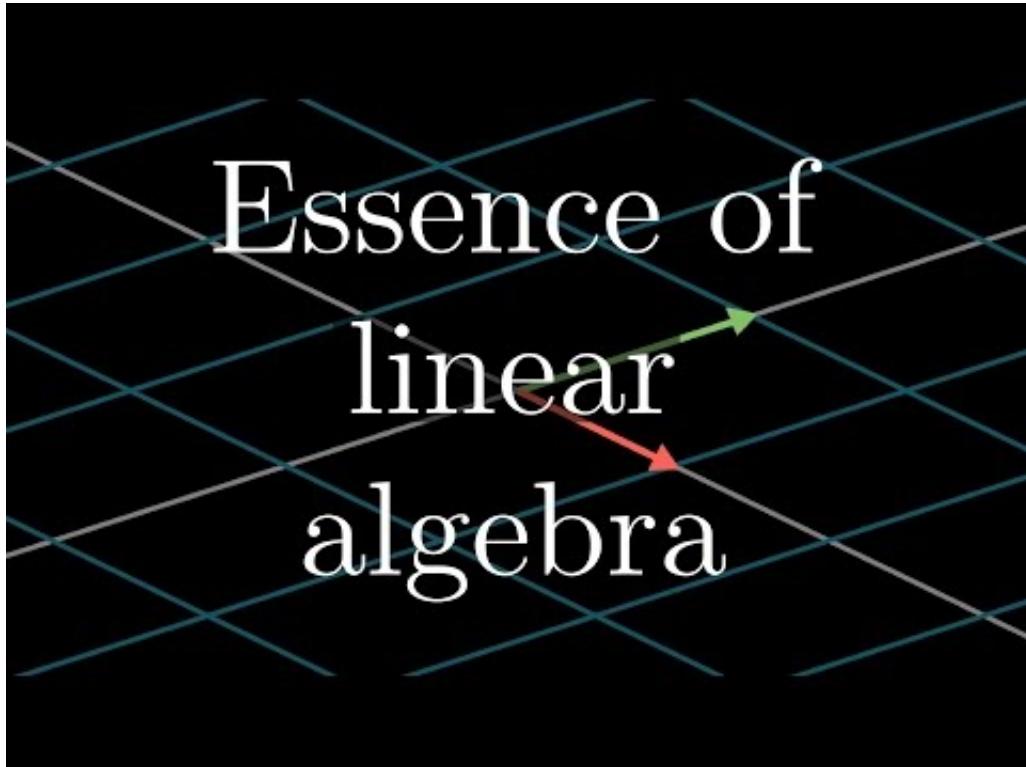


# Machine Learning

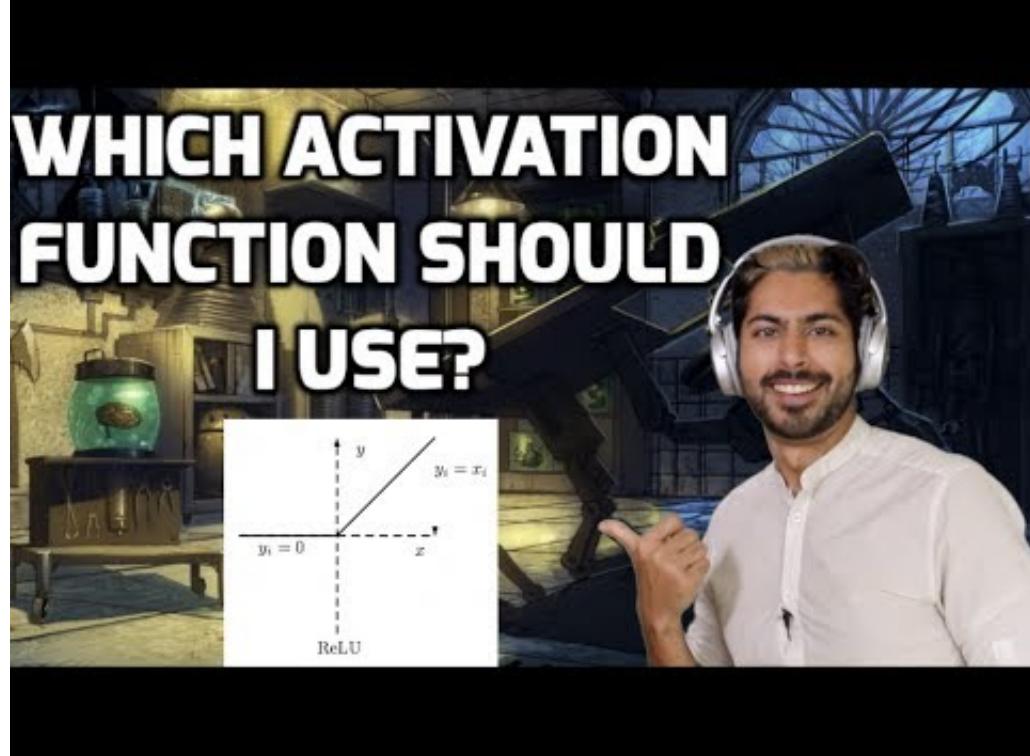
## Videos

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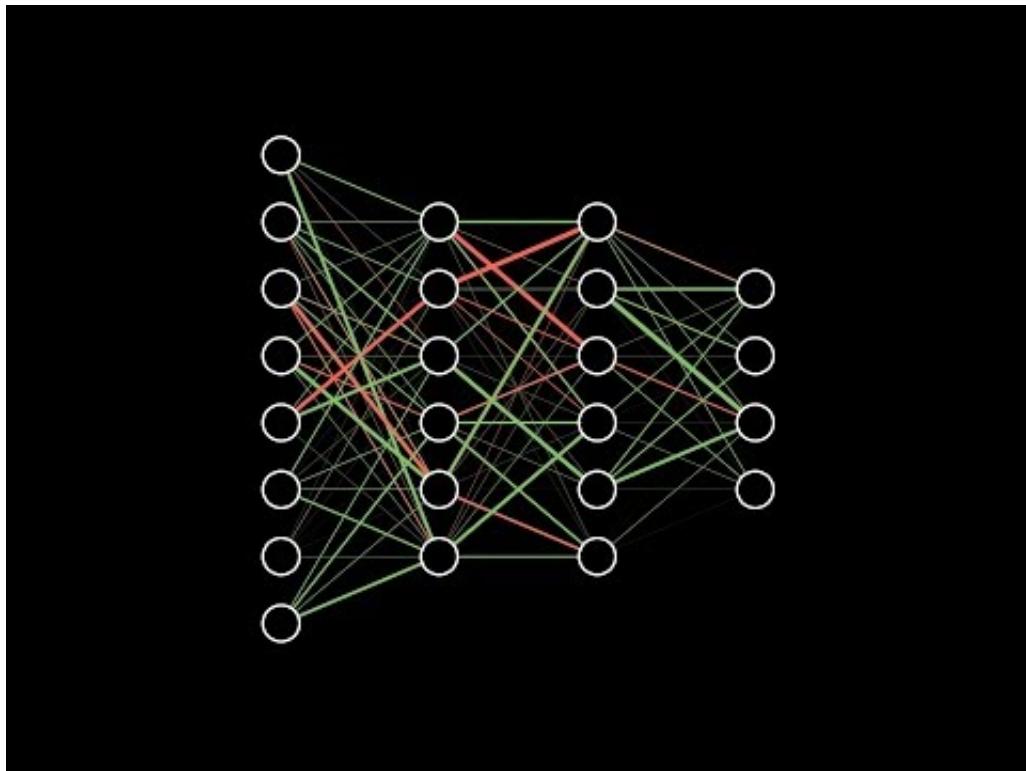
### Linear Algebra



### Activation Functions

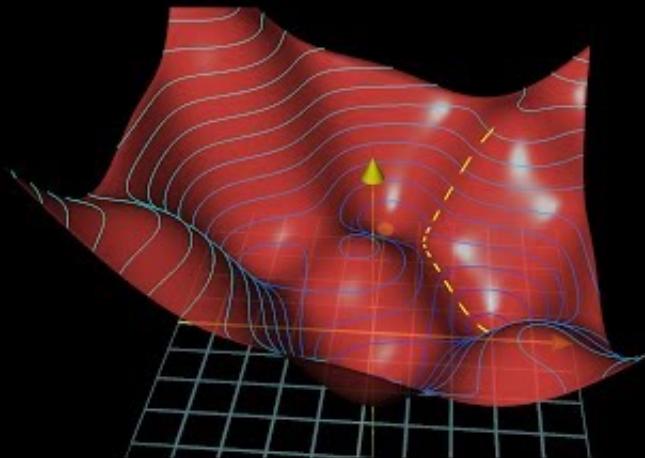


## What is a Neural Network



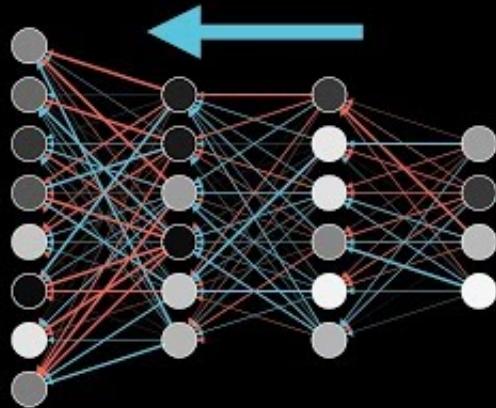
Gradient descent, how neural networks learn

# How machines learn



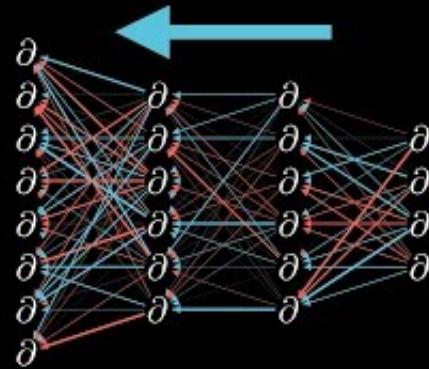
## Backpropagation

Backpropagation

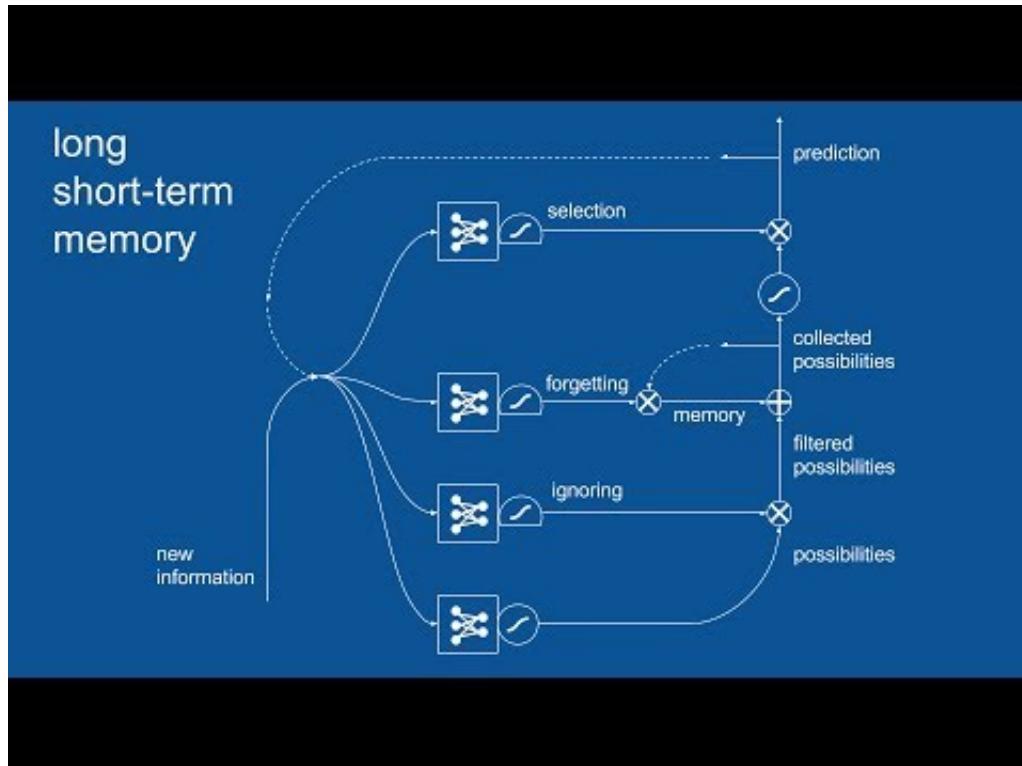


## Backpropagation Calculus

# Backpropagation calculus



## Long Short-Term Memory



## Links

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## Blogs / Articles

[The Unreasonable Effectiveness of Recurrent Neural Networks Blog Post](#)

[Data Science and Robots Blog](#)

[Understanding LSTM Networks](#)

[EEG event classification with convolutional neural networks - A First Pass/Brief Overview](#)

[Reddit Machine learning](#)

[Closing the Simulation-to-Reality Gap for Deep Robotic Learning](#)

[pybullet by Alexander Fabisch](#)

[Pytransform - lightweight tool to translate between conventions, debug, and visualize](#)

[Alexander Fabisch - Robotics Python](#)

## Code

[Torch-rnn Char-rnn update](#)

[Xgboost](#)

[Xgboost Node](#)

## Frameworks & Websites

[TensorFlow](#)

[Keras](#)

[Try TensorFlow](#)

[Colab](#)

[Kaggle](#)

[Moniel - Interactive Notation for Computational Graphs](#)

[OpenAI](#)

[OpenAI Github](#)

[DeepMind - Lab 3D platform for agent-based AI research](#)

[DeepMind - Sonnet](#)

[Install Anaconda](#)

## Companies

[Baidu](#)

[DeepMind](#)

## Books

[Deep learning with python book](#)

[Deep learning with python code](#)

[Neural Networks and Deep Learning by Michael Nielsen](#)

[Programming Robots with ROS](#)

[ROS Programming: Building Powerful Robots](#)

[ROS Robotics By Example](#)

## Lectures

[Recurrent Neural Network Lecture](#)

## People

[Andrej Karpathy](#)

[Andrew Ng](#)

[Geoffrey Hinton](#)

## Notes

- **Convolutional Neural Network (CNN)** good for **image recognition**
- **Recurrent Neural Networks** and **Long short-term memory** good for **speech recognition**

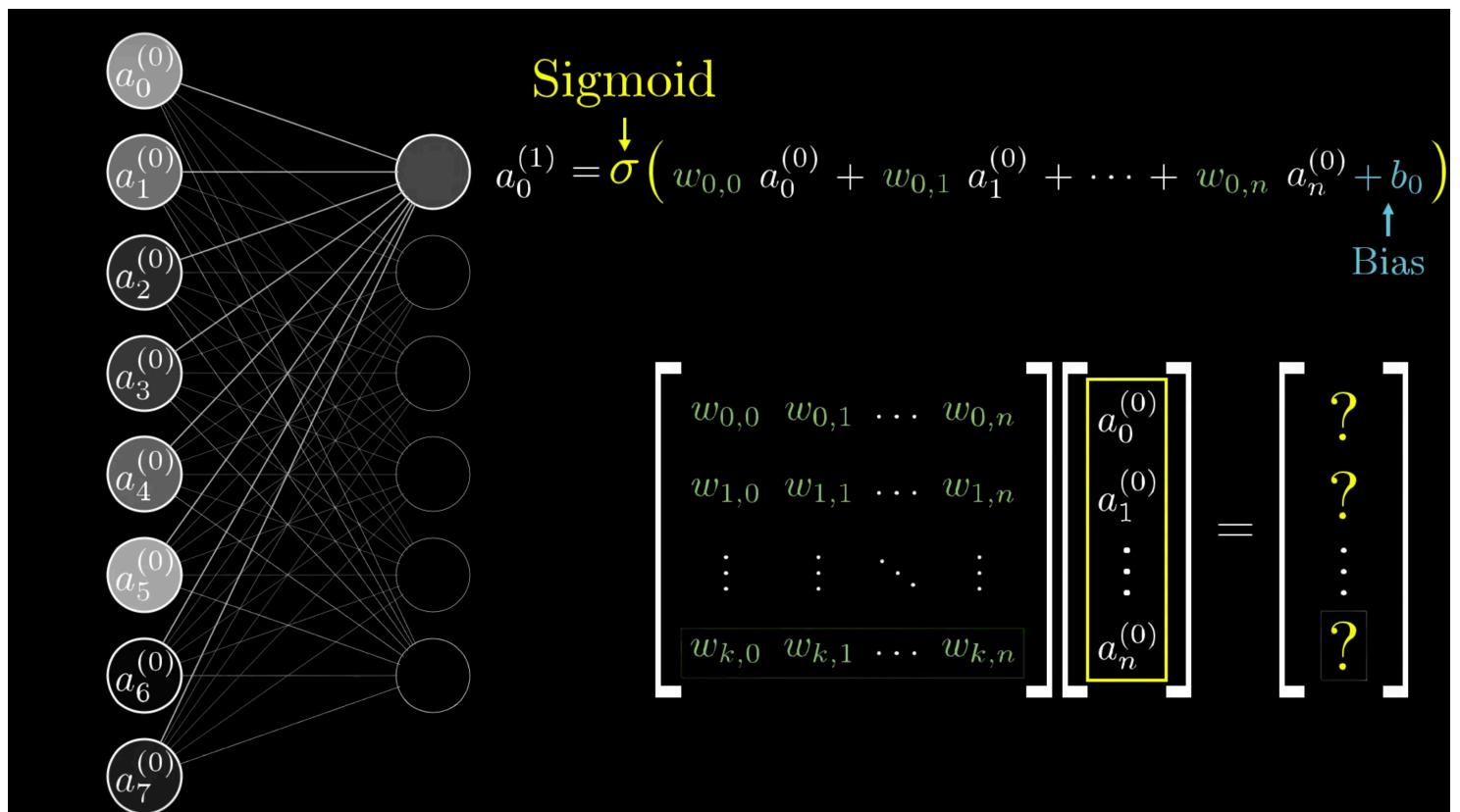
- Transforming a set of real numbers to normalized values **Logistic functions**, **Logistic Curve** - [Sigmoid Function](#)
- **Weight engineering?** applying weights to areas/components you care about.
- **Cost function** provides feedback to the network
- Learning is minimizing a cost function
- Categorical data is handled using [One hot encoding procedures](#)

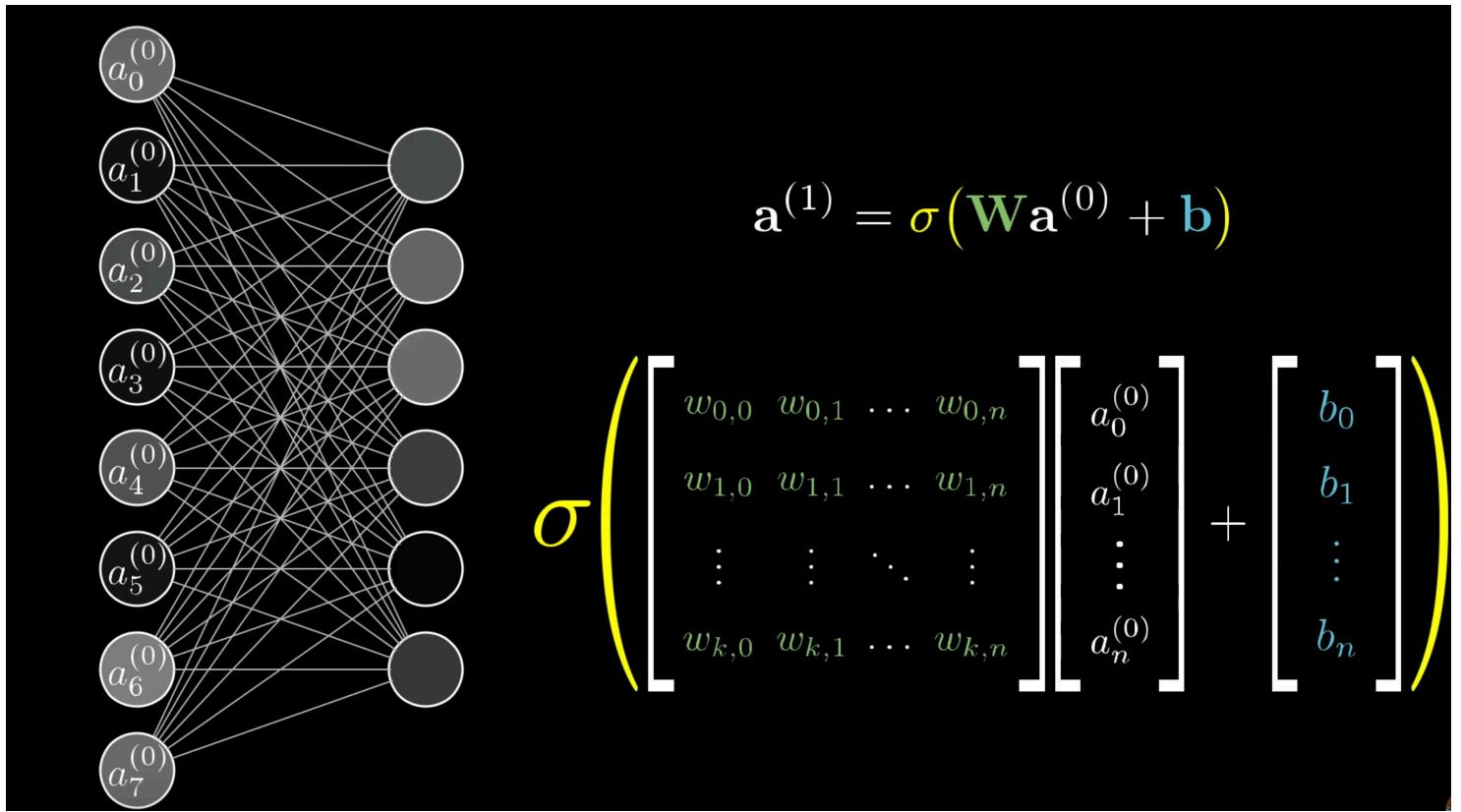
## Activation Function & General Notation

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### Notation for weights and neuron activations

(Note: Sigmoid approach replaced by RELU activation function)





## BackProp

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**Chain Rule (Calculus) and relevance to cost function in Neural networks (Backprop)(One neuron)**

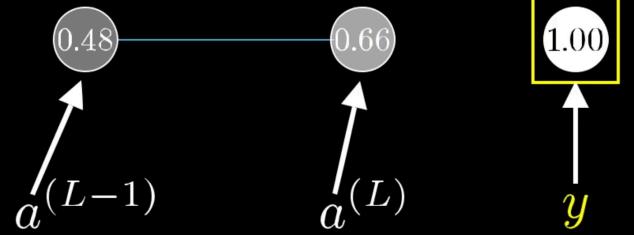
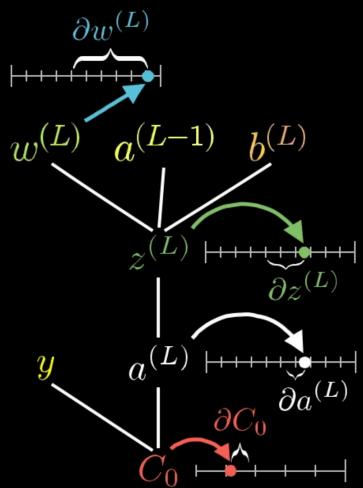
$$\frac{\partial C_0}{\partial w^{(L)}} = \frac{\partial z^{(L)}}{\partial w^{(L)}} \frac{\partial a^{(L)}}{\partial z^{(L)}} \frac{\partial C_0}{\partial a^{(L)}}$$

$$C_0(\dots) = (a^{(L)} - y)^2$$

$$z^{(L)} = w^{(L)} a^{(L-1)} + b^{(L)}$$

$$a^{(L)} = \sigma(z^{(L)})$$

Desired output



$$\frac{\partial C_0}{\partial w^{(L)}} = \frac{\partial z^{(L)}}{\partial w^{(L)}} \frac{\partial a^{(L)}}{\partial z^{(L)}} \frac{\partial C_0}{\partial a^{(L)}}$$

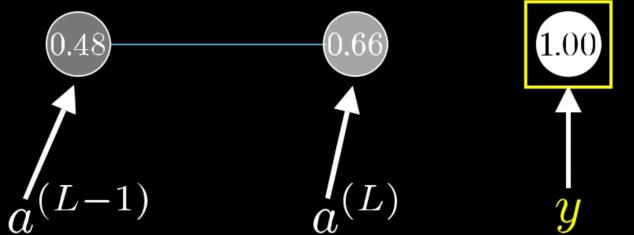
$$C_0 = (a^{(L)} - y)^2$$

$$z^{(L)} = w^{(L)} a^{(L-1)} + b^{(L)}$$

$$\frac{\partial C_0}{\partial a^{(L)}} = 2(a^{(L)} - y)$$

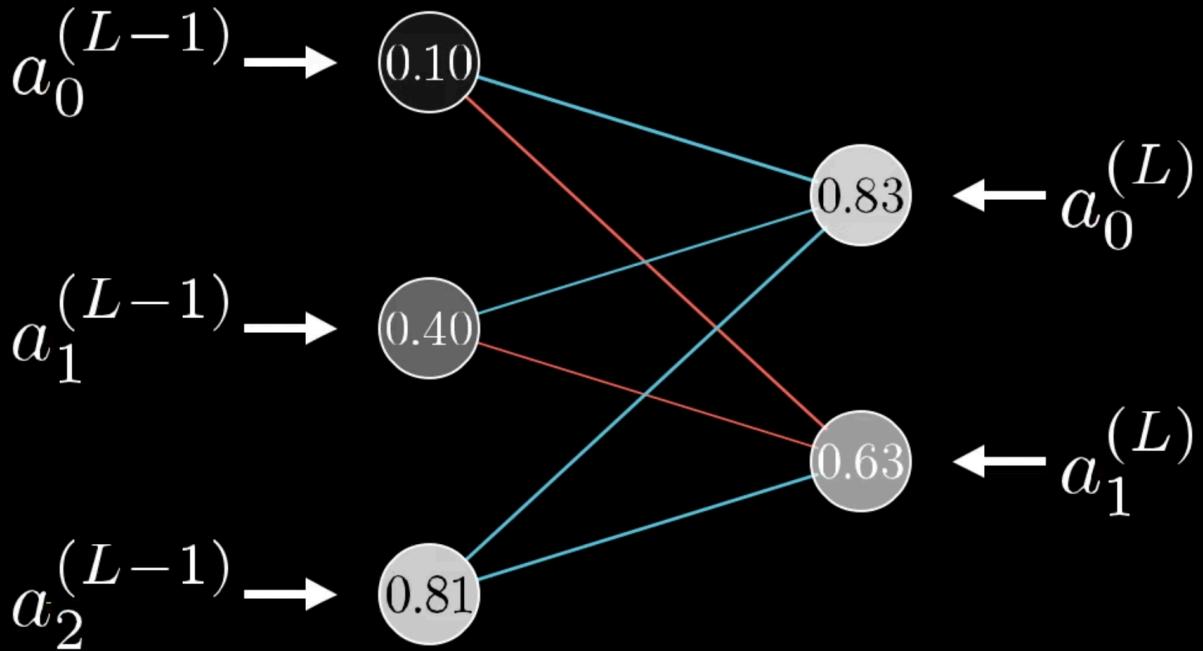
$$a^{(L)} = \sigma(z^{(L)})$$

$$\frac{\partial a^{(L)}}{\partial z^{(L)}} = \sigma'(z^{(L)})$$



$$\frac{\partial z^{(L)}}{\partial w^{(L)}} = a^{(L-1)}$$

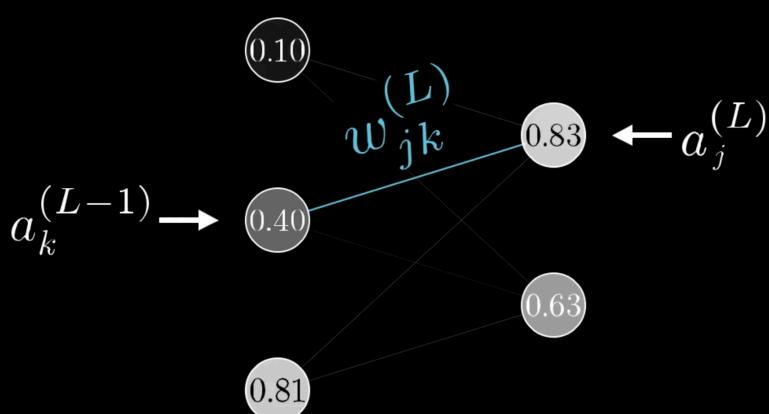
**Chain Rule (Calculus) and relevance to cost function in Neural networks (Backprop)(multi neuron)**



$$\frac{\partial C_0}{\partial w_{jk}^{(L)}} = \frac{\partial z_j^{(L)}}{\partial w_{jk}^{(L)}} \frac{\partial a_j^{(L)}}{\partial z_j^{(L)}} \frac{\partial C_0}{\partial a_j^{(L)}}$$

$$z_j^{(L)} = \dots + w_{jk}^{(L)} a_k^{(L-1)} + \dots$$

$$a_j^{(L)} = \sigma(z_j^{(L)})$$



$$C_0 = \sum_{j=0}^{n_L-1} (a_j^{(L)} - y_j)^2$$