

# Motivation for Numerical Methods

- Sometimes an ODE may not be in one of the forms discussed in this course, so it might be difficult to find the exact solution.
- Sometimes an exact solution might not even exist.
- In such cases, a numerical approximation for the solution may be obtained.
- There are many different types of numerical methods to choose from (e.g. Euler's method, Modified Euler's method, Runge's method, Runge-Kutta methods).
- We will focus on the use of Euler's method.

# Existence and Uniqueness Theorem

- Consider the 1st order IVP

$$\frac{dy}{dx} = f(x, y), \quad y(x_0) = y_0.$$

If  $f$  and  $\frac{\partial f}{\partial y}$  are continuous in the closed rectangle

$$R = \{(x, y) : |x - x_0| \leq a, |y - y_0| \leq b\}$$

then  $\exists$  a unique solution  $y(x)$  of the given IVP in an interval  $|x - x_0| \leq h \leq a$ .

# Example

- Consider the IVP

$$\frac{dy}{dx} = \frac{2y}{x}, \quad y(x_0) = y_0.$$

- $f(x, y) = \frac{2y}{x}$  and  $\frac{\partial f}{\partial y} = \frac{2}{x}$ . Both are undefined for  $x = 0$ .
- Using separation of variables, the general solution is

$$y(x) = Ax^2.$$

- The IVP has
  - a unique solution in an open interval containing  $x_0$  if  $x_0 \neq 0$ ,
  - no solution if  $x_0 = 0$  and  $y_0 \neq 0$ ,
  - infinite solutions if  $x_0 = 0$  and  $y_0 = 0$ .

# MATLAB Review

# Starting MATLAB

- Run **MATLAB R2017a** from the Desktop
- The different MATLAB windows:
  - **Command Window** (centre): This is where you type commands.
  - **Workspace** (right): All variables currently stored are displayed here.
  - **Current Folder** (left): Lists files stored in the current directory.
  - **Command History** (accessed through the Layout tab in the Home menu): Stores all commands entered.
  - **Graphics Window** (pop-up): Displays plots/graphs.
  - **Editor Window**: Used to create/edit MATLAB codes.

# MATLAB as a Calculator

- Arithmetic Operations

Addition	+	
Subtration	-	
Multiplication	*	.*
Division	/	./
Exponentiation	^	.^

- Unless otherwise specified, MATLAB assigns computed values to a variable called **ans**
- Variables can be assigned values using `=`
- `.*`, `./` and `.^` are element-wise operations.

# Built-In Constants and Functions

Name	MATLAB syntax	Remarks
$\pi$	pi	
$10^x$	1ex	Powers of 10
$\sqrt{x}$	sqrt(x)	Square root function
$e^x$	exp(x)	Exponential function
$\log(x)$	log10(x)	log base 10
$\ln(x)$	log(x)	log base e
$\sin(x)$	sin(x)	Measured in radians
	sind(x)	Measured in degrees
$\arcsin(x)$ , $\sin^{-1}(x)$	asin(x)	Inverse trig functions
$\sinh(x)$	sinh(x)	Hyperbolic functions

# MATLAB as a Calculator - Examples

- Click in the Command Window and type each of the following commands:

```
>> 3+4*(1+6/3)
```

```
>> pi^2-sqrt(ans)+cos(45)/cosh(45)
```

```
>> x=exp(3)*log10(3)+atan(3)/log(3)
```

```
>> y=20+log(csch(x-1)^2)
```

```
>> z=1+y/x
```

```
>> z*3e-2
```

```
>> ans
```



# Variables

- A variable name may contain only letters, digits, and underscores, and must begin with a letter.
  - Punctuation marks are not allowed!
  - **Note:** MATLAB is case-sensitive!
- A variable can be assigned a numerical value, an array of numerical values or a string of characters.
- Use single quotation marks ' ' around any text that is to be entered as a character string.
- A variable cannot be given the same name as a MATLAB keyword, and also should not be given any name that already exists in MATLAB.

# Useful Commands and Tools

- *clear* **x y** - deletes only variables **x** and **y**
- *clear* - deletes all current variables in the workspace
- *clc* - clears the Command Window
- *quit* - ends the session and closes MATLAB
- Hold down **Control** + **C** on the keyboard - this interrupts the current command execution, which is often useful for aborting commands that are taking too long to complete.
- While the Command Window is active, use the **Up** and **Down** arrow keys on the keyboard to access commands stored in the Command History.

# Useful Commands and tools

- A semicolon (;) is used to suppress the output - the output is still stored in the Workspace, but it is not displayed in the Command Window.
- An ellipsis (...) is used to enter input on an additional line - this is useful when typing long lines of MATLAB code.
- % is used for commenting. MATLAB does not run any commands appearing after a % in a line - this is useful for documenting and explaining what your code does.
- **help** - lists all the help topics
- **help xyz** - provides help on topic xyz
- Note: Online support for MATLAB can be found at:  
[www.mathworks.com/help/matlab/](http://www.mathworks.com/help/matlab/)

# Formatting the Command Window Display

- MATLAB uses double-precision floating point arithmetic - values are stored accurate to 15 decimal places.
- However, MATLAB displays only 4 decimal places by default.
  - To display 15 decimal places, type **format long**
  - To display only 4 decimal places, type **format short** (default)
  - To display numbers as fractions, type **format rat**
- By default, MATLAB displays a blank line between each line of text in the Command Window.
  - To disable this feature, type **format compact**
  - To enable it, type **format loose**

# Inputting Arrays

- **Row vector** `>> x=[0 1 2 3]` or `x=[0,1,2,3]`
- **Column vector** `>> y=[0;1;2;3]`
- **Matrix** `>> Z=[0 1 2 3; 4 5 6 7]`
- Other ways of entering row vectors
  - `>> x=1:2:6`
  - `>> x=linspace(1,6,3)`
- **Special Matrices**
  - `>> zeros(m,n)` - zero matrix
  - `>> ones (m,n)` - matrix of ones
  - `>> eye(m,n)` - ones on leading diagonal; zeros elsewhere

# Indexing

- You can ask MATLAB for the number stored in row 2, column 3 of a matrix  
`>> Z(2,3)`
- Or for all the elements stored in row 2  
`>> Z(2,:)`
- Or for all the elements stored in column 3  
`>> Z(:,3)`
- Or change the value stored in a position  
`>> Z(2,3)=2`

# Matrix Operations

- Elementwise addition or subtraction (must be of the same dimensions)  
`>> A+B` or `A-B`
- Multiplication (must have the same inner dimensions)  
`>> A*B`
- Element-wise multiplication or division  
`>> A.*B` or `A./B`
- Element-wise powers  
`>> A.^m`

# Matrix Operations

- Transpose of a matrix  $Z$  (denoted  $Z^T$ )  
`>> Z'`
- Dimensions of a matrix  $Z$   
`>> size(Z)`
- Number of elements in a matrix  $Z$   
`>> numel(Z)`
- Length of a vector  $x$   
`>> length(x)`



# Function Handles - Self Reading

- A function handle is a data class that stores an association to a function.
- It allows you to indirectly call a function by using its associated handle rather than the actual function name.
- Function handles are entered in the format  
`fun_handle=@fun_name`  
`>> f=@sqrt`  
`>> f(9)`  
`>> g=@cos`
- Function handles are treated as scalars (or  $1 \times 1$  arrays).

# Anonymous Functions - Self Reading

- MATLAB has several built-in functions (e.g. cosine, square root, etc.)
- We can also program user-defined functions using
  - Function files (discussed later)
  - **Anonymous function** definitions using function handles
- An anonymous function is one that does not explicitly exist in MATLAB, but is associated with a function handle.

```
>> dotsquare=@(x) x.^2
```

```
>> dotsquare(1:5)
```

```
>> z=@(x,y) x.^2+y.^2
```

```
>> z(1:5,[2 3 5 7 11])
```

## 2D Plots

- Plotting a curve of  $y$  versus  $x$   
`>> plot(x,y)`
- Adding an x- or y-axis label  
`>> xlabel('text'); ylabel('text')`
- Inserting a title  
`>> title('text')`
- Example:  
`>> t=linspace(-pi,pi); u=t.^2;`  
`>> plot(t,u)`  
`>> xlabel('t'); ylabel('u')`  
`>> title('Plot of u versus t')`

## 2D Plots

- You can change the line color, line style or marker style  
`>> plot(x,y,'m+-')` produces a solid magenta curve with plus sign markers

Line Color		Line Style		Marker Style	
yellow	y	solid (default)	-	plus	+
magenta	m	dashed	- -	circle	o
cyan	c	dotted	:	asterisk	*
red	r	dash-dot	-.	point	.
green	g			cross	x
blue	b			square	s
black	k			diamond	d

## 2D Plots

- You can plot in different figures by calling a figure before plotting  
`>> figure(2)`
- You can overlay multiple plots on the same graph by using the hold command  
`>> plot(x,y)`  
`>> hold on`  
`>> plot(x,z,'g')`  
`>> hold off`
- Or by using the plot command  
`>> plot(x,y,x,z,'g')`

# Script Files

- A **script** is a file containing a valid set of MATLAB commands.
- Scripts are used to type multiple command lines which can then all be run at once.
- A script can be run by
  - typing its name in the Command Window and pressing enter, or
  - clicking the Run icon in the Editor window.
- The script must be saved, and the folder in which the file is saved must be displayed in the “Current Folder” window for the script to run.
- Variables created when a script is run are saved in the Workspace (referred to as global variables).

# Naming Script Files

- A script name
  - must begin with a letter
  - can contain only letters, digits, and underscores
  - **punctuation marks are not allowed!**
  - should be no longer than 63 characters
- Never give a script file the same name as
  - one of the variables it computes, or
  - a built-in function.
- The **exist** command can be used to check if a name, say “**xyx**”, can be used for a script.
  - Type **exist('xyz')** in the Command Window.
  - If MATLAB returns 0 then you can use the name.

# Function Files

- A function file takes user-defined inputs each time it is run.
- The first line in a function file must be of the form:  
`function [ out1,out2,... ] = fun_name( in1,in2,... )`
- `out1,out2,...` are the names of the output variables. The square brackets can be omitted if there is only one output variable.
- `in1,in2,...` are the names of the input variables. The values of these variables must be specified each time the function is run.
- The same rules for naming script files also apply to function files. Additionally, the file must be saved with the same name as the function, i.e. `fun_name.m`, or else it will not run.



# Function Files

- Variables used within a function file are not stored in the Workspace; only the output variables are stored.
- A function can be called with a command of the form

```
>> [ out1,out2,... ] = fun_name( in1val,in2val,... )
```

- **in1val,in2val,...** are the values specified for the input variables.
- If “[ out1,out2,... ]” is omitted, then only the first output is stored in the variable **ans**.
- The **feval** command is another way to evaluate functions

```
>> feval(fun,x1,x2,...,xn) - evaluates the function  
fun with input arguments x1, x2, ..., xn. This is  
equivalent to fun(x1,x2,...,xn)
```

# Control Structures

- Loops are used to perform a series of commands as many times as necessary.
  - A stopping criterion determines when a loop stops.
- Some other control structures perform conditional checks and execute only the commands associated with certain conditions.

# for Loop

- Used to execute a series of commands a fixed number of times.

- Basic format:

```
for i=a:k:b  
    commands to be executed in each loop  
end
```

- Example:

```
function S=sums(n)  
S=0;  
for k=1:n  
    S=S+k;  
end  
end
```

# while Loop

- Execute a series of commands while a specified condition is true.
- Basic format:

```
while expression  
    commands to be executed in each loop  
end
```

- Example:

```
function [S,n]=sums2(x)  
S=0; n=0;  
while S<x  
    S=S+rand(1);  
    n=n+1;  
end  
end
```

# if Statements (if-elseif-else)

- An **if** statement evaluates logical expressions and executes the specified commands when the answer is true.
- Basic format:

```
if expression1  
    commands to be executed if expression1 is true  
elseif expression2  
    commands to be executed if expression2 is true  
else  
    commands to be executed otherwise  
end
```

# Relational and Logical Operators

Relational Operators		Logical Operators	
equal to	==	and	&
greater than	>	or	
less than	<	not	~
greater than or equal to	>=		
less than or equal to	<=		
not equal to	~=		

# if Statements (if-elseif-else)

- Example:

```
x=-3:0.1:3;  
y=zeros(1,length(x));  
for i=1:length(x)  
    if x(i)>-1 & x(i)<1  
        y(i)=x(i)^2+1;  
    else  
        y(i)=2;  
    end  
end  
plot(x,y)
```

# Euler's Method



# Derivation of Euler's Method

- Consider a general IVP

$$\frac{dy}{dx} = f(x, y), \quad y(x_0) = y_0, \quad x \in [a, b]$$

that satisfies the existence and uniqueness criteria.

- We can approximate  $\frac{dy}{dx}$  using

$$\frac{dy}{dx} = \lim_{h \rightarrow 0} \frac{y(x+h) - y(x)}{h} \approx \frac{y(x+h) - y(x)}{h}.$$

- Therefore

$$y(x+h) \approx y(x) + h \cdot f(x, y) \quad (1)$$

# Derivation of Euler's Method

- Let's discretize the interval  $[a, b]$  into  $N$  subintervals.
- The total number of points is  $N + 1$
- The size of each subinterval is  $h = \frac{b-a}{N}$
- Denote the points  $x_j = a + h \cdot j$ , for  $j = 0, 1, 2, \dots, N$   
 $x_0 = a,$   
 $x_1 = a + h,$   
 $x_2 = a + 2h,$   
 $\vdots$   
 $x_{N-1} = a + (N - 1) \cdot h,$   
 $x_N = b$

# Derivation of Euler's Method

- Taking  $x = x_j$  in equation (1) gives

$$y(x_j + h) \approx y(x_j) + h \cdot f(x_j, y(x_j))$$

- Since  $x_j = a + h \cdot j$  we have

$$y(a + hj + h) \approx y(x_j) + h \cdot f(x_j, y(x_j))$$

$$\therefore y(a + h(j + 1)) \approx y(x_j) + h \cdot f(x_j, y(x_j))$$

$$\therefore y(x_{j+1}) \approx y(x_j) + h \cdot f(x_j, y(x_j))$$

# Algorithm for Euler's Method

$$y(x_{j+1}) \approx y(x_j) + h \cdot f(x_j, y(x_j)), \quad j = 0, 1, \dots, N-1 \quad (2)$$

- $h$  is the step-size
- $N + 1$  is the number of discretized points in the interval  $[a, b]$
- $x_0 = a, x_1 = a + h, x_2 = a + 2h, \dots$   
 $x_{N-1} = a + (N - 1) \cdot h$  and  $x_N = b$
- Since we have  $y(x_0) = y_0$ , we can solve for  $y(x_1)$ , then use this to solve for  $y(x_2)$  and so on.
- Thus, we obtain approximate values for  $y$  at the discretized values of  $x$ .
- This method is sometimes too slow (if  $h$  is small) or too inaccurate (if  $h$  is large).

# Example

- Consider the IVP

$$\frac{dy}{dx} = x + y - 1, \quad y(0) = 2, \quad x \in [0, 0.75]$$

- The exact solution is

$$y_{\text{exact}} = 2e^x - x.$$

- Let's apply Euler's Method to find an approximate solution.
- Take  $N = 3$  subintervals.
- There are 4 points; the step-size is  $h = \frac{0.75-0}{3} = 0.25$
- The points are  $x_0 = 0$ ,  $x_1 = 0.25$ ,  $x_2 = 0.5$  and  $x_3 = 0.75$

# Example

- Apply Euler's method:

$$y(x_{j+1}) \approx y(x_j) + h \cdot (x_j + y(x_j))$$

- $y(x_1) \approx y(x_0) + h \cdot (x_0 + y(x_0) - 1)$
  - $y(0.25) \approx 2 + 0.25 \times (0 + 2 - 1) = 2.25$
  - $y(0.5) \approx 2.25 + 0.25 \times (0.25 + 2.25 - 1) = 2.625$
  - $y(0.75) \approx 2.625 + 0.25 \times (0.5 + 2.625 - 1) = 3.15625$
- The exact value of  $y(0.75)$  is given by

$$y_{\text{exact}}(0.75) = 2e^{0.75} - 0.75 \approx 3.484$$

- The error is significant because  $h$  is too large.

# MATLAB Code for Euler's Method

```
function [x,y] = Euler(a, b, N, y0, f)
% MATLAB code for using Euler's Method to solve the general 1st order IVP
% dy/dx=f(x,y) on the interval [a,b] with y(a)=y0

% Inputs:    a and b define the interval [a,b]
%            N is the number of subintervals
%            y0 is the value of y(a)
%            f is the function f(x,y) which must be defined separately

% Outputs:  x stores the discretized values of x in the interval [a,b]
%            y stores the corresponding approximate values of the solution

h=(b-a)/N; % determines the step-size needed
x=linspace(a,b,N+1); % discretizes the interval for x
y=zeros(1,N+1); % initializes y as a vector of zeros
y(1)=y0; % stores the value of y(a) as the first entry in the y vector
for i=1:N % using a for loop to compute the remaining y values
    y(i+1)=y(i)+h*feval(f,x(i),y(i)); % Algorithm for Euler's Method
end
plot(x,y) % displays a plot of y versus x
end
```

# Underestimates/Overestimates

- Euler's Method will normally produce **either** an underestimate **or** an overestimate of the actual solution.
- An underestimate can be identified by
  - a graph that is concave upward (the gradient increases as  $x$  increases), or
  - an increase in the approximate solution as the step-size is decreased (as  $h$  tends to zero, the approximate solution increases towards the actual solution).
- An overestimate can be identified by
  - a graph that is concave downward (the gradient decreases as  $x$  increases), or
  - a decrease in the approximate solution as the step-size is decreased (as  $h$  tends to zero, the approximate solution decreases towards the actual solution).