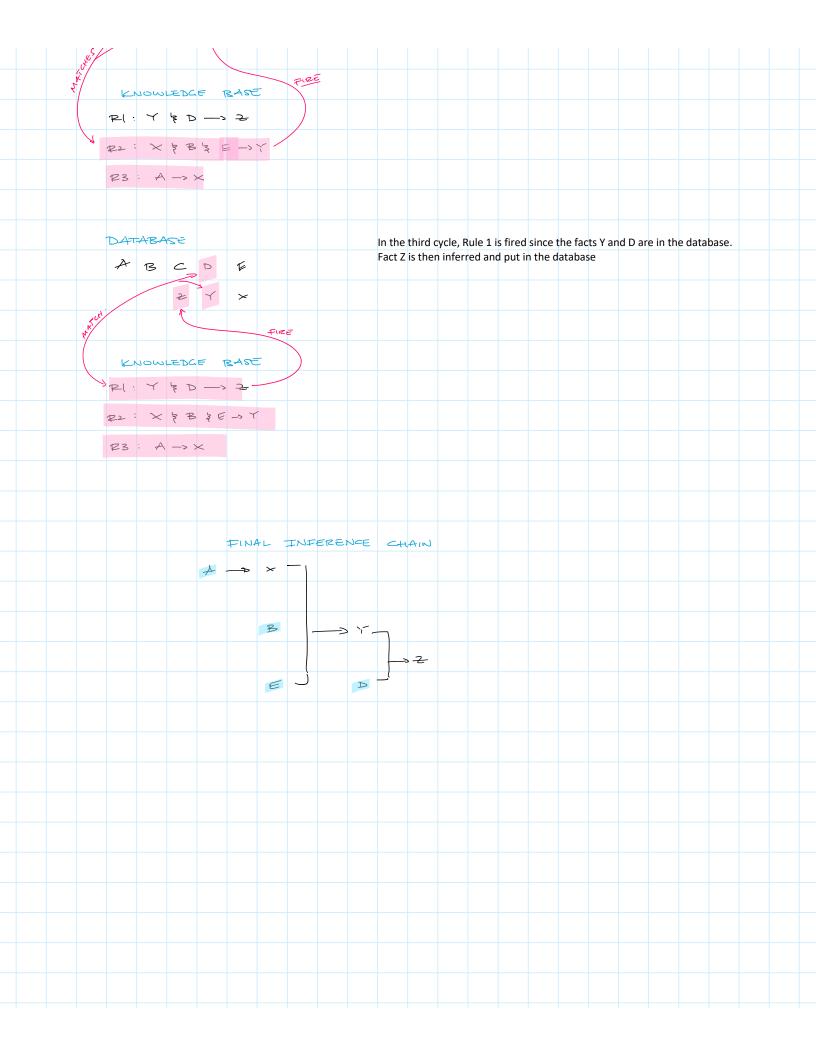
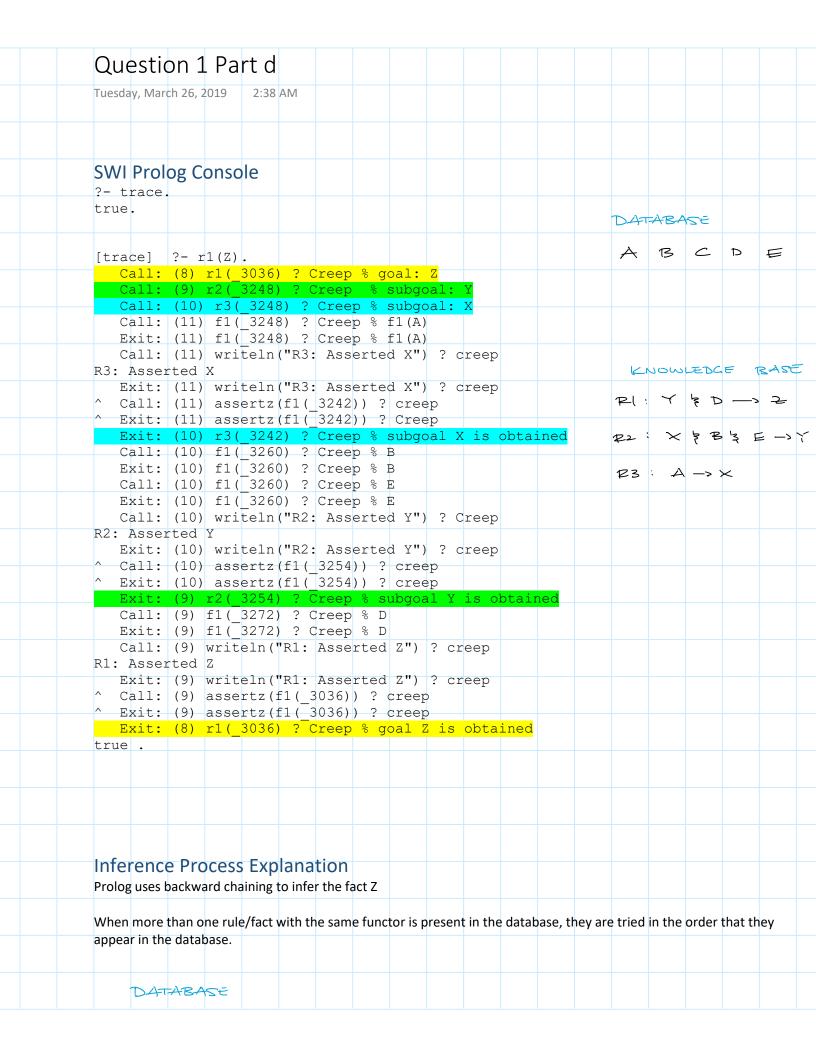
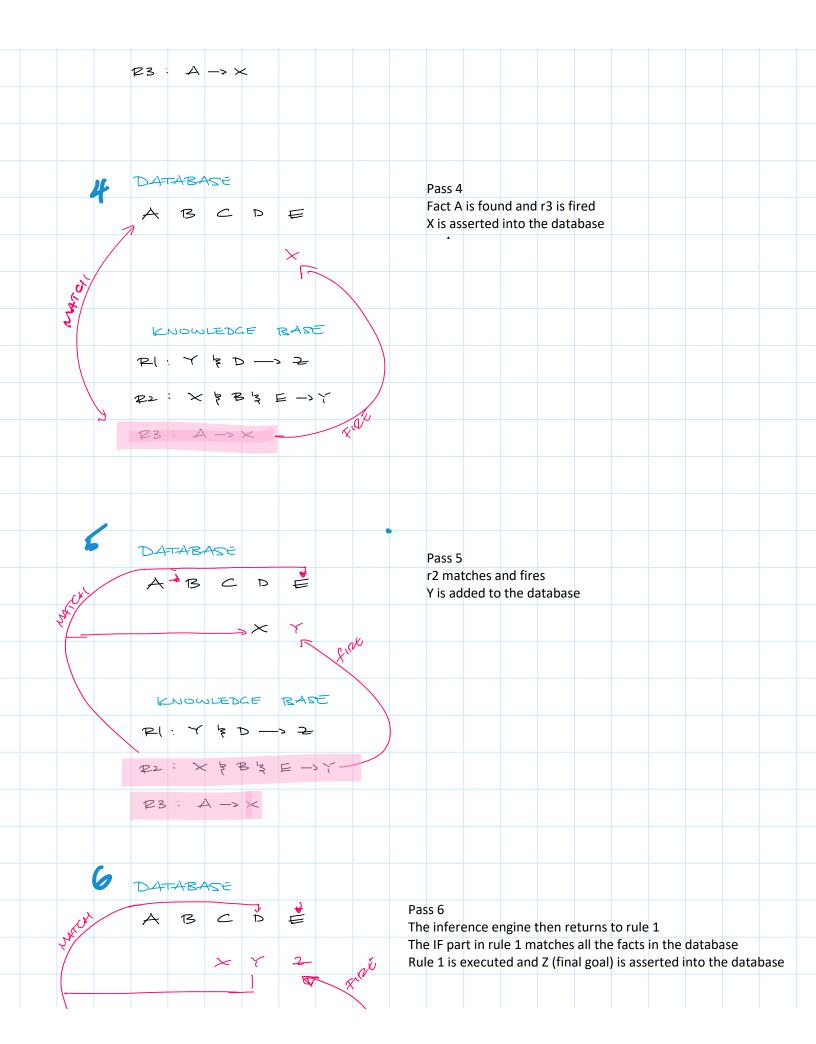
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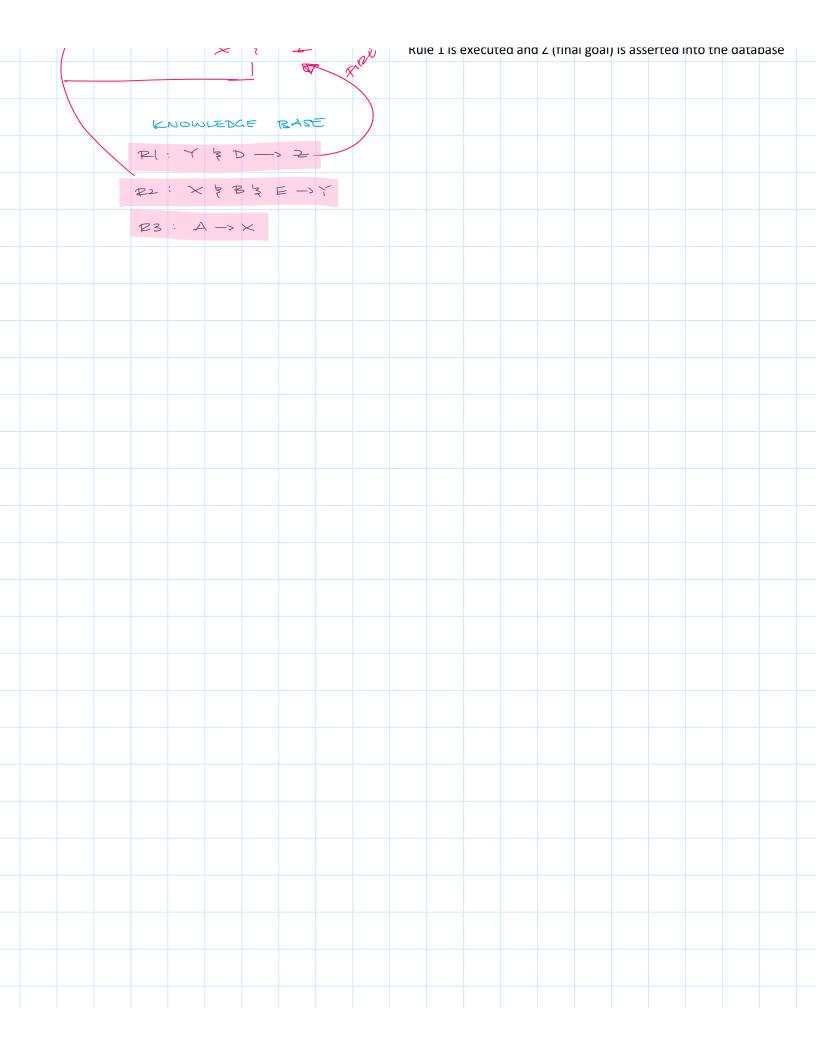
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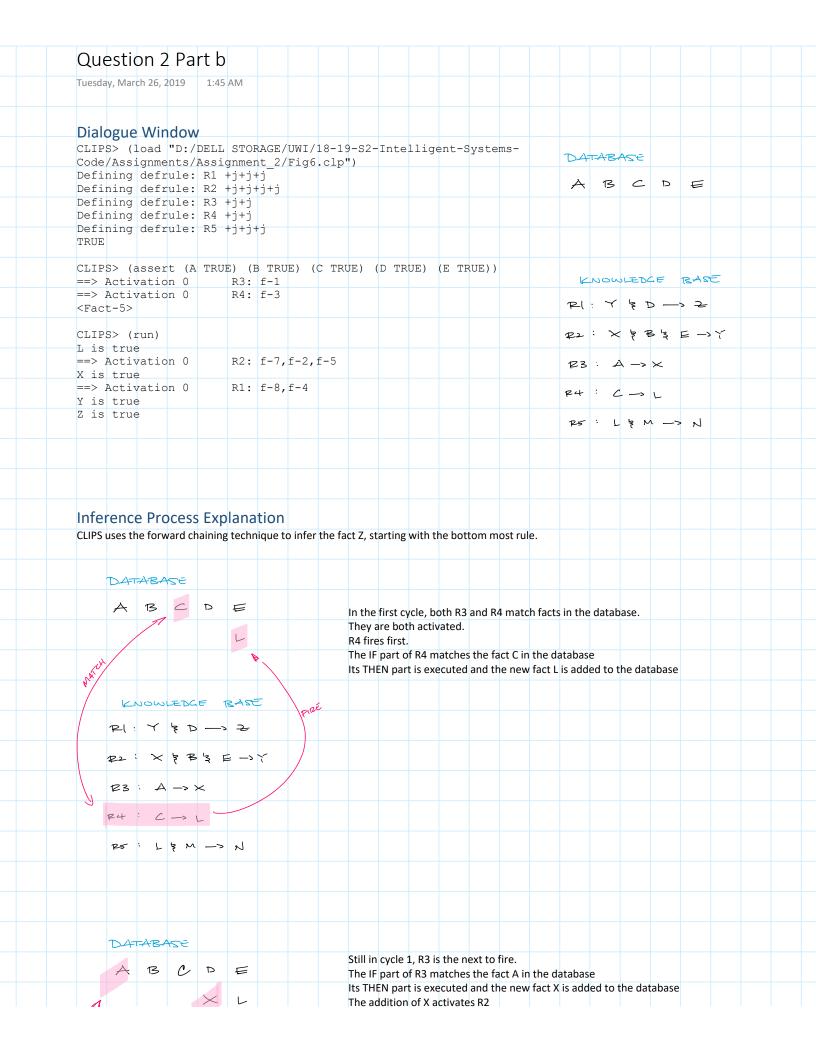


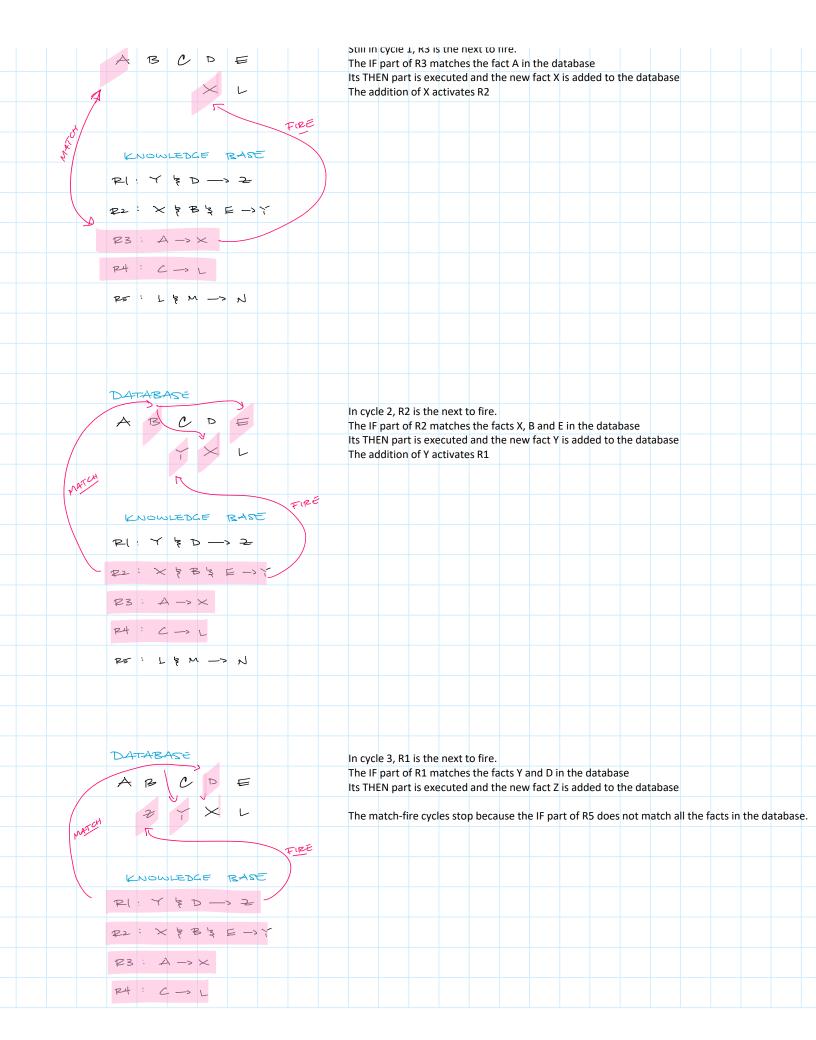


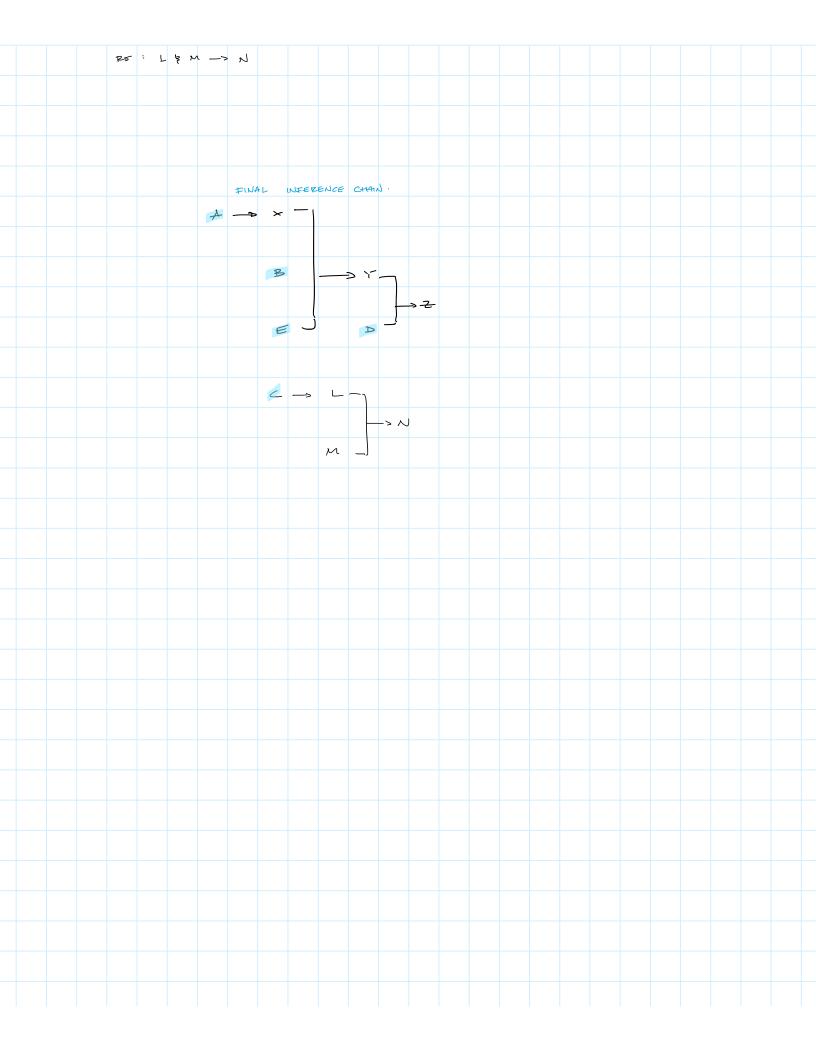
Pass 1: Inference engine attempts to infer fact Z It searches the knowledge base to find the rule that has fact Z in its THEN part The engines finds and stacks r1 The IF part of r1 (Y and D) must be established Pal: Y & D -> 2 Pass 2 Inference engine sets up the subgoal Y It checks the database but the fact Y is not there The knowledge base is searched again for a rule with Y in its the part. The engine located and stacks R2	
It searches the knowledge base to find the rule that has fact Z in its THEN part The engines finds and stacks r1 The IF part of r1 (Y and D) must be established P(: Y & D \rightarrow \frac{1}{2} \subseteq - \frac{1}{2}	
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part.	n
The engine located and stacks R2	
KNOWLEDGE RAST	
P(: Y & D -> 2	
22 : × ₹ B '\$ E →> ``	
23 · A -> ×	
3 DATABASE	
Pass 3 The inference engine sets up the subgoal X	
It checks the database for fact X and fails to find it	
It searches for the rule that infer X (call this r3)	
KNOWLEDGE BASE	
P(: Y & D -> 2	
22: X & B 3 E -> 1	











Question 2 Part d Tuesday, March 26, 2019 9:53 PM **SWI Prolog Console** Note: Backward chaining is a goal-driven technique. This means the process starts at the goal state Z and works it way backwards though the chain to find sub goals. This means that any rules that are not directly connected to the goal state is NEVER fired. For this reason, R4 and R5 are never fired in this scenario. This implies that the solution for Question 2 Part d is essentially the same as Question 1 Part d. ?- trace. true. [trace] ?-r1(Z). Call: (8) r1(_3036) ? Creep % goal: Z Call: (9) r2(_3248) ? Creep % subgoal: Y Call: (10) r3(3248) ? Creep % subgoal: X Call: (11) f1(3248) ? Creep % f1(A) Exit: (11) f1(3248) ? Creep % f1(A) Call: (11) writeln("R3: Asserted X") ? creep R3: Asserted X Exit: (11) writeln("R3: Asserted X") ? creep Call: (11) assertz(f1(3242)) ? creep ^ Exit: (11) assertz(f1(3242)) ? Creep Exit: (10) r3(3242) ? Creep % subgoal X is obtained Call: (10) f1(3260) ? Creep % B Exit: (10) f1(3260) ? Creep % B Call: (10) f1(_3260) ? Creep % E Exit: (10) f1(3260) ? Creep % E Call: (10) writeln("R2: Asserted Y") ? Creep R2: Asserted Y Exit: (10) writeln ("R2: Asserted Y") ? creep Call: (10) assertz(f1(3254)) ? creep ^ Exit: (10) assertz(f1(3254)) ? creep Exit: (9) r2(_3254) ? Creep % subgoal Y is obtained Call: (9) f1(3272) ? Creep % D Exit: (9) f1(3272) ? Creep % D Call: (9) writeln("R1: Asserted Z") ? creep R1: Asserted Z Exit: (9) writeln("R1: Asserted Z") ? creep Call: (9) assertz(f1(3036)) ? creep ^ Exit: (9) assertz(f1(3036)) ? creep Exit: (8) r1(3036) ? Creep % goal Z is obtained true . Inference Process Explanation Same explanation as Question 1 Part d. The only difference is this version has the two extra rules (r4 and r5) that are never fired since they do not help in inferring the fact Z.