

Object-Oriented Programming In Mechatronic Systems

Summer School

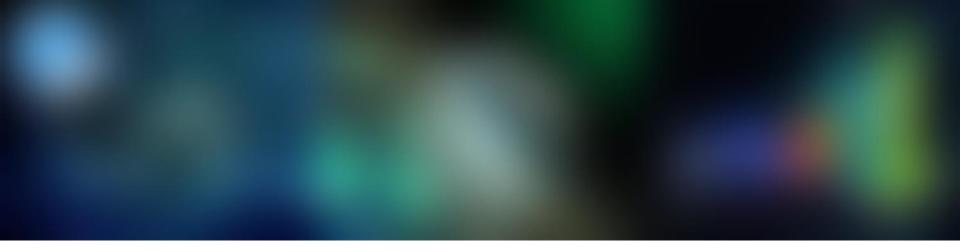
Final Project Preparations
Aachen, Germany, August 10th, 2018

Cybernetics Lab IMA & IfU Faculty of Mechanical Engineering RWTH Aachen University









Final Project







Final Project: Motivation

Mechatronic systems are everywhere!





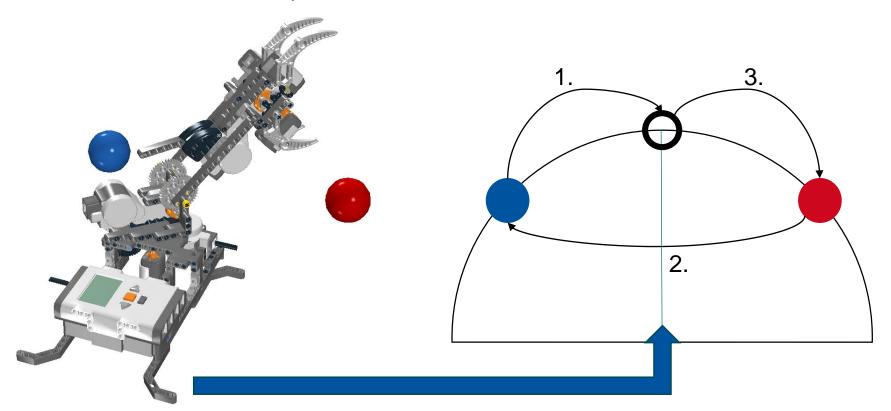




Final Project: Robot Programming

In the final project, you will program a real robot!

- We use LEGO Mindstorm robots
- The task: Find and swap colored balls with the robot









Final Project: Robot Programming

The robots have several elements



Touch sensor



Light sensor



Ultrasonic sensor



NXT (Brick): The robot's core



Ports



Buttons















After finishing the preparation, you can start with the final project!

- Find teams to work together
- Get a LEGO Mindstorms robot pack
- Follow the instructions to install required software & prepare your Laptop







Download the installation files from our website



https://sloumotion.github.io/opms_2018/

Module 7 - Introduction to Mechatronic Systems Topics

Excursus: Introduction to Mechatronic Systems

Material

Lecture Slides

Final Project

- Setup Instructions
- Installation Files
- Project Template



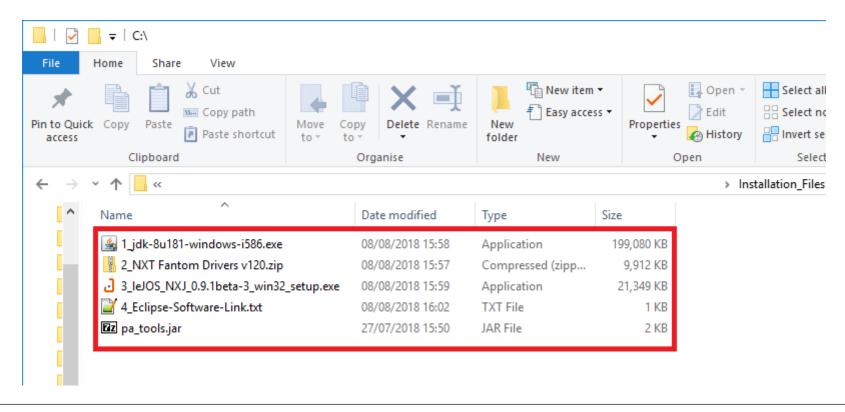




Download the installation files from our website



https://sloumotion.github.io/opms_2018/









1. Java SDK (32 bit)

- Run (double-click) 1_jdk-8u181-windows-i586.exe
- Follow the instructions

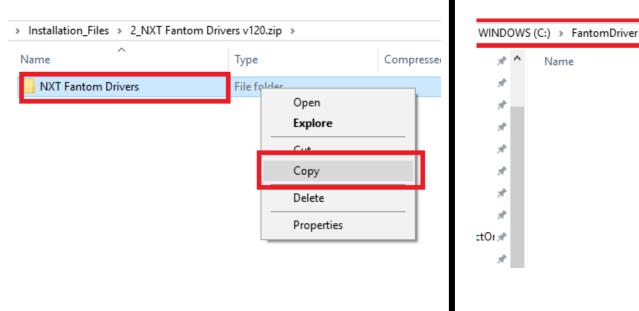


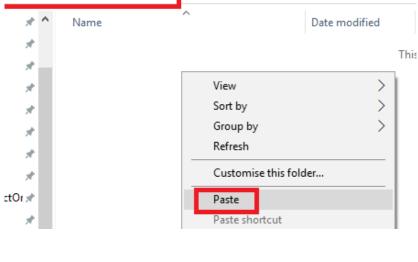




2. Extract the Fantom driver

- On your laptop, create the directory C:\FantomDriver\
- Enter (double-click) 2_NXT Fantom Drivers v120.zip
- Right-click the folder and copy it to the directory created above





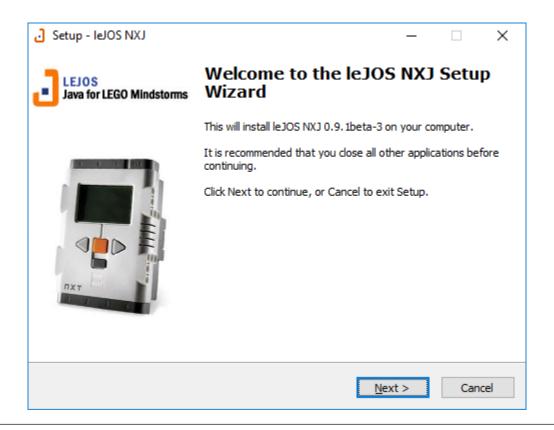






Install leJOS

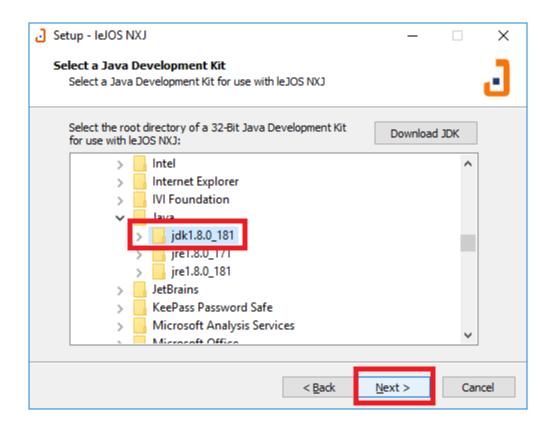
Run 3_leJOS_NXJ_0.9.1beta-3_win32_setup.exe







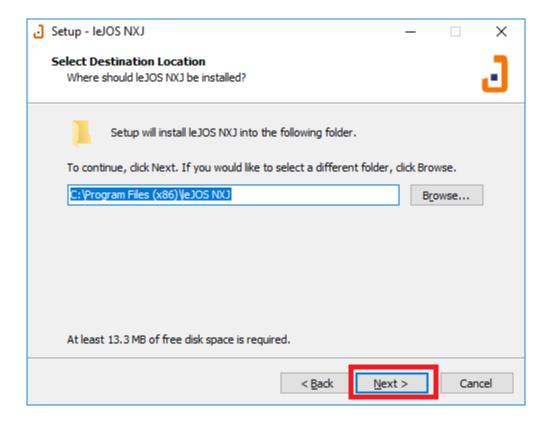








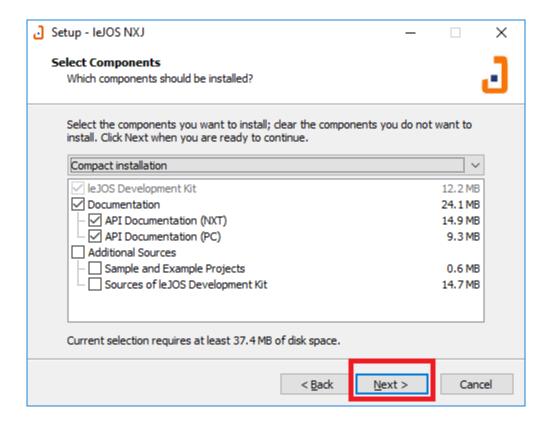








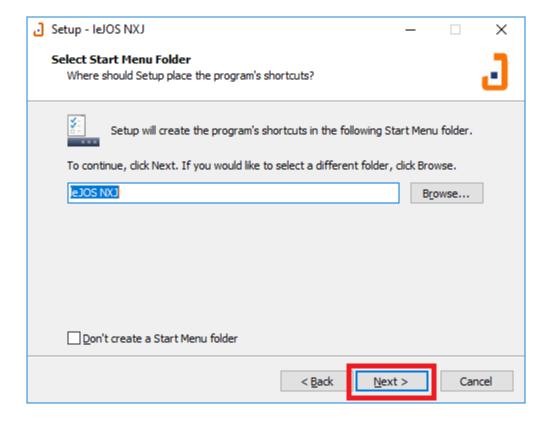








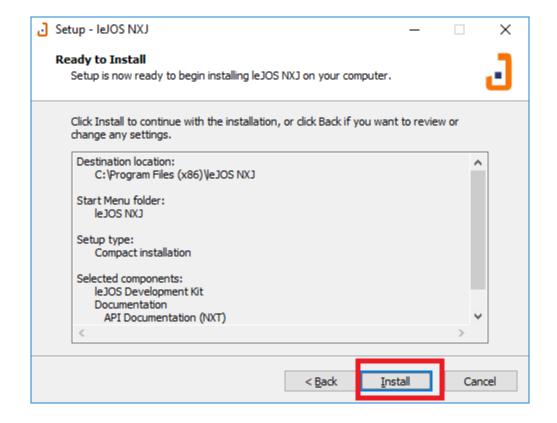
















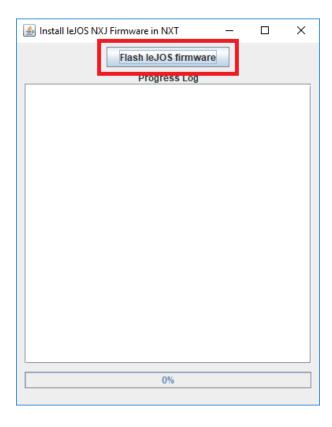












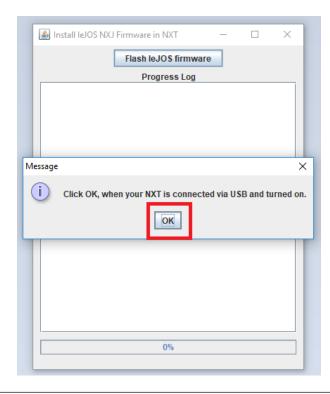






Prepare the robot: Flash leJOS

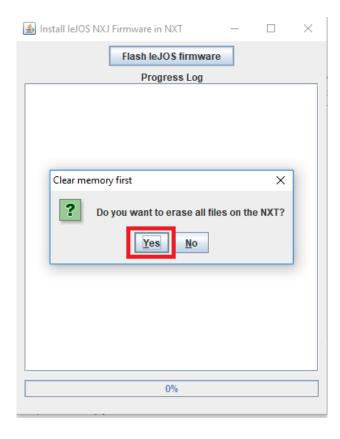
Connect the robot via USB & turn it on















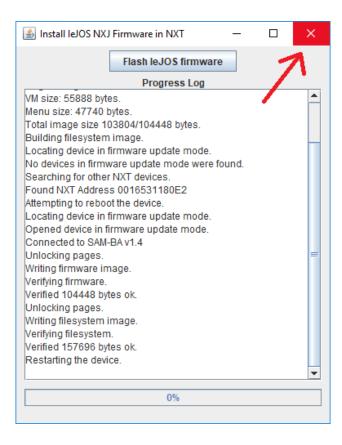








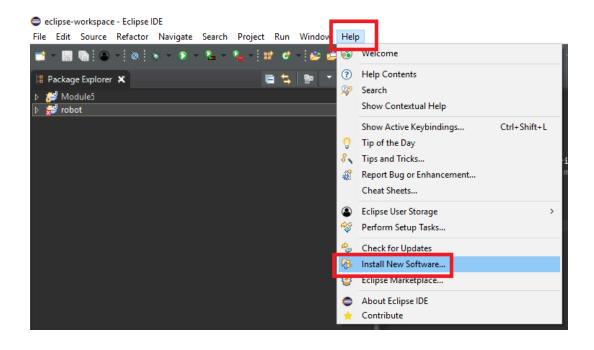












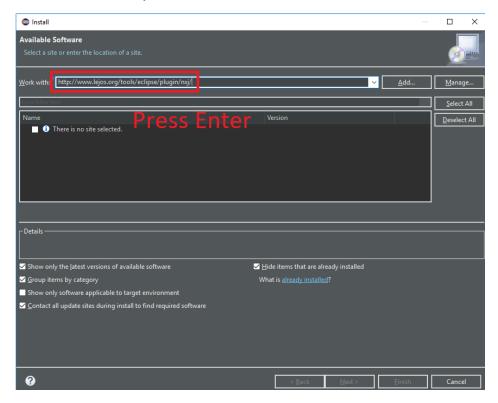






Install robot software in Eclipse

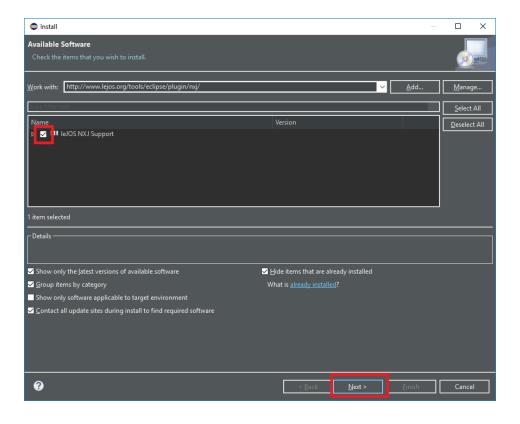
http://www.lejos.org/tools/eclipse/plugin/nxj/ (Copy this link from our website)







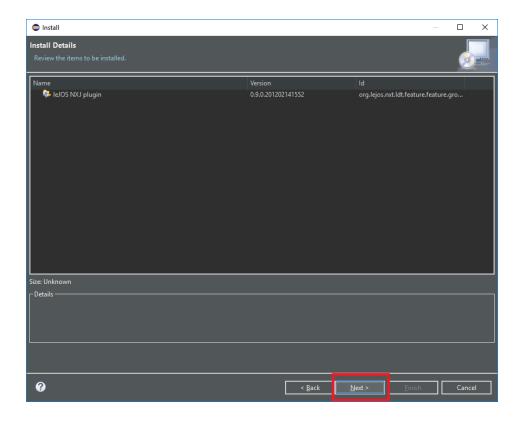








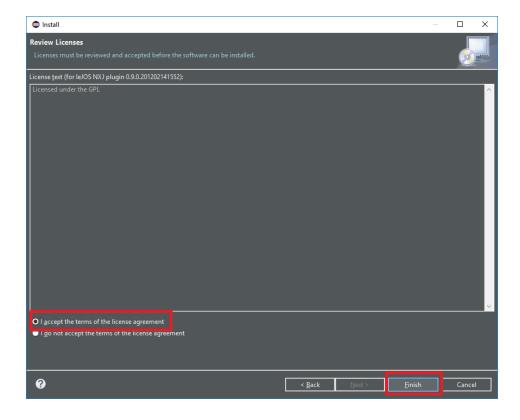








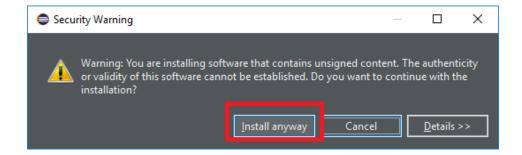








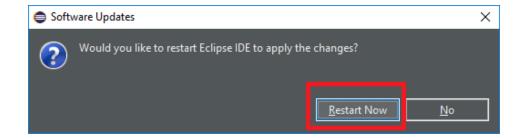








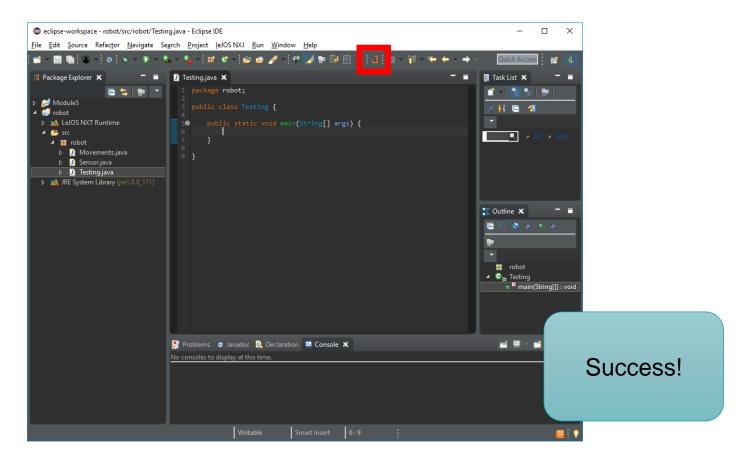










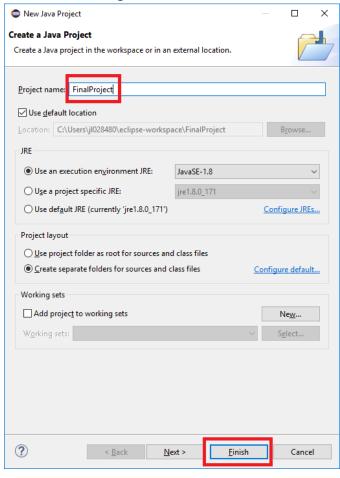








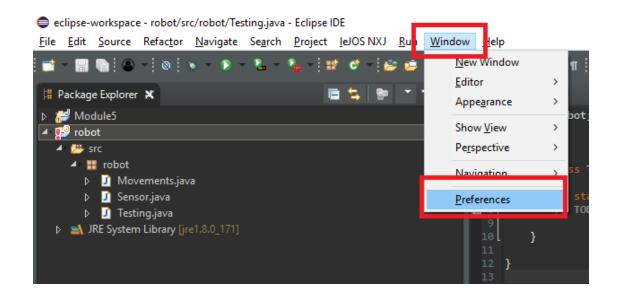
Create a Java project "FinalProject"







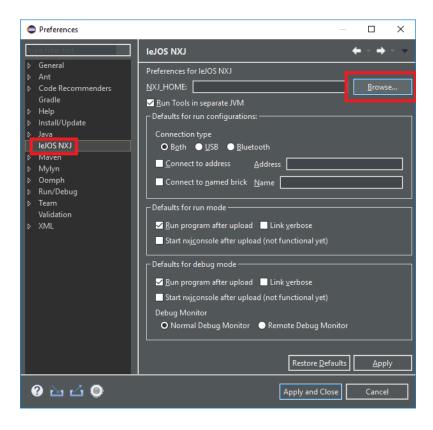








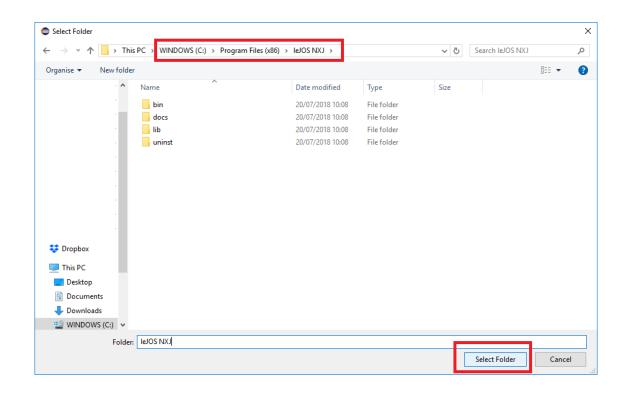








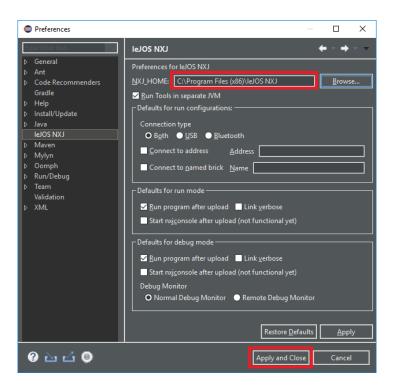


















Use leJOS to access the robot!

```
eclipse-workspace - robot/src/robot/Testing.java - Eclipse IDE

File Edit Source Refactor Navigate Search Project leJOS NXJ Run Window Help

Package Explorer X

Module5

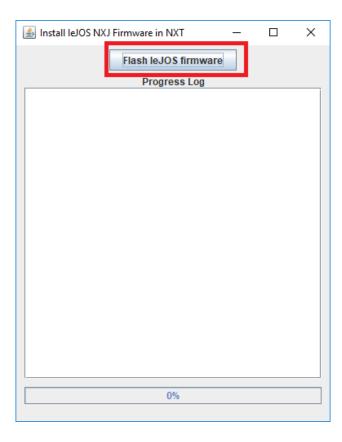
Modu
```







Use leJOS to access the robot!

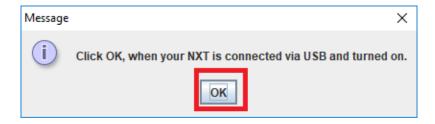








Use leJOS to access the robot!

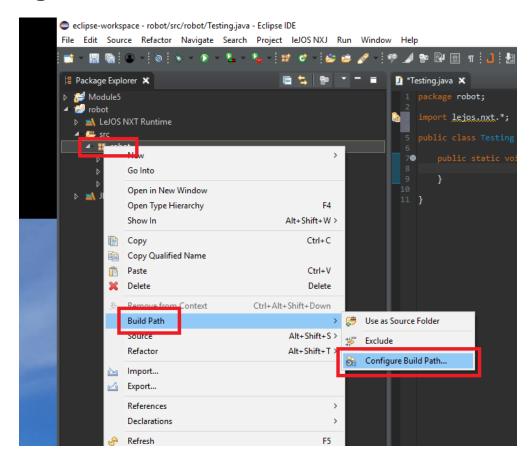


Beep-beep on the robot → Success!





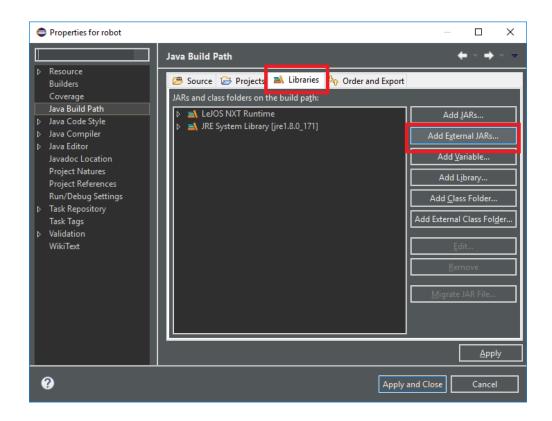








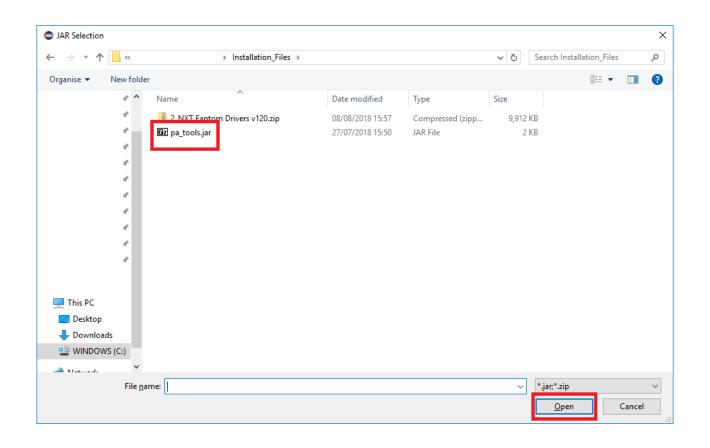








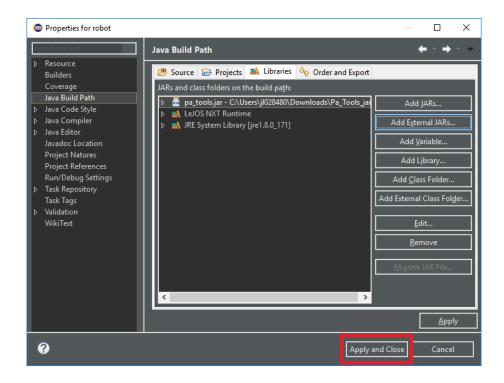










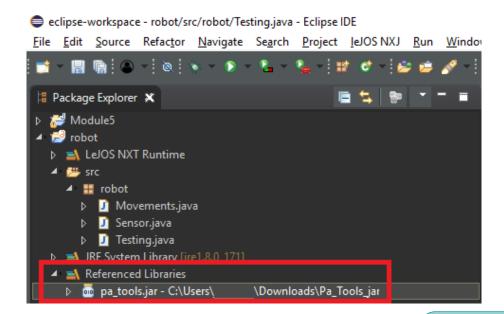








Final step: Settings



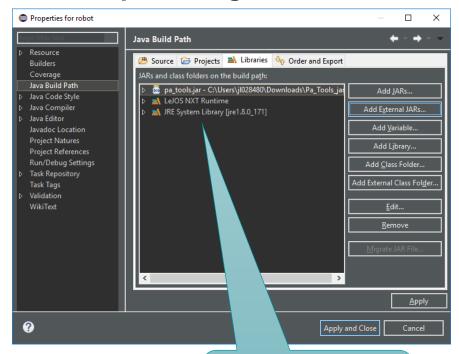
Success!



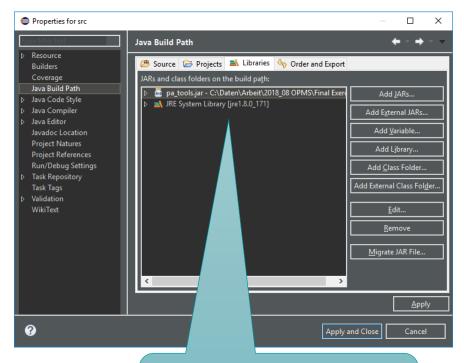




Final step: Settings



3 entries?
→ You are done!



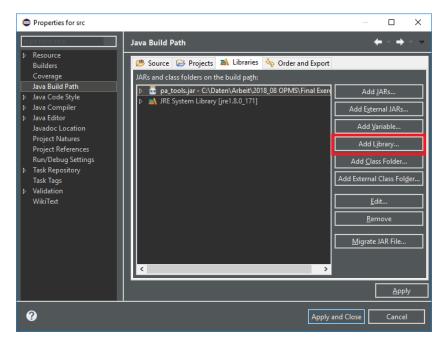
2 entries?

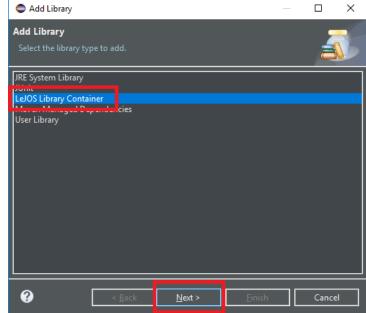
→ Just one more step







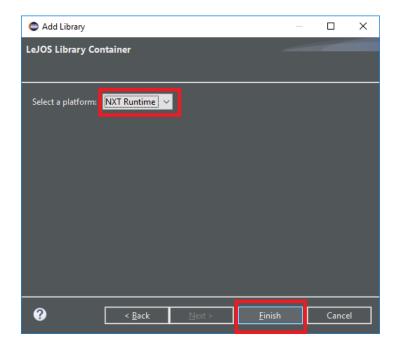


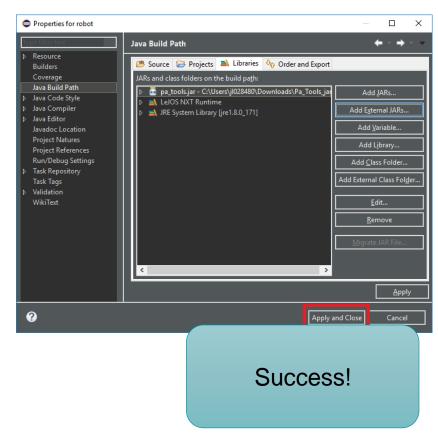




















Thank you very much!





