

Autonomous Multiple Cycle Farming in Space



Dominic Allard, Philip Bernhard, Joshua Calhoun, Courtney Cline, Giampiero Corsbie, Timothy Frazier, Kali Jenson, Bryce Johnson, & Christopher Millsap

Faculty Advisor(s): Dr. Elisabeth Kames, Dept. of Mechanical Engineering, & Dr. Philip Chan, Dept. of Computer Science, Florida Institute of Technology

OBJECTIVE

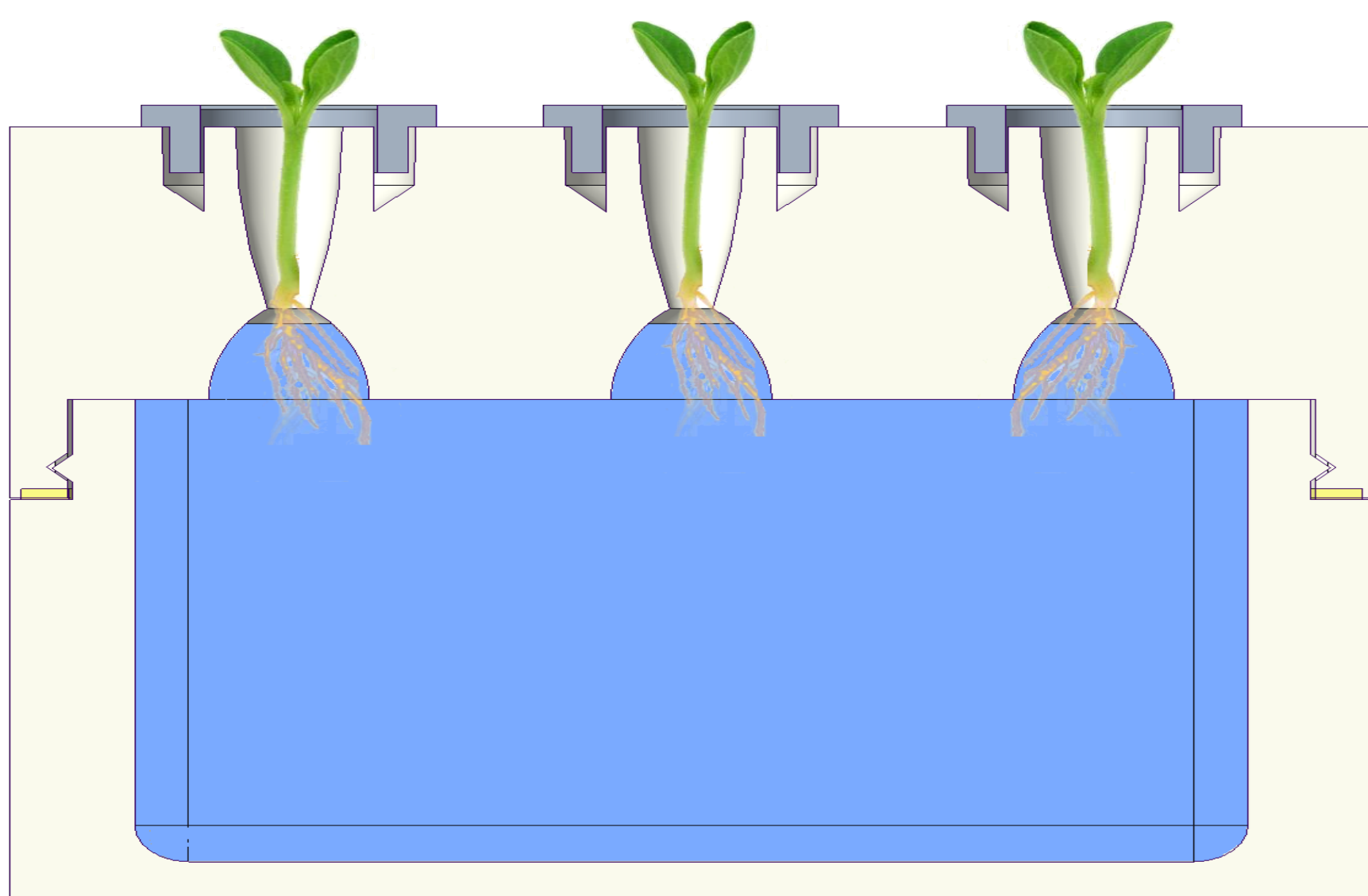
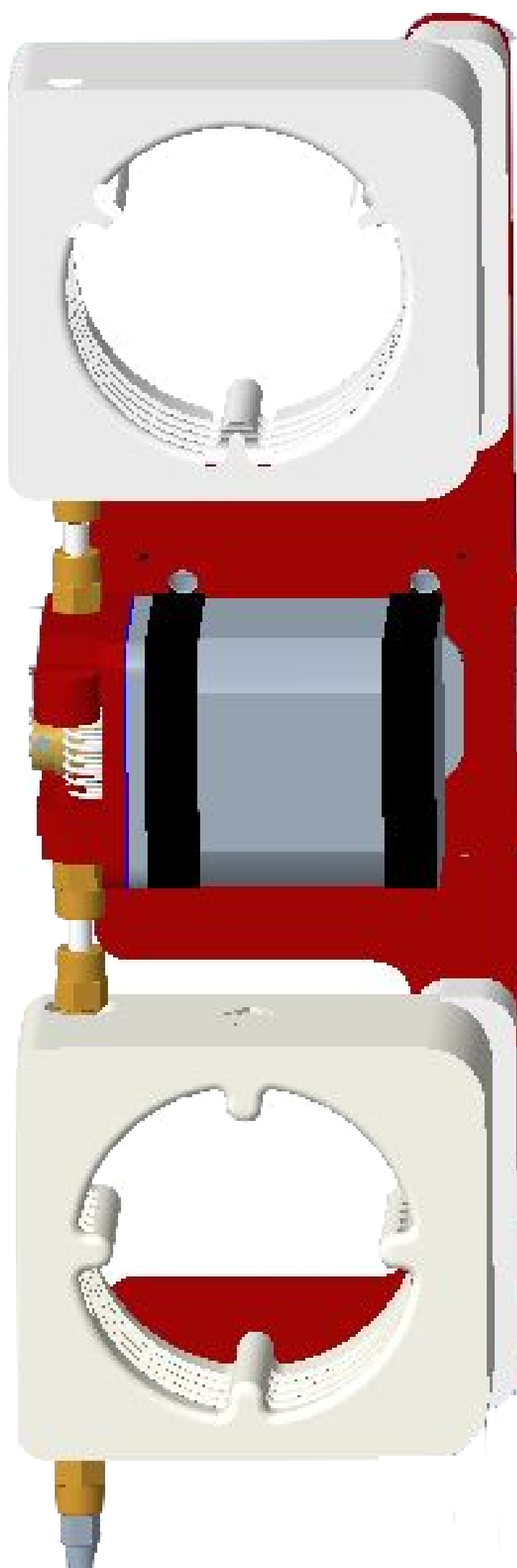
With NASA gearing up for the Artemis program and space exploration expanding rapidly to accommodate life beyond Earth, there exists a need to grow food autonomously that can support humans reliably, without compromising valuable time, or energy, from other missions in space. Therefore, students across multiple disciplines joined forces to build an Autonomous Multiple Cycle Farming System (AMCF) that grows plants autonomously through robotic functions with limited human interaction for multiple cycles.

DESIGN CRITERIA

To make an autonomous system that seeds, grows, and harvests plants, three major systems are needed: water delivery, planting system, and base. In conjunction with these three systems, there will need to be a power supply, lighting, nutrients, and plumbing for support. Design is in accordance with SSP 52000-IDD-ERP NASA ISS requirements.

SEEDING SYSTEM

The End Effector is capable of planting seeds in microgravity by forcing seeds out with filament driven by a stepper motor. The seeds are precisely placed into their respective tray hole.

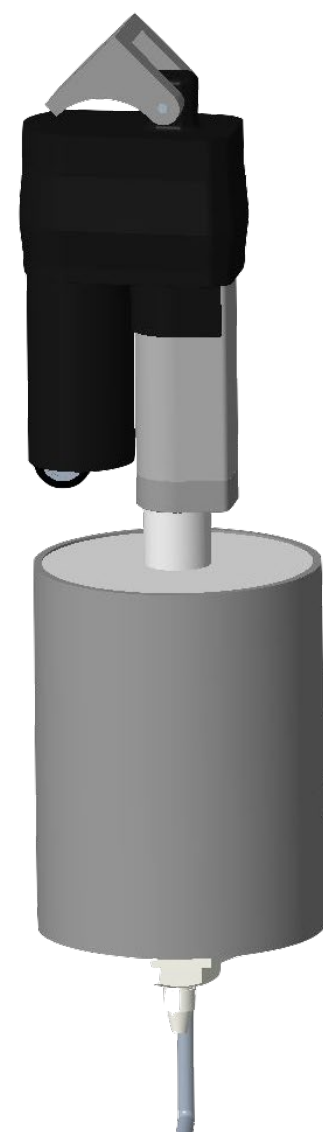


GROWTH CHAMBER DESIGN



WATER DELIVERY

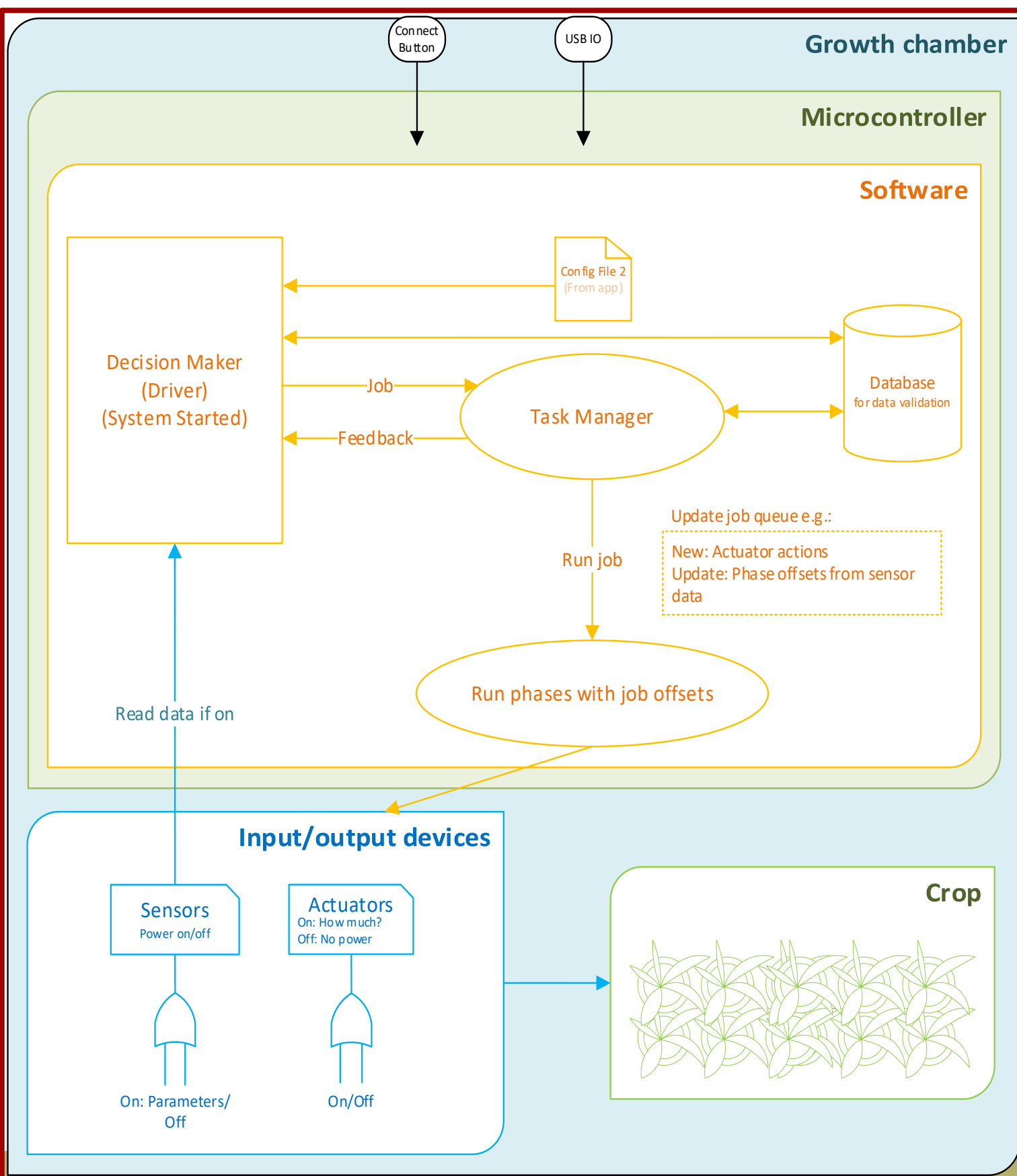
The water delivery system is comprised of an aluminum tank, that controls the intake and outflow of water nutrient solution with a linear actuated plunger while solenoid valves control the direction of the water through commands of the software.



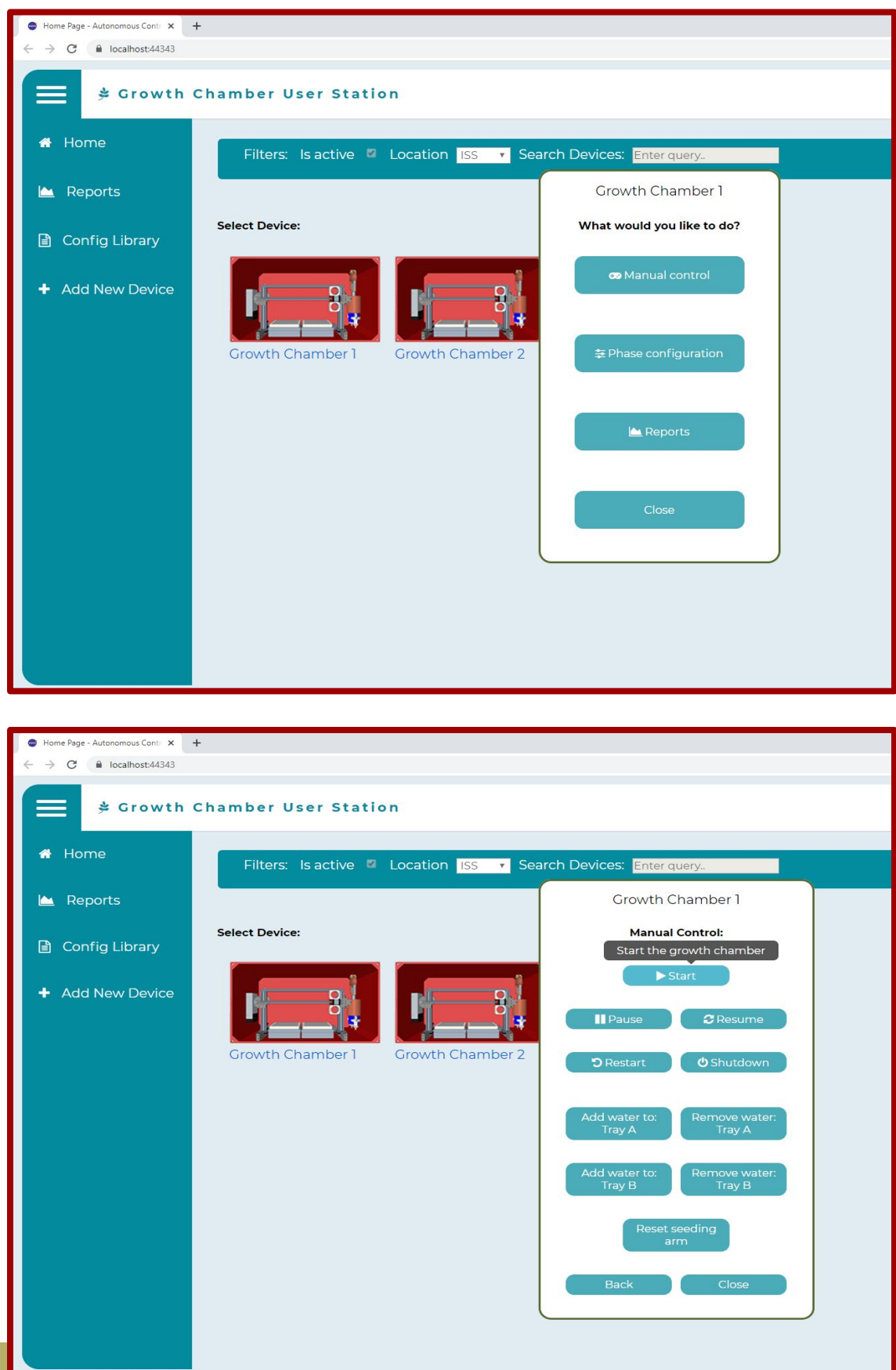
FARMING CHAMBER & USER STATION

The Growth Chamber **runs autonomously** based on user configurations and the User Station allows users to **manually control, update configurations, and view reports.**

CHAMBER



USER STATION



TESTING & VALIDATION

Multiple iterations of the tray were tested through growth cycles, in order to achieve the requirement of 70% harvest. The circuitry and software was also successfully tested over several weeks, proving the autonomous capabilities of the system.



COST ANALYSIS

| Component | Cost |
|--------------------------------|-----------|
| Planting System & End Effector | \$560.21 |
| Water Delivery & Tray | \$329.16 |
| Lighting & Electrical | \$83.95 |
| Miscellaneous & Case | \$341.74 |
| Total | \$1315.06 |

FUTURE PLANS

It is with great pleasure to announce that we have already submitted the Autonomous Multiple Cycle Farming System concept to two different NASA programs: “Technology Advancement Utilizing Suborbital Flight Opportunities ‘Tech Flights’,” as well as “Student Payload Opportunity with Citizen Science (SPOCS)” at Johnson Space Center.

ACKNOWLEDGEMENTS

We would like to thank Ralph F. Fritsche of NASA Kennedy Space Center who advised us since the beginning about important areas in the current industry. We would also like to thank Dr. Lisa Kames, and Dr. Markus Wilde of Florida Institute of Technology for their commitment on future endeavors.

