

## Possible Improvements

- Implementation of a possibility to save data: The data stored in the variable „databuffer“ might be used. By using a sampling rate the size of the file could be reduced.
- By now the image is only shown in black & white. If the color could be chosen by the user, a better visibility might be reached.
- As only one test camera was available, the option to choose another camera still has to be tested.
- The VRmUsbCamAPI.py could be extended. By now it is only working with single-sensor cameras. Furthermore the possible camera settings can be read out, which is not used yet. For further possibilities see the documentations of the camera and the SDK located in `..\VRmagicUSBCam\SDK\docs`.
- The fit performance can be improved.
- Introduce a “reference amplitude” displayed in the amplitude bar.