

Part 4: Sampling

Building a GPS receiver from scratch

Chris Doble

1 Hardware

2 Parameters

- Centre frequency
- Bandwidth
- Sampling rate

3 I/Q samples

- Definition
- Different frequencies
- Complex values

1 Hardware

2 Parameters

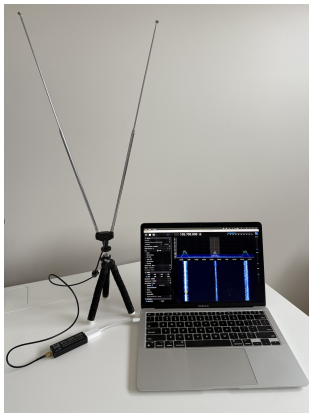
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Hardware

- Software defined radio (SDR) dongle





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$$f = 1575.42 \text{ MHz}$$

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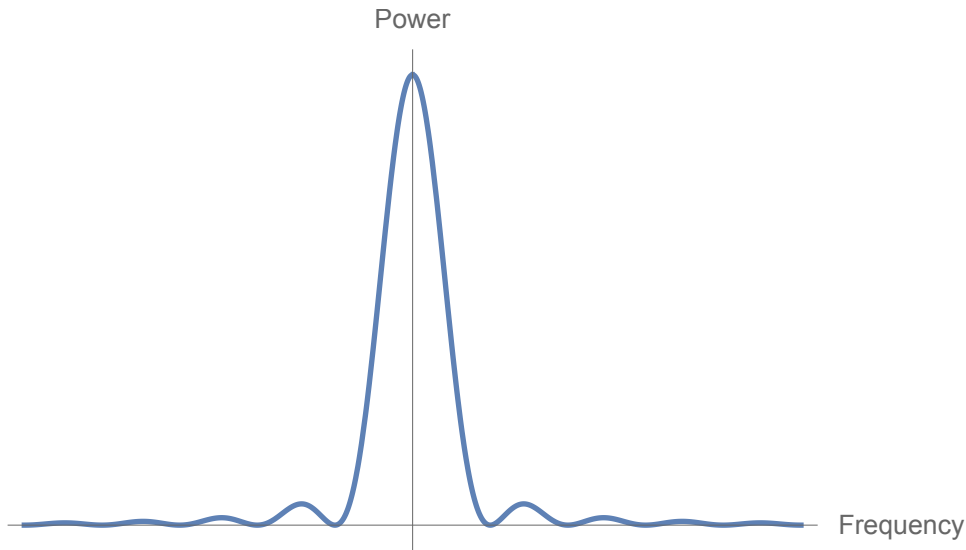
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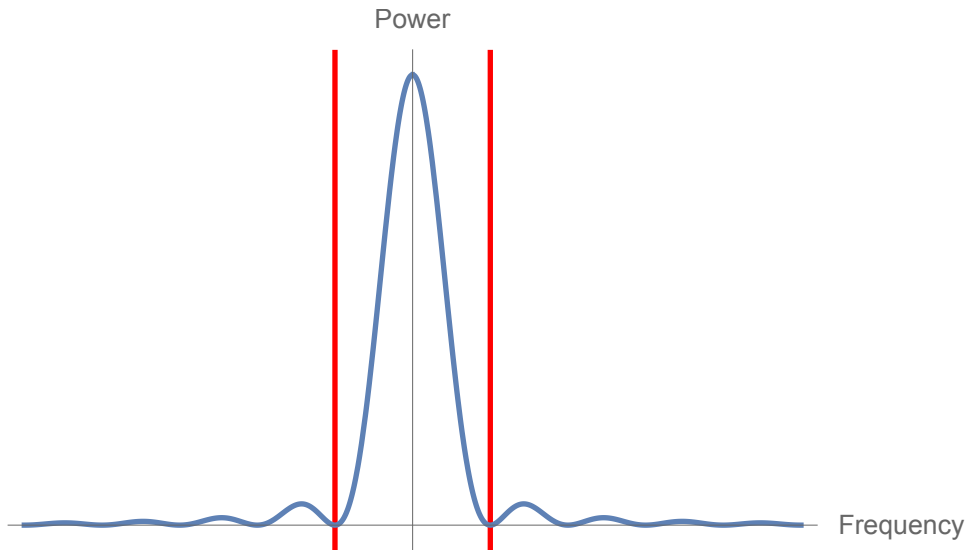
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The power spectrum of BPSK



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$$B = 2.046 \text{ MHz}$$

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$$f_{L1} = 1575.42 \text{ Mhz} \approx 1.6 \text{ GHz}$$

The Nyquist-Shannon sampling theorem

If the maximum frequency contained within a signal is f_{\max} ,
then the signal can be determined from its samples
if the sampling rate is greater than $2f_{\max}$.

$$f_{\max} = f + \frac{B}{2}$$

$$\begin{aligned} f_{\max} &= f + \frac{B}{2} \\ &= 1575.42 \text{ MHz} + \frac{2.046 \text{ MHz}}{2} \end{aligned}$$

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$$\begin{aligned}f_{\max} &= f + \frac{B}{2} \\&= 1575.42 \text{ MHz} + \frac{2.046 \text{ MHz}}{2} \\&= 1576.443 \text{ MHz} \\&\approx 1.6 \text{ GHz} \\f_s &= 2f_{\max} \\&\approx 3.2 \text{ GHz}\end{aligned}$$

What is the RTL-SDRs sample rate?

The maximum sample rate is 3.2 MS/s (mega samples per second). However, the RTL-SDR is unstable at this rate and may drop samples. The maximum sample rate that does not drop samples is 2.56 MS/s, however some people have had luck with 2.8MS/s and 3.2 MS/s working well on some USB 3.0 ports.

<https://www.rtl-sdr.com/about-rtl-sdr/>

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- $f_{\max} = 1.023 \text{ MHz} \Rightarrow f_{\text{Nyquist}} = 2.046 \text{ MHz} \Rightarrow$ within SDR dongle's capabilities

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$$f(t) = A(t) \cos(2\pi ft + \phi(t))$$

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$$\begin{aligned} f(t) &= A(t)[\cos(2\pi ft) \cos(\phi(t)) + \cos(2\pi ft + \pi/2) \sin(\phi(t))] \\ &= A(t) \cos(\phi(t)) \cos(2\pi ft) + A(t) \sin(\phi(t)) \cos(2\pi ft + \pi/2) \end{aligned}$$

The definition of I/Q samples

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where $I(t) = A(t) \cos(\phi(t))$ and $Q(t) = A(t) \sin(\phi(t))$.

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$$\begin{aligned} f(t) &= A \cos(2\pi f_2 t) \\ &= A \cos(2\pi(f_1 + \Delta f)t) \\ &= A \cos(2\pi f_1 t + 2\pi \Delta f t) \end{aligned}$$

Sampling a signal of a different frequency

$$\begin{aligned}f_1 \\f_2 &= f_1 + \Delta f \\f(t) &= A \cos(2\pi f_2 t) \\&= A \cos(2\pi(f_1 + \Delta f)t) \\&= A \cos(2\pi f_1 t + 2\pi \Delta f t) \\&= A \cos(2\pi f_1 t + \phi(t))\end{aligned}$$

where $\phi(t) = 2\pi \Delta f t$.

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$$\begin{aligned}\hat{D}_i(t)P\hat{R}N_i(t) &= \pm 1 \\ z\hat{D}_i(t)P\hat{R}N_i(t) &= z(\pm 1) \\ &= Ae^{j\phi}(\pm 1) \\ &= \pm Ae^{j\phi}\end{aligned}$$

Recap

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 - Pairs of numbers that describe the signal
 - Often expressed as a single complex number
 - If the signal has a different frequency, the I/Q samples will continually rotate