

# Christopher Xie

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CONTACT INFORMATION	<i>E-mail:</i> <a href="mailto:chrisdxie@gmail.com">chrisdxie@gmail.com</a> , <a href="mailto:chrisxie@cs.washington.edu">chrisxie@cs.washington.edu</a> <i>Website:</i> <a href="https://chrisdxie.github.io/">https://chrisdxie.github.io/</a> <i>Phone:</i> (510) 693-0502
RESEARCH INTERESTS	Statistical Machine Learning, Probabilistic Inference
EDUCATION	<b>Ph.D.</b> , University of Washington September 2015 - Present Computer Science and Engineering  <b>Bachelor of Science</b> , University of California, Berkeley May 2015 Electrical Engineering and Computer Science, GPA: 3.87/4.0
RESEARCH EXPERIENCE	<b>Graduate Research Assistant</b> , University of Washington September 2015 - Present Advisor: <i>Emily Fox</i> <ul style="list-style-type: none"><li>Modifying Stochastic Variational Inference for lengthy time series models including Hidden Markov Models and Autoregressive Hidden Markov Models.</li></ul> <b>Undergraduate Research Assistant</b> , University of California, Berkeley June 2014 - May 2015 Advisor: <i>Pieter Abbeel</i> <ul style="list-style-type: none"><li>Explored the use of Optimism-Driven Exploration with Model Predictive Control in order to learn system dynamics on the fly while performing specific tasks.</li><li>Combined globally optimal planners with generic boundary value problem solvers implemented with Sequential Convex Programming to solve optimal motion planning for arbitrary dynamics.</li></ul> Advisor: <i>Stuart Russell</i> September 2013 - June 2014 <ul style="list-style-type: none"><li>Used Contingent Bayesian Networks to attack the problem of Relation Extraction. Devised a proposal distribution for Metropolis-Hastings Markov Chain Monte Carlo inference for our model of the world. Performed inference using probabilistic programming language BLOG.</li></ul>
PUBLICATIONS	Christopher Xie, Jur van den Berg, Sachin Patil, Pieter Abbeel. Toward Asymptotically Optimal Motion Planning for Kinodynamic Systems using a Two-Point Boundary Value Problem Solver. <i>Proc. IEEE Int. Conf. on Robotics and Automation - ICRA, 2015.</i>
PUBLICATIONS UNDER REVIEW	Christopher Xie, Teodor Moldovan, Sergey Levine, Sachin Patil, Pieter Abbeel. Model-based Reinforcement Learning with Parametrized Physical Models and Optimism-Driven Exploration. <i>Proc. IEEE Int. Conf. on Robotics and Automation - ICRA, 2016.</i>
TEACHING EXPERIENCE	<b>University of California, Berkeley</b> , Berkeley, CA  <i>Teaching Assistant</i> , CS189: Introduction to Machine Learning January - May, 2015 Taught by Professor Peter Bartlett and Alyosha Efros.  <i>Teaching Assistant</i> , CS189: Introduction to Machine Learning January - May, 2014 Taught by Professor Jitendra Malik and Alyosha Efros.
PROFESSIONAL EXPERIENCE	<b>Google</b> , Mountain View, CA May - August, 2015 <i>Software Engineering Intern</i> Worked on Google Glass (now known as Project Aura).

**eBay, Inc.**, San Jose, CA

May - August, 2013

*Applied Research Intern, Trust Science*

Trained neural network and decision tree models to classify fraudulent activity using features extracted from clickstream data only. Optimized them to prevent loss from fraud.

**International Computer Science Institute**, Berkeley, CA

April 2012 - April 2013

*Student Researcher, Artificial Intelligence Group*

FrameNet: Developed software to collect crowdsourced data from Amazon Mechanical Turk.

MetaNet: Collaborated with linguists to create a Russian metaphor search using parsed Russian sentences to extract verb-noun relations and clustering algorithms to search for potential new metaphors.

HONORS AND  
AWARDS

CSE Educators Endowed Fellowship in Computer Science & Engineering (UW)

Eta Kappa Nu Membership

Student Member of IEEE

SKILLS

Proficient in Python, Matlab, C++, Java

Skilled at Hadoop, Hadoop Streaming, Hive, bash shell scripting/automation

HOBBIES

- Taekwondo - Received medals from many national and international tournaments. Member of the Alternate Junior National Team in 2010.
- Music - Played keyboard in multiple bands, performed all over the Bay Area.