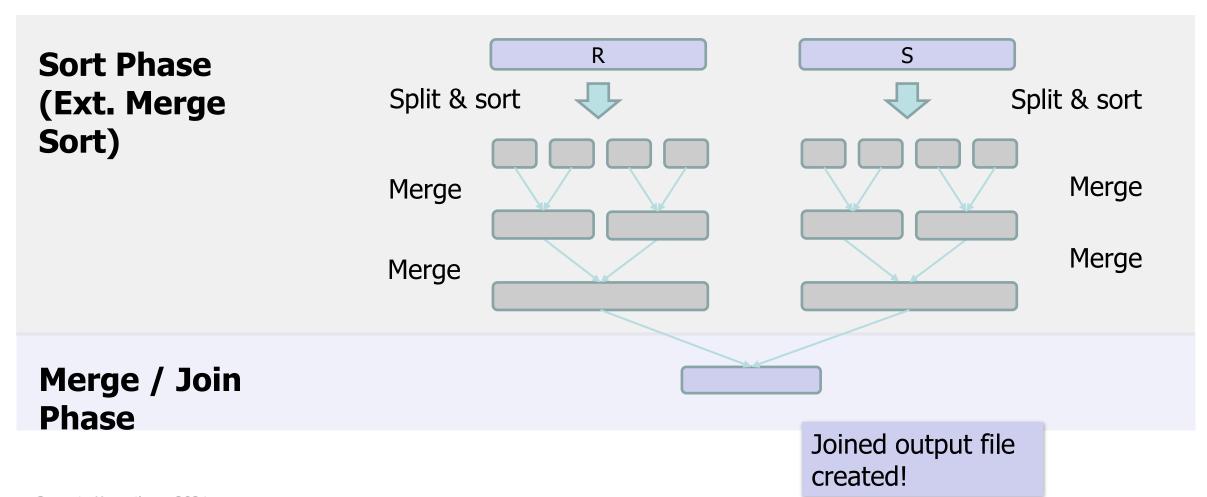
Note that we are only considering equality join conditions here

- 1. Sort R, S on A using *external merge sort*
- 2. Scan sorted files and "merge"

Note that if R, S are already sorted on A, SMJ will be awesome!

Given **B+1** buffer pages

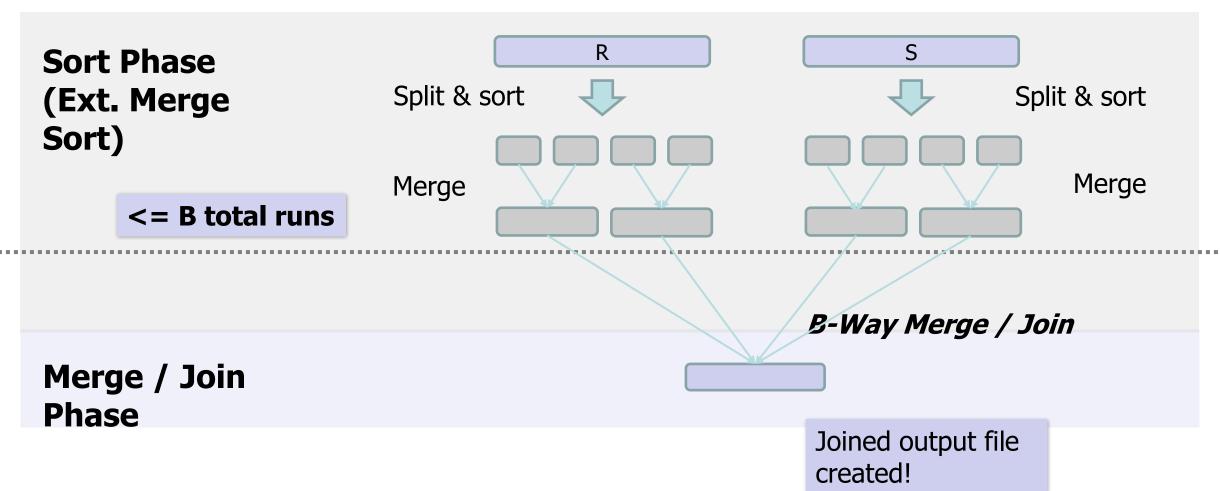
Unsorted input relations



Simple SMJ Optimization

Given **B+1** buffer pages

Unsorted input relations



Simple SMJ Optimization

Given **B+1** buffer pages

- Now, on this last pass, we only do P(R) + P(S) IOs to complete the join!
- If we can initially split R and S into B total runs each of length approx. <= 2(B+1),
 assuming repacking lets us create initial runs of ~2(B+1) then we only need 3(P(R) + P(S)) + OUT for SMJ!
 - 2 R/W per page to sort runs in memory, 1 R per page to B-way merge / join!
- How much memory for this to happen?

$$- \frac{P(R) + P(S)}{B} \le 2(B+1) \Rightarrow \sim P(R) + P(S) \le 2B^2$$

- Thus, $max{P(R), P(S)} \le B^2$ is an approximate sufficient condition

If the larger of R,S has \leq B² pages, then SMJ costs 3(P(R)+P(S)) + OUT!

Hash Join (HJ)

Recall: Hashing

- Magic of hashing:
 - A hash function h_B maps into [0,B-1]
 - And maps nearly uniformly
- A hash collision is when x != y but $h_B(x) = h_B(y)$
 - Note however that it will <u>never</u> occur that x = y but $h_B(x) != h_B(y)$
- We hash on an attribute A, so our hash function $h_B(t)$ has the form $h_B(t.A)$.
 - Collisions may be more frequent.

To compute $R \bowtie S$ on A:

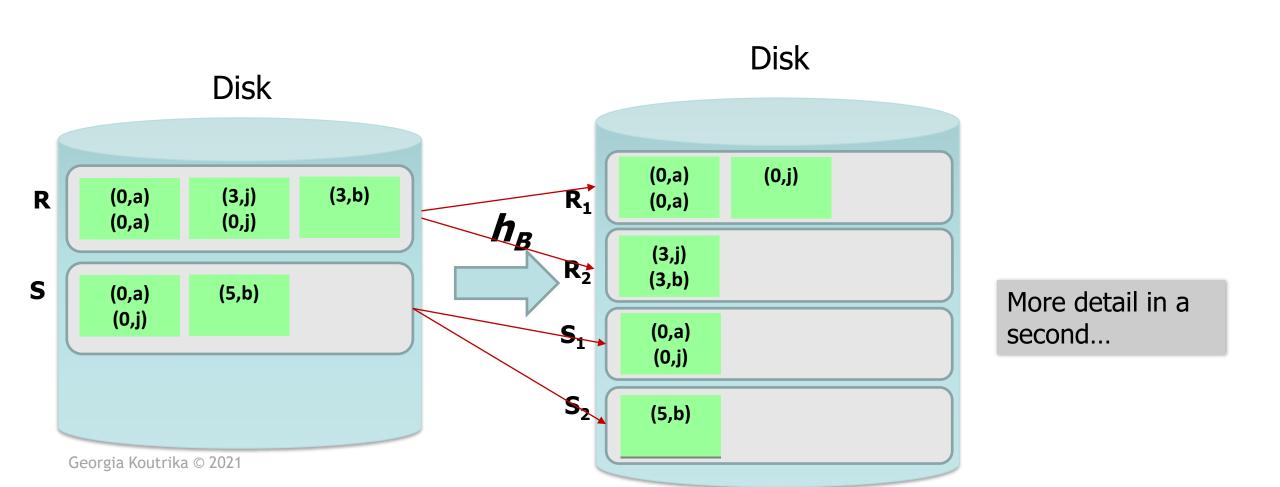
Note again that we are only considering equality constraints here

- Partition Phase: Using one (shared) hash function h_B, partition R and S into B buckets
- 2. Matching Phase: Take pairs of buckets whose tuples have the same values for h, and join these
 - 1. Use BNLJ here; or hash again \rightarrow either way, operating on small partitions so fast!

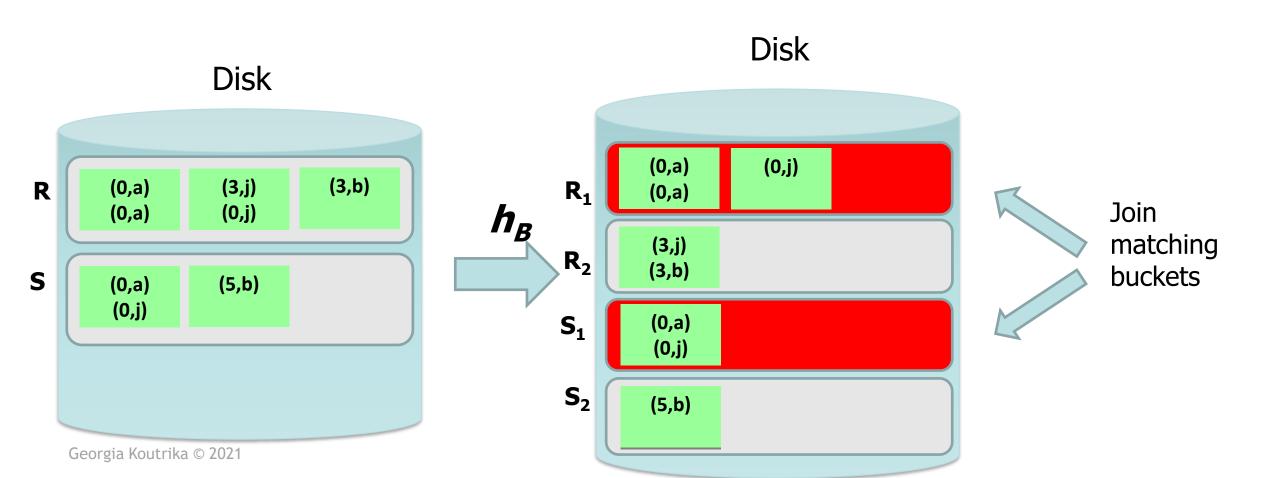
We **decompose** the problem using $h_{B'}$ then complete the join

Assume each page has two tuples (one per row)

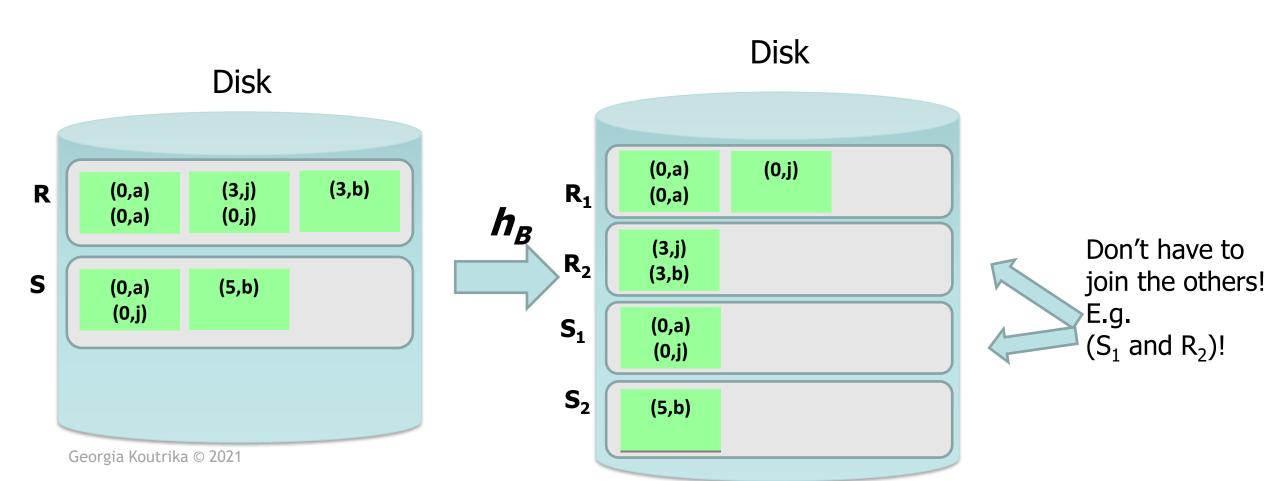
1. Partition Phase: Using one (shared) hash function h_B , partition R and S into B buckets



2. Matching Phase: Take pairs of buckets whose tuples have the same values for h_B , and join them



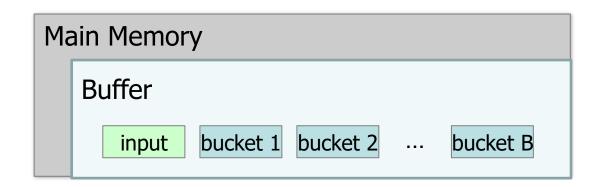
2. Matching Phase: Take pairs of buckets whose tuples have the same values for h_B , and join them



Goal: For each relation, partition relation into **buckets** such that if $h_B(t.A) = h_B(t'.A)$ they are in the same bucket

Given B+1 buffer pages, we partition into B buckets:

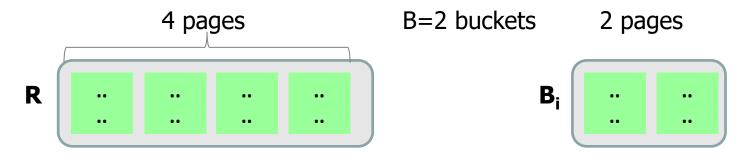
- We use B buffer pages for output (one for each bucket), and 1 for input
 - The "dual" of sorting.
 - For each tuple t in input, copy to buffer page for h_B(t.A)
 - When a bucket page fills up, flush to disk.



How big are the resulting buckets?

- Given N input pages, we partition into B buckets:
 - → Ideally our buckets are each of size ~ N/B pages

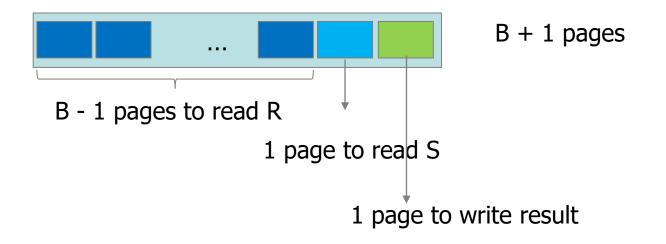
Given **B+1** buffer pages



- What happens if there are hash collisions?
 - Buckets could be > N/B
 - We'll do several passes...
- What happens if there are duplicate join keys?
 - Nothing we can do here... could have some **skew** in size of the buckets

RECALL: Block Nested Loop Join (BNLJ)

Buffer



```
Compute R ⋈ S on A:
  for each B-1 pages pr of R:
   for page ps of S:
    for each tuple r in pr:
     for each tuple s in ps:
        if r[A] == s[A]:
        yield (r,s)
```

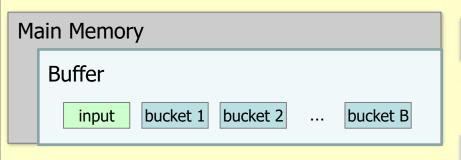
How big *do we want* the resulting buckets?

- Recall: If we want to join a bucket from R and one from S, we can do BNLJ in linear time if $P(R) \le B 1!$
 - And more generally, being able to fit bucket in memory is advantageous
- Ideally, our buckets would be of size $\leq B 1$ pages
 - 1 for input page, 1 for output page, **B-1** for each bucket
- We can keep partitioning buckets that are > B-1 pages, until they are $\leq B-1$ pages
 - Using a new hash key which will split them...

Let's see how we do the partitioning then!

Recall for BNLJ:

$$P(R) + \frac{P(R)P(S)}{R-1}$$

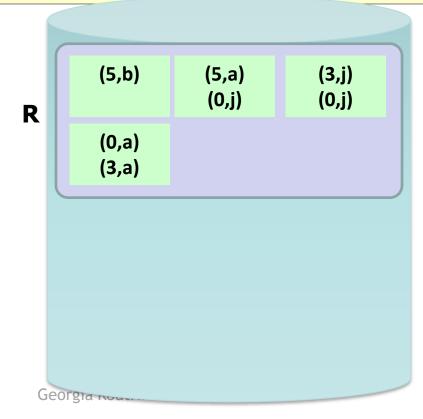


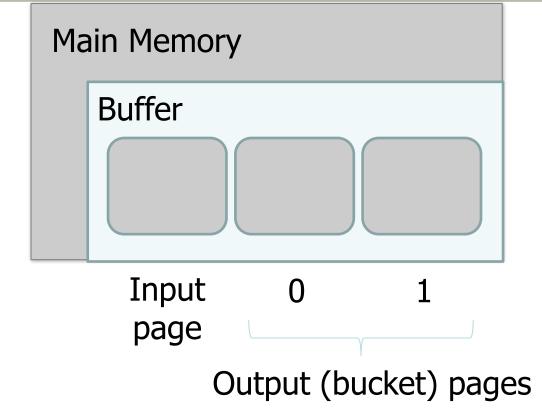
Given B+1=3 buffer pages

We partition into B = 2 buckets using hash function h_2 so that we can have one buffer page for each bucket (and one for input)

Our goal (for the join) will be to get B = 2 buckets of size $<= B-1 \rightarrow 1$ page each

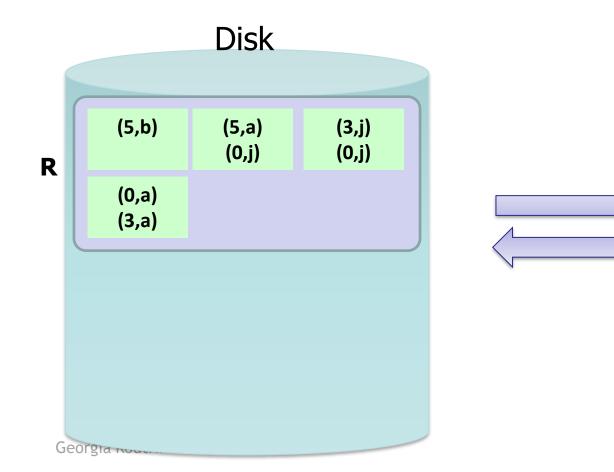
Disk

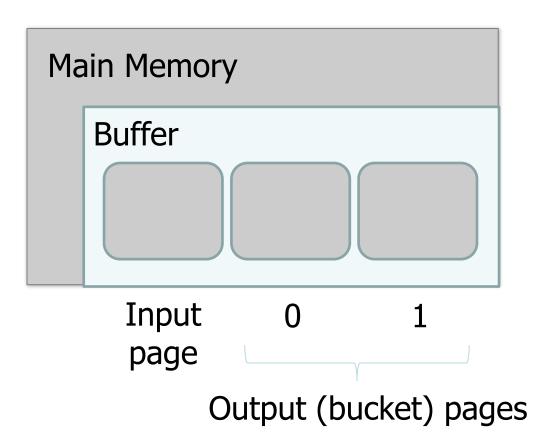




Given B+1 = 3 buffer pages

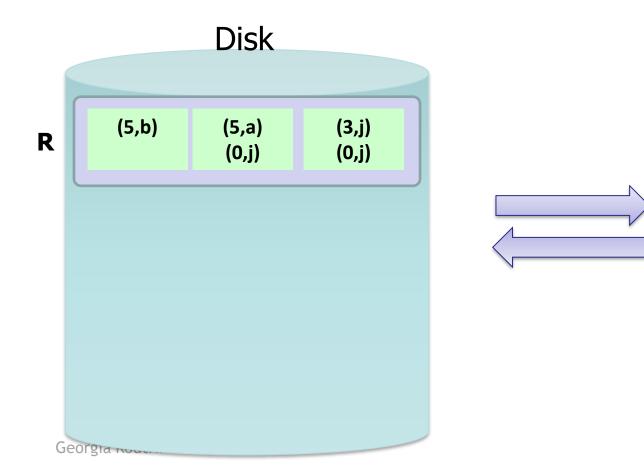
1. We read pages from R into the "input" page of the buffer...

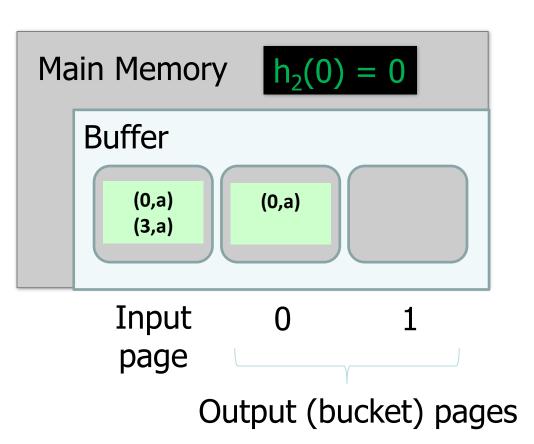




Given B+1=3 buffer pages

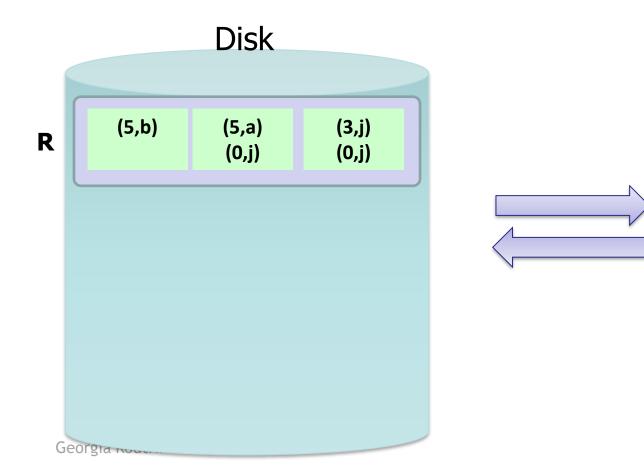
2. Then we use **hash function** h_2 to sort into the buckets, which each have one page in the buffer

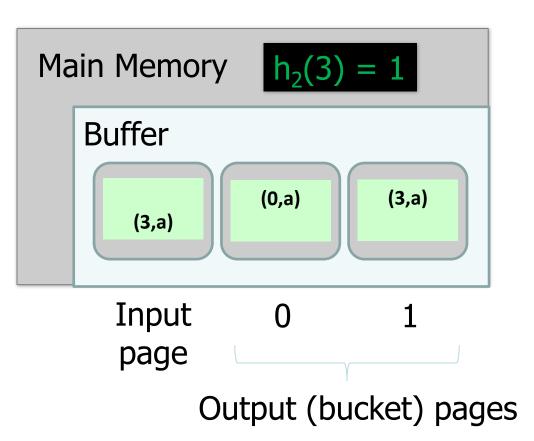




Given B+1=3 buffer pages

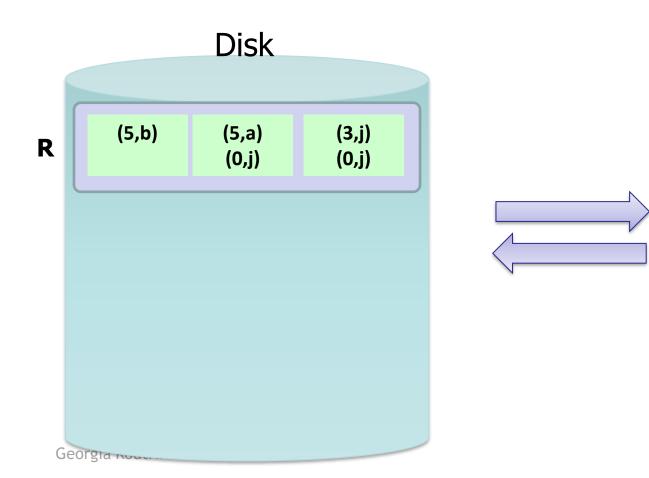
2. Then we use **hash function** h_2 to sort into the buckets, which each have one page in the buffer

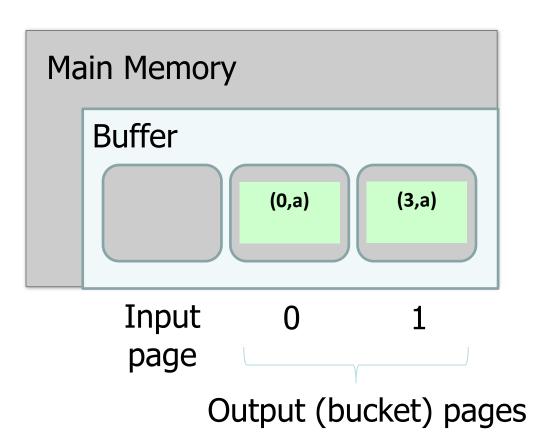




Given B+1=3 buffer pages

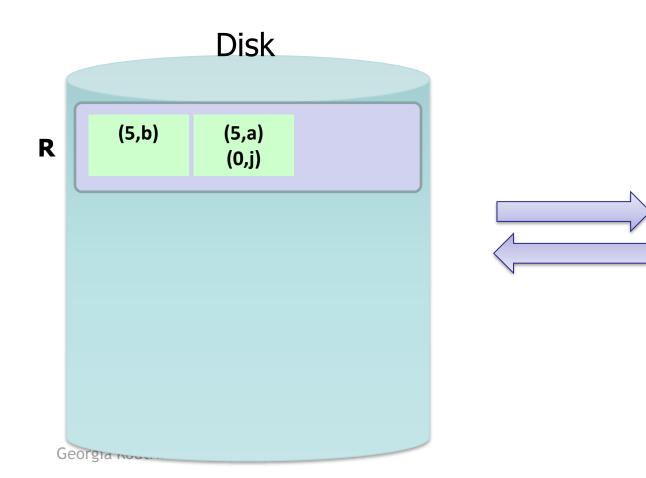
3. We repeat until the buffer bucket pages are full...

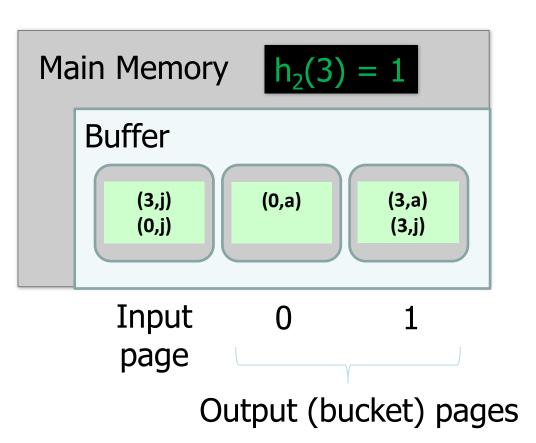




Given B+1=3 buffer pages

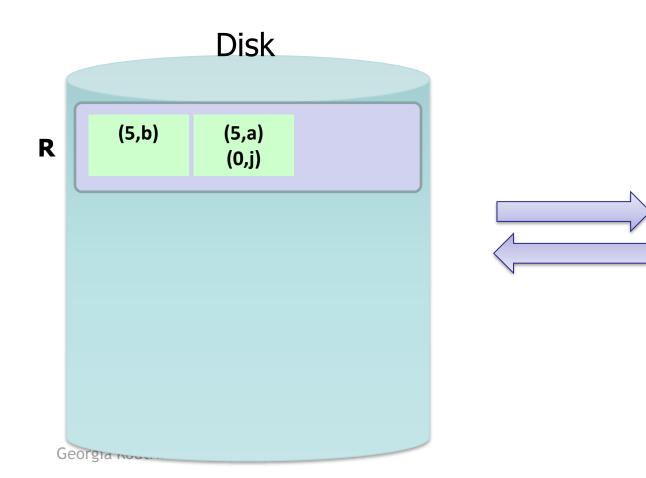
3. We repeat until the buffer bucket pages are full...

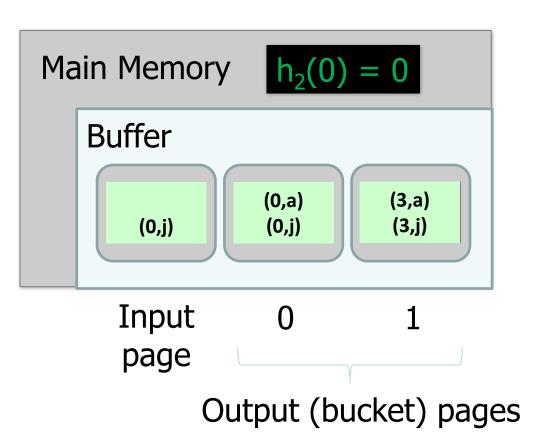




Given B+1=3 buffer pages

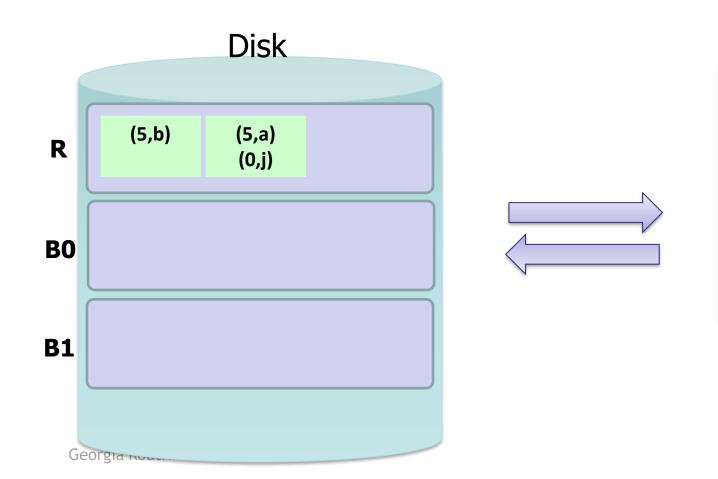
3. We repeat until the buffer bucket pages are full...

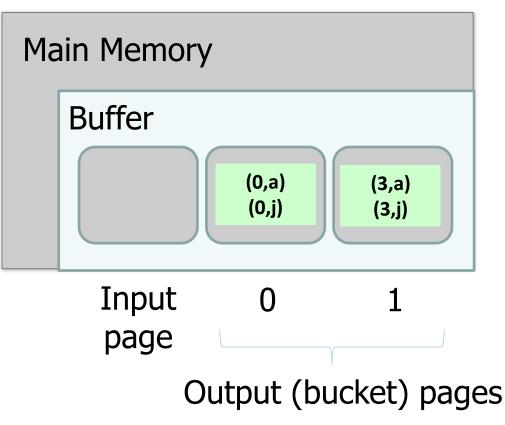




Given B+1=3 buffer pages

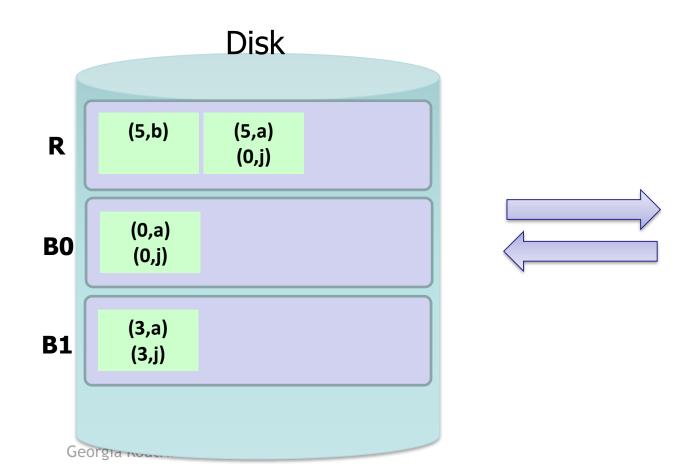
3. We repeat until the buffer bucket pages are full... then flush to disk

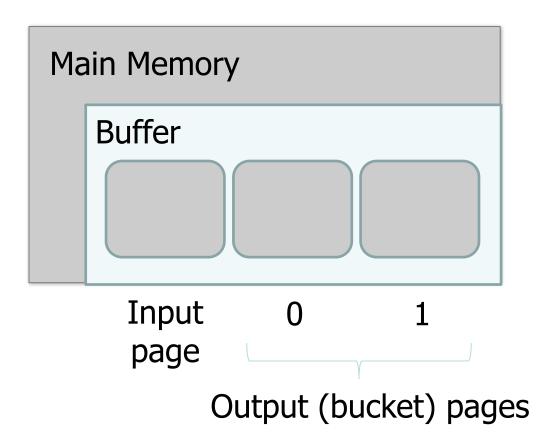




Given B+1=3 buffer pages

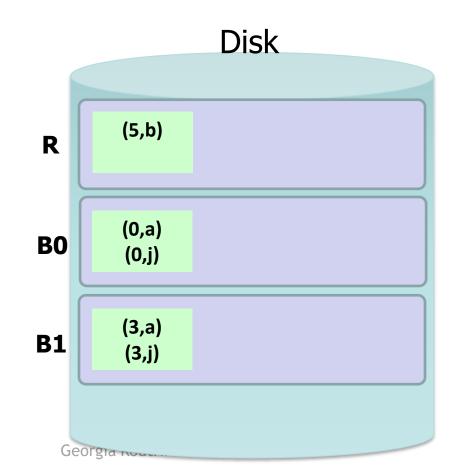
3. We repeat until the buffer bucket pages are full... then flush to disk



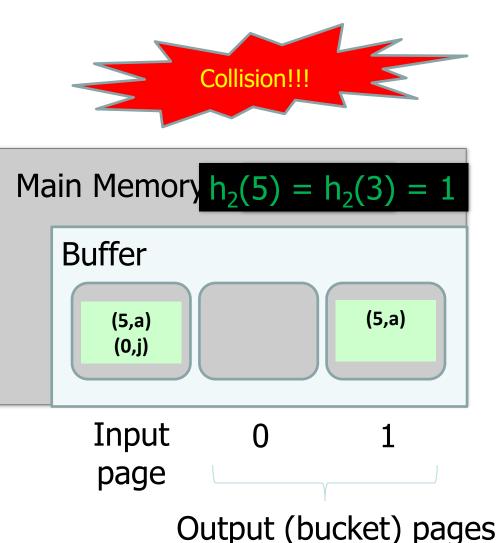


Given B+1=3 buffer pages

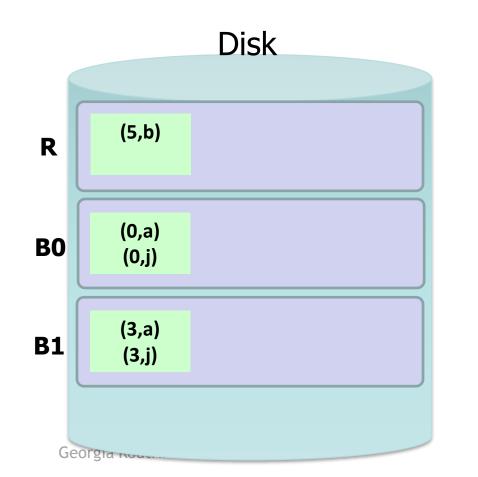
Note that collisions can occur!



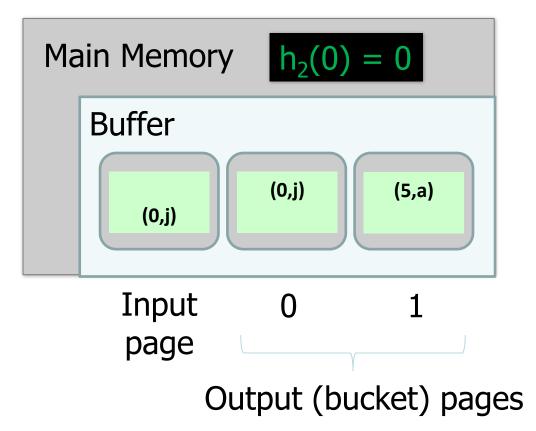




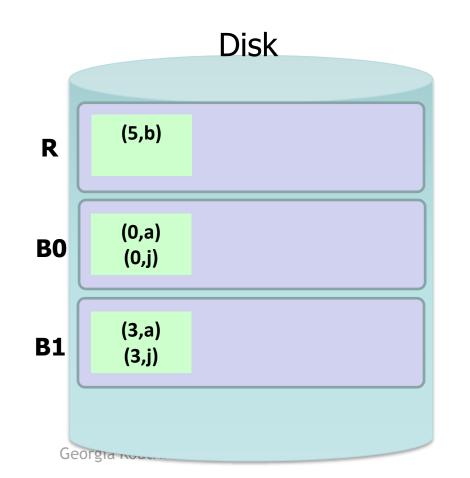
Given B+1 = 3 buffer pages



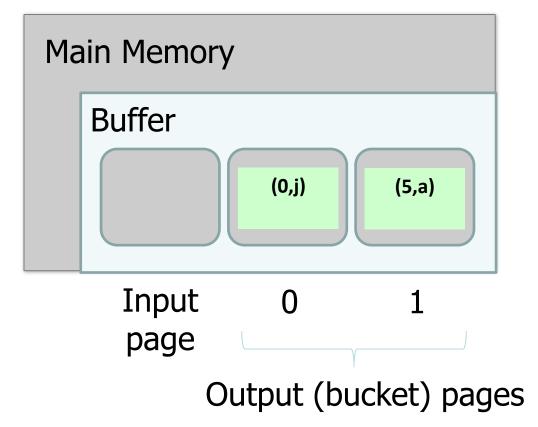




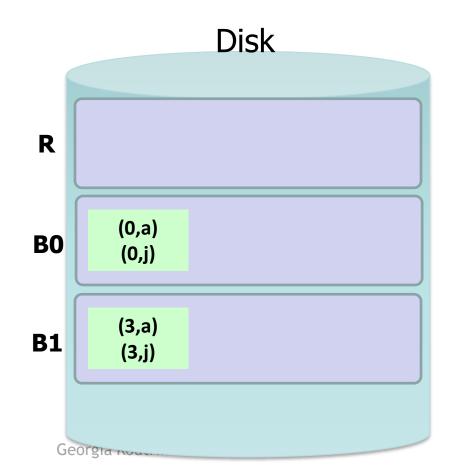
Given B+1=3 buffer pages



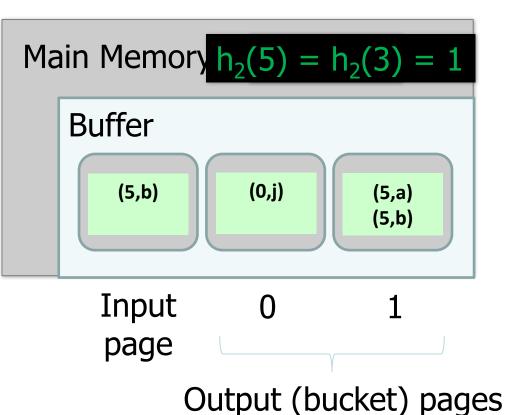




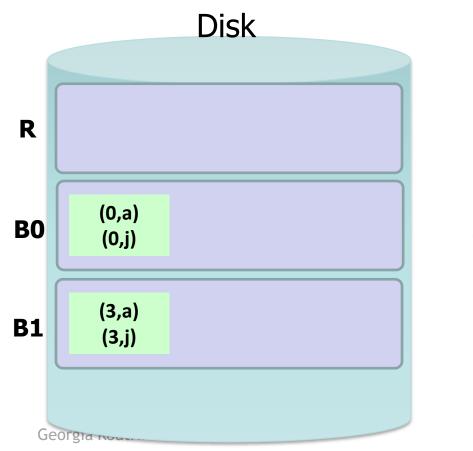
Given B+1 = 3 buffer pages



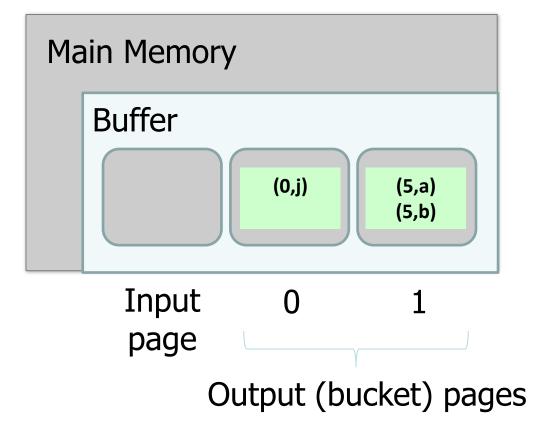




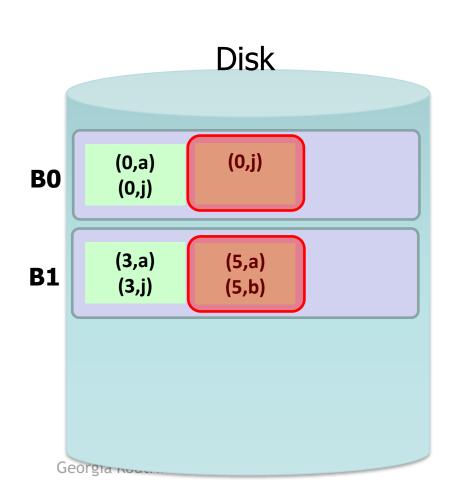
Given B+1=3 buffer pages







Given B+1=3 buffer pages

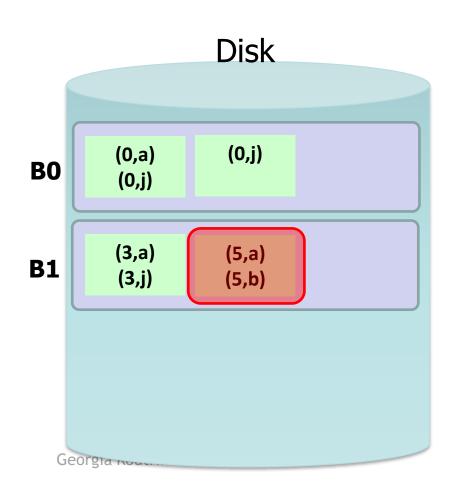


We wanted buckets of size **B-1 = 1...**however we got larger ones due to:

(1) Duplicate join keys

(2) Hash collisions

Given B+1=3 buffer pages



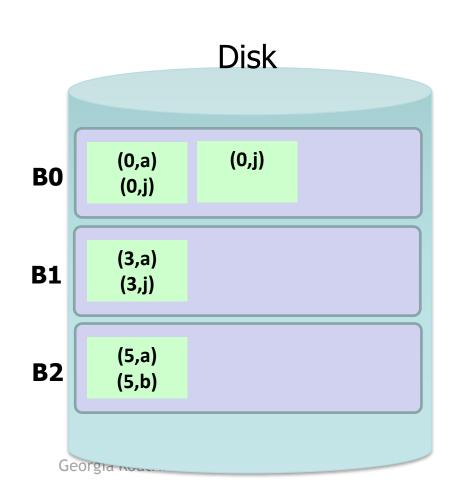
To take care of larger buckets caused by (2) hash collisions, we can just do another pass!

What hash function should we use?

Do another pass with a different hash function, h'_{2} , ideally such that:

$$h'_{2}(3) != h'_{2}(5)$$

Given B+1=3 buffer pages



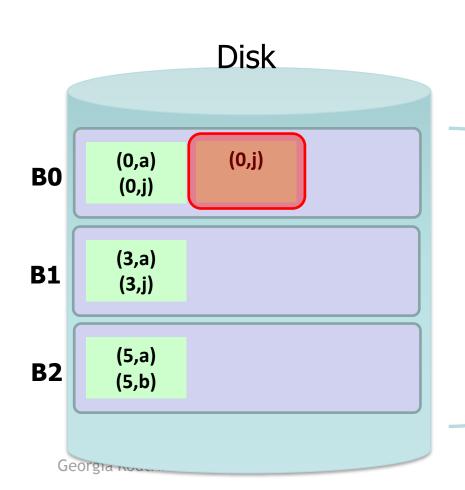
To take care of larger buckets caused by (2) hash collisions, we can just do another pass!

What hash function should we use?

Do another pass with a different hash function, h'_{2} , ideally such that:

$$h'_{2}(3) != h'_{2}(5)$$

Given B+1 = 3 buffer pages

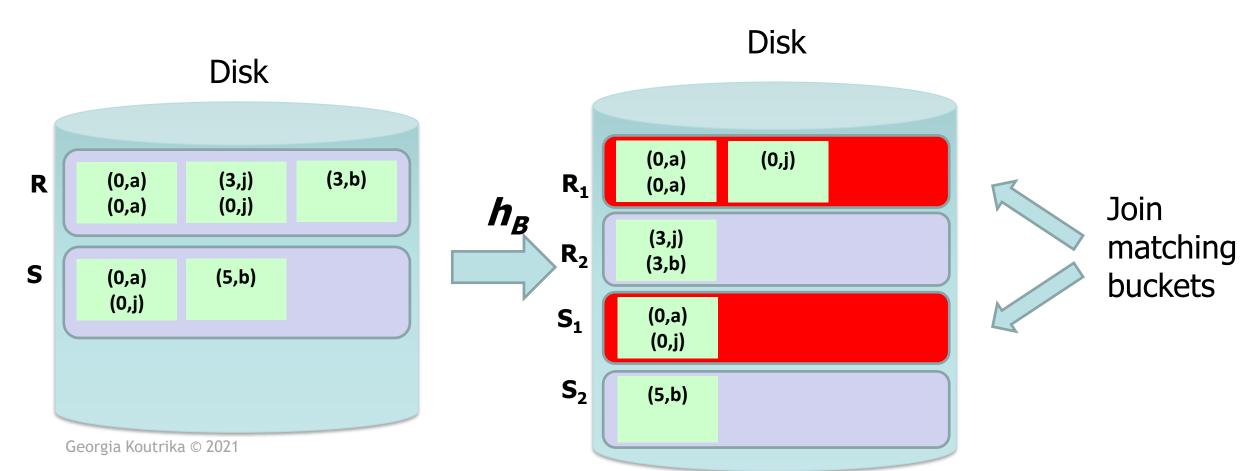


What about duplicate join keys? Unfortunately this is a problem... but usually not a huge one.

We call this unevenness in the bucket size **skew**

Now that we have partitioned R and S...

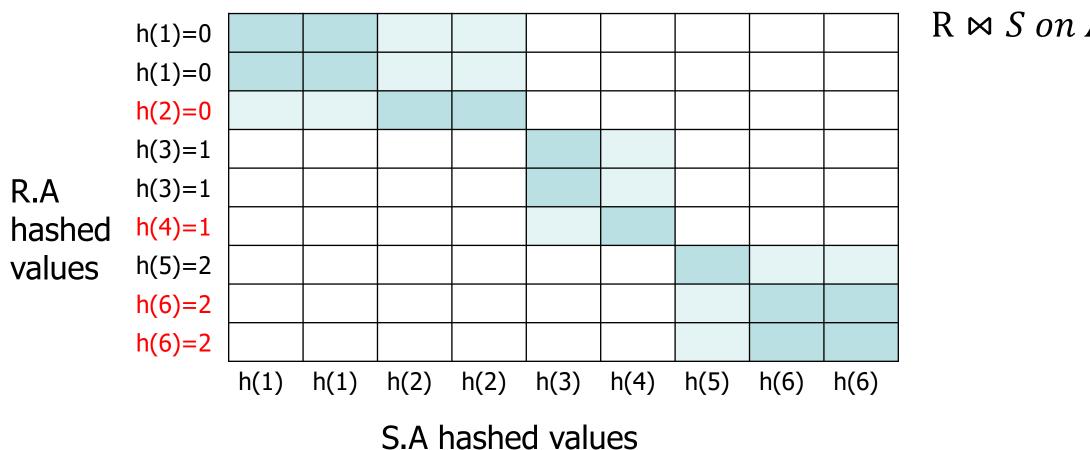
 Now, we just join pairs of buckets from R and S that have the same hash value to complete the join!



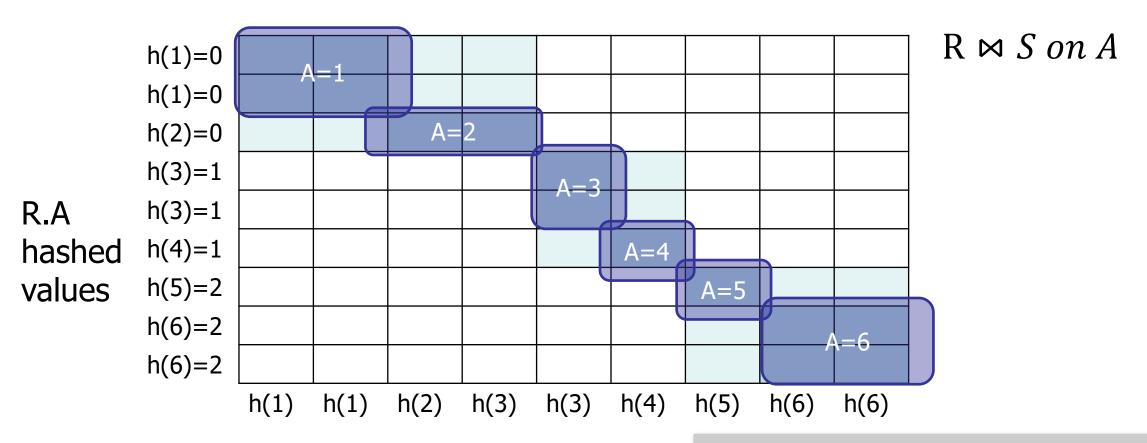
- Note that since $x = y \rightarrow h(x) = h(y)$, we only need to consider pairs of buckets (one from R, one from S) that have the same hash function value
- If our buckets are $\sim B-1$ pages, can join each such pair using BNLJ in linear time; recall (with P(R) = B-1):

BNLJ Cost:
$$P(R) + \frac{P(R)P(S)}{B-1} = P(R) + \frac{(B-1)P(S)}{B-1} = P(R) + P(S)$$

Joining the pairs of buckets is linear! (As long as smaller bucket <= B-1 pages)



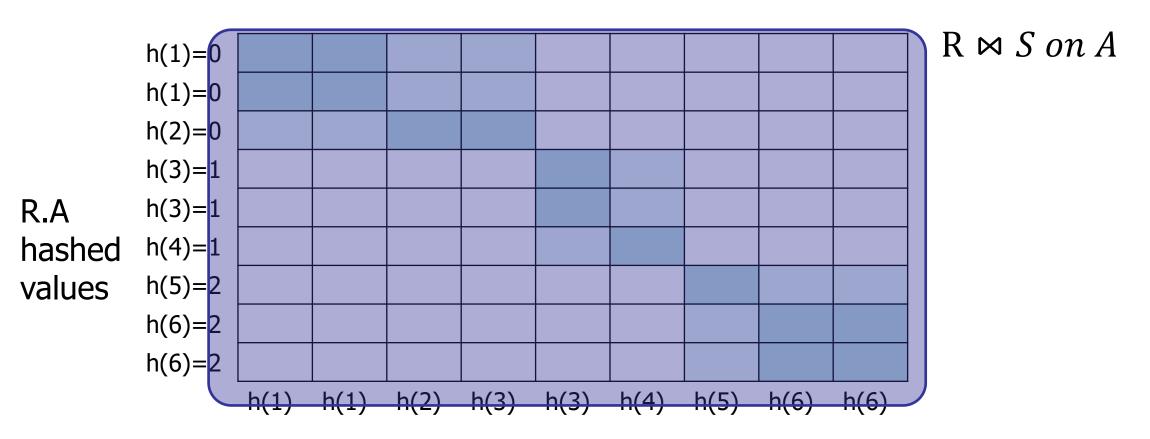
 $R \bowtie S \ on \ A$



S.A hashed values

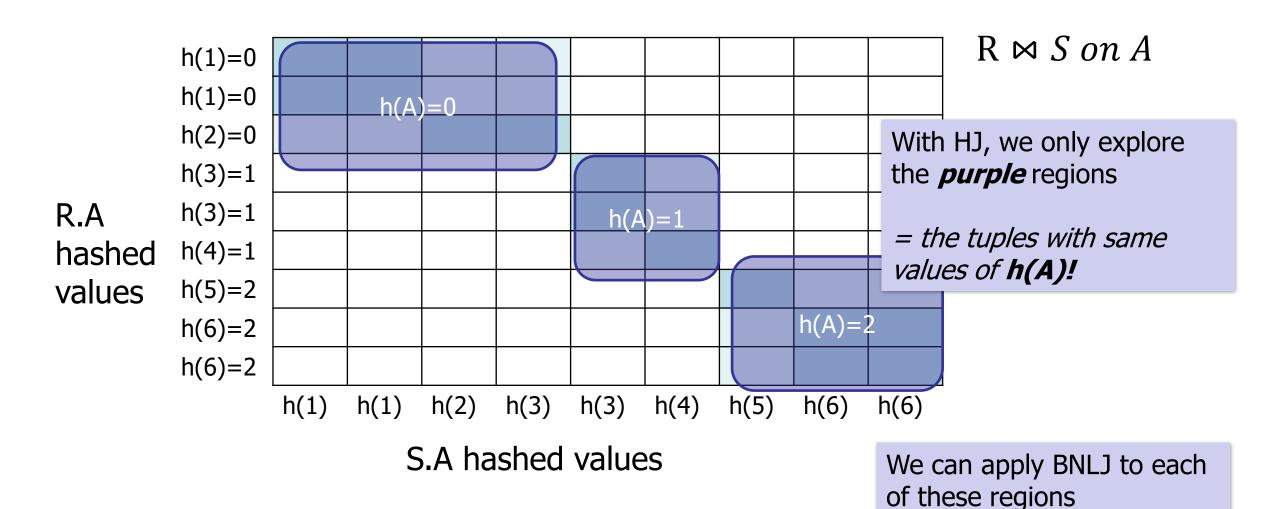
To perform the join, we ideally just need to explore the dark blue regions

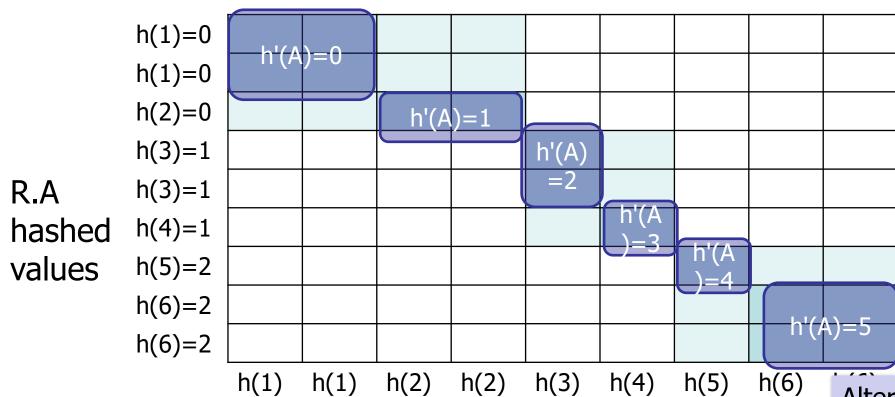
= the tuples with same values of the join key A



S.A hashed values

With a join algorithm like BNLJ that doesn't take advantage of equijoin structure, we'd have to explore this **whole grid!**





 $R \bowtie S \ on \ A$

S.A hashed values

Alternative to applying BNLJ:

We could also hash again, and keep doing passes in memory to reduce further!

Hash Join Summary

- Given enough buffer pages as on previous slide...
 - Partitioning requires reading + writing each page of R,S
 - \rightarrow 2(P(R)+P(S)) IOs
 - Matching (with BNLJ) requires reading each page of R,S
 - \rightarrow P(R) + P(S) IOs
 - Writing out results could be as bad as P(R)*P(S)... but probably closer to P(R)+P(S)

HJ takes $\sim 3(P(R)+P(S)) + OUT$ IOs!

Sort-Merge v. Hash Join

• Given enough memory, both SMJ and HJ have performance:

$$\sim$$
3(P(R)+P(S)) + *OUT*

- "Enough" memory =
 - SMJ: $B^2 > max\{P(R), P(S)\}$
 - HJ: $B^2 > min\{P(R), P(S)\}$

Hash Join superior if relation sizes differ greatly. Why?

Summary

$$T(R) = # of tuples in R$$

$$P(R) = \# \text{ of pages in } R$$

Nested Loop Join (NLJ)

$$P(R) + T(R)*P(S) + OUT$$

Block Nested Loop Join (BNLJ)

$$P(R) + \frac{P(R)}{B-1}P(S) + OUT$$

Index Nested Loop Join (INLJ)

$$P(R) + T(R)*L + OUT$$

Sort Merge Join (SMJ)

Hash Join (HJ)

$$3(P(R)+P(S)) + OUT!$$

With lot of memory

How much memory do we need for HJ?

• Given B+1 buffer pages

- + WLOG: Assume P(R) <= P(S)
- Suppose (reasonably) that we can partition into B buckets in 2 passes:
 - For R, we get B buckets of size ~P(R)/B
 - To join these buckets in linear time, we need these buckets to fit in B-1 pages, so we have:

$$B-1 \ge \frac{P(R)}{B} \Rightarrow \sim B^2 \ge P(R)$$

Quadratic relationship between *smaller relation's* size & memory!