

bp0

JOINT_2

JOINT_1

JOINT_0

CONTACT

1i-Sigmoid

MOTOR_0

-3.9

1.1

0o-Sigmoid

-1.1

-6.2

2o-Sigmoid

1.6

-5.2

MOTOR_1

-6.9

5.6

2.7

MOTOR_2

3-Sigmoid

MOTOR_0

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