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DB-88E6218/RD-88E6208

Rapid Development Kit Getting Started Guide

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Getting Started Guide

Document Status			
Advanced Information	This document contains design specifications for initial product development. Specifications may change without notice. Contact Marvell Field Application Engineers for more information.		
Preliminary Information	This document contains preliminary data, and a revision of this document will be published at a later date. Specifications may change without notice. Contact Marvell Field Application Engineers for more information.		
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Section 1. Introduction

Thank you for purchasing the Marvell® Rapid Development Kit for the DB-88E6218 and RD-88E6208 boards. This kit is designed to help reduce the time and effort required by users in bringing to market a product with industry-leading features and robustness. A careful look at what we have to offer in this kit will help you understand the benefits of Marvell's software offering. This particular guide helps you understand the tools you have at your disposal. It introduces you to the capabilities of each software component in the Rapid Development Kit. It also describes how to build and install new software.

Use of the source code, binaries, and other deliverables provided in the Rapid Development Kit first requires acceptance of the *Marvell Software License agreement* provided with the kit.

In addition to the VxWorks BSP for the DB-88E6218 board, the kit also has demo BSPs in VxWorks and uClinux for the RD-88E6208 platform.

Copy the contents of the Rapid Development Kit CD to your computer according to the following instructions:

* * * * * * * * * * * * * * * * * * * *			
BSP	Instructions		
DB-88E6218 VxWorks			
RD-88E6208 uClinux Demo	Copy the contents of the RD-88E6208\Demo-Linux directory to your Linux PC. Read the readme.txt file as well as the uClinux installation guide (SW_uClinuxInstallationGuide.pdf) found in the following directory of your CD: RD-88E6208\Demo-linux\docs.		
RD-88E6208 VxWorks Demo	Copy the contents of the RD-88E6208\Demo-VxWorks directory on the CD to the following directory for VxWorks: (WINDBASE)\target\config\RD-88E6208 Read the readme.txt file found at (WINDBASE)\target\config\RD-88E6208\Doc. It explains the layout of the BSP directory and also provides details on setting up the network configuration and loading multiple interfaces once the system has been brought up.		

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Section 2. Rapid Development Kit Components

The components of the Rapid Development Kit are as follows. If any of these components are missing, contact your Marvell Field Application Engineer:

Switch API This API is the user-level interface to the switch. The API is developed to support

applications such as Quality of Service, NAT, and routing, without the developer hav-

ing to know details of the registers and tables on the hardware

The source code for the Switch API and driver can be found in **Switch Source Code**

'(WINDBASE)\target\config\DB-88E6218\Doc\Sample Switch Soft-

ware\QDDriver1.3e'.

Along with the driver and the API for the switch are sample source files that can be used to quickly start your development efforts. These are provided for reference only.

The source files utilize the switch APIs. The relevant files can be found in (WINDBASE)\target\config\DB-88E6218\Doc\Sample Switch Software

\QDDriver1.3e\Sample'

Switch Driver This software layer receives requests from the Switch API and invokes the low-level

SMI layer drivers to access hardware registers.

SOHO Product Software Architecture

Specification

This document explains the functionality of the switch. In particular, it explains the Marvell API layer, the driver layer, as well as a BSP-dependant SMI driver component. For further details see the SOHO Product Software Architecture Specification

provided with this kit.

UniMAC Driver This component allows customers to access the underlying hardware interfaces

through a single API for a unified 802.3 MAC device. The actual physical interface is transparent to the user. This also allows for dynamic configuration and movement of the different ports between different networks (subnets). The UniMAC driver is OSindependent. For further details see the UniMAC User Guide, which is a part of the

Rapid Development Kit.

This document explains the functionality of the UniMAC driver and API. For further **UniMAC User Guide**

details see the UniMAC User Guide (MV-S800058-00) provided with this kit in

'(WINDBASE)\target\config\DB-88E6218\Doc\'.

A complete BSP for VxWorks is provided for the DB-88E6218 board. This BSP is **BSP for DB-88E6218**

based on Tornado 2.1.1 for ARM.

Demo BSPs for RD-88E6208

Demonstration quality BSPs are provided for the RD-88E6208 boards, for both VxWorks and uClinux operating systems. The Tornado version to use is Tornado

2.1.1 for ARM.

BSP Reference Manuals

This document explains the functionality of the BSP. For further details see the BSP

User Manual provided with this kit in

'*(WINDBASE)\target\config\DB-*88E6218\Doc\'. - VxWorks for DB88E6218,

from root...' \RD-88E6208\Demo-linux\Docs' - uClinux for RD-88E6208

'(WINDBASE)\target\config\RD-88E6208\Doc\' - VxWorks for RD-88E6208

Rapid Development Kit This document. **Getting Started Guide**

If any of these components are missing, contact your Marvell Field Application Engineer.

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Section 3. Bringing Up the System

3.1 VxWorks

Install the BSP under the WINDBASE/target/config directory of your PC. This PC will function as the Windows Host system that talks to the DB-88E6218/RD-88E6208 board or Target system. This BSP is released in a zip file. Unzip the file to receive the BSP.

The root directory contains the following sub-directories:

VxWorks_Images Use these images to install a pre-built image and debug your system.

Doc Includes:

- BSP User Manual
- readme.txt
- License agreement
- UniMAC User Guide
- Switch User Guide
- Switch Source code

QDdry Includes:

- Internal switch library QDLib.a
- Directory under which the switch driver header files are located

To bring up the target system using the pre-built image supplied along with the Rapid Development Kit, do the following:

- Set up the host system so it has an IP address of 10.4.0.250.
 (On startup the boot code searches for this IP address to download an image.) You can change this via the armboot boot program.
- 2. Make sure the TFTP server is running on the host system.
- Connect through the serial interface and set the baud rate to 38400.
- 4. At the ARMBoot Application prompt (serial interface) type: ARMboot-> tftp 100000 vxworks.st_rom.bin When the prompt returns with Done, type: ARMboot-> go 100000 This starts the VxWorks image on the target with IP address of 10.2.50.127



Note

For further details see section 4.3 (System Software Preparation) of the BSP User Manual supplied with the Rapid Development Kit.

3.2 uCinux

See the SW_uClinuxInstallationGuide.pdf file for instructions. This can be found in the following directory on your CD:

RD-88E6208\Demo-linux\Docs

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Section 4. Build Method

4.1 VxWorks

To build a new VxWorks image do the following:

- 1. Make sure you have Tornado 2.1.1 for ARM installed on your system.
- 2. Open up a DOS command prompt.
- Go to the BSP root directory under WINDBASE/target/config. This has your target system's BSP-related files.
- Make the modifications to the files that you wish to change.
- Run torvars.bat from your BSP directory to set up the environment variables before you build.
 The torvars.bat file is located in your Tornado build tree under '(WINDBASE)/host/x86-win32/bin/torvars.bat'
- Type make clean followed by make <imagetype> at the DOS command prompt. You can specify the imagetype you require. For example, make vxWorks.st_rom makes a compressed standalone VxWorks image (with target shell and symbol table).

For further details see the VxWorks Programmers Guide.

4.2 uClinux

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See the SW_uClinuxInstallationGuide.pdf file for instructions. This can be found in the following directory on your CD:

RD-88E6208\Demo-linux\Docs



Section 5. Revision History

Table 1: Revision History

Revision #	Date	Comments
А	13 February 2003	Initial Release

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