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## **EE 445L – Lab 9:**

# **Temperature Data Acquisition System**

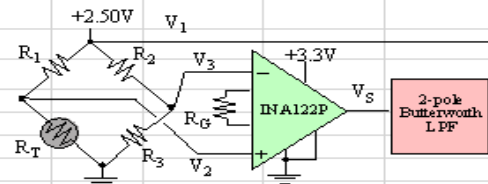
### **0.0: Objectives:**

We will further study the concepts of ADC conversion and the Nyquist Theorem. Specifically, we plan to develop a temperature measurement system that uses a thermistor. We plan to analyze different performance measurements of the system including precision, resolution, and accuracy. To realize a working system, we will also have to understand some general concepts of analog circuit design. Our circuit will require the use of an operational amplifier and instrumentation amplifier. We need to calibrate these analog circuits in a way that will allow for the most accurate temperature measurements in the overall system. That means we also must gain a deep understanding of how these integrated circuits work and the parameters associated with them.

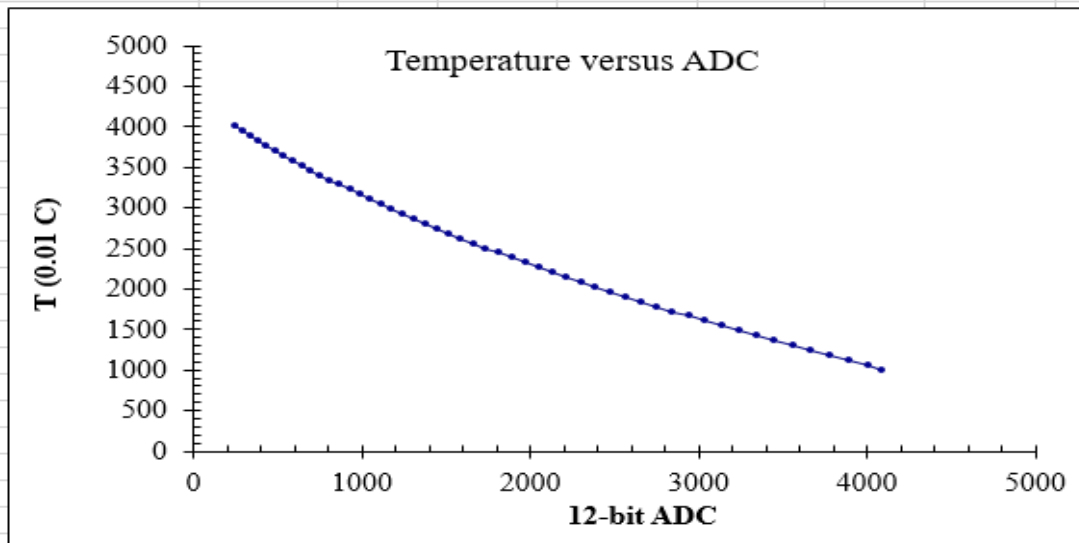
## 1.0: Sensor Calibration:

Here is a snapshot of our calibration Excel sheet.

1	1) Enter two point calibration	Thermistor interface design process by Jonathan Valvano						
2		R(k $\Omega$ )	T( $^{\circ}$ C)					
3	First Point=	95.8	25					
4	Second Point=	69	34					
5	H1=	0.0002995			$T=1/(H0+H1\ln(R))-273.15$	$1/(T+273.15)=H0+H1\ln(R)$		
6	H0=	0.0019877			$R=R0\exp(b/(T+273.15))$	$\ln(R)=\ln(R0)+(b/(T+273.15))$		
7	R0 = exp(-H0/H1)=	0.001311			$x=\ln(R)$	$y=1/(T+273.15)$	$\ln(R)/b-\ln(R0)/b=1/(T+273.15)$	
8	$\beta=1/H1=$	3339.0538			4.5622627	0.003354	$H0=-\ln(R)/b$	
9					4.2341065	0.003256	$H1=1/b$	
10	Embedded Systems. Real-Time Interfacing to ARM Cortex M Microcontrollers							
11	See Sections 10.2.7 and 10.6							
12	2) Define ADC precision, ADC max, fixed-point format				Dissipation Constant			
13	ADC	12 bits			D(mW/ $^{\circ}$ C)= 2.5			
14	ADCmax	4095 alternatives			Self-heat error is $\Delta T=P/D$			
15	ADCmax	3.3 V						
16	fixed-point	0.01 C						
17								
18	3) Decide the values of Vref, R1, R2, Tmin, and Tmax							
19	V1 (V)	2.5						
20	R1(k $\Omega$ )=	470			R2 (k $\Omega$ )=	470		
21					R3 (k $\Omega$ )=	50		
22	V3(V)=	0.240						
23								
24	4) Build instrumentation amp using INA122 or equivalent (e.g., AD627)							
25	Desired Gain=	7.62						
26		INA122						
27			AD623					



28	desired Rg	76.48	15.12	k $\Omega$					
29	Actual Rg	7.50E+01	15	k $\Omega$					
30	Gain w/actual	7.67	7.67						
31		5+200k/Rg	1+100k/Rg						
32	choose gain			other					
33	Desired gain	AD627	AD623	20					
34	0	1	0	0	<= set 1 to select,	this gain is used=>	7.67		
35									

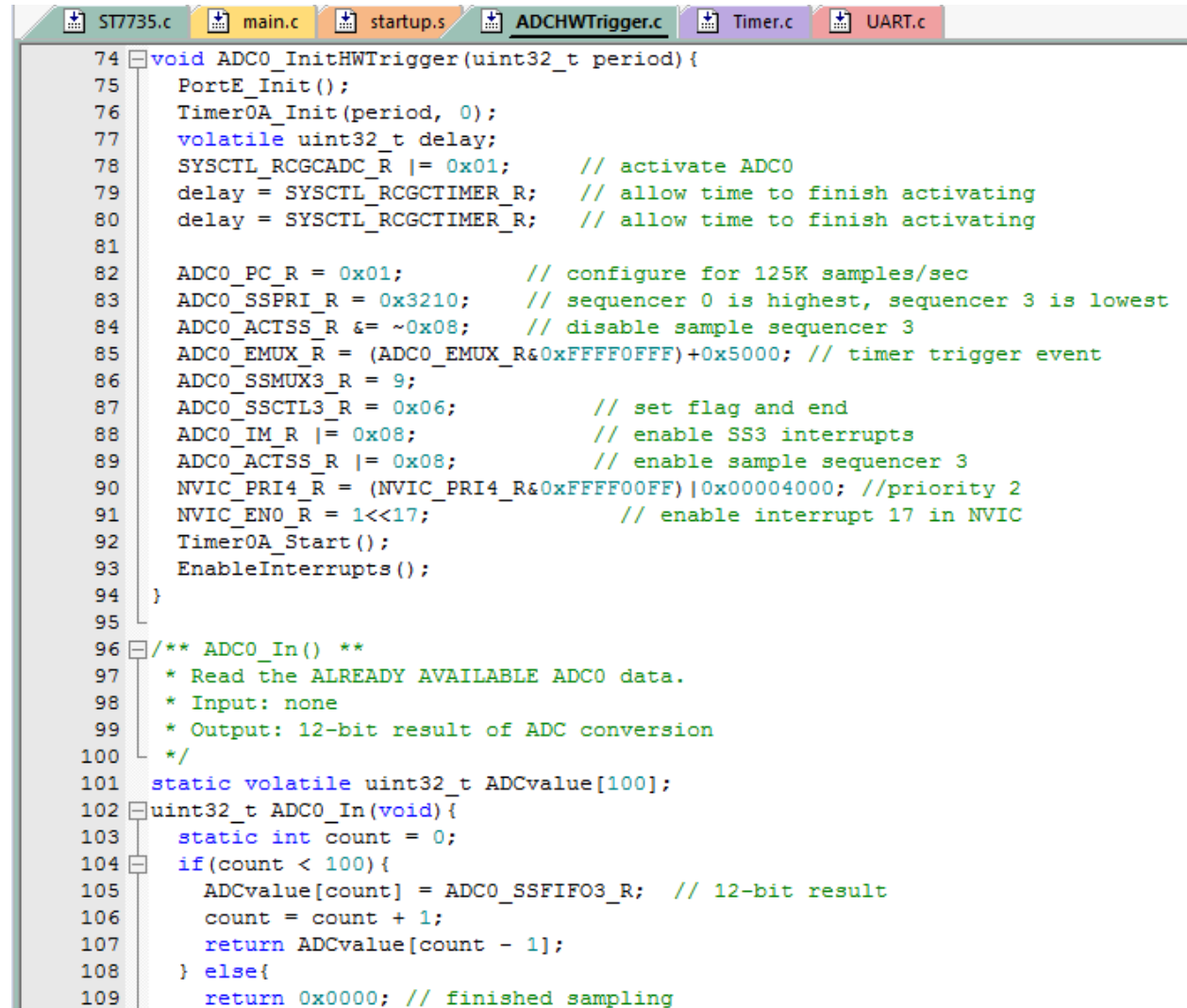


57		T ( $^{\circ}$ C)	RT (k $\Omega$ )	V2 (V)	V2-V3 (V)	Vs (V)	ADC	T (fixed)	Power (mW)
58	0	10	173.391	0.674	0.433	3.322	4095	1000	0.0026
59	1	10	173.391	0.674	0.433	3.322	4095	1000	0.0026

## 2.0: ADC Initializations:

There are many ways to trigger the ADC, but we implemented Processor, Timer, and Continuous trigger initialization methods.

### 1) Hardware Triggered (GP Timer 0A)



```
74 void ADC0_InitHWTrigger(uint32_t period){
75     PortE_Init();
76     Timer0A_Init(period, 0);
77     volatile uint32_t delay;
78     SYSTCL_RCGCADR |= 0x01; // activate ADC0
79     delay = SYSTCL_RCGCTIMER_R; // allow time to finish activating
80     delay = SYSTCL_RCGCTIMER_R; // allow time to finish activating
81
82     ADC0_PC_R = 0x01; // configure for 125K samples/sec
83     ADC0_SSRI_R = 0x3210; // sequencer 0 is highest, sequencer 3 is lowest
84     ADC0_ACTSS_R &= ~0x08; // disable sample sequencer 3
85     ADC0_EMUX_R = (ADC0_EMUX_R & 0xFFFF0FFF) + 0x5000; // timer trigger event
86     ADC0_SSMUX3_R = 9;
87     ADC0_SSCTL3_R = 0x06; // set flag and end
88     ADC0_IM_R |= 0x08; // enable SS3 interrupts
89     ADC0_ACTSS_R |= 0x08; // enable sample sequencer 3
90     NVIC_PRI4_R = (NVIC_PRI4_R & 0xFFFF00FF) | 0x00004000; //priority 2
91     NVIC_EN0_R = 1 << 17; // enable interrupt 17 in NVIC
92     Timer0A_Start();
93     EnableInterrupts();
94 }
95
96 /** ADC0_In() **
97  * Read the ALREADY AVAILABLE ADC0 data.
98  * Input: none
99  * Output: 12-bit result of ADC conversion
100 */
101 static volatile uint32_t ADCvalue[100];
102 uint32_t ADC0_In(void){
103     static int count = 0;
104     if(count < 100){
105         ADCvalue[count] = ADC0_SSFI03_R; // 12-bit result
106         count = count + 1;
107         return ADCvalue[count - 1];
108     } else{
109         return 0x0000; // finished sampling
110     }
```

## 2) Software Triggered (Processor)

```
ADCSWTrigger.c ST7735.c main.c startup.s ADCHWTrigger.c Timer.c UART.c
57 // Sequencer 0 priority: 1st (highest)
58 // Sequencer 1 priority: 2nd
59 // Sequencer 2 priority: 3rd
60 // Sequencer 3 priority: 4th (lowest)
61 // SS3 triggering event: software trigger
62 // SS3 1st sample source: Ain9 (PE4)
63 // SS3 interrupts: enabled but not promoted to controller
64 void ADC0_InitSWTrigger(void){
65     PortE_Init();
66     SYSCTL_RCGCADC_R |= 0x0001; // 0) activate ADC0
67     while((SYSCTL_PRADC_R&0x0001) != 0x0001){}; // good code, but not yet implemented in simula
68     ADC0_PC_R &= ~0xF; // 1) clear max sample rate field
69     ADC0_PC_R |= 0x1; // 2) Sequencer 3 is highest priority
70     ADC0_ACTSS_R &= ~0x0008; // 3) disable sample sequencer 3
71     ADC0_EMUX_R &= ~0xF000; // 4) seq3 is software trigger
72     ADC0_SSMUX3_R &= ~0x000F; // 5) clear SS3 field
73     ADC0_SSMUX3_R += 9; // set channel
74     ADC0_SSCTL3_R = 0x0006; // 6) no TS0 D0, yes IE0 END0
75     ADC0_IM_R &= ~0x0008; // 7) disable SS3 interrupts
76     ADC0_ACTSS_R |= 0x0008; // 8) enable sample sequencer 3
77 }
78
79
80 //-----ADC0_In-----
81 // Busy-wait Analog to digital conversion
82 // Input: none
83 // Output: 12-bit result of ADC conversion
84 uint32_t ADC0_In(void){
85     uint32_t result;
86     ADC0_PSSI_R = 0x0008; // 1) initiate SS3
87     while((ADC0_RIS_R&0x08)==0){}; // 2) wait for conversion done
88     // if you have an A0-A3 revision number, you need to add an 8 usec wait here
89     result = ADC0_SSFI03_R&0xFFF; // 3) read result
90     ADC0_ISC_R = 0x0008; // 4) acknowledge completion
91     return result;
92 }
```

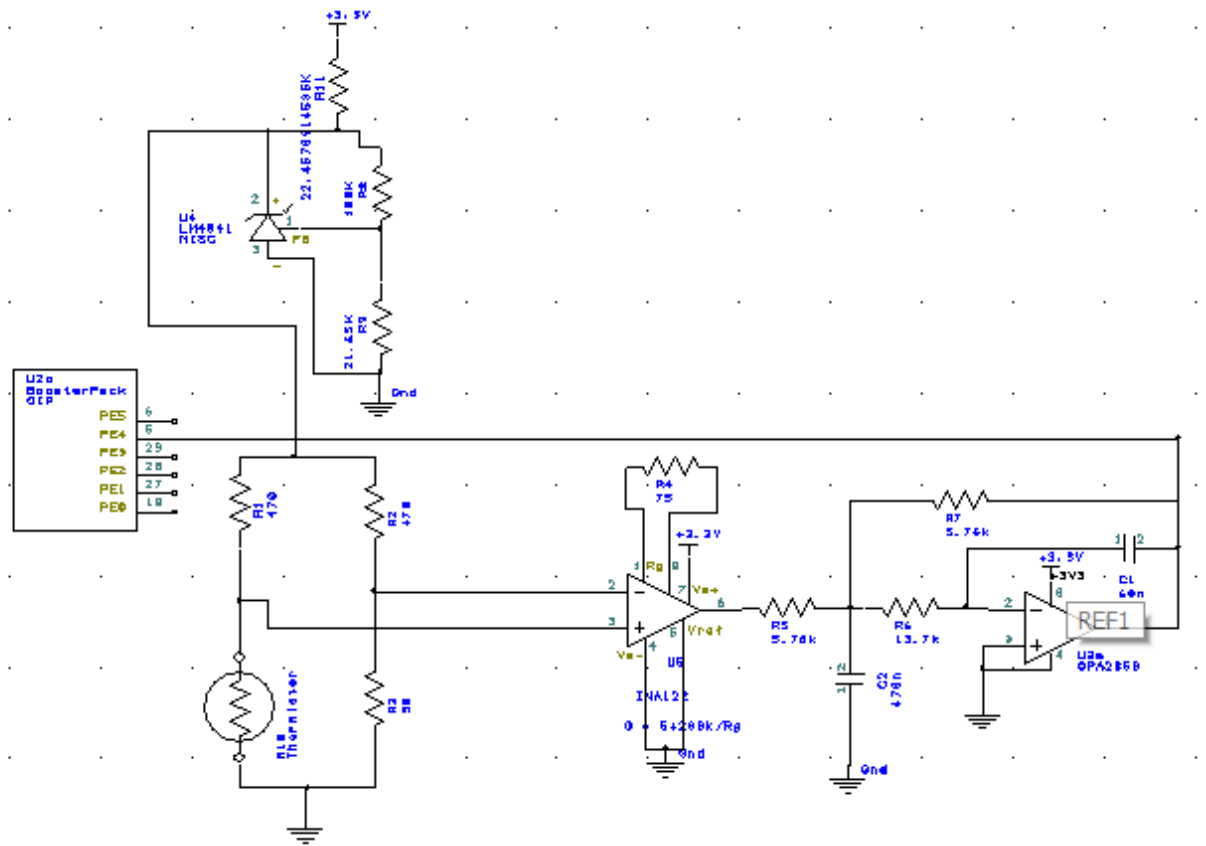
### 3) Continuous (Automatic and Endless)

```
ADCContinuous.c  ADCSWTrigger.c  ST7735.c  main.c  startup.s  ADCHWTrigger.c  Timer.c  UART.c

7  */
8
9  #include <stdint.h>
10 #include "tm4c123gh6pm.h"
11 static void PortE_Init(void);
12
13 /** ADC0_InitContinuous() **
14  * Initialize ADC0 SEQ3 for continuous sampling
15  * Output: none
16  */
17 void ADC0_InitContinuous(){
18     PortE_Init();
19     SYSCTL_RCGCADCR |= 0x0001;    // 0) activate ADC0
20     while((SYSCTL_PRADC_R&0x0001) != 0x0001){}; // good code, but not yet implemented in simulator
21     ADC0_PC_R &= ~0xF;            // 1) clear max sample rate field
22     ADC0_SSPR1_R = 0x3210;        // 2) sequencer 3 is lowest
23     ADC0_ACTSS_R &= ~0x0008;      // 3) disable sample sequencer 3
24     ADC0_EMUX_R |= 0xF000;        // 4) seq3 is continuous sample
25     ADC0_SSMUX3_R &= ~0x000F;     // 5) clear SS3 field
26     ADC0_SSMUX3_R += 9;           // set channel
27     ADC0_SSCTL3_R = 0x0004;       // 6) no TS0 D0 END0, yes IE0
28     ADC0_IM_R &= ~0x0008;        // 7) disable SS3 interrupts
29     ADC0_ACTSS_R |= 0x0008;       // 8) enable sample sequencer 3
30 }
31
32 /** ADC0_In() **
33  * Read the ALREADY AVAILABLE ADC0 data.
34  * Input: none
35  * Output: 12-bit result of ADC conversion
36  */
37 uint32_t ADC0_In(void){
38     uint32_t result;
39     result = ADC0_SSIFIFO3_R&0xFFFF; // 3) read result
40     return result;
41 }
42
```

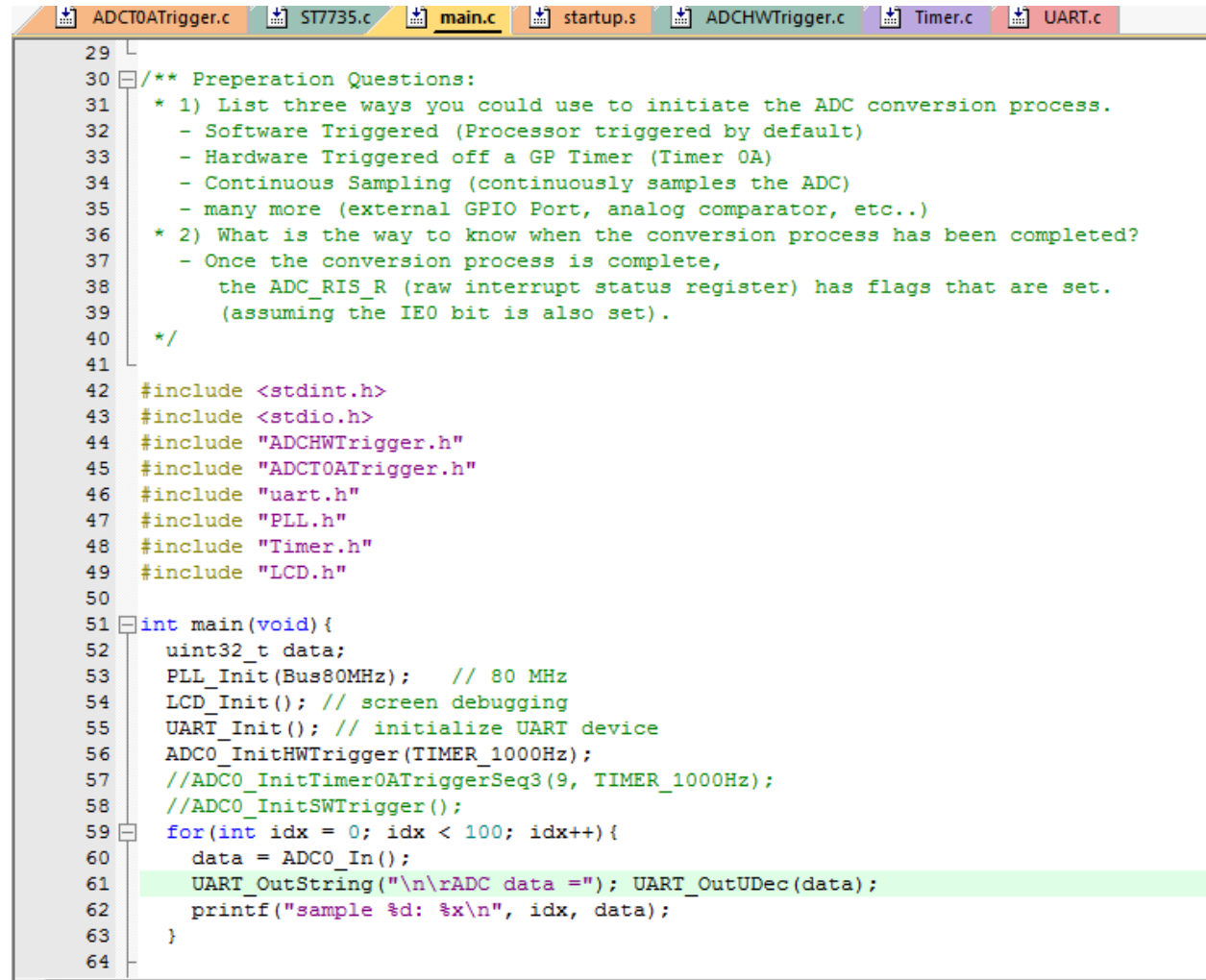
### 3.0: Hardware Design:

Below is the schematic design of our thermistor interface and Butterworth filter.



## 4.0: Nyquist Sampling Driver:

Below is a snapshot of our main sampling driver. It also includes the preparation questions.



```
29 |
30 | /** Preparation Questions:
31 |  * 1) List three ways you could use to initiate the ADC conversion process.
32 |  *    - Software Triggered (Processor triggered by default)
33 |  *    - Hardware Triggered off a GP Timer (Timer 0A)
34 |  *    - Continuous Sampling (continuously samples the ADC)
35 |  *    - many more (external GPIO Port, analog comparator, etc..)
36 |  * 2) What is the way to know when the conversion process has been completed?
37 |  *    - Once the conversion process is complete,
38 |  *      the ADC_RIS_R (raw interrupt status register) has flags that are set.
39 |  *      (assuming the IEO bit is also set).
40 |  */
41 |
42 | #include <stdint.h>
43 | #include <stdio.h>
44 | #include "ADCHWTrigger.h"
45 | #include "ADCT0ATrigger.h"
46 | #include "uart.h"
47 | #include "PLL.h"
48 | #include "Timer.h"
49 | #include "LCD.h"
50 |
51 | int main(void){
52 |     uint32_t data;
53 |     PLL_Init(Bus80MHz); // 80 MHz
54 |     LCD_Init(); // screen debugging
55 |     UART_Init(); // initialize UART device
56 |     ADC0_InitHWTrigger(TIMER_1000Hz);
57 |     //ADC0_InitTimer0ATriggerSeq3(9, TIMER_1000Hz);
58 |     //ADC0_InitSWTrigger();
59 |     for(int idx = 0; idx < 100; idx++){
60 |         data = ADC0_In();
61 |         UART_OutString("\n\rADC data ="); UART_OutUDec(data);
62 |         printf("sample %d: %x\n", idx, data);
63 |     }
64 | }
```