

# MATH425 Homework 1

Chris Camano: ccamano@sfsu.edu

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## 1 Problem 1:

Solve the following system:

$$u + v + w = -2$$

$$3u + 3v - w = 6$$

$$u - v + w = -1$$

expressed as an augmented matrix this system of linear equations is:

$$\begin{bmatrix} 1 & 1 & 1 & -2 \\ 3 & 3 & -1 & 6 \\ 1 & -1 & 1 & -1 \end{bmatrix}$$

the following matrix when reduced to row echelon form reveals the solution to the system of linear equations.

$$\begin{bmatrix} 1 & 1 & 1 & -2 \\ 3 & 3 & -1 & 6 \\ 1 & -1 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & \frac{3}{2} \\ 0 & 1 & 0 & -\frac{1}{2} \\ 0 & 0 & 1 & -3 \end{bmatrix}$$

implying that the solution to the system is that:

$$u = \frac{3}{2}$$

$$v = -\frac{1}{2}$$

$$w = -3$$

## 2 Problem 2:

Choose h and k such that the system below has (a) no solution, (b) a unique solution, and (c) many solutions. Give separate answers for each part.

$$x_1 + 3x_2 = 2$$

$$3x_1 + hx_2 = k$$

$$\begin{bmatrix} 1 & 3 & 2 \\ 3 & h & k \end{bmatrix}$$

(a) No solutions:

$$\mathbf{R2} = -3\mathbf{R1} + \mathbf{R2}$$

$$\begin{bmatrix} 1 & 3 & 2 \\ 3 & h & k \end{bmatrix} = \begin{bmatrix} 1 & 3 & 2 \\ 0 & h-9 & k-6 \end{bmatrix}$$

Thus the system is inconsistent when  $\mathbf{h=9}$  and  $k \neq 6$

(b) A unique solution

by the logic of the reduction in part a the system is consistent for all values of h not equal to 9 as there will be a pivot in row 2 if this is the case.

(c) Infinite solutions

By the logic of the reduction in part a the system is consistent with Infinite solutions when  $\mathbf{h=9}$  and  $\mathbf{k=6}$ .

### 3 Problem 3:

Consider the system below:

$$4x_1 + x_2 + 3x_3 = 9$$

$$x_1 - 7x_2 - 2x_3 = 12$$

$$8x_1 + 6x_2 - 5x_3 = 15$$

$$\begin{bmatrix} 4 & 1 & 3 & 9 \\ 1 & -7 & -2 & 12 \\ 8 & 6 & -5 & 15 \end{bmatrix}$$

(a) Column-space view: Find the vectors  $v_1, v_2, v_3$  and write the system as a vector equation:

$$x_1 v_1 + x_2 v_2 + x_3 v_3 = \begin{bmatrix} 9 \\ 12 \\ 15 \end{bmatrix}$$

$$x_1 \begin{bmatrix} 1 \\ -7 \\ 6 \end{bmatrix} + x_2 \begin{bmatrix} 3 \\ -2 \\ -5 \end{bmatrix} + x_3 \begin{bmatrix} 3 \\ -2 \\ -5 \end{bmatrix} = \begin{bmatrix} 9 \\ 12 \\ 15 \end{bmatrix}$$

(b) Row-space view: Find the vectors  $w_1, w_2, w_3$  and  $x$  such that the system is equivalent to:

$$w_1 \cdot x = 9$$

$$w_2 \cdot x = 12$$

$$w_3 \cdot x = 15$$

$$\begin{aligned}w_1 &= [4, 1, 3] \\w_2 &= [1, -7, -2] \\w_3 &= [8, 6, -5]\end{aligned}$$

$$\begin{aligned}[4, 1, 3] \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_2 \end{bmatrix} &= 9 \\[1, -7, -2] \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_2 \end{bmatrix} &= 12 \\[8, 6, -5] \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_2 \end{bmatrix} &= 15\end{aligned}$$

Let  $x$  be the following solution to the system to validate this claim. Solution obtained

using row operations.  $\begin{bmatrix} \frac{328}{121} \\ \frac{-14}{11} \\ \frac{-23}{121} \end{bmatrix}$

$$\begin{aligned}[4, 1, 3] \cdot \begin{bmatrix} \frac{328}{121} \\ \frac{-14}{11} \\ \frac{-23}{121} \end{bmatrix} &= 9 \\[1, -7, -2] \cdot \begin{bmatrix} \frac{328}{121} \\ \frac{-14}{11} \\ \frac{-23}{121} \end{bmatrix} &= 12 \\[8, 6, -5] \cdot \begin{bmatrix} \frac{328}{121} \\ \frac{-14}{11} \\ \frac{-23}{121} \end{bmatrix} &= 15\end{aligned}$$

## 4 Problem 4:

Determine if  $\mathbf{b}$  is a linear combination of the vectors formed from the columns of the matrix  $\mathbf{A}$ .

$$\mathbf{A} = \begin{bmatrix} 1 & -2 & -6 \\ 0 & 3 & 6 \\ 1 & -2 & 5 \end{bmatrix}, \mathbf{b} = \begin{bmatrix} 11 \\ -5 \\ 9 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & -6 & 11 \\ 0 & 3 & 6 & -5 \\ 1 & -2 & 5 & 9 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & \frac{241}{33} \\ 0 & 1 & 0 & \frac{-43}{33} \\ 0 & 0 & 1 & \frac{-2}{11} \end{bmatrix}$$

A unique solution exists for the given existence problem therefore yes  $\mathbf{b}$  is a linear combination of the vectors in  $\mathbf{A}$

## 5 Problem 5

Let  $f(z) = az + b$  where  $z \in \mathbb{C}$ . Find  $a$  and  $b$  if  $f(z)$  translates  $z$  one unit up and one unit to the right, rotates the result by  $\frac{\pi}{2}$  clockwise and scales the resulting complex number by 2.

Since the input value  $z$  is rotated around clockwise by  $\frac{\pi}{2}$  this means that part of the coefficient must be  $e^{-\frac{\pi}{2}i}$  so to start we have:

$$f(z) = e^{-\frac{\pi}{2}i}z + b$$

Next we must scale the complex number by 2 modifying the function to be

$$f(z) = 2e^{-\frac{\pi}{2}i}z + b$$

Finally to move each output up one and one to the right we must add  $1 + i$  to the result for a final description of

$$f(z) = 2e^{-\frac{\pi}{2}i}z + (1 + i)$$