**Cortical efficient coding dynamics shape behavioral performance.**

Chris Angeloni1,2, Wiktor Młynarski3, Aaron M. Williams2,5, Katherine C. Wood2, Linda Garami2, Eugenio Piasini5, Ann Hermundstad4, Maria N. Geffen2,5

1Department of Psychology, University of Pennsylvania, Philadelphia, PA, USA

2Department of Otorhinolaryngology, University of Pennsylvania, Philadelphia, PA, USA

3Institute of Science and Technology Austria, Klosterneuburg, Austria

4Janelia Research Campus, Howard Hughes Medical Institute, Ashburn, VA, USA

5Department of Neuroscience, Department of Neurology, University of Pennsylvania, Philadelphia, PA, USA

**Abstract**

The efficient coding hypothesis postulates that neurons shape their response properties to match their dynamic range to the statistics of incoming signals. However, whether and how the dynamics of efficient neuronal adaptation inform behavior has not been directly shown. Here, we trained mice to detect a target presented in noise shortly after a change in the noise contrast. The observed changes in cortical gain and behavior followed the predictions of a normative model of efficient cortical sound processing; specifically, target detection and sensitivity improved in low contrast relative to high contrast noise. Furthermore, the time course of target detectability varied depending on contrast, decreasing rapidly after a transition to high contrast, and increasing more slowly after a transition to low contrast. The auditory cortex was required for detection of targets in noise, and cortical neuronal responses exhibited the predicted patterns of target detectability. The magnitude of gain modulation in cortical neurons predicted individual differences in behavioral performance. Combined, our results demonstrate that efficient neural codes in auditory cortex directly influence perceptual behavior.

**Introduction**

As we navigate the world around us, the statistics of the environment can change dramatically. The efficient coding hypothesis postulates that neurons match their limited dynamic range to the statistics of incoming sensory signals1. Thus, through adaptation of their response properties, neurons can preserve their ability to encode information within many types of environments2–4. Neuronal adaptation to the statistics of the environment has been found throughout different sensory modalities and brain regions5–13. In the auditory system, neurons exhibit contrast gain control, adapting the gain of their response function to match the variability in level (contrast) of the incoming sounds14–18. Yet it remains unknown whether and how the dynamics of contrast gain control in the auditory system inform behavior, as a direct link between neuronal adaptation and behavior has not been previously established. The goal of our study was to test the hypothesis that the dynamics of contrast gain adaptation in auditory cortex reflect efficient coding of incoming sounds in a manner that shapes behavioral performance in an auditory task.

The efficient coding hypothesis has been formally implemented through normative models of brain function3,4,19–22. These models allow us to assess whether and how neuronal adaptation shapes sensory information and simulate how such adaptation might constrain behavior. There has been previous work demonstrating that efficient codes can explain psychophysical biases23 and shape the rate of information transmission when stimulus statistics change dynamically20,22. These studies, which are either theoretical in nature or based in human psychophysics, rely on assumptions of neuronal mechanisms of efficient coding that were not simultaneously measured. As such, there are no studies combining behavioral psychophysics with recordings of brain activity to simultaneously test the neural assumptions and behavioral predictions of these models.

Psychophysical studies suggest that the auditory system exhibits adaptation to acoustic contrast. In humans, target volume discriminability is greater in low contrast than in high contrast, an effect consistent with gain control observed in primary auditory cortex24. Similar effects have also been shown in ferrets performing an acoustic localization task, where it was demonstrated that neural responses in the inferior colliculus of anesthetized ferrets changed in a manner consistent with previously observed perceptual shifts10. However, it remains unclear whether the observed behavioral effects are indeed due to changes in gain in auditory neurons, as previous behavioral studies were not performed with simultaneous neural recordings, so a direct relationship between neural gain and perceptual performance has yet to be assessed.

Our first goal for the study was to build a formal framework based on efficient coding to model the dynamics of contrast gain control and thereby predict how behavioral performance should adapt after a change in contrast. We then derived a novel generalized linear model (GLM) to estimate moment-to-moment changes in neural gain, and we found that the dynamics of gain modulation in auditory cortex matched the predictions of the efficient coding model. Next, to directly test the role of efficient coding in auditory behavior, we trained mice to detect targets in different contrast backgrounds. Contrast-induced changes in behavioral sensitivity and detection dynamics followed the model predictions. Furthermore, we found that auditory cortex was necessary for target detection in the presence of noise. Building on this finding, we found that population activity in auditory cortex was predictive of individual differences in behavior and that the dynamics of cortical encoding of targets had time courses similar to our model and to the observed behavior. Finally, we used linear nonlinear models to monitor cortical gain during the task, finding that variability in neural gain predicted variability in task performance. Combined, our results identify a novel relationship between efficient neuronal coding and acoustic behavior, and they provide a normative framework that can be used to predict the dynamics of behavioral performance in response to changing sensory environments.

**Results**

*A novel target-in-noise detection task and normative model for task predictions.*

To assess how perceptual performance is impacted by stimulus contrast, we devised a GO/NO-GO task in which mice were trained to detect targets embedded in different contrast backgrounds. During each trial, the mouse was presented with dynamic random chords (DRCs) of one contrast, which transitioned after 3 s to the other contrast. At variable delays after the contrast transition, broad-band target chords were superimposed on the background chords, and mice were trained to lick for a water reward upon hearing the target. Target trials were interleaved with noise-only trials, during which the mouse was trained to withhold licking, but would receive a 7s timeout for licking after the contrast switch (Figure 1a,b). To assess behavioral sensitivity to targets, we parametrically varied target volume in each contrast (Figure 1c, top panel), and to assess behavioral adaptation, we parametrically varied target timing (Figure 1c, bottom panel). This stimulus design allowed us to quantitatively test whether and how the dynamics of adaptation to background contrast affect behavioral performance.

To predict the optimal time course of contrast gain control and its impact on target detection behavior, we developed a normative model of task performance constrained by efficient neural coding. In this model, we simulated a neuron designed to encode stimuli with minimal error. To efficiently exploit its finite dynamic range, the model neuron estimated the contrast of recent stimuli, and adjusted the gain of its nonlinearity to match the estimated contrast value (Figure 1d, panels 1-3; *Online Methods*)20,22. Adding targets at different levels and times relative to contrast transitions then allowed us to probe the sensitivity of the model neuron to targets of varying strength over the time course of adaption (Extended Data Figure 1c,d). When varying target strength and measuring target discriminability, we found decreased “detection” thresholds and steeper slopes in low contrast relative to high contrast (Figure 1e). When varying target timing, we observed two timescales that affected the target discriminability: 1) An abrupt drop in discriminability after a transition to high contrast; 2) A slower change in discriminability in both contrasts, as the gain of the model neuron adapted to the background (Figure 1f,g). We quantified these asymmetric dynamics by fitting exponential functions to each transition. To summarize, the normative model poses three primary predictions: When adapted to low contrast, 1) target detection thresholds will be lower and 2) sensitivity to changes in target volume will be higher; 3) Discriminability over time will be asymmetric: rapidly decreasing after a switch to high contrast, but slowly increasing after a switch to low contrast (Figure 1h).

*Estimated cortical gain dynamics follow normative model predictions.*

Most previous work on contrast gain control utilized static models of contrast adaptation, measuring the steady-state gain after the neuron has fully adapted to the new stimulus15,17,24,25, but see26,27. A major goal of the current study was to analyze the dynamics of gain control, so we developed a Poisson GLM to estimate the gain of neurons in auditory cortex at each time step following a contrast transition. This model was fit to data recorded from the auditory cortex of an untrained mouse (n = 97 neurons) presented with 3s alternations of low and high contrast noise (Figure 2a,b). A brief description of the model follows (see *Online Methods* for more detail).

The inference model is a Poisson GLM that decomposes the relationship between spiking activity () and the presented sounds () into a stimulus component (), a contrast component (), and an interaction between the stimulus and the contrast (). We then calculated a gain modulation index () from the fitted model parameters (Figure 2b). For comparison, we also fit previously described linear-nonlinear (LN) models to each neuron15,17,24,25, one with a static output nonlinearity (static-LN), and one with a contrast-dependent, or gain-controlled (GC), output nonlinearity (GC-LN, Figure 2c). Model results for a representative neuron are plotted in Figure 2d-g. Qualitatively, the GLM with gain control (GC-GLM) outperforms standard LN models, principally by capturing the adaptation after the transition (Figure 2d, middle panel), and it allowed us to analyze gain modulation over time, (Figure 2d, bottom panel; Figure 2g). Importantly, the fit of the GC-LN model and GC-GLM model both demonstrate gain control, characterized by high gain in low contrast and low gain in high contrast (Figure 2f and g, respectively), suggesting that both models capture similar gain estimates.

To test whether the GC-GLM could better account for the data, we compared cross-validated correlations of the model predictions with the trial averaged PSTH for all each neuron, finding a significant effect of model type on the correlations (n = 97 neurons; Kruskall-Wallis test: *H*(2) = 93.61, p = 6.70e-21). Post-hoc Wilcoxon Sign-Rank tests found that the GC-GLM correlation was significantly higher (Median (*Mdn*) = 0.75, Inter-Quartile Range (*IQR*) = 0.24) compared to the GC-LN model (*Mdn* = 0.54, *IQR* = 0.49, *p* = 4.41e-6) and the static-LN model (*Mdn* = 0.25, *IQR* = 0.73, *p* = 9.56e-10). Consistent with previous studies, we also found that the LN model with gain control outperformed the static model (*p* = 3.50e-6, Figure 2g). We then quantified whether the GLM detected significant gain control in the population by subtracting the gain estimate in low contrast from high contrast after the value of stabilized (1s post transition) and found significant gain control (*Mdn*: -0.10, *IQR*:

**Graphical user interface, diagram

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**a,** Experimental setup. **b,** GO/NO-GO task design. *Left:* example NO-GO trials. From top to bottom: spectrogram of an example low-to-high contrast trial (colorbar indicates volume in dB SPL); waveform for sample spectrogram; example spectrogram for a high-to-low contrast trial; waveform for example spectrogram; temporally jittered response window to estimate false alarms; schematic lick responses in the response window; timeout of 7 seconds delivered after the first lick. Vertical red dashed line indicates the contrast switch after 3 seconds. Black scale bar indicates 1s. *Right:* example GO trials. From top to bottom: same as in left panel, except the response window immediately follows target presentation and licks within the target window trigger a ~5µL water reward. **c,** Target manipulation waveforms. *Top:* overlaid trials where target volume differed. Volume is indicated by the amplitude and colorbar. *Bottom:* trials where target timing differed. The red vertical dashed line indicates the contrast switch. **d,** Normative model of the task. *Left inset*: volume distributions for backgrounds (light lines) and targets (dark lines) in low and high contrast. (1) Spike generation process: a model neuron encodes stimuli sampled from a 1-dimensional sensory stimulus stream consisting of a background that transitions between low and high contrast (light lines); target stimuli (solid dots) were used to assess sensitivity. The stimulus response of the neuron is transformed by a sigmoidal function whose output is used to generate stochastic spikes. (2) The observed spike counts are decoded and integrated over a brief time window and used to estimate the current variance of the stimulus. (3) This estimate is then fed back upstream and used to adjust the gain of the model neuron to minimize the expected error in the estimate of stimulus variance at each time step. *Bottom insets*: Sample probability distributions of observing k spikes in response to the noise background (light lines) or targets (dark lines) at time step 7 after switches to high (red) or switches to low contrast (blue). **e,** Model psychometric functions. Discriminability between model spike rates in response to the background and targets as a function of contrast and target volume. Light dots indicate model discriminability whereas the solid lines indicate logistic fits to the data. Dashed lines indicate detection thresholds. **f,** Model target discrimination as a function of time and contrast. Dashed vertical line indicates the time where the background contrast changes. Light dots denote model discriminability at each time step. Solid lines are exponential fits to the data. Each time course is the discriminability of targets at approximate threshold volume for that contrast (1.5 target mean and 2.25 target mean for low and high contrast respectively).  **g,** The average change in gain of the model after each contrast transition. **h,** Model predictions for the effects of contrast on psychometric thresholds, slopes, and adaptation time constants, as estimated by logistic and exponential fits in **e** and **f**.

0.35, Wilcoxon sign-rank test: *rank* = 233, *Z* = -2.90, *p* = 0.004; Figure 2i). To further validate the GLM estimates of gain, we compared the gain control index from the GC-GLM to that of the GC-LN model, and we found a significant relationship between the two indices (linear regression: *F*(1,95) = 12.20, *p* = 7.33e-4, *R2* = 0.11; Figure 2j). These results demonstrate that the GC-GLM better accounts for the neural data by incorporating gain adaptation dynamics, and we conclude that this method captures a similar estimate of neural gain when compared to standard models.

Using the GC-GLM, we estimated the time course of gain control by computing conditioned on the contrast transition and fit each trace with an exponential function (Figure 2g). In neurons with gain control, the average time course of demonstrates asymmetric adaptation, rapidly decreasing after a switch to high contrast, and slowly increasing after a switch to low contrast (n = 45 neurons; Figure 2k). Within this same population, we quantified the timescale of adaptation to each contrast using the time constant () of each exponential fit, finding significantly longer time constants in low contrast (*Mdn* = 0.29, *IQR* = .39) relative to high contrast (*Mdn* = 0.048, *IQR* = 0.094; Wilcoxon sign-rank test: *rank* = 918, *Z*  = 4.52, *p* = 6.16e-6). This asymmetry in gain adaptation agreed with the predictions of the normative model (Figure 1g) and with previously described behavior of optimal variance estimators19. Next, we tested whether similar dynamics were reflected in behavioral sensitivity to targets in noise.

*Mouse behavioral detection is modulated by background contrast.*

Mice were initially trained in a simple version of the GO/NO-GO task, where they were required to lick in response to a target and withhold licking on trials without a target (Figure 1b, 3a). Mice learned this task reliably, typically reaching criterion performance of 80% correct within 2-3 weeks in either contrast (Figure 3b). Observed false alarm rates were significantly larger in high contrast compared to low contrast (Extended Data Figure 3a), suggesting that detection is more difficult in high contrast, which we discuss next.

By varying the volume of presented targets, we collected psychometric curves for each mouse in each contrast. Figure 3c plots the performance of an example mouse overlaid with average psychometric fits, whereas Figure 3d plots the group averages for each contrast. Across all mice (n = 25), we found that targets were easier to detect in low contrast, observing significantly lower detection thresholds in low contrast (Mean (*M*)= 7.47, standard deviation (*SD*) *=* 1.59) compared to high contrast (*M =* 13.20, *SD =* 2.54; paired t-test: *t(23)* = -8.71, *p* = 9.59e-9, Figure 3e). Next, we computed how sensitive mice were to changes in target volume by calculating the maximum slope of the psychometric curve for each mouse. We found that in the full cohort of mice, there was no significant change in slope (Extended Data Figure 3b), which contradicted our normative model predictions (Figure 1e). Investigating further, we found that the range of target volumes had a significant effect on psychometric slopes. Namely, targets drawn from a narrow range of volumes resulted in steeper psychometric slopes than targets drawn from a wide range (Extended Data Figure 3c-f), regardless of the background contrast. To test the pure influence of contrast on psychometric slope, we tested a subset of mice with target volumes matched across the contrast conditions. In this cohort (n = 7; Figure 2f), we found significantly lower target thresholds in low contrast (*M* = 6.80, *SD =* 2.73) compared to high contrast (*M =* 14.96, *SD =* 3.51; paired t-test: *t(3)* = -3.59, *p* = 0.036; Figure 3g) and significantly steeper slopes in low contrast (*M* = 0.051, *SD =* 0.0068) compared to high contrast (*M =* 0.042, *SD =* 0.0064; paired t-test: *t(3)* = 3.42, *p* = 0.042; Figure 3h). These results demonstrate that background contrast has a substantial impact on detection threshold, and that mice are more sensitive to changes in the volume of targets presented in low contrast.

To assess behavioral adaptation to the background contrast, we presented targets at threshold volume at variable delays following the contrast transition. We observed behavioral time courses consistent with our normative model and with gain measured in auditory cortex: after a switch to high contrast, mice initially detected targets with high accuracy that decreased over time, while in low contrast the detection rate increased over time (Figure 3i). We found that in high contrast, the first significant drop in performance occurred between the first two time points, while in low contrast the first significant increase in performance occurred between the first and third time points (Figure 3i, Table 1). Then, by fitting each mouse’s adaptation time course with an exponential function and comparing time constants for each contrast, we also found that behavioral adaptation is significantly faster in high contrast (*Mdn* = 0.023, *IQR* = 0.082) compared to low contrast (*Mdn =* 0.13, *IQR* = 0.13; Wilcoxon sign-rank test (n = 21): *rank*  = 547, *Z* = 2.75, *p* = 0.0060; Figure 3j). Taken together, these behavioral results confirm the three predictions from our normative model (Figure 1h): 1) Detection thresholds are lower in low contrast; 2) Psychometric slopes are higher in low contrast; 3) Performance decreases rapidly in high contrast and increases gradually in low contrast.

*Auditory cortex is necessary for detection in noise.*

Previous studies have shown that while gain control is present in many areas across the auditory pathway, it is strongest in auditory cortex15,24. As such, we hypothesized that auditory cortex was likely to be a

**Diagram

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**a,** Schematic for acute recordings from auditory cortex. **b,** Schematic of Poisson generalized linear model (GLM) design. *From left to right:* The external variables considered by the model are the stimulus spectrogram, the stimulus contrast, and observed spikes. First, a spectrotemporal receptive field (STRF) is estimated. Second, we fit the parameters of a GLM with gain control (GC-GLM) designed to isolate the contributions of: 1) Stimulus drive, ; 2) The multiplicative interaction between the contrast and the stimulus drive, ; 3) Pure contrast drive, . The history of the contrast predictors were smoothed with a B-spline basis set. The linear combination of the predictors and fitted weights was then passed through an exponential nonlinearity to produce spike rate predictions. **c,** Schematic of linear-nonlinear models. As in **b**, we first fit a STRF which is then passed through either a static exponential nonlinearity (static-LN) or independent nonlinearities fit separately to low and high contrast periods (GC-LN). **d,** Neuronal responses and model fits to a representative neuron. *Top*: a spike raster for the example neuron. Each period of contrast is indicated by the blue (low contrast) and red (high contrast) bars. *Middle*: PSTH of the example cell is plotted with a grey fill and black outline. The predictions of the static-LN model are plotted in grey, the GC-LN model in green, and the GC-GLM model in orange. All traces were smoothed with a 10ms wide Gaussian filter for visualization. *Bottom*: the gain modulation index, (red trace). Grey dashed line at 1 indicates the gain of a neuron with neutral gain. The dashed black line indicates the gain of a neuron with perfect, instantaneous gain control. **e,** The STRF fitted to this neuron. **f,** The nonlinearities fitted to low (blue) and high (red) contrast in the GC-LN model for the example neuron. Points indicate the mean observed firing rate (ordinate), binned according to observed filter prediction values (abscissa). Solid lines indicate exponential function fits to the underlying points. **g,** The estimate of the gain, , for the example neuron after each contrast switch (dashed red and blue lines). The solid red and blue lines are fits of an exponential function to the underlying traces. Dashed grey and black lines indicate neutral and perfect gain control values as in **d**. **h,** Cross-validated Pearson’s correlations between the trial-averaged firing rate trace and the model predictions. Grey, green, and orange dots indicate the correlations for each neuron (n=95) for the static-LN, GC-LN, and GC-GLM models, respectively. Open circles indicate the median correlation, and the error bars indicate 2.5-97.5 percentiles. Results of Wilcoxon Sign-Rank tests are indicated with asterisks. **i,** Distribution of gain control estimated by the GLM for the recorded population. Here, gain control is defined as after the estimate has stabilized to its final value (ie. after 1s). Dashed vertical line indicates no gain control, while the solid orange line indicates the median of the distribution. Asterisks indicate the results of a Wilcoxon Sign-Rank test. **j,** Correspondence between gain control estimates from the GC-GLM model (abscissa) and the previously reported GC-LN model (ordinate). Black dots indicate the data for each neuron, while linear model fit and error are indicated by the grey line. Asterisks indicate significance of the linear fit to the data. **k,** Average time course of the gain estimate w for neurons with true gain control (i.e., their gain control value is less than 0, n = 45). Light red and blue lines indicate the average value of for transitions to high and low contrast, respectively (±SEM over neurons). Solid red and blue lines are exponential fits to the averages after the transition, which is marked by the dashed black line. **i,** Distributions of adaptation time constants of w after transitions to low, in blue, and high contrast, in red. Each dot indicates a neuron, with the black line linking within neuron measures. Asterisks indicate the results of a Wilcoxon Sign-Rank test. In all plots: ns, not significant; †p<0.1; \*p<0.05; \*\*p<0.01; \*\*\*p<0.001; \*\*\*\*p<0.0001.

key brain area supporting the detection of sounds in the presence of background noise, particularly when using background sounds known to modulate neuronal gain. To test whether auditory cortex is necessary for task performance, we inactivated auditory cortex using the GABA-A receptor agonist muscimol. In n = 2 untrained mice, we first validated that muscimol disrupts cortical coding of target sounds by applying muscimol topically to the cortical surface during passive playback of the behavioral stimuli, finding near complete suppression of target responses (Extended Data Figure 4a-f, *Supplementary Information*).

To test whether inactivation of auditory cortex affects behavioral performance, we repeated the same experiments in behaving mice, administering muscimol or saline bilaterally through chronically implanted cannulae (n = 4; Figure 4a). As observed in cortex, there was a profound decrease in the response rates to targets and noise in both contrasts (Figure 4b). We quantified these effects on the psychometric curve using a 3-way ANOVA with cortical intervention (muscimol or saline), contrast, and target volume as factors (n = 44 behavioral sessions). We found significant main effects of cortical intervention (*F*(1,307) = 278.63, *p* = 3.83e-44), contrast (*F*(1,307) = 4.39, *p* = 0.037), and volume (*F*(6,307) = 40.90, *p =* 7.54e-36). Post-hoc tests showed that muscimol application significantly decreased hit rates by 31% (95% CI: [28,35]), whereas hit rates were significantly elevated in low contrast by 4.9% (95% CI: [2.6,7.6]). Furthermore, we observed significant interactions between target volume and cortical intervention (*F*(6,307) = 14.11, *p* = 4.47e-14), and between target volume and contrast (*F*(6,307) = 2.97, *p* = 7.87e-3), but we did not observe a significant interaction between contrast and cortical intervention. To quantify the effects of muscimol on psychometric performance, we extracted response rates to the loudest target, false alarm rates, thresholds, and slopes of psychometric functions fit to each session, and we found that muscimol significantly reduced every measure of psychometric performance, with the exception of behavioral threshold (Figure 4c, Table 1). From these results, we can conclude that auditory cortex is necessary for performing target in noise detection, regardless of background contrast.

A potential alternative effect of muscimol is a general loss of function that is not specific to hearing target sounds. To control for this, we devised another task where mice (n = 2) detected targets in silence (Figure 4e), in addition to targets in noise (Figure 4d). To ensure equivalency between the two tasks, we took the highest-volume target trials in the noise task (25dB SNR in high contrast; Figure 4d, left panel) and removed the background noise during the target detection period (Figure 4e, left panel). As such, mice were presented with the exact same targets as in the previous task, but without the flanking noise, allowing us to test whether auditory cortex is specifically required for detection in the presence of noise.

To assess psychometric performance in this new task, we modulated detection difficulty by attenuating the volume of each target. As observed previously, inactivation of auditory cortex hindered detection in high contrast noise (Figure 4d, right panel). However, cortical inactivation had little effect on psychometric performance in silence (Figure 4e, right panel). We quantified these effects on the psychometric curve using a 3-way ANOVA with cortical intervention (muscimol or saline), task (detection in noise or silence), and target volume as factors (n = 26 sessions). We found significant main effects of intervention (*F*(1,181) = 62.83, *p* = 3.62e-13), task (*F*(1,181) = 6.82, *p* = 9.86e-3), and volume (*F*(6,181) = 46.16, *p* = 1.69e-32). Post-hoc tests showed that muscimol significantly reduced hit rates by 21.8% (95% CI: [15.2,25.2]). Hit rates to targets presented in silence were significantly elevated by 6.7% relative to targets presented in noise (95% CI: [1.7,11.6]). Furthermore, we found significant interactions between cortical intervention and task type (*F*(1,181) = 6.36, *p* = 0.013), intervention and volume (*F*(6,181) = 3.47, *p* = 2.98e-3), and volume and task type (*F*(6,181) = 8.47, *p* = 5.43e-8). As before, we parameterized psychometric performance by fitting each session with a psychometric curve, and we extracted response rates to the loudest target volume, false alarm rates, response rates at threshold volume, and slopes of psychometric functions. During the target in noise task, we found significant effects of muscimol on the response rates at maximum volume and threshold, a moderate effect on psychometric slope, and no effect on false alarm rate. However, muscimol application had no significant effect on any of these measures in the target in silence task (Figure 4f, Table 1). Taken together, these results show that while both cortical inactivation and the presence or absence of background noise affect behavioral performance, these effects interact: muscimol has a larger effect on performance when background noise is present.

Combined, our findings demonstrate that the auditory cortex is specifically required for detection in the presence of background noise. Our next goal was to test whether neuronal activity in AC is predictive of behavioral performance.

*Cortical codes predict individual behavioral performance.*

To better understand how representations in auditory cortex could give rise to behavior, we chronically recorded from populations of neurons in auditory cortex while mice performed the psychometric task (Figure 5a; n = 12 mice overall [n = 11 mice in low contrast sessions, n = 8 mice in high contrast sessions]).

**Diagram

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**a,** Schematic of GO/NO-GO paradigm. **b,** Behavioral performance for the contrast in which each mouse was first trained relative to the first session of task exposure (n=12 mice were first trained in low contrast, n=13 mice were first trained in high contrast). Dots indicate a session, while the traces indicate a running average using a 7 day window. Blue dots and traces indicate sessions in which mice detected targets in low contrast (i.e., after high-to-low contrast transitions), while red dots and traces indicate sessions in which mice detected targets in high contrast (i.e., after low-to-high contrast transitions). **c,** Psychometric functions in low and high contrast for one mouse (mouse ID indicated in the upper left). Each dot indicates percent correct for a single volume in a single session, while the solid lines indicate average psychometric fits. Colors as in **b**. **d,** Psychometric functions averaged for n=25 mice in low and high contrast. Error bars indicate ±SEM over mice at individual target SNRs, while the solid lines are logistic function fits to the average performance per contrast. **e,** Psychometric thresholds per contrast. Each dot represents a mouse, lines connect performance of individual mice on low and high contrast sessions. Bars indicate the average threshold over mice, while error bars in black indicate threshold ±SEM over mice. **f,** Behavioral psychometric functions for n=4 mice tested using the same target volumes in each contrast. Dots with error bars indicate average performance ±SEM over mice as a function of contrast and target volume. Overlaid, dark-colored curves indicate psychometric fits to the averages, with the black dot indicating the average threshold. Light-colored lines indicate the psychometric curves of individual mice. Black, dashed horizontal line indicates chance performance (percent correct = 0.5) performance. **g,** Psychometric thresholds per contrast. Each dot represents a mouse, lines indicate where mice participated in both low and high contrast sessions. Bars indicate the average threshold over mice, while error bars in black indicate threshold ±SEM over mice. **h,** Psychometric slopes per contrast. Presentation as in **g**. **i,** Behavioral performance as a function of contrast and target time relative to the switch in contrast for n=21 mice. Dots with error bars indicate average performance ±SEM over mice. Solid curves indicate exponential function fits to the average over mice. Black, dashed vertical line indicates the contrast switch. Horizontal lines at the top of the plot indicate significant changes in performance between the first target presentation time and subsequent target presentation times, as assessed by Wilcoxon Sign-rank tests with false discovery rate correction for multiple comparisons. **j,** Average time constant of exponential fits in low and high contrast. Presentation as in **h**. Unless otherwise noted, blue markers indicate data where targets were presented in low contrast and red indicates data where targets were presented in high contrast. In all plots: ns, not significant; †p<0.1; \*p<0.05; \*\*p<0.01; \*\*\*p<0.001; \*\*\*\*p<0.0001.

To leverage our ability to simultaneously record from multiple neurons, we adapted a population vector approach28 to generate metrics of target from noise discriminability using population activity (*Online Methods*). This method allowed us to project trial distributions in -dimensional neural space along a single dimension that separated target and noise trials (Figure 5d, left panel). We then estimated the criterion projection value that best predicted whether each trial contained a target or just noise29 (Figure 5d, right).

This population decoding method allowed us to estimate neurometric functions that could be directly compared to psychometric functions for each mouse (Figure 5e). On average, neurometric and psychometric functions were qualitatively similar (Figure 5f). To quantify the relationship between neural and behavioral performance, we calculated average thresholds and slopes for each mouse and used multiple linear regression to predict behavioral thresholds from stimulus contrast and neuronal thresholds (n = 19 mice). This model significantly predicted the observed thresholds (*F*(1,16) = 16.20, *p* = 2.34e-5, *R2* = 0.74), revealing that neuronal thresholds (*β* = 0.50, *p* = 0.020) and contrast (*β* = 3.034, *p* = 0.043) were significant predictors (Figure 5g). We then tested whether neurometric and psychometric thresholds were similarly affected by background contrast using a 2-way ANOVA, with thresholds as the dependent variable and threshold measure (psychometric or neurometric) and contrast as independent variables. We found a main effect of contrast (*F*(1) = 29.30, *p* = 5.00e-6), but no main effect of threshold measure (*F*(1) = 0.02, *p* = 0.89) and no interaction between measure and contrast (*F*(1) = 0.04, *p* = 0.85), which demonstrates that behavioral and neural thresholds were similarly affected by background contrast. As expected, post-hoc t-tests found no difference between neural and behavioral thresholds (mean change [95% confidence interval] *=* 0.19 [-1.38, 1.76], *p* = 0.81), and found that low contrast significantly decreased thresholds relative to high contrast (-4.77 [-6.34, -3.19], *p* = 5.43e-7). Taken together, these results demonstrate that population thresholds in auditory cortex are highly predictive of behavioral thresholds, and both neuronal and behavioral thresholds are modulated by contrast as predicted by gain control.

Next, we applied the same statistical analysis to neurometric and psychometric slopes, finding that neurometric slopes and contrast significantly predicted behavioral slopes (multiple regression: *F*(1,16) = 12.00, *p* = 6.63e-4, *R2* = 0.60). Examination of the individual predictors found that neuronal slopes were significantly predictive of behavioral slopes (*β* = 0.67, *p* = 0.0018), while contrast was not predictive (*β* = 0.010, *p* = 0.16) (Figure 5h). Repeating the ANOVA described above, we found a significant main effect of slope measure (*F*(1) = 5.88, *p* = 0.021) and contrast (*F*(1) = 8.31, *p* = 0.0068), but we found no significant interaction between the two (*F*(1) = 0.18, *p* = 0.67). Post-hoc testing revealed that neuronal slopes were significantly shallower than neuronal slopes (-0.015 [-0.027, -0.0024] PC/dB, *p* = 0.021). We also found that low contrast slopes were significantly shallower than high contrast slopes (-0.018 [-0.030, -0.0052] PC/dB, *p =* 0.0068), conflicting with our previous behavioral findings (Figure 3h). However, if we averaged only the sessions where mice were presented matched target volumes in low and high contrast, we found a significant main effect of contrast (*F*(1) = 5.98, *p* = 0.028) and slope measure (*F*(1) = 10.62, *p* = 0.0057). Post-hoc testing of this cohort revealed significantly steeper slopes in low contrast compared to high contrast (0.0071 [0.00087, 0.013], *p =* 0.028), and significantly shallower slopes of the neurometric functions compared to the psychometric functions (-0.0094 [-0.016, -0.0032], *p* = 0.0057; Extended Data Figure 5a). These results were consistent with our previous behavioral findings (Figure 2h), demonstrating that when target volumes are matched, increases in stimulus contrast induce a decrease in neurometric and psychometric slopes.

Taken together, these results demonstrate that parameters of neurometric and psychometric functions are affected by contrast in similar ways, consistent with our normative model. We also find that individual variation in psychometric performance is predicted by population activity in auditory cortex, independently of the effect of contrast.

*Asymmetric neural adaptation to targets.*

Using the same population decoding approach described above, we measured how cortical discriminability of target from noise trials evolved as a function of time and contrast during sessions where mice heard targets at threshold volume presented at different offsets relative to the contrast switch. While neuronal adaptation was qualitatively similar to behavioral performance, we quantified neuronal adaptation using the procedure applied to the behavioral time courses (n = 43 sessions, Figure 3i). As in behavior, we found that in high contrast, the first significant drop in performance occurred between the first two target times, while in low constrast, the first significant drop occurred between the first and third target times.Finally, to quantify the speed of neural adaptation, we fit the average neural discrimination time course for each mouse with an exponential function (n = 8 mice). Consistent with the behavioral results, we found asymmetric adaptation in the neural responses, with larger adaptation time constants in low contrast (*Mdn* = 0.14, *IQR* = 0.21) relative to high contrast (*Mdn* = 0.033, *IQR =* 0.16;Wilcoxon sign-rank test (n = 8): *rank*  = 28, *Z* = nan, *p* = 0.016).

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**Figure 4.**

**a,** Setup schematic for muscimol application in behaving mice. *Bottom*: legend indicating colors used for each background condition. **b,** Behavioral psychometric functions during muscimol or saline application for n=4 mice. Dark solid lines and filled circles indicate average performance after saline injection. Dark dashed lines and open circles indicate average performance after muscimol injection. Light solid and dashed lines are psychometric curves from individual sessions. Error bars indicate ±SEM. across sessions. **c,** Behavioral performance metrics as a function of contrast and pharmacological intervention. Open circles indicate performance in individual sessions. Colored bars indicate average performance across sessions. Bars with low transparency and solid outlines are averages after saline application, while high transparency bars with dashed outlines are averages after muscimol application. Clockwise from the upper left are plots of the following: max response rate, false alarm rate, psychometric threshold, and the maximum slope of the psychometric curve. **d,** *Left*: Example stimulus spectrogram for the target-in-noise detection task with the corresponding waveform below. The scale bar indicates 1 second, and the colorbar indicates the volume for each time-frequency bin (silence is black). *Right*: psychometric performance for n=2 mice in the target-in-noise task, with target volume on the abscissa and probability of responding on the ordinate. Filled circles and dark solid lines indicate average performance after saline injection and psychometric fits to the average. Red open circles and dark dashed lines indicate average performance after muscimol injection and psychometric fits to the average. Light red solid and dashed lines are psychometric curves from individual sessions. Error bars indicate ±SEM across sessions. **e,** *Left*: Example stimulus spectrogram for the target-in-silence detection task with the corresponding waveform below. Time scale and volume scale as in **d**. *Right*: psychometric performance for n=2 mice (same mice as in **d**) in the target-in-silence task, with target attenuation relative to the highest volume target from the target-in-noise task on the abscissa and probability of responding on the ordinate. Black filled circles and dark solid lines indicate average performance after saline injection and psychometric fits to the average. Open circles and dark dashed lines indicate average performance after muscimol injection and psychometric fits to the average. Light grey solid and dashed lines are psychometric curves from individual sessions. Error bars indicate ±SEM across sessions. **f,** Behavioral performance metrics as a function of task type (detection in noise or detection in silence) and pharmacological intervention. Formatting and metrics as in c (with the exception of response rate at threshold). Dark and light red bars indicate performance in the detection-in-noise task, with application of saline or muscimol. Dark and light grey bars indicate performance in the detection-in-silence task, with application of saline or muscimol. In all plots: ns*p*>0.1; †*p*<0.1, \**p*<0.05, \*\**p*<0.01, \*\*\**p*<0.001, \*\*\*\**p*<0.0001.

*Cortical gain predicts behavioral performance.*

Our behavioral results and model provide strong evidence that gain control in the auditory system shapes patterns of behavioral performance. To assess the role of cortical gain in behavior, we leveraged the design of our background sounds to estimate the STRFs and nonlinearities of neurons recorded while mice performed the task. For each neuron, we fit a model with a static nonlinearity (static-LN) or a model with gain control (GC-LN; Figure 6a).

Figure 6b-d plots data from a representative neuron recorded during behavior. The estimated STRF for this example unit is shown in Figure 6c with the nonlinearities estimated for each model in Figure 6d. The fits of the GC- and static-LN models to the data are plotted in the bottom of Figure 6b. We first compared the cross-validated performance of the static-LN model versus the GC-LN model, finding higher correlations using the GC-LN model (*Mdn* = 0.81, *IQR* = 0.17) relative to the static-LN model (*Mdn* = 0.67, *IQR* = 0.12; Wilcoxon sign-rank test (n = 2,792 neurons): *rank* = 3.84e5, *Z* = -36.75, *p* = 1.20e-295; Extended Data Figure 5h). After pooling all of the neurons recorded across all mice and sessions, and after including only neurons with strong stimulus responses in both contrasts (*Online Methods*), we observed significantly higher gain in low contrast (*Mdn* = 0.099, *IQR* = 0.13) than in high contrast (*Mdn* = 0.041, *IQR* = 0.023; Wilcoxon sign-rank test (n = 2,792 neurons): *rank* = 3.57e6, *Z* = 38.03, *p* = 2.15e-316; Figure 6e, inset). These results demonstrate that LN models can more accurately predict cortical activity when these models incorporate gain control, and they confirm previous reports of robust gain control in ferret and mouse auditory cortex14,17.

Based on our previous results, we predicted that the amount of gain in auditory cortex would predict target detectability. When fitting the GC-LN model, we separately estimated neural gain during the adaptation period of the trial and the target period of the trial (Figure 6b). To quantify the effects of contrast and trial period on gain, we performed a 2-way ANOVA, with gain as the dependent variable, and with contrast, trial period, and their interaction as factors. As expected from previous results, we found a significant main effect of contrast (*F*(1,4540) = 441.90, *p* = 1.066e-93). Furthermore, there was a significant main effect of trial period (*F*(1,4540) = 34.84, *p* = 3.85e-9) and a significant interaction between contrast and trial period (*F*(1,4540) = 78.94, *p* = 9.051e-19). Post-hoc tests revealed that, in low contrast, gain during the target period increased by 0.032 [0.024, 0.040] (*p* = 3.77e-9), but did not change in high contrast (-0.0065 [-0.014, 0.0014], *p* = 3.77e-9; Figure 6e). These findings indicate that neural gain is not only sensitive to stimulus contrast, but also increases during the target period of the task, specifically in low contrast.

To visualize the gross relationship between gain and psychometric performance, we first averaged the gain of stimulus-responsive neurons during the target period of the task (i.e., the time window after the contrast switch) for each session. We then selected only low contrast sessions and split the data by the median gain in the target period, separately computing the average psychometric curves for sessions in the bottom versus the top 50th percentile of gain (Figure 6f, inset). We observed that sessions with high gain had steeper slopes and lower thresholds than sessions with low gain (Figure 6f). To quantify this relationship between gain and task performance, we fit a mixed-effects model using contrast and gain during the target period as fixed effects, mouse identity as a random effect, and either psychometric slopes or thresholds as the dependent variable. This approach allowed us to separate the behavioral impact of gain control from effects of session-to-session fluctuations in gain (for full results of the following models, see Supplementary Table 1).

To test the effects of contrast and gain on psychometric thresholds, we fit the full model, as described above (n = 168 sessions across 13 mice). Then, to assess whether the inclusion of session-to-session variability in gain improved the model fit, we compared the full model to a null model that only included contrast. We found that the model that included gain was a better predictor of behavioral threshold than was the null model (Likelihood Ratio Test: (1) = 4.74, *p* = 0.029), indicating that thresholds decreased by about 2.59 dB SNR ±1.18 (standard error) for every 10% increase in gain. Using a similar procedure, we found that contrast was also a significant predictor of behavioral threshold (Likelihood Ratio Test: (1) = 5.84, *p* = 0.016), with the step from low to high contrast inducing a decrease in behavioral thresholds of 3.01 dB SNR ±1.23 (standard error).

We applied the same analysis to test the effects of contrast and gain on psychometric slopes (Figure 6f), again finding that gain significantly predicted psychometric curves (Likelihood Ratio Test: (1) = 5.09, *p* = 0.024), where the psychometric slope increased by 0.13 dB/PC ±0.059 (standard error) for every 100% increase in gain. However, contrast did not significantly improve the fit of this model (Likelihood Ratio Test: (1) = 1.57, *p* = 0.21). This result is not entirely unexpected, given that we observed no effect of contrast on psychometric slopes when comparing across sessions with different target distributions (Extended Data Figure 2b), which is true of the sessions used in this analysis.

Our findings suggest that the relationship between gain and psychometric performance is shaped by two sources: contrast-induced gain control and spontaneous fluctuations in gain from session to session. To

Diagram

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**a,** Experimental setup for chronic ACtx recordings from behaving mice. **b,** Example spiking responses to targets and noise in low contrast during behavior. The top portion of the plot is a spike raster ordered by target volume (colors indicate trial identity according to the legend). Below the raster is a trial-averaged PSTH, smoothed with a 2ms standard deviation Gaussian kernel. *Inset:* Area under the ROC curve (AUC) when discriminating noise from target responses across trials. The dashed horizontal line indicates chance performance (0.5). Error bars are the bootstrapped 95% confidence interval of the AUC value. **c,** Neurograms of populations of simultaneously recorded neurons during a low contrast and high contrast session from the same mouse. Neurons are plotted along the ordinate, while target volume is plotted along the abscissa. Within each plot, the shade indicates the neural response to each target volume, with the average response to noise alone subtracted. Asterix indicates the responses of the neuron in panel **b**. **d,** Discriminating targets from noise using population responses. *Left:* schematic of coding direction analysis. In high dimensional neural space, noise trials are represented as a gray point-cloud, while target responses are represented as a blue point-cloud. The coding direction (CD) is the vector defining the average difference between these two point-clouds as indicated by the arrow. *Right:* trial distributions of projections along the coding direction for one session (session CA118-200707, as plotted in **c**). The blue distribution shows the projection values for 20 dB SNR targets, while the gray distribution shows the projection values during noise-only trials. The vertical red line is the criterion used to compute performance (percent correct for these distributions is indicated by the arrow in panel **e**). **e,** Example neurometric and psychometric curves. *Left:* Low contrast curves. Light blue circles and solid lines indicate psychometric performance and a logistic fit, respectively. Dark blue circles and solid lines indicate neurometric performance from the session plotted in the left panel of **c**. The horizontal dashed line indicates chance performance (percent correct = 0.5). The arrow indicates the neural performance computed from the distributions and criterion plotted in **d**. *Right:* High contrast curves from the same mouse for the session plotted in the right panel of **c**. **f,** Average psychometric and neurometric functions across mice. Light circles indicate average behavioral performance, dark red and blue circles indicate average neural performance. Light solid curves indicate logistic fits to average behavioral performance, while vertical lines indicate the fit thresholds. Dark solid lines indicate fits and thresholds for the neural data. The dashed horizontal line indicates chance performance (percent correct = 0.5). Shades of blue and red indicate averages over low and high contrast, respectively. **g,** Relationship between behavioral and neural thresholds. Each circle represents the average behavioral and neural threshold for each mouse for each contrast (as indicated by the circle fill color). Grey lines and shaded areas indicate the linear regression fit across contrasts, ±95% confidence interval. The solid black line indicates unity. Black asterisks indicate significant multiple regression fits to the data; within that model: grey asterisks indicate that neural thresholds are significant predictors of behavior, while red asterisks indicate that contrast is a significant predictor.  **H,** Relationship between behavioral and neural slopes. Appearance as in **g**. **i,** Population decoder performance in each contrast transition, as a function of target presentation relative to the transition (indicated by the dashed vertical black line at 0s). Ticks on the abscissa indicate average target time from the transition in milliseconds. Solid lines and circles indicate the percent correct performance of a target decoder after a switch to low contrast (blue) or high contrast (red). Error bars indicate ±SEM over sessions. Horizontal lines indicate significant changes in performance between the first target presentation time and subsequent target presentation times, as assessed by Wilcoxon Sign-rank tests with false discovery rate correction for multiple comparisons. The span of the lines indicates the target times being compared, while the color of the lines indicates whether the test was performed within high contrast (red) or low contrast (blue). **j,** Adaptation time constants of exponentials fitted to the average neural decoder performance for each mouse in each contrast. Blue and red circles indicate the adaptation time constants from neural populations for each mouse in low and high contrast respectively. Solid black lines indicate time constants from the same mouse. In all plots: ns*p*>0.1; †*p*<0.1, \**p*<0.05, \*\**p*<0.01, \*\*\**p*<0.001, \*\*\*\**p*<0.0001.

further disentangle the relationship between these two sources of behavioral modulation, we repeated the mixed effects models, this time using gain during the adaptation period as the predictor of interest. We hypothesized that gain in this period should not be predictive of behavioral performance, as there were no targets presented during this portion of the trial. We found that this was indeed the case; we did not observe any predictive relationship between gain during this period and behavioral performance (Extended Data Figure 5i-k; Supplementary Table 1). In summary, we used a linear-nonlinear model to measure cortical gain in behaving mice, finding robust gain control in line with previous findings. Furthermore, we found that gain increased in the target period of the trial relative to the adaptation period, and that psychometric performance is predicted by both the stimulus contrast and by session-to-session changes in cortical gain during target detection.

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**Figure 6.**

**a,** Schematic of the linear nonlinear models fit to behavioral recordings. Spectrograms concatenated across trials were used to estimate a STRF using normalized reverse correlation. The relationship between the STRF prediction (grey trace) and observed spikes were used to estimate two models: a static model where the nonlinearity is estimated across all trial periods or a GC model where the nonlinearity is estimated separately for low and high contrast. **b,** Example background-locked responses from a well-tuned cortical unit across the trial duration. The top portion of the plot is a spike raster sorted by the frozen noise scenes (Scene 1-5) of the background. The contrast of the adaptation and target periods are indicated by the red and blue rectangles on the top of the plot. The bottom portion of the plot is a trial-averaged PSTH of the observed spiking, binned every 25ms (black trace). The colored traces are the predictions of the static model (grey) and GC model (orange). Correlations of the model predictions, and trial-averaged PSTHs are indicated in the legend. **c,** STRF for this example neuron. STRF values are indicated by the colorbar. **d,** Estimated nonlinearities for this example neuron. Points indicate the mean observed firing rate (ordinate), binned according to observed filter prediction values (abscissa). Solid lines indicate exponential function fits to the underlying points. Each line is a fit to the test set in 10 cross-validation runs. Blue and red lines and dots are the nonlinearities in low and high contrast for the GC model, while the grey lines and dots are for the static model (here, they are obscured by the high contrast data). **e,** Gain control in auditory cortex during the task. In the main figure, each probability density is the distribution of gain values in high and low contrast across neurons with NR below 100. Lighter shaded histograms indicate gain during the adaptation period and darker shaded histograms indicate gain during the target period (labelled by “A” and “T”, respectively). Asterisks indicate post-hoc test results for adaptation vs. target gain in each contrast. *Inset*: gain distributions for each contrast, regardless of trial period. Dashed vertical lines indicate the median of each distribution, asterisks indicate the results of a Wilcoxon Sign-Rank test across contrast. **f,** Average psychometric curves in low contrast split by cortical gain estimated during the target period of the stimulus. Light blue data points indicate the average performance in sessions where average gain was below the across-session median gain. Dark blue data points indicate average performance in sessions where average gain was above the median. Solid lines are psychometric fits to the data, with the thresholds plotted vertically from 0.5. Error bars indicate ±s.e.m. *Inset*: Histogram of average target gain over sessions. The dashed red vertical line indicates the median gain, light blue bars indicate sessions below the median, and dark blue bars indicate sessions above the median. **g,** Relationship between gain and behavioral threshold. Each circle represents the average gain and behavioral threshold for each session and contrast (blue and red dots indicate low and high contrast target periods, respectively). Grey lines indicate linear best fit. **h,** Relationship between gain and behavioral slope. Appearance as in **g**. In all plots: ns*p*>0.1; †*p*<0.1, \**p*<0.05, \*\**p*<0.01, \*\*\**p*<0.001, \*\*\*\**p*<0.0001.

**Discussion**

On a daily basis, we navigate through many auditory environments, each defined by different statistical properties. The dynamic range, or contrast, of acoustic inputs poses a challenge to the auditory system, which is composed of neurons with limited dynamic range in their response. The efficient coding hypothesis predicts that as acoustic contrast shifts, neurons throughout the auditory pathway should adjust their sensitivity in order to match their limited dynamic range to that of the stimulus distribution1. Multiple studies have demonstrated that indeed, neurons throughout the auditory pathway exhibit such contrast adaptation14–17. Whereas recent work has demonstrated a link between efficient cortical codes and human psychophysical performance24, whether neuronal contrast adaptation plays a role in auditory perception has not been previously examined simultaneously with behavior.

In this study, we directly linked neuronal contrast gain control to auditory behavior by combining a theoretical model of efficient coding, behavioral psychophysics, and simultaneous manipulation and recordings of cortical activity. First, we developed a normative model based on efficient coding20,30, which predicted that: (1) Detection thresholds of targets should be lower in low contrast than in high contrast; (2) Sensitivity to changes target volume should be greater in low contrast relative to high contrast; and (3) Detection should adapt asymmetrically: increasing slowly after a switch to low contrast, but decreasing rapidly after a switch to high contrast (Figure 1). Then, we used a novel variant of a Poisson GLM to confirm that gain control dynamics in auditory cortex are indeed asymmetric. To test the model predictions behaviorally, we trained mice to detect a target in background noise while shifting the contrast of the background between high and low contrast. As predicted by the model, mice had lower detection thresholds and were more sensitive to changes in target volume in low contrast. Behavioral adaptation was also asymmetric, decreasing rapidly after a switch to high contrast and increasing slowly after a switch to low contrast, in agreement with our model and with previous theoretical models19 (Figure 3). Furthermore, we found that AC is necessary for this detection-in-noise task (Figure 4). When recording in AC, we found that the parameters of neurometric functions were predictive of psychometric functions on a mouse-to-mouse basis, and we also showed that target discriminability adapted asymmetrically, as expected (Figure 5). Finally, we found that cortical gain during the target period of the task could predict behavioral thresholds and slopes on a session-to-session basis, independently of the effect of contrast (Figure 6). Taken together, these results support our hypothesis that efficient coding at the neuronal level shapes auditory behavior.

*The role of cortex in behavior.*

The role of auditory cortex in auditory behavior has been subject of debate. A number of prior studies found that auditory cortex was not required for relatively simple behavioral tasks such as frequency discrimination or detection31,32. Rather, many studies found that auditory cortex is primarily involved in more complex behaviors, such those requiring temporal expectation33, localization34, or discrimination of more complex sounds35–37. Consistent with previous findings38, we found that AC inactivation selectively impaired the detection of targets in a noisy background, but did not impair detection of targets in silence (Figure 4). Furthermore, on a subject-by-subject basis, neuronal activity in AC was correlated with behavioral performance of the subject (Figures 5, 6). This set of results establishes that AC is necessary for the detection of targets in background noise and supports the more general notion that AC is required for more difficult auditory tasks.

While the previous work demonstrates the necessity of auditory cortex in behavioral performance, the brain areas and mechanisms supporting the transformation from stimulus to decision are an active field of study39,40. By recording during the task, we were able to leverage behavioral variability to show that behavioral performance covaried with representations of targets within small neural populations (Figure 5), and with cortical gain (Figure 6). There is a large body of literature relating cortical codes to behavioral variability: early studies in the visual system suggested that information from relatively small numbers of neurons was sufficient to match or outperform animal behavior in psychophysical tasks41–43 and that behavioral choice can be predicted from activity in sensory areas29,43. These accounts suggest that variability in bottom-up sensory encoding drives the variability in behavioral output. However, more recent work suggests that variability in sensory areas is driven by top-down influences44–47, which are modulated by attention and learning48–51. Interestingly, a recent study imaging tens of thousands of neurons in the visual cortex demonstrated that cortical representations had higher acuity than behaving mice, yet did not correlate with behavioral performance, suggesting that perceptual discrimination depends on post-sensory brain regions52.

Our results suggest that bottom-up adaptation to stimulus statistics shapes behavioral output: We observed asymmetric time courses of target discrimination following a change in contrast (Figure 3) that were qualitatively consistent with the predictions of efficient coding (Figure 1), resembled temporal asymmetries of gain adaptation in auditory cortex in the absence of behavior (Figure 2), and resembled patterns of target-driven activity in auditory cortex during the task (Figure 5). Indeed, there have been other studies demonstrating that individual differences in sensory-guided behaviors are reflected in cortical activity53,54, are bidirectionally modulated by cortical manipulation55,56, and can be predicted from tuning properties in auditory cortex57,58. While our results cannot rule out top-down input as the causal driver of sensory decisions, they do support the notion that the sensory information upon which decisions are made is shaped by neuronal adaptation, which thus affects behavioral outcomes.

*Roles of gain in the auditory system.*

Neurons throughout the auditory system adapt to the statistics of the acoustic environment, including distributions of stimuli over time59,60, more complex sound patterns27,61, and task-related or rewarded stimuli62–67. Inspired by the latter studies, we intentionally designed our stimuli using unbiased white-noise backgrounds, which allowed us to fit encoding models to our data. Using these methods, we focused on contrast gain control as a fundamental statistical adaptation that relates to efficient coding14,17,18,24. In this study, we developed a novel form of Poisson GLM that allowed us to quantify the contribution of multiplicative interactions between the stimulus and stimulus contrast to the activity of neurons in auditory cortex. Using the fitted parameters of the model, we were able to accurately estimate neuronal gain as a function of time. This approach allowed us to verify that gain adaptation in auditory cortex is asymmetric (Figure 2), as predicted from efficient coding theory19 and as shown in previous work25.

Furthermore, we found that behavioral detection of targets adapted asymmetrically (Figure 3), similar to observed gain adaptation in auditory cortex. This suggested that the dynamics of contrast gain control influenced task performance. Indeed, we found that both stimulus contrast and session-to-session fluctuations in gain predicted psychometric performance (Figure 6). These results suggest two sources of gain modulation in auditory cortex: 1) Bottom-up adaptation to stimulus statistics (i.e., contrast gain control), and 2) session-to-session modulation of gain. Previous studies have demonstrated this latter phenomenon, suggesting that top-down gain modulation underlies attention44,45,68 and optimal behavioral states69,70. Our results suggest that automatic forms of gain control, as well as session-to-session fluctuations in gain, modulate behavior, and they provide a starting point for dissecting the neural mechanisms underlying these two forms of gain modulation.

*Cellular mechanisms of gain control.*

While this and other studies demonstrated contrast gain control in the auditory system, the neuronal mechanisms driving gain adaptation at a cellular level remain unclear. In the current study, we have likely recorded from a mixed population of excitatory and inhibitory neurons. Different inhibitory neuronal subtypes exhibit specific roles in adaptation71,72. Although specific inhibitory neuronal subtypes facilitate divisive or subtractive control of excitatory responses in visual73,74 and auditory cortex75,76, the role of these interneurons in contrast gain control has been inconclusive18. Furthermore, we were able to separate the behavioral contribution of contrast gain control from stimulus-invariant changes in gain. Whether these two forms of gain control share common neural substrates is unclear. By combining previously mentioned optogenetic methods with behavioral tasks, future studies may explore and test the specific role of local circuits and top-down modulation in gain control and behavior.

*The missing link between efficient coding and behavior.*

Combined, our results develop a framework and provide support for the role of efficient neuronal coding in behavior. The efficient coding hypothesis has emerged as one of the leading principles in computational neuroscience that has shaped our understanding of neuronal coding, architecture, and evolution1,21,77–79. Prior research found that human behavior follows principles of efficiency23,24. Our work now provides a framework for linking the principles of neuronal coding with behavioral performance. Additionally, we have introduced a novel form of Poisson GLM designed to detect multiplicative interactions between presented stimuli and other variables. While in this study we focused on the multiplicative effect of contrast, this approach could in theory be applied to any other time-varying signal that modulates neuronal gain, such as movement80,81, arousal69,70, or targeted experimental interventions74–76,82. In summary, we expect the theoretical frameworks and modelling methods applied here to have broad utility in the study of neuronal adaptation, a fundamental function of the nervous system.

**Online Methods**

*Animals*.

All experiments were performed in adult male (n = **xxx**) and female (n = **xxx**) mice (The Jackson Laboratory; age 12-15 weeks; weight 20-30g; **STRAINS**, etc.), housed with, at most, five mice per cage, at 28°C on a 12-h light:dark cycle with food provided ad libitum, and a restricted water schedule (see *Water Restriction*). All experiments were performed during the animals’ dark cycle. All experimental procedures were in accordance with NIH guidelines and approved by the Institutional Animal Care and Use Committee at the University of Pennsylvania.

*Surgery*.

Mice were anesthetized under isoflurane (1-3%). Prior to implantation, all mice were administered subcutaneous doses of buprenorphine (Buprenex, 0.05-0.1 mg/kg) for analgesia, dexamethasone (0.2 mg/kg) to reduce brain swelling, and bupivicane (2 mg/kg) for local anesthesia. In mice undergoing electrophysiological experiments, two ground screws attached to ground wires were implanted in the left frontal lobe and right cerebellum, with an additional skull screw implanted over the left cerebellum to provide additional support. A small craniotomy was performed over the target stereotactic coordinates relative to bregma, -2.6mm anterior, -4.3mm lateral. Either custom 16-channel microdrives, 32-, or 64-channel shuttle drives (cite) holding tetrode bundles of polyimide-coated nichrome wires were chronically implanted over auditory cortex, and tetrodes were lowered 800um below the pial surface. The exposed tetrodes were covered with GelFoam (Pfizer) or sterile silicone lubricant and sealed with Kwik-Cast (World Precision Instruments). The plastic body of the microdrive and a custom stainless-steel headplate were secured to the skull using dental cement (C&B Metabond) and acrylic (Lang Dental). Mice undergoing only behavioral experiments were implanted with two skull screws in the cerebellum, and a headplate was mounted on the skull as previously described. An antibiotic (Baytril, 5mg/kg) and analgesic (Meloxicam, 5mg/kg) were administered daily (for 3 days) during recovery.

*Water restriction*.

Following surgical recovery (3 days post-operation), each mouse’s weight was monitored for three additional days to establish a baseline weight. Over the next seven days, mice were water deprived, beginning with a daily ration of 120uL/g and gradually decreasing their ration to 40-50uL/g. During the task, if mice did not receive their full ration, the remainder of their ration was provided in their home cage. Mouse weight relative to baseline was monitored during all stages of water restriction. Additional health signs were used to determine a health score and subsequent treatment plan if a mouse lost more than 20% of baseline weight, as described by previously published methods83 and approved by the Institutional Animal Care and Use Committee at the University of Pennsylvania.

*Behavioral apparatus*.

During the GO/NO-GO task, the mouse was head-fixed in a custom-built, acoustically isolated chamber. A capacitive touch sensor (AT42QT1010, SparkFun) soldered to a lick spout monitored lick activity. Water rewards were dispensed from a gravity fed reservoir, controlled by a solenoid valve (161T011, Neptune Research) calibrated to deliver approximately 4-5uL of water per reward84. Low-level task logic – such as lick detection, reward and timeout delivery, and task timing intervals – was directly controlled by an Arduino Uno microprocessor running custom, low-latency software routines. High-level task logic, such as trial randomization, stimulus buffering and presentation, and online data collection and analysis were controlled by custom MATLAB (Mathworks) software communicating with the Arduino over a USB serial port. Digital waveforms were converted to analog signals via a soundcard (Lynx E44, Lynx Studio Technology, Inc.) or a National Instruments card (NI PCIe-6353) and delivered through an ultrasonic transducer (MCPCT-G5100-4139, Multicomp). The transducer was calibrated to have a flat frequency response between 3 kHz and 80 kHz using a 1/4-inch condenser microphone (Brüel & Kjær) positioned at the expected location of the mouse’s ear, as described previously85,86. During electrophysiological recording sessions, licks were detected using an optical interrupt sensor (EE-SX771, Omron Automation), to prevent lick-related electrical artifacts introduced by contact with the capacitive sensor.

*Behavioral timeline*.

Each mouse underwent four stages in the behavioral task: 1) water restriction and habituation, 2) behavioral training, 3) psychometric testing, and, 4) offset testing. During the induction of water restriction, mice were simultaneously habituated to head-fixation in the behavioral chambers and receiving water through the lick spout, by providing a water reward for any licks separated by more than 2 s. After the mouse began to receive its entire ration by licking in the booth, behavioral training was initiated (typically 1 week). Each mouse was initially trained and tested in one contrast condition (see *Stimuli*), with the initial training condition counterbalanced across mice. Behavioral performance was monitored during training, and mice were considered trained after completing at least three consecutive sessions with over 80% percent correct (~2-3 weeks). After completing training, behavioral thresholds were measured during at least three sessions in which psychometric stimuli were presented (see *Stimuli*). After estimating the behavioral threshold for each mouse, offset stimulus sets were generated using threshold-level targets. After completion of at least three sessions in the offset task, each mouse was then retrained on the remaining contrast condition. Upon reaching the training criterion of 80% in the new contrast condition, mice were then tested in the psychometric and offset tasks as previously described. For mice in electrophysiological experiments, this sequence of training and testing was continued until the recording site yielded less than three units, or until the mouse stopped performing in the task.

*Stimuli*.

All stimuli were created in MATLAB and sampled at 192 kHz or 200 kHz and 32-bit resolution. A set of dynamic random chords (DRCs) were created with different contrasts, similarly to those described in previous studies14,17,24. This stimulus was used 1) to measure the spectrotemporal receptive fields of neurons by fitting a linear-nonlinear model, and 2) to modulate the gain of auditory neurons by manipulating stimulus contrast. To construct a DRC, amplitude modulated pure tones were generated at multiple frequencies and then superimposed to create a chord. In some experiments, 34 frequencies were sampled between 4 and ~40kHz in 1/10 octave steps, in the remaining experiments, 33 frequencies were sampled between 4 and 64kHz in 1/8 octave steps. The amplitude envelope of each tone was generated as follows: every 25 ms, amplitudes for each frequency were sampled from a uniform distribution with a mean of 50 dB and a width of ±5 dB in low contrast or ±15 dB in high contrast. Between each 20 ms chord, the amplitude envelope of each frequency band was linearly ramped over 5 ms to the amplitude value for the next chord, such that the total duration of each chord and its ramp was 25 ms. To synthesize the stimuli, amplitude envelopes were multiplied by a sine wave of their respective frequencies, and summed to produce the final waveform. Each time a set of DRCs was generated, 5 unique random number generator seeds were used to restrict the background noise to 5 distinct scenes (see raster in Figure 6 for an example of spike-locking to the repeated scenes).

In all stages of behavioral training and testing, stimuli created for each trial consisted of a DRC background containing a change in contrast, and the presence or lack of a target at a delay after the change in contrast. Each trial was initialized with 3 seconds of DRC noise of one contrast, followed by a switch to the other contrast. Targets consisted of a fixed chord composed of 17 frequencies pseudo-randomly sampled from the frequencies contained in the DRC background, such that the target frequencies were uniformly distributed across the frequency range of the background. To add targets to the background noise, the target amplitude at each target frequency was simply added to a single chord in the amplitude envelope of the background, and ramped as described previously; this procedure ensured that target timing was perfectly aligned to changes in the background noise, removing asynchronous timing cues that could be used by the animal to detect the target. Target amplitudes are described in values of signal-to-noise ratio (SNR) relative to the average level of the background noise (ie. a 50 dB target embedded in 50 dB noise would have an SNR of 0 dB). We note that because the targets only contained power in half of the frequency bands used to construct the noise background, target SNRs were typically above 0 dB (see Table 2 for a breakdown of SNRs used across all mice). In all trials, targets were embedded after a change in the background contrast, with a delay and volume dependent on the current training or testing stage (see *Behavioral Task*).

*Efficient coding model.*

We simulated a model neuron that encodes incoming stimuli via an adapting neural nonlinearity. Stimuli were drawn from a Gaussian distribution whose mean was fixed over time but whose standard deviation could switch over time between a low and a high value ( and , respectively). At each time , a stimulus was drawn from the distribution , transformed via a saturating nonlinearity of the form , distorted by Gaussian noise with variance , and finally discretized into discrete levels to generate a response . This discrete response was linearly decoded to extract an estimate of the current stimulus: . The recent history of stimulus estimates was used to update an estimate of the underlying standard deviation: . The estimate was then used to select the parameters of the encoder () and the decoder () on the next timestep. The encoding and decoding parameters were chosen to minimize the expected error in decoding stimuli given the neuron’s current estimate of the underlying standard deviation: 20,22.

The parameters of the encoder and decoder were adapted based on a background stimulus with a mean that was fixed over time and a standard deviation that switched between low and high values and , respectively. We used this adapting nonlinearity to determine how well this model neuron could discriminate target stimuli from this background. Target stimuli were sampled from a Gaussian distribution with a fixed mean and with a variance that was scaled in proportion to the variance of the background ( and , respectively). At each timestep, we computed the Bhattacharyya coefficient () of the response distributions produced by background versus target stimuli: . We used as our measure of discriminability.

We simulated the behavior of this model using a background “probe” stimulus whose standard deviation switched every timesteps. We simulated cycles of this probe stimulus, where each cycle consisted of timesteps in the low state, followed by timesteps in the high state. This yielded timeseries of the gain and offset of the adapting nonlinearity, as well as distributions of the neural response to the background and target stimuli at each timepoint following a switch in standard deviation. We averaged the gain and offset across cycles to obtain the average properties of the encoder at each timepoint following a switch. We used the distribution of responses to target and background stimuli, measured across cycles, to compute the discriminability at each timepoint following a switch. All simulations were performed with the following values: , ,, 0 to 3 in 0.25 steps, , ,,,. For Figure 1g, model discriminability in each contrast was fit with a logistic function to estimate the sensitivity and threshold of the model. The thresholds for each contrast were then used to select target volumes to plot discriminability over time (, ; Figure 1f).

*Behavioral task*.

We employed a GO/NO-GO task to measure the ability of mice to detect targets in noise. In this task, each trial consisted of a noise background with a contrast shift, along with the presence or absence of a target after the change in contrast. Mice were trained to lick when they detect a target (hit), or to withhold licking in the absence of a target (correct reject). This behavior was reinforced by providing a 4-5 uL water reward when the mouse performed a hit, and by initiating a 7-10 s timeout when the mouse licked in the absence of a target (false alarm). Any licks detected during the timeout period resulted in the timeout timer being reset. In a subset of mice, we introduced an additional trial abort period coincident with the first part of the contrast background, before the contrast switch. Any licks detected in this abort period resulted in the trial being reset after a 7-10 s timeout, until the mouse withheld from licking during this period. In this task, misses and correct rejects were not rewarded or punished. Trials were separated by a minimum 1.5s inter-trial-interval (ITI). To discourage spontaneous licking, licks were monitored during this period, and if any licks occurred the ITI timer was reset.

All of the behavioral tasks varied the timing of the target relative to the contrast shift, which required a method for estimating hit rates and false alarm rates at different times during each trial, and to reward and punish the animal during these times in an unbiased manner. To approach this issue, we considered licks as responses only during a 1 s response window after a target presentation in the trial (eg. if a target was presented 500 ms post-contrast-switch, the response window persisted from 500 to 1500 ms post-contrast-switch). To apply this method to noise-only trials, in which no targets were presented, we considered noise trials as target trials containing infinitely small target amplitudes. For each noise trial, we assigned a response window with equiprobable delay matched to the target conditions and considered only licks within those “target” response windows. Thus, over the course of a session, we randomly sampled lick probabilities in noise trials during the same temporal windows as those licks considered during target trials. Using this scheme, we treated target and noise trials identically, and estimated hit rates and false alarm rates over time in an unbiased manner.

Each mouse performed three stages in the behavioral task: training, psychometric testing, and offset testing. During the training task, trials consisted of two types, noise trials or target trials presented with equal probability. To facilitate learning, we selected target SNRs at the highest end of the range described previously: in low contrast training sessions, targets were 16 dB SNR, and in high contrast training sessions, targets were 20 dB SNR. To prevent response bias as a function of target timing, we randomly varied the target delay between 250, 500, 750 and 1000 ms after the contrast change in each trial. During the psychometric testing task, there were 7 trial types consisting of noise trials and target trials spanning six different SNRs (Table 2). Based on behavioral piloting, we presented high SNR trials with a greater probability, to prevent mice from giving up during the task. In low and high contrast psychometric sessions, the probability of a noise trial was 0.4, the probability of the four lowest target SNRs was 0.05 each, and the probability of the two highest target SNRs was 0.2 each. As in training, target timing was varied randomly between 250, 500, 750 and 1000 ms after the contrast change in each trial. After completing at least three sessions of the psychometric task, stimuli were generated for the offset testing task. This task consisted of 15 unique trial types: 3 target volumes (noise trials, threshold target trials, and high SNR target trials), and 5 target delays relative to the contrast change (25, 75, 225, 475, 975 ms delay). Threshold target amplitudes were determined individually for each mouse by fitting psychometric curves averaged over several sessions with a psychometric function, and extracting the volume at which the slope of the psychometric curve was steepest (see *Behavioral and Neural Detection Performance*). Based on behavioral piloting, noise trials, threshold target trials, and high SNR target trials were presented with probabilities of 0.4, 0.2, and 0.4, respectively. Target delay on each trial was selected with equal probability. In all behavioral stages, trial order was pseudorandomly generated, such that there were no more than three target or noise trials in a row.

A subset of mice (n = 2), were presented targets in the presence of noise (Figure 4). To generate this stimulus set without changing the basic structure of the task or stimuli, we simply took the spectrograms of all stimuli containing 25 dB SNR targets from the low-to-high contrast stimulus sessions, and set the stimulus power flanking each target to zero. This manipulation was only performed in the target period, and the low contrast adaptation period of the trials remained the same. Thus, the targets and adaptation periods were identical to those presented in the target in noise task (see Figure 2e). To vary the difficulty of the task, the volume of the target was manipulated using the following values: -75, -60, -45, -30, -15, and 0 dB attenuation relative to the 25 dB SNR target. Mice were previously trained in the target in noise task prior to performing the target in silence task. Before psychometrically varying the target attenuation, mice were trained in the new task to criterion performance. Mice generalized very rapidly to the new task, reaching 97% and 94% training accuracy on the first day of exposure to targets in silence (performance for mouse CA124 and CA125, respectively).

*Chronic muscimol application*.

A separate cohort of mice (n = 4) were bilaterally implanted with 26 GA guide cannulae (PlasticsOne, C315GMN-SPC mini, cut 5 mm below pedestal) in auditory cortex. The surgery was performed as described previously with the following modifications. After the skull was leveled using a stereotax, two small craniotomies were performed -2.6 mm anterior, ±4.3 mm lateral from bregma, over auditory cortex. The guide cannulae along with dummy infusion cannulae (PlasticsOne, C315DCMN-SPC mini, cut to fit 5 mm C315GMN with a 0.5 mm projection depth) were sterilized in an autoclave. The dummy cannulae were partially screwed into the guide cannulae and placed in a stereotaxic clamp. After zeroing the tip of the guide cannula to the brain surface, the cannula was lowered to 500 μm below the cortical surface. This depth was chosen because the infusion cannulae (PlasticsOne, C315LIMN-SPC mini) project 500 μm from the end of the guide cannulae when screwed in completely, leading to a final depth of 1000 μm – the location of auditory cortex. The dummy cannulae were then fully screwed down and this procedure was repeated for the next cortical hemisphere.

Prior to injecting, two injection syringes (Hamilton Syringe, 10μL Gaslight #1701) and tubing (C313CT tubing 023x050 PE50) were backfilled with mineral oil. Sterilized infusion cannulae were then attached to each syringe and ~500nL of muscimol (diluted with 1x PBS to .25 mg/mL; Sigma Aldrich, M1523) or 0.9% sterile saline was drawn up into the injection cannulae using a dual injector (Harvard Apparatus, Pump 11 Pico Plus Elite). The mouse was then headfixed and the dummy cannulae were removed and sterilized. The loaded infusion cannulae were then screwed all the way into the guide cannulae and 400 nL of muscimol or saline was infused bilaterally at a rate of 250 nL/minute. The infusion cannulae were then replaced with the dummy cannulae and the mouse rested in its home cage for 30-45 minutes before beginning the behavioral session.

*Acute electrophysiological recordings.*

For acute recordings used to fit the GC-GLM model (Figure 2), neuronal signals were recorded from n = 1 awake, untrained mouse. Prior to the recording session, the mouse was anesthetized and a headpost and ground pin were implanted on the skull (see *Surgery*). On the day of the recording, the mouse was briefly anesthetized with 3% isoflurane and a small craniotomy was performed over auditory cortex using a dental drill or scalpel (~1 mm x 1 mm craniotomy centered approximately 1.25 mm anterior to the lambdoid suture along caudal end of the squamosal suture). A 32 channel silicon probe (Neuronexus) was then positioned perpendicularly to the cortical surface and lowered at a rate of 1-2 μm/s to a final depth of 800-1200 μm. As the probe was lowered, trains of brief noise bursts were repeated, and if stimulus locked responses to the noise bursts were observed, the probe was determined to be in auditory cortex. The probe was then allowed to settle for up to 30 minutes before starting the recording. Neuronal signals were amplified and digitized with an Intan headstage (RHD 32ch) and recorded by an openEphys acquisition board87 at a rate of 30 kHz.

For this experiment, the mouse was presented with 3 s DRCs alternating between low and high contrast (uniform distribution with a mean of 50 dB and a width of ±5 dB in low contrast or ±15 dB in high contrast at a chord rate of 25 ms, as described in *Stimuli*). In order to accurately fit the GLM in an unbiased manner, these stimuli were highly random, composed of 100 unique chord patterns for each contrast (Extended Data Figure 2i,j**)**. For each of the two recording sites, 5 repeats of this stimulus set were played.

*Behavioral electrophysiological recordings*.

Neural signals were acquired from awake, behaving mice as they performed the psychometric and offset testing tasks described previously. Chronically implanted, 16-, 32-, or 64-channel microdrives87,88 were connected to one or two 32 channel Intan amplifier headstages. Amplified signals were recorded at 30 kHz using an openEphys acquisition board via an SPI cable, where the signals were digitized. Spikes were then sorted using Kilosort, as described previously.

For all recordings, broadband signals were filtered between 500 and 6000 Hz, offset corrected, and re-referenced to the median across all active channels. The preprocessed data was then sorted using KiloSort89 or KiloSort2 and the resulting clustering was manually corrected in phy2 according to community-developed guidelines. The resulting units were labelled as single units if they exhibited a clear refractory period and did not need to be split. Splitting assessments were made through manual examination of principle component features for the two best channels of a cluster. If two noticeable clusters in feature space were evident in a unit, the unit was either manually split, or classified as a multiunit.

*Generalized linear model.*

To justify the form of GLM used here, we discuss a how a model neuron could implement gain control in the simplest terms, and then structure our inference model to extract the parameters of this model neuron. We will assume that the activity of the model neuron is driven by three sources: 1) stimulus drive, 2) stimulus contrast, and 3) the multiplicative interaction between the two, which we use to define the gain (for a formal definition of this forward model and the inference model, see *Supplementary Information*).

As discussed previously, the stimulus used in our experiments is a one-dimensional signal that evolves in discrete time steps:

where is the stimulus spectrogram that varies as a function of time and frequency . Each time and frequency bin of is sampled from a uniform distribution defined by an average value and contrast (see *Stimuli* and *Acute Electrophysiological Recordings*).

We assume that the hypothetical neuron responds selectively at some frequency and time lag, defined by a filter, or STRF with history and frequency components. Given , we can define the stimulus drive as

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|  |  | (1) |

where at each time , is a row vector of size frequencies by lags (ie. a matrix of the lagged stimulus spectrogram) and is the STRF collapsed to a single row vector of the same size.

In the spirit of efficient coding theory, and as shown in previous work, we assume that the gain of the neuron should be inversely proportional to the contrast, such that (ie. when contrast is low gain should be high, and vice-versa). We also define “neutral” gain to be the average of the gain of the neuron in low and high contrast. Putting these two features together, we can summarize the gain of the neuron as

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|  |  | (2) |

where is the harmonic mean of the contrast between the low and high conditions (see *Supplementary Information*). In the case of a 3-fold change in contrast, this function constrains the gain of the neuron between 1.5 and 5, with a neutral value of 1. As mentioned previously, we consider gain to be the multiplicative interaction between the stimulus drive and the contrast, such that the contribution of gain control to the response of the neuron is related to .

To summarize, we considered a hypothetical neuron driven by the stimulus according to a STRF and by the interaction between the stimulus drive and the contrast . To infer the relative weights of each of these components of the neural response, we defined a Poisson GLM with an intercept term and the following predictors:

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|  |  | (3) |

In other words, the model is composed of a stimulus predictor , a contrast predictor , and their interaction. Therefore, the GLM models the firing rate at time as a Poisson distribution with the following mean:

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|  |  | (4) |

where are the parameters to be inferred. Based on our behavioral data (Figure 3) and the predictions of the efficient coding model (Figure 1), we expected the influence of contrast on neural gain to be asymmetric and smooth. To enforce both of these qualities in the GLM, we first defined the contrast predictors from a set of cubic B-spline temporal basis functions, then defined separate contrast predictors for transitions to low and high contrast. Incorporating these changes, we can redefine equation 4 above as

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|  |  | (5) |

where denotes element-by-element “broadcasting” multiplication and is a matrix of contrast predictors convolved with a set of basis functions and separated by contrast transitions (see *Supplementary Information*). For the sake of clarity, note that in the expression above, is a number, is a column vector of length , is a number, is a -by- matrix, and and are column vectors of length , where is the number of splines.

So far, we outlined a hypothetical neuron which implements gain control, and a GLM with which we can approximate the behavior of this neuron. Next, we describe how to use the fitted parameters to quantify the gain of the neuron. Conceptually, an increase or decrease in the gain of the neuron is analogous to more or less sensitivity to small changes in the stimulus. Based on this intuition, we focused on how the response of the neuron (as modelled by a fitted GLM) is expected to change between conditions where the gain is expected to contribute (ie. in the presence of gain control) and where it is not (ie. in the absence of gain control, where gain is “neutral”). Following this logic, we derived a definition for gain as the ratio between the sensitivity of the fitted model with changes in contrast, compared to the sensitivity of the same model when the contrast is at a reference value, which we defined previously as :

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|  |  | (6) |

where is the estimated gain at time , and is a reference contrast design matrix identical to except that all non-zero elements are set to 1 (see *Supplementary Information* for full derivation of ).

To fit the model, we implemented a two-step procedure. In the first step, the STRF of the neuron was estimated according to the model

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|  |  | (7) |

For the second step, we calculated the stimulus drive as described in equation 1, and then fit equation 5 to the data for each neuron using in MATLAB. This entire fitting procedure was 10-fold cross-validated with folds stratified across trials of each contrast. In the first step, we fit STRF with frequency bins according to the stimulus spectrogram ( = 33 or 34, see *Stimuli*) and a history window of 300 ms ( = 12). When fitting the full model, we defined the contrast design matrix to capture 1000 ms of contrast history around each transition ( = 40), convolved with a set of B-spline temporal basis functions90 (here, we used B-splines with a degree of 3 and 7 knots such that = 8).

To validate the model, we first simulated neurons according to the forward model outlined above (Extended Data Figure 2a), while varying the amount of gain control and the temporal trajectory of gain in different simulation runs. We found that the GLM accurately predicted the STRF shape, spike rates and gain trajectories across a variety of simulation parameters (Extended Data Figure c, e-h). For a detailed description and discussion of the simulation results, see *Supplementary Information* and Supplementary Table 3.

*Behavioral and Neural Detection Performance.* To calculate performance in target-in-noise detection task we adopted commonly used signal detection theory methods41,91 to estimate the ability of an ideal observer to discriminate between two sensory distributions: in our case, a distribution for target trials and a distribution for noise trials. When analyzing behavior, we computed the percent correct performance of an ideal observer92 as a function of the probability of hits and false alarms:

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|  |  | (8) |

where is cumulative probability of the normal distribution ( in MATLAB), is the inverse of the normal distribution (ie. the z-score, in MATLAB), is the hit rate, and is the false alarm rate. For psychophysical performance, hit rates and false alarm rates near 0 and 1 were adjusted using the log-linear rule93, to reduce biases in performance estimation caused by low numbers of trials.

To calculate neural performance in the same reference frame as the behavior, we employed similar ideal observer techniques. First, neuronal responses (either spike rates or single units, or population projection values), were averaged in a 100ms window post target onset (for noise trials, this window was randomly chosen on each trial to coincide with target presentation times on target trials). Then, using the distributions of responses during target and noise trials, we computed receiver-operating-characteristic curves and took the area under the curve (AUC) as the percent correct of an ideal observer discriminating between the target and noise distributions. To determine whether the AUC value for a given set of trial distributions was significantly different from chance, we performed a bootstrap procedure where we sampled from all the trials with replacement 500 times and recomputed AUC for each sample. If the 95% confidence intervals for this bootstrapped distribution did not include chance (.5), we defined that AUC value as significant. For population analyses which generated single-trial predictions, neural hit and false alarm rates were transformed to percent correct as described above.

To characterize performance, psychometric curves were fit with a logistic function:

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|  |  | (9) |

where is the x-offset of the function, determined the slope, or sensitivity of the function, determined the guess rate (lower bound), determined the lapse rate (upper bound) and was stimulus volume. determined the threshold of this function, defined as the volume corresponding to the steepest part of the curve. This function was fit to behavioral or neural performance using constrained gradient descent ( in MATLAB) initialized with a 10x10 grid-search of parameters and .

To characterize adaptation time constants, adaptation curves were fit with an exponential function

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|  |  | (10) |

where determined the y-offset of the function, was a multiplicative scaling factor, and was the time constant of the exponential in units of time . This function was fit to behavioral or neural responses using constrained gradient descent initialized with a 10x10x10 grid search across all three parameters.

*Population response metrics.*

On sessions where three or more neurons were simultaneously recorded, we used a coding direction technique28 to estimate the ability of neural populations to discriminate targets from noise. First, target and noise spike rates for each neuron were averaged in a 100ms window post-target onset. Then, using a leave-one-out procedure, we computed a trial averaged population vector for target trials, , and a separate average population vector for noise trials, . We then estimated the coding direction in high dimensional neural space that best separated the target and noise responses: The held out trial was then projected along this dimension, by taking the population response vector on that trial and projecting it along the estimated coding direction using the dot product: . This procedure was repeated holding out each trial, and estimating the coding direction from the remaining trials. For psychometric testing sessions, the target responses from the two loudest target volumes were used to estimate coding direction, and in offset testing sessions the target responses from the high SNR target trials were used. After computing projections for every trial, the resulting matrix was normalized between 0 and 1.

*Population classifier*.

Based on previously described methods29, we used a criterion-based decision rule to estimate how a hypothetical down-stream neuron may read out the neural activity of a population of neurons. As before, trial distributions of neural responses to targets and noise were created from the average activity in a 100ms window post-target. Then, we sampled 100 criterion values between the minimum and maximum response, and for each criterion estimated the proportion of correct trials under two decision rules: 1) report target present if the response is greater than the criterion, or, 2) report target present if the response is less than the criterion. By assessing these two decision rules, responses that may be suppressed by target presence were treated equally to those in which target presence enhanced the neural response. Finally, we chose the criterion and decision rule that yielded the highest proportion of correct trials, and computed neural hit rates and false alarm rates for each target level, and noise-only trials. These hit rates and false alarm rates were then transformed to percent correct according the formula above, to ensure equivalency with the behavioral metrics.

*Linear-nonlinear model*.

First, we selected only neurons in the dataset which had reliable responses to stimulus repeats. To determine response reliability, we computed a noise ratio (NR) for each neuron, which describes the amount of variability in the response due to noise versus the amount of variability in the response driven by the stimulus94,95. Values approaching 0 indicate increasingly reliable responses to the stimulus, so for remaining analyses, we included neurons with NR < 100.

The linear nonlinear model was then composed of two main parts, a spectrotemporal receptive field (STRF) and a set of rectifying nonlinearities. The STRF was fit using normalized reverse correlation

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|  |  | (11) |

where is the stimulus design matrix defined in equation 1 and is the spike count in each 25 ms bin of the DRC stimulus. When defining , we used a history window of 300 ms ( = 12) and frequency bins corresponding to the frequencies composing the dynamic random chords (see *Stimuli*). After fitting the STRF, we fit the nonlinearities of the neuron. This two-step fitting procedure was repeated using 10 fold cross-validation, as described below.

For each fold, we selected 90% of the trials for training, leaving the remaining 10% to be held out for testing. Within each trial, we excluded neuronal responses around transitions from silence, or transitions in contrast, to prevent the model from overfitting strong transients in the neural response. Additionally, we excluded neural responses within a 50ms window after target presentations, to prevent overfitting to target responses. Given these exclusion criteria, we calculated the duration of stimulus sampled in the shorter target period for each trial, and, for that trial, sampled the same duration of stimulus within the adaptation period. This procedure ensured that the model was fit to the same amount of high and low contrast stimulation, to minimize overfitting to one condition. Then, a stimulus design matrix was made using these stimulus periods, and the STRF was fit using equation 11. During an initial pilot experiment, we tested whether STRF properties were affected by stimulus contrast, and found STRFs to be largely stable when estimated separately for each contrast (*Supplementary Information* and Extended Data Figure 5b-g). Therefore, we used both periods of contrast to estimate .

Using the STRF fit to the training data, we computed the linear drive by convolving the STRF with the lagged spectrogram of the training stimulus (equation 1). We then separated the linear predictions into low and high contrast periods. For each contrast period, we generated a histogram of the linear prediction values (50 bins), and for each bin, computed the mean spike rate of the neuron when the linear prediction fell within those bin edges (Figure 6d, scatter points). The resulting set of linear prediction values and average spike rates were fit with an exponential function:

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|  |  | (12) |

where determined the minimum firing rate, was a multiplicative scaling factor, determined the gain of the exponent, and determined the x-offset, or firing threshold of the neuron. This function was fit to each cell using constrained gradient descent ( in MATLAB), using a 10x10 grid search for parameters and . These fits were determined for each contrast, and the gain for each contrast for each neuron was estimated using . This entire process was repeated for each cross-validation fold, and the final parameter estimates for the STRF and nonlinearities were taken as the average over the 10 runs.

To determine the relationship between neuronal gain and behavioral performance, we examined our dataset of neurons collected during the psychometric task. First, we selected all of the neurons with significant AUC values to at least two of the six targets to ensure that we were sampling from neurons with information about target volume. Then, across all of these neurons for each mouse, we computed the average neural gain for each contrast. We then compared neural gain for each mouse to corresponding average psychometric thresholds and slopes to assess the relationship between neural gain and behavioral performance.

*Inclusion criteria*. Unless otherwise noted, behavioral sessions in which the false alarm rate exceeded 50% were discarded from analysis. One mouse (ID: CA122) had consistently high false alarm rates in the high contrast condition, so we excluded high contrast sessions from this mouse from all analyses. For Figure 5g-i, sessions with stable population decoding performance were included (defined as sessions where more than half of the target volumes or times elicited significant population AUC values, as determined by the bootstrap procedure described previously). For Figure 6e-h, only neurons with noise ratios less than 100 were included in all analyses.

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**Supplementary Information**

**Experimental Procedures**

*Acute Electrophysiological Recordings with Muscimol or Saline.*

Neural signals were recorded from n = 2 awake, untrained mice. Prior to the recording session, each mouse was anesthetized and a headpost and ground pin were implanted on the skull (see *Surgery* in the main text). On the day of the recording, the mouse was briefly anesthetized with 3% isoflurane and a small craniotomy was performed over auditory cortex using a dental drill or scalpel (~1mm x 1mm craniotomy centered approximately 1.25mm anterior to the lambdoid suture along caudal end of the squamosal suture). A 32 channel silicon probe (Neuronexus) was then positioned perpendicularly to the cortical surface and lowered at a rate of 1-2μm/s to a final depth of 800-1200μm. As the probe was lowered, trains of brief noise bursts were repeated, and if stimulus locked responses to the noise bursts were observed, the probe was determined to be in auditory cortex. The probe was then allowed to settle for up to 30 minutes before starting the recording.

For the muscimol and saline recordings (Extended DataFigure 3), a durotomy was performed over the injection site and baseline neural responses to the behavioral stimuli were recorded. Then, 2.5μL of .25mg/mL muscimol or 0.9% sterile saline solution was topically applied to the surface of auditory cortex and allowed 30 minutes to penetrate the tissue. The same stimuli were then recorded again after the elapsed time. In these recordings, the same targets and DRC background presented during behavior were presented. Neural signals from n = 2 mice (1 mouse for muscimol application, 1 mouse for saline application) were amplified and digitized using a Cheetah Digital LYNX system (Neuralynx) at a rate of 32kHz.

*Acute Electrophysiological Recordings for Sup. Fig 5b-g*

Neural signals were recorded from n = 9 awake, untrained mice of several-cre strains (somatostatin-cre, n = 5; parvalbumin-cre, n = 2; VGAT-cre, n = 2). These mice were similarly implanted with a headplate and groundpin, as described in *Surgery*. Additionally, each mouse was bilaterally injected with 700 uL of Flex-ChR2 during the initial surgery in auditory cortex, then bilaterally implanted with opto-cannulae which projected 500 um below the brain surface above auditory cortex. During the recordings, mice were presented with dynamic random chord stimuli (DRC) which changed contrast every 3 s. At each time step, the chords were randomly drawn from a uniform distribution with a center of 50 dB SPL and a spread of either 7.5 dB SPL or 15 dB SPL in low and high contrast respectively. Each chord was presented for 4 ms with a 1 ms linear ramp between each chord. Chords were composed of 25 frequencies between 1 and 64 kHz, spaced 0.25 octaves apart. On a subset of trials, 470 nm LED or laser light was continuously shone or pulsed at 25 Hz through the opto-cannulae for the duration of the 3 s of contrast period (power measured at the fiber tip ~2-5 mW). For the purposes of this study, we discarded all trials with light presentation.

**Muscimol application disrupts cortical encoding of targets**

In n = 2 awake, naïve mice, we first recorded baseline responses to the stimuli used in the psychometric task, then topically applied muscimol or saline, waited 30 minutes, and recorded stimulus responses again. After muscimol application, there was a marked decrease in neural responses to targets compared to the baseline recordings (Extended DataFigure 1b, left). Notably, in our saline control, we observed little to no change in neural responses after saline application (Extended DataFigure 4b, right). We next compared how contrast, volume and muscimol or saline application changed the responses during the pre- and post-application periods, finding that muscimol drastically reduced the firing rates between pre- and post-application periods, while saline moderately increased firing rates (Extended DataFigure 4c,d, Table 1). We speculate that the small increase in firing rate between pre- and post-saline application is due to changes in recording quality or due to neural drift over the ~1 hour recording session, and note that the effect size of saline pre-post application is very small (*η2* = 0.0046) when compared to the effect size of muscimol (*η2* = 0.38). We then used a 3-way ANOVA to compare the effects of muscimol, contrast, and target volume on target responses in the saline and muscimol recording sessions. We found a significant main effect of muscimol (*F*(1) = 322.65, *p* = 4.88e-67) and volume (*F*(6) = 15.48, *p* = 1.98e-17), but no main effect of contrast (*F*(1) = 0.39, *p* = 0.53), indicating nearly complete suppression of responses to both targets and noise in high and low contrast (Extended DataFigure 4e,f). These results confirmed that muscimol effectively disrupts the cortical coding of our behavioral stimuli.

**Muscimol application does not prevent licking**

An additional alternative effect of muscimol is a general loss of the ability to lick. To assess this, we monitored the lick probability of the mice throughout the trial duration, and found that muscimol specifically reduced licking responses during the period where targets were presented (Wilcoxon rank-sum test: *T* = 337, *z* = -4.23, *p* = 2.34e-5; Extended DataFigure 4g, right panel of Extended DataFigure 4h). Mice also tended to lick immediately after the trial onset (Extended DataFigure 4i, green trace), but we found that the lick rates under muscimol and saline conditions were identical during this period (Wilcoxon rank-sum test: *T* = 528, *z* = 0.23, *p* = 0.81; Extended DataFigure 4h, left panel). These results suggest that muscimol does not impair the mouse’s ability to lick in general, but results in a specific deficit in licking in response to targets.

**STRF stability across contrasts**

Based on a pilot study of neuronal data acutely recorded from auditory cortex, we tested whether STRF properties were affected by stimulus contrast. We recorded spiking activity in response to DRCs that changed contrast every 3 seconds. Out of the 700 units identified from n = 9 mice, we selected the subset of neurons with noise ratios below 100 for further analysis (n = 129). For each neuron, we computed the STRF using a spike triggered average in each contrast (Extended DataFigure 5b), then computed 100 “random” STRFs by shuffling the stimulus in time within each contrast. For each shuffle, we computed the correlation of the true low contrast STRF with the shuffled high contrast STRFs to generate a null distribution of low-high contrast STRF correlations. We then compared the true correlations of the low and high contrast STRF with this null distribution, defining them as significantly correlated if the true correlation fell outside the 99th percentile of the null distribution. We found that nearly all of the low and high contrast STRFs were significantly correlated (124/129 neurons, 96%), suggesting that contrast doesn’t change the overall structure of the STRF (Extended DataFigure 5d).

To further quantify these results, we tested whether more concrete STRF properties such as best frequency (BF), lag, and max value were affected by contrast. First, we de-noised each STRF by determining the significance of each pixel. To do this, we compared the value of each pixel to the distribution of shuffled value for that pixel, and retained only pixels determined to be significant (three standard deviations of the shuffled value). Based on the de-noised STRFs, we computed average frequency and temporal components by averaging over each STRF dimension (Extended DataFigure 5c). We then estimated the BF and lag as the max of these components, and determined the max STRF value by finding the max value over all pixels. Next, we compared each measure across STRFs from low and high contrast. We found that the maximum pixel value was significantly greater in high contrast (Median (*Mdn*) = 1.33, inter-quartile range (*IQR*) = 1.28) than in low contrast (*Mdn* = 0.56, *IQR* = 0.62; Wilcoxon signed-rank test: *z* = -9.78, *rank* = 0, *p* = 1.39e-22; Extended DataFigure 5e, e). On the other hand, we found a non-significant trend towards lower BFs in low contrast (*Mdn* = 19.03 kHz, *IQR* = 35.74 kHz) compared to high contrast (*Mdn* = 22.63 kHz, *IQR* = 47.09 kHz; Wilcoxon signed-rank test: *z* = 1.78, *rank* = 1761, *p* = 0.076; Extended DataFigure 5f), and no significant change in lag (Wilcoxon signed-rank test: *z* = -0.93, *rank* = 1776, *p* = 0.35; Extended DataFigure 5g). Taken together, these results demonstrate that the frequency and temporal modulation of sound responses are consistent across contrasts, supporting previously published findings.

**Generalized linear model of contrast gain control dynamics**

A primary goal of the current study was to estimate the influence of stimulus contrast on neural gain dynamics, for instance, after a switch from one contrast to another. To approach this problem, we first define a model neuron with dynamic gain control.

*Forward model*

To best approximate the stimuli used in our experiments, we define the stimulus environment of our model as a one-dimensional signal that evolves in discrete time steps:

,

where is a stimulus spectrogram that varies as a function of time and frequency . Each time and frequency bin of is sampled from a normal distribution defined by an average value and contrast at time .

To approximate the behavior of real neurons, we define a model neuron that has a two-dimensional linear filter (representing the STRF of the neuron):

,

where stimulus filter is defined as a two-dimensional gaussian distribution as a function of history and frequency . The filter location in frequency-history space is defined by its mean and covariance matrix . The stimulus drive of the neuron at each time step, , is then computed as the convolution of the stimulus matrix and the linear filter:

|  |  |  |
| --- | --- | --- |
|  |  | (1) |

where at each time is a row vector of length (ie. a matrix of the stimulus spectrogram lagged by lags) and is a row vector of the filter of the same length.

The model neuron has a firing rate that depends only on the stimulus drive and the contrast at time . We then assume that the number of spikes emitted by the neuron at each time step follow a Poisson distribution:

where is the firing rate at time , given by

|  |  |  |
| --- | --- | --- |
|  |  | (2) |

where is a gain control function, and , , and are parameters of the model. The parameter represents the baseline response of the neuron, is a scaling factor of the stimulus drive, and represents the operating point of the gain. For ease of interpretation, we require to be adimensional, such that

|  |  |  |
| --- | --- | --- |
|  |  | (3) |

where and are the high and low contrast values. This constraint forces the neutral value of the gain, to be the midpoint between gain in the high and low contrast conditions.

*Optimal gain control*

In the spirit of the efficient coding principle, we derived a form for that will guarantee that, under certain conditions, the dynamic range of the neuron will be approximately conserved under changes in contrast. To do this, we define the dynamic range as

|  |  |  |
| --- | --- | --- |
|  |  | (4) |

which can be rewritten using equation 2 as

|  |  |  |
| --- | --- | --- |
|  | . | (5) |

If the argument of the exponentials is not too large, we can linearize this expression to obtain

|  |  |  |
| --- | --- | --- |
|  |  | (6) |

and that is approximately independent of provided that . So, for our model, we set

|  |  |  |
| --- | --- | --- |
|  |  | (7) |

where is the harmonic mean of and :

|  |  |  |
| --- | --- | --- |
|  |  | (8) |

Finally, to validate that our fitting methods are sensitive to real world neurons, which do not necessarily adjust their gain to perfectly account for changes in contrast, we consider an interpolation scheme that smoothly transforms a model with positive gain control to a similar model without gain control, or with “anti” gain control. To do this, we redefine as follows:

|  |  |  |
| --- | --- | --- |
|  |  | (9) |

so that by changing we can control whether gain control is optimal (), non-existant (), or “anti” ().

Putting everything together, the final expression for the firing rate of the forward model is

|  |  |  |
| --- | --- | --- |
|  |  | (9) |

*Generalized linear model*

The forward model developed in the previous section provides a simple approximation of the relationship between the stimulus, stimulus contrast and neuronal responses. We also note that the form of the forward model lends itself to estimation using a Poisson GLM, provided that the predictors are chosen appropriately. As such, we define the inference model as a Poisson GLM with an intercept term and the following predictors:

In other words, the model is composed of a stimulus predictor (), a contrast predictor (), and their interaction. Therefore, the GLM models the data at time as a Poisson distribution with the following mean:

|  |  |  |
| --- | --- | --- |
|  |  | (11) |

where are the parameters to be inferred, and, as defined previously, is the stimulus drive of the neuron determined by its STRF.

*Model fitting*

To fit the model, we took a two-step approach. First we found the best-fit filter (STRF) for the neuron. Then, we fit the full GLM to determine how the linear drive determined by the STRF is modulated by contrast. In the first step, the linear drive is obtained by fitting the model

|  |  |  |
| --- | --- | --- |
|  |  | (12) |

where is a design matrix defined as a function of frequency bins and history lags , and is the fitted STRF. Stimulus drive is then computed as in equation 1**.**

We then define the full model according toequation 9,

|  |  |  |
| --- | --- | --- |
|  |  | (13) |

where and is a set of cubic B-spline temporal basis functions. By defining a matrix as follows

|  |  |  |
| --- | --- | --- |
|  |  | (14) |

we can rewrite equation 13 in a more compact form:

|  |  |  |
| --- | --- | --- |
|  |  | (15) |

where denotes element-by-element “broadcasting” multiplication.

To fit asymmetric changes in firing rate after transitions to low or high contrast, we took the simple approach of defining separate sets of contrast predictors for each transition type. This amounted to modifying by masking transitions to high contrast or transitions to low contrast with zeros, such that the model fit a window of 40 time bins around each contrast transition. To do so, we created a new matrix by duplicating column-wise. Then, we define the first columns as predictors for the transition to low contrast by masking a 1 second period around each transition to high contrast with zeros. This same procedure was repeated for the remaining columns in , instead masking out the transition to low contrast. Substituting this into equation 15, we obtain

|  |  |  |
| --- | --- | --- |
|  |  | (16) |

For the sake of clarity, note that in the expression above, is a number, is a column vector of length , is a number, is a -by- matrix, and and are column vectors of length .

*Defining gain*

We have outlined a forward model for simulating neural activity according to efficient coding of stimulus contrast, and described an inference model (a Poisson GLM) for estimating the influence of the stimulus, stimulus contrast, and their interaction. In this section, we describe how to use the fitted parameters to quantify the amount of gain control in the neuron.

Conceptually, an increase or decrease in the gain of a system is analogous to more or less sensitivity to small changes in the stimulus, dependent what is modulating the gain (in our case, the recent history of the contrast). Based on this intuition, we focus on how the response of the neuron (as modelled by a fitted GLM) is expected to change between conditions where the gain is expected to contribute (ie. in the presence of gain control) and where it is not (ie. in the absence of gain control, where gain is “neutral”).

To do this, we start by considering the gradient of the link function (the log rate) at time with respect to :

|  |  |  |
| --- | --- | --- |
|  |  | (17) |

We can immediately read equation 17 as “the STRF of the model is modulated by a factor of at time ”, and define the gain based on this intuition, but we’ll take a slightly longer and more formal route to get at the same result.

The gradient is a vector with the same dimensionality of and , and it encapsulates all information about the sensitivity of the link function to small changes in as a given time. Because is not a scalar (it has components), these changes can happen along many dimensions, and the sensitivity can be different in different directions. We can define the gain based on the sensitivity to changes in a specific direction (assume for concreteness that , although this is not necessary for the derivation below). If , where is some scalar, then

|  |  |  |
| --- | --- | --- |
|  |  | (18) |

by definition of the gradient. We can then define the gain along direction as the ratio between the sensitivity of the log rate to changes along and the sensitivity one would have if the contrast was at some reference value where we define by construction. If we do so, we obtain

|  |  |  |
| --- | --- | --- |
|  |  | (19) |

Note that this definition does not depend on the initial choice of , or even on the specifics of the choice of basis functions used to define . In conclusion, by reasoning about the sensitivity of the response of the fitted GLM, we define a value which captures the relationship between the true gain and the stimulus contrast .

*Simulations*

To validate our inference model, we simulated neural activity according to the generative model defined in the *Forward Model* section (Extended DataFigure 2a). We were interested in capturing several dimensions upon which the generative model could vary, namely, the amount of gain control in the simulated neurons , and the dynamics of the gain function .

To parametrically control the evolution of gain over time, we simulated different temporal trajectories of gain control, by modifying as follows

|  |  |  |
| --- | --- | --- |
|  |  | (20) |

where the gain ­­ after a switch to contrast transitions from the gain in the previous contrast to the gain in the current contrast according to an exponential function with time constant . Note that could vary between the two contrasts to simulate asymmetric dynamics.

For each neuron, we first generated a STRF and linear drive according to equation 1(Extended DataFigure 2b,d). For different sets of simulated neurons, we parametrically varied the amount of gain control between -1 and 1, and varied the gain time courses to simulate three types of gain adaptation dynamics: 1) Slow transitions to low contrast with fast transitions to high contrast, 2) Fast, symmetric transitions to each contrast, 3) Fast transitions to low contrast and slow transitions to high contrast (Extended DataFigure 2f).

We simulated 100 neurons for each combination of and , with other simulation parameters held constant (SupplementaryTable 3). Extended DataFigure 2e plots the average firing rates and overlaid model fits for three sets of simulations with optimal gain control () while varying . Importantly, the model flexibly captured the gain dynamics in the three simulated adaptation time course conditions, with the gain estimate following the true gain trajectory (Extended DataFigure 2f). For additional values of , the model accurately predicted the firing rates (Extended DataFigure 2g) and gain trajectories (Extended DataFigure 2h). We observed that some combinations of and elicited large firing rate transients, particularly in the cases where simulated gain slowly adapted after a switch to high contrast (bottom panels in Extended DataFigure 2e, f, g, h). This behavior is expected, as gain remains relatively high for a longer period after the switch, causing large fluctuations in firing rate as the stimulus drive during high contrast is increased. These large firing rate transients seemed to reduce the accuracy of gain estimate , but we observed that the predicted time courses still captured the overall asymmetries present in the underlying model.

During our behavioral recordings, we used a limited number of background noise scenes (n = 5) to reduce the overall size of the stimulus set. However, it became clear that our model required a larger sample of stimulus space to accurately estimate gain. To demonstrate this, we plotted the simulation results when neurons were exposed to 100 unique noise scenes (Extended DataFigure 2i) compared to simulations where neurons were only exposed to 5 unique noise scenes, as in our behavioral recordings (Extended DataFigure 2j). We observed that with 100 scenes, estimates of were very close to the true gain values, but were consistently underestimated in the case of 5 noise scenes, even in the case of perfect gain control. As such, when analyzing our behavioral recordings, we used a standard linear-nonlinear model to estimate neural gain (Figure 5), as we previously found that gain estimates from the GLM were highly correlated with gain estimated from the LN model (Figure 2i).

**Supplementary Table 1:** Statistical Comparisons.

|  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- |
| **Comparison** | **Figure** | **Center** | **Spread** | **N** | **Test** | **Statistic** | **Effect Size** | **p-value** |
| Behavior percent correct, low contrast: time 1 vs. time 2 | 2g | T1: 0.68  T2: 0.70  (median) | T1: 0.10  T2: 0.15  (IQR) | 21 mice | Two-tailed Wilcoxon sign-rank test (FDR corrected92 for multiple comparisons) | Z = -1.93  Rank: 60 | =  -0.42 | 0.054 |
| Behavior percent correct, low contrast: time 1 vs. time 3 | T1: 0.68  T3: 0.82  (median) | T1: 0.10  T3: 0.092  (IQR) | Z = -4.01  Rank: 0 | =  -0.88 | 5.96e-5 |
| Behavior percent correct, low contrast: time 1 vs. time 4 | T1: 0.68  T4: 0.87  (median) | T1: 0.10  T4: 0.190  (IQR) | Z = -4.01  Rank: 0 | =  -0.88 | 5.96e-5 |
| Behavior percent correct, low contrast: time 1 vs. time 5 | T1: 0.68  T5: 0.91  (median) | T1: 0.10  T5: 0.11  (IQR) | Z = -4.01  Rank: 0 | =  -0.88 | 5.96e-5 |
| Behavior percent correct, high contrast: time 1 vs. time 2 | T1: 0.82  T2: 0.77  (median) | T1: 0.083  T2: 0.19  (IQR) | Z = 2.84  Rank: 181 | =  0.62 | 0.005 |
| Behavior percent correct, high contrast: time 1 vs. time 3 | T1: 0.82  T3: 0.77  (median) | T1: 0.083  T3: 0.14  (IQR) | Z = 2.17  Rank: 163 | =  0.47 | 0.030 |
| Behavior percent correct, high contrast: time 1 vs. time 4 | T1: 0.82  T4: 0.78  (median) | T1: 0.083  T4: 0.16  (IQR) | Z = 3.36  Rank: 195 | =  0.73 | 7.80e-4 |
| Behavior percent correct, high contrast: time 1 vs. time 5 | T1: 0.82  T5: 0.79  (median) | T1: 0.083  T5: 0.12  (IQR) | Z = 1.94  Rank: 157 | =  0.42 | 0.052 |
| ANOVA for effects of pre-post muscimol application, contrast, and volume on firing rate in ACtx | S4c | n/a | n/a | 42 neurons | 3-way ANOVA | Fpre-post(1) = 812.54  Fcontrast(1) = 22.64  Fvolume(6) = 21.70 | η2 = 0.38  η2 = 0.011  η2 = 0.061 | 4.48e-136  2.19e06  2.77e-24 |
| ANOVA for effects of pre-post saline application, contrast, and volume on firing rate in ACtx | S4d | n/a | n/a | 104 neurons | 3-way ANOVA | Fpre-post(1) = 15.40  Fcontrast(1) = 0.43  Fvolume(6) = 76.067 | η2 = 0.0046  η2 = 1.29e-4  η2 = 0.14 | 8.89-5  0.51  1.76e-88 |
| Percent correct max dB SNR, low contrast: muscimol vs. saline | 3c | Musc.: 0.10  Saline: 0.85  (median) | Musc.: 0.67  Saline: 0.27  (IQR) | 10 musc.. sessions, 10 saline sessions (4 mice) | Two-tailed Wilcoxon rank-sum test | Z = -2.76  Rank: 68 | =  -0.62 | 0.0058 |
| Threshold (dB SNR), low contrast: muscimol vs. saline | Musc.: 14.78  Saline: 9.66  (median) | Musc.: 18.46  Saline: 6.88  (IQR) | Z = 0.72  Rank: 115 | =  0.16 | 0.47 |
| FA rate, low contrast: muscimol vs. saline | Musc.: 0.026  Saline: 0.132  (median) | Musc.: 0.10  Saline: 0.85  (IQR) | Z = -2.91  Rank: 66 | =  -0.65 | 0.0036 |
| Max slope (PC/dB), low contrast: muscimol vs. saline | Musc.: 0.026  Saline: 0.072  (median) | Musc.: 0.056  Saline: 0.030  (IQR) | Z: -2.68  Rank: 69 | =  -0.60 | 0.0073 |
| Percent correct max dB SNR, high contrast: muscimol vs. saline | Musc.: 0.06  Saline: 0.80  (median) | Musc.: 0.10  Saline: 0.85  (IQR) | 13 musc.. sessions, 10 saline sessions  (4 mice) | Z = -4.06  Rank: 92 | =  -0.83 | 4.96e-5 |
| Threshold (dB SNR), high contrast: muscimol vs. saline | Musc.: 16.77  Saline: 18.80  (median) | Musc.: 21.33  Saline: 5.89  (IQR) | Z = -0.35  Rank: 156 | =  -0.071 | 0.73 |
| FA rate, low contrast: muscimol vs. saline | Musc.: 0.027  Saline: 0.213  (median) | Musc.: 0.10  Saline: 0.85  (IQR) | Z = -3.19  Rank: 107 | =  -0.65 | 0.0014 |
| Max slope (PC/dB), high contrast: muscimol vs. saline | Musc.: 0.012  Saline: 0.058  (median) | Musc.: 0.024  Saline: 0.018  (IQR) | Z = -3.77  Rank: 97 | =  -0.77 | 1.66e-4 |
| Percent correct max dB SNR, target in high contrast : muscimol vs. saline | 3f | Musc.: 0.07  Saline: 0.82  (median) | Musc.: 0.51  Saline: 0.095  (IQR) | 5 musc. sessions, 5 saline sessions  (2 mice) | Two-tailed Wilcoxon rank-sum test | Z = nan  Rank: 15 | =  nan | 0.0079 |
| Percent correct at threshold, target in high contrast: muscimol vs. saline | Musc.: 0.03  Saline: 0.53  (median) | Musc.: 0.35  Saline: 0.11  (IQR) | Z = nan  Rank: 17 | =  nan | 0.032 |
| FA rate, target in high contrast : muscimol vs. saline | Musc.: 0.12  Saline: 0.23  (median) | Musc.: 0.22  Saline: 0.11  (IQR) | Z = nan  Rank: 21 | =  nan | 0.22 |
| Max slope (PC/dB), target in high contrast : muscimol vs. saline | Musc.: 0.038  Saline: 0.057  (median) | Musc.: 0.046  Saline: 0.012  (IQR) | Z = nan  Rank: 19 | =  nan | 0.095 |
| Percent correct max dB SNR, target in silence: muscimol vs. saline | Musc.: 0.85  Saline: 0.92  (median) | Musc.: 0.23  Saline: 0.15  (IQR) | 8 musc. sessions, 8 saline sessions  (2 mice) | Z = nan  Rank: 53 | =  nan | 0.13 |
| Percent correct at threshold, target in silence : muscimol vs. saline | Musc.: 0.11  Saline: 0.22  (median) | Musc.: 0.28  Saline: 0.22  (IQR) | Z = nan  Rank: 55 | =  nan | 0.20 |
| FA rate, target in silence : muscimol vs. saline | Musc.: 0.029  Saline: 0.041  (median) | Musc.: 0.038  Saline: 0.11  (IQR) | Z = nan  Rank: 60 | =  nan | 0.44 |
| Max slope (PC/dB), target in silence : muscimol vs. saline | Musc.: 0.028  Saline: 0.031  (median) | Musc.: 0.015  Saline: 0.0048  (IQR) | Z = nan  Rank: 63 | =  nan | 0.65 |
| Neural percent correct, low contrast: time 1 vs. time 2 | 5i | T1: 0.79  T2: 0.83  (median) | T1: 0.15  T2: 0.22  (IQR) | 43 sessions | Two-tailed Wilcoxon sign-rank test (FDR corrected92 for multiple comparisons)  Adjusted alpha level: 0.0088 | Z = -1.12  Rank: 418 | =  -0.17 | 0.26 |
| Neural percent correct, low contrast: time 1 vs. time 3 | T1: 0.79  T3: 0.85  (median) | T1: 0.15  T3: 0.15  (IQR) | Z = -3.61  Rank: 198 | =  -0.56 | 0.00031 |
| Neural percent correct, low contrast: time 1 vs. time 4 | T1: 0.79  T4: 0.92  (median) | T1: 0.15  T4: 0.20  (IQR) | Z = -4.68  Rank: 103 | =  -0.72 | 2.89e-6 |
| Neural percent correct, low contrast: time 1 vs. time 5 | T1: 0.79  T5: 0.91  (median) | T1: 0.15  T5: 0.16  (IQR) | Z = -5.34  Rank: 31 | =  -0.82 | 9.44e-8 |
| Neural percent correct, high contrast: time 1 vs. time 2 | T1: 0.78  T2: 0.74  (median) | T1: 0.15  T2: 0.12  (IQR) | Z = 2.62  Rank: 690 | =  0.40 | 0.0088 |
| Neural percent correct, high contrast: time 1 vs. time 3 | T1: 0.78  T3: 0.76  (median) | T1: 0.15  T3: 0.13  (IQR) | Z = 1.45  Rank: 593 | =  0.22 | 0.15 |
| Neural percent correct, high contrast: time 1 vs. time 4 | T1: 0.78  T4: 0.83  (median) | T1: 0.15  T4: 0.20  (IQR) | Z = -0.24  Rank: 453 | =  -0.037 | 0.81 |
| Neural percent correct, high contrast: time 1 vs. time 5 | T1: 0.78  T5: 0.83  (median) | T1: 0.15  T5: 0.16  (IQR) | Z = -2.00  Rank: 307 | =  -0.31 | 0.045 |
| Mixed-effects model:  threshold ~ gain\_target + contrast + (1|mouse)  Fixed effects: target gain, contrast  Random effects: mouse ID  Outcome variable: threshold | 6g | **Model Coefficients**  Estimate ± standard error  [tstat(df), p-value] | | 168 sessions | Likelihood ratio test against model without gain:  threshold ~ contrast + (1|mouse) | (1) = 4.74 |  | 0.029 |
| Intercept: 10.81±1.25  t(120) = 8.62, p = 3.27e-14  Target gain: -25.64±11.80  t(120) = -2.20, p = 0.030  Contrast: 3.01±1.23  t(120)= 2.45, p = 0.016 | |
| Likelihood ratio test against model without contrast:  threshold ~ gain\_target + (1|mouse) | (1) = 5.84 |  | 0.016 |
| Mixed-effects model:  slope ~ gain\_target + contrast + (1|mouse)  Fixed effects: target gain, contrast  Random effects: mouse ID  Outcome variable: slope | 6h | Intercept: 0.042±0.0063  t(120) = 6.74, p = 5.72e-10  Target gain: 0.13±0.059  t(120) = 2.28, p = 0.024  Contrast: 0.0077±0.059  t(120)= 1.26, p = 0.21 | | 168 sessions | Likelihood ratio test against model without gain:  slope ~ contrast + (1|mouse) | (1) = 5.094 |  | 0.024 |
| Likelihood ratio test against model without contrast:  slope ~ gain\_target + (1|mouse) | (1) = 1.57 |  | 0.21 |
| Mixed-effects model:  thresh ~ gain\_adapt + contrast + (1|mouse)  Fixed effects: adaptation gain, contrast  Random effects: mouse ID  Outcome variable: threshold | S5m | Intercept: 6.53±1.51  t(120) = 4.34, p = 3.01e-5  Adaptation gain: 36.44±32.59  t(120) = 1.12, p = 0.27  Contrast: 3.11±1.66  t(120)= 1.88, p = 0.063 | | 168 sessions | Likelihood ratio test against model without gain:  thresh ~ contrast + (1|mouse) | (1) = 1.24 |  | 0.26 |
| Likelihood ratio test against model without contrast:  thresh ~ gain\_adapt + (1|mouse) | (1) = 3.47 |  | 0.062 |
| Mixed-effects model:  slope ~ gain\_adapt + contrast + (1|mouse)  Fixed effects: adaptation gain, contrast  Random effects: mouse ID  Outcome variable: threshold | S5n | Intercept: 0.063±0.0076  t(120) = 8.35, p = 1.40e-13  Adaptation gain: -0.16±0.16  t(120) = -0.96, p = 0.34  Contrast: 0.0058±0.0084  t(120)= 0.70, p = 0.49 | |  | Likelihood ratio test against model without gain:  slope ~ contrast + (1|mouse) | (1) = 0.91 |  | 0.34 |
| Likelihood ratio test against model without contrast:  slope ~ gain\_adapt + (1|mouse) | (1) = 0.49 |  | 0.49 |

**Supplementary Table 2:** Target SNRs used during psychometric testing.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Target Volumes** | **[n]: Mouse IDs** | **n Sessions (total)** | **n High-Low Contrast Sessions** | **n Low-High Contrast Sessions** |
| 0, 5, 10, 15, 20, 25 dB SNR | [12]: CA102, CA104, CA106, CA107, CA118, CA119, CA121, CA122, CA123, CA124, CA125, CA126 | 214 | 111 | 103 |
| -5, 0, 5, 10, 15, 20 dB SNR | [8]: CA102, CA104, CA106, CA107, CA118, CA119, CA121, CA122 | 31 | 31 | 0 |
| 0, 4, 8, 12, 16, 20 dB SNR | [1]: CA046 | 1 | 0 | 1 |
| 5, 8, 11, 14, 17, 20 dB SNR | [4]: CA118, CA119, CA121, CA122 | 68 | 52 | 16 |
| 8, 10.4, 12.8, 15.2, 17.6, 20 dB SNR | [15]: CA046, CA047, CA048, CA049, CA051, CA052, CA055, CA061, CA070, CA072, CA073, CA074, CA075, CA104, CA107 | 111 | 0 | 111 |
| -4, 0, 4, 8, 12, 16 dB SNR | [11]: CA051, CA052, CA055, CA061, CA070, CA072, CA073, CA074, CA075, CA102, CA106 | 91 | 91 | 0 |
| -5, -1, 3, 7, 11, 15 dB SNR | [5]: CA046, CA047, CA048, CA049, CA051 | 19 | 19 | 0 |
| -75, -60, -45, -30, -15, 0  dB attenuation rel. 25dB SNR | [2]: CA124, CA125 | 20 | n/a | n/a |

**Supplementary Table 3:** GLM Simulation Parameters

|  |  |
| --- | --- |
| **Parameter** | **Value** |
|  |  |
|  |  |
| centroid (frequency bin , history bin ) |  |
| covariance matrix |  |
| dimensions () |  |
| Baseline rate |  |
| Stimulus scaling |  |
| Gain operating point |  |
| Gain control |  |
| Adaptation time constants |  |
| Simulated noise scenes |  |
| Contrast history |  |
| B-spline degree, knots |  |

Diagram, engineering drawing

Description automatically generated**Extended Data Figure 1 (related to Figure 1). Normative model responses, predictions, and example response distributions.**

**a,** The firing rate of the simulated neuron as a function of time. Traces shaded in blue or red indicate the firing rate to periods of low or high contrast background noise, respectively. The green trace indicates the model response to overlaid targets. **b,** The true contrast (labelled as variance) of the stimulus (blue, red, and dashed grey lines) along with the average model estimate of the contrast (solid black line) over time. **c,** Discriminability as a function of time and contrast. Each trace indicates target from noise discriminability over time, with the trace color indicating the contrast after the switch. The dashed vertical line indicates the time of the contrast switch. Open circles indicate time samples used to plot the distributions in **d**. **d,** Target (green) and noise (blue or red) distributions as a function of time and contrast. The top row includes responses to targets and noise in low contrast. Each column denotes a different time step relative to the change in contrast, as indicated by the column title. The bottom row is the same, but for high contrast. Arrows between **c** and **d** indicate distributions which yielded the indicated value of discriminability in the trace.

**Diagram, schematic

Description automatically generatedExtended Data Figure 2 (related to Figure 2). Simulation results to validate the GC-GLM.**

**a,** Schematic of simulated neurons in the forward model. Each neuron received broadband noise inputs which changed contrast every 2s. A STRF modelled by a 2D-gaussian function with added noise filtered the stimulus to generate a linear response. This filter response was then modulated by a gain control function, which controlled the amount and time-course of gain control for the simulated neuron. This gain modulated output was then exponentiated and stochastic spikes were generated according to a Poisson process. **b,** Example STRF from one simulated neuron. Colorbar indicates STRF magnitude. **c,** Model estimate of the STRF averaged across 100 simulated neurons. **d,** Example linear drive for one simulated neuron over 500 trials (ie. the filter response of the STRF convolved with the stimulus). **e,** Each panel plots the average firing rates of 100 simulated neurons (solid teal lines) and corresponding GC-GLM fits (dashed black lines) when simulating perfect gain control (GC = 1.0). Each row corresponds to 100 simulations of different gain time courses, with the top row depicting a slow transition to low contrast, with a fast transition to high contrast. The middle row plots simulations were both transitions were fast. The bottom row plots simulations where the transition to low contrast was fast, with a slow transition to high contrast. The corresponding rows of panels **f**, **g**, and **h**, are the results of simulations with the same gain time courses. **f,** Average gain time-course of the simulated neurons (solid teal lines) and the corresponding GC-GLM estimate of the gain, , averaged over 100 simulations (black dashed lines). Insets of each panel depict the contrast kernels (dashed lines) and gain kernels (solid lines) estimated for each contrast. Blue lines indicate kernels after a switch to low contrast and red lines indicate kernels after a switch to high contrast. **g,** Average log firing rate for simulations with different gain time-courses and different degrees of gain control (GC value; the legend in the lower left indicates the color-GC value mapping). Each plotted line indicates the average firing rate/prediction for 100 simulations. **h,** Average gain time-course of all simulations (solid colored lines) and the average estimates of (dashed grey lines). **i,** Simulations with 100 unique stimulus scenes, repeated 5 times each. Left panel plots the average firing rates and model fits. Right panel plots the true gain time-course (solid lines) and the average model gain estimate, (dashed lines). The shaded areas indicate 2.5 and 97.5 percentiles of the gain estimates. **j,** Simulations with 5 unique stimulus scenes, repeated 100 times each. Formatting as in **i**. For panels **e-j**, the GC value colors and line formatting are indicated in the legend on the bottom right.

Chart, scatter chart

Description automatically generated

**Extended Data Figure 3 (related to Figure 3). Behavioral slopes are affected by the target volume range.**

**a,** The effect of contrast on the false alarm rates in psychometric sessions (n = 25 mice). Each dot and line represent a mouse, the blue and red bars indicate the mean false alarm rate for low and high contrast ±SEM. Results of a paired t-test (*t*(23) = -6.02, *p* = 3.90e-6) across contrast revealed a significantly higher false alarm rate in high contrast (Mean(*M*) = 0.22, standard deviation(*std*) = 0.080) compared to low contrast (*M* = 0.13, *std =* 0.054). **b,** Comparison of psychometric slopes across all mice (n = 25). Formatting as in **a**. Results of a paired t-test (*t*(23) = -1.55, *p* = 0.135) across contrast revealed no significant difference between the slopes. **c,** Average psychometric curves and percent correct for mice presented with a narrow range of targets (range = 15 dB SNR; Table 2, row 4; dashed lines and open dots), and those presented with a wide range of targets (range = 25 dB SNR; Table 2, row 1; solid lines and filled dots) in low contrast. Errorbars indicate ±SEM. **d,** Psychometric slope for each mouse when low contrast targets came from narrow or wide target distributions. Different shaded bars indicate the mean for each condition ±SEM. Results of an unpaired t-test (*t*(9) = 2.33, *p =* 0.044) indicated significantly larger slopes in response to narrow target distributions (*M =* 0.061, *std*  = 0.0060) compared to wide target distributions (*M* = 0.051, *std* = 0.0073). **e**, Average psychometric curves and percent correct for mice presented with a narrow range of targets (average of range = 12 or 15 dB SNR; Table 2, rows 5 or 4; dashed lines and open dots) or wide range of targets (range = 25 dB SNR; Table 2, row 1; solid lines and filled dots) in high contrast. **f,** Psychometric slope for each mouse when high contrast targets came from narrow or wide distributions. Formatting as in **d**. Results of an unpaired t-test (*t*(28) = 5.49, *p* = 7.29e-6) indicated a significantly larger slopes in response to narrow target distributions (*M* = 0.11, *std* = 0.033) compared to wide target distributions (*M* = 0.049, *std* = 0.017) in high contrast. In all plots: ns*p*>0.1; †*p*<0.1, \**p*<0.05, \*\**p*<0.01, \*\*\**p*<0.001, \*\*\*\**p*<0.0001.

Diagram

Description automatically generated

**Extended Data Figure 4 (related to Figure 4). Confirmation of cortical inactivation with muscimol.**

**a,** Setup schematic for acute muscimol recordings in ACtx. **b,** Example spike rasters from two different neurons pre- and post-muscimol or saline application. On top of the raster is the timeline for each recording. A baseline recording of all stimuli was performed prior to muscimol application, then all stimuli were recorded again 30 minutes after application. Rasters are sorted by contrast and target volume, with color indicating low or high contrast backgrounds, color shade indicating target volume, and grey indicating noise only trials (-Inf). *Left panel:* raster of target and noise responses of a representative neuron recorded prior to muscimol application, followed by the raster for the same neuron 30 minutes after muscimol application. *Insets:* Mean firing rate for each condition. Shade indicates target volume and the scale bar indicates the firing rate. Error bars are ±SEM across trials. *Right panel:* Example neuron before and after application of saline. Formatting as in left panels. **c,** Firing rates before and after muscimol application as a function of target volume and contrast. Dark dashed lines indicate spike rates recorded pre-muscimol application and light dashed lines indicate the responses post-application. **d,** Firing rates before and after saline application. As in **c**, dark lines are responses recorded prior to saline application and light lines indicate responses recorded after saline application. In **c** and **d**, blue and red plots indicate responses during low contrast and high contrast, respectively, and the circles not connected by a line and labelled “-Inf” are responses to noise alone. **e,** Area under the ROC curve (AUC) averaged across neurons after drug application in muscimol and saline recording sessions in low contrast. Filled circles and solid lines are responses after saline was applied while open circles and dashed lines are responses after muscimol was applied. Error bars indicate ±SEM across neurons. **f,** Same as **e**, but for high contrast. **g,** Lick probability over time during muscimol or saline sessions. Dashed vertical lines indicate trial onset (0 s) and the contrast switch (3 s). Green traces are muscimol sessions and black traces are saline sessions. The shading around each trace indicates ±SEM across sessions. **h,** *Left:* comparison of lick probability during the adaptation period. *Right:* comparison of lick probability during the target period. Each circle indicates a session and color is as in **g**. **i,** Cumulative probability of licking throughout the trial, normalized within muscimol or saline conditions to sum to 1. Colors as in **g**, **h**. Shading indicates ±SEM across sessions. In all plots: ns*p*>0.1; †*p*<0.1, \**p*<0.05, \*\**p*<0.01, \*\*\**p*<0.001, \*\*\*\**p*<0.0001.

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**Extended Data Figure 5 (related to Figures 5 and 6). STRFs are unaffected by contrast, and the relationship between gain during adaptation periods in the trial and behavior.**

**a,** Neural against behavioral psychometric slopes for n = 6 mice presented with the same target volumes in high and low contrast. Formatting as in Figure 5g. **b,** Example STRFs from one neuron estimated from each contrast period. *Left*: Low contrast STRF. The main plot depicts the thresholded STRF values as a function of time and frequency. Inset is the original STRF, which has the same axis. Above the main plot is the temporal average across columns of the STRF, and to the right is the frequency average across rows. *Right*: High contrast STRF. Colorbar indicates the color-mapping for both of the thresholded STRF plots. In both panels, blue traces indicate values estimated in low contrast, and red traces indicate values estimated in high contrast. **c,** Average centered frequency (*top*) and temporal (*bottom*) STRF components for low and high contrast (red and blue traces, respectively). Light shade indicates ±SEM across neurons. **d,** Histogram of correlations between low and high contrast STRFs for neurons with noise ratios (NR) below 100 (n = 129 neurons). Shaded bars indicate correlations that were not significantly different from chance, fwhile unshaded bars indicate significant correlations, as determined by a permutation test. *Inset*: Proportions of the correlations in the population found not-significant (grey) and significant (white). **e,** Maximum STRF value across all pixels for low and high contrast, plotted for each neuron. Solid line indicates unity. The size of each circle indicates the NR of each neuron, with larger dots for smaller NR (see legend). P-value indicates the results of a Wilcoxon sign-rank test. **f,** Best frequency for each neuron in low and high contrast. Formatting as in **e**. **g,** Lag of the maximum STRF response for each neuron in low and high contrast. Formatting as in **e** and **f**. **h,** Correlation coefficients between the prediction of a linear-nonlinear model using STRFs estimated from the a model without gain control (static-LN) versus a model with gain control (GC-LN). Each dot indicates a neuron. The red solid line indicates unity. The red “x” indicates the median correlation in each contrast. Asterisks indicate the significance of a Wilcoxon Sign-Rank test. **i,** Psychometric performance in low contrast, averaged based on a median split of average cortical gain during the adaptation period of the trial. Light dots and lines indicate the session average and psychometric fit to sessions in the bottom 50th percentile of gain, while dark dots and lines indicate the same values for sessions in the top 50th percentile of gain. Errorbars on the data are ±SEM across sessions. *Inset*: distribution of average gain in each session estimated from the adaptation period. The red dashed line indicates the median of the distribution, and the histogram bars are shaded according to whether they fall above (light blue) or below (dark blue) the median. **j,** Session-wise relationship between average gain in the adaptation period and psychometric threshold. Each dot indicates the gain and threshold for a single session, and its color indicates the contrast of the adaptation period. The grey line is the best linear fit to the data. The text in the lower right indicates the results of Likelihood Ratio Tests for models including gain as a predictor (in grey) or contrast as a predictor (in red). Full statistical results in Supplementary Table 1. **k,** Same as in **j**, but plotting psychometric slope as a function of gain. In all plots: ns*p*>0.1; †*p*<0.1, \**p*<0.05, \*\**p*<0.01, \*\*\**p*<0.001, \*\*\*\**p*<0.0001.