Ans. 2 marks for this differentiation

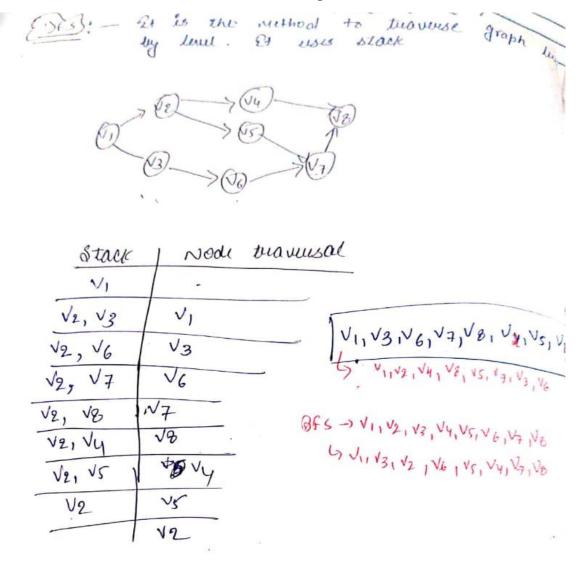
Feature	BFS	DFS
Exploration	Level-by-level traversal, guaranteed shortest path (unweighted)	Deepest path first traversal, no guarantee of shortest path
Data Structure	Queue (FIFO)	Stack (LIFO)
Applications	Shortest paths, minimum spanning trees, bipartiteness, level-order tree traversal	Topological sorting, cycle detection, connected components
Visualization	Expands outward like ripples in water	Explores like navigating a maze

NOTE - Students may take any example of graph and its traversal. For the reference 1 example is below:

1.5 marks for DFS

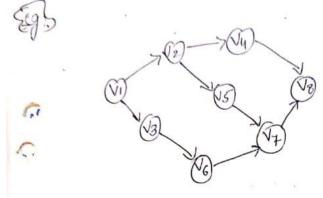
1.5 marks for BFS

0.5 each for definition and 1, mark each for example.



- . 3 states are used in traversal
- -) Ready > Noole doesn't much to queue
-) waiting) Node is intented into the quie but from
- > Photessed = Noon is memored from the queue & phi

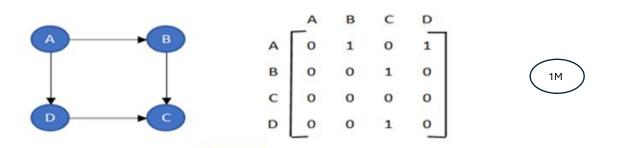
its adjacent node.) stard with a node. Progresses by analysing its) we use queue for BES



Queu	Node tru	-
AVI	٧,	0.00
-V2, V3	J2_	
V3, V4, V5	V3	
V5, V6, V8	Vy	
V6, V8, V7	15	
VB, V7,	V6	
\ <u></u>	18	
C Scanned with Ca	17	

Adjacency Matrix:

- An adjacency matrix is a way to represent a graph as a 2D array (matrix). In an adjacency matrix, rows and columns represent vertices of the graph, and each cell indicates whether there is an edge between the corresponding vertices. If there is an edge between vertex i and vertex j, then the cell at row i and column j will have a value indicating the weight of the edge (if the graph is weighted) or simply 1 (if the graph is unweighted).



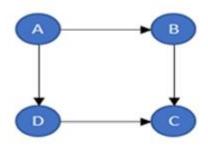
ii) Adjacency List

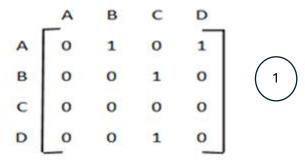
An adjacency list is another way to represent a graph, where each vertex in the graph maintains a list of its adjacent vertices. For each vertex in the graph, there is a list (array, linked list, etc.) containing references or indices to the vertices that are adjacent to it. If the graph is weighted, each entry in the adjacency list can store both the identifier of the adjacent vertex and the weight of the edge.

If the graph is unweighted, the adjacency list may only need to store the identifiers of adjacent vertices.

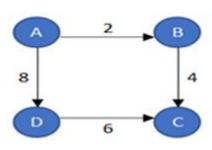
Example:

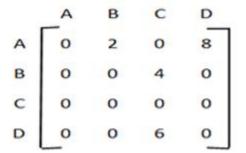
Directed unweighted weigh Graph





Example Weighted graph

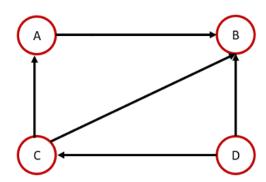




iii) Transitive Closure

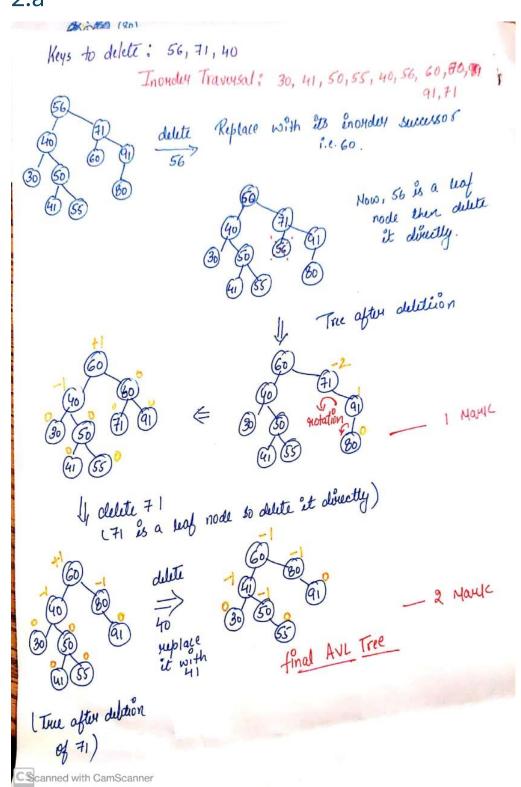
Transitive Closure in a graph shows the path between the nodes. In other words, if there exists a path between node x and node y, then there should be a corresponding edge(s) between these in Graph. The final transitive Closure Ti j (k) of a graph is a Boolean matrix, where if there is a path between two vertices, it is indicated by 1 in the Matrix, otherwise 0.

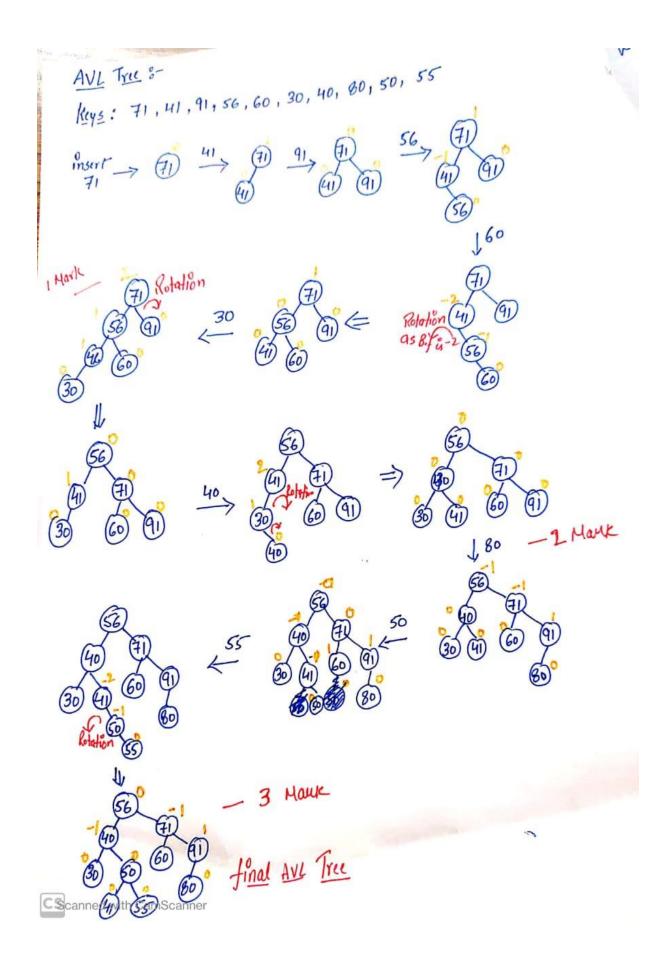
Example

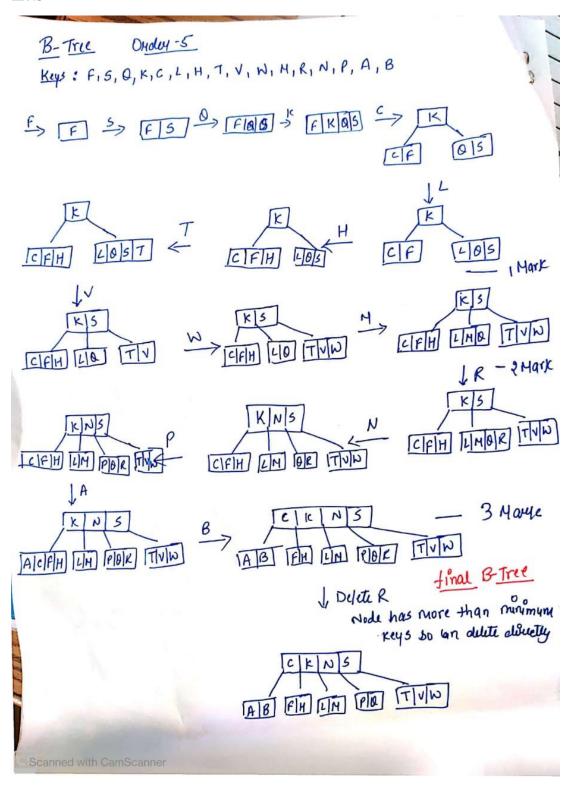


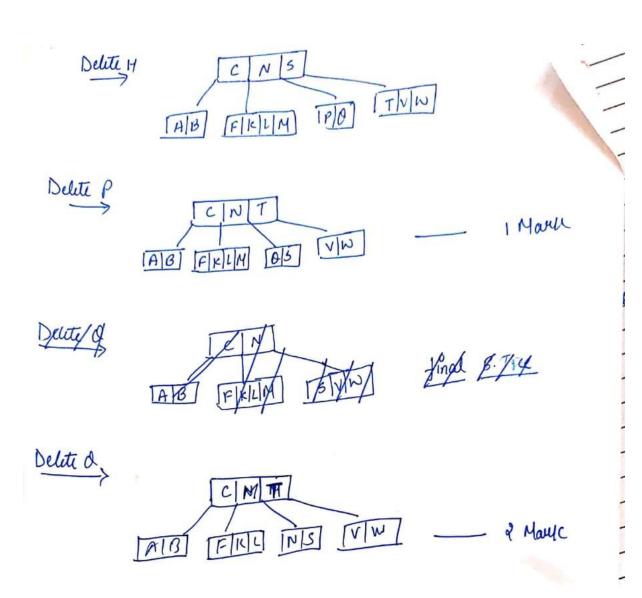
Transitive Closure:

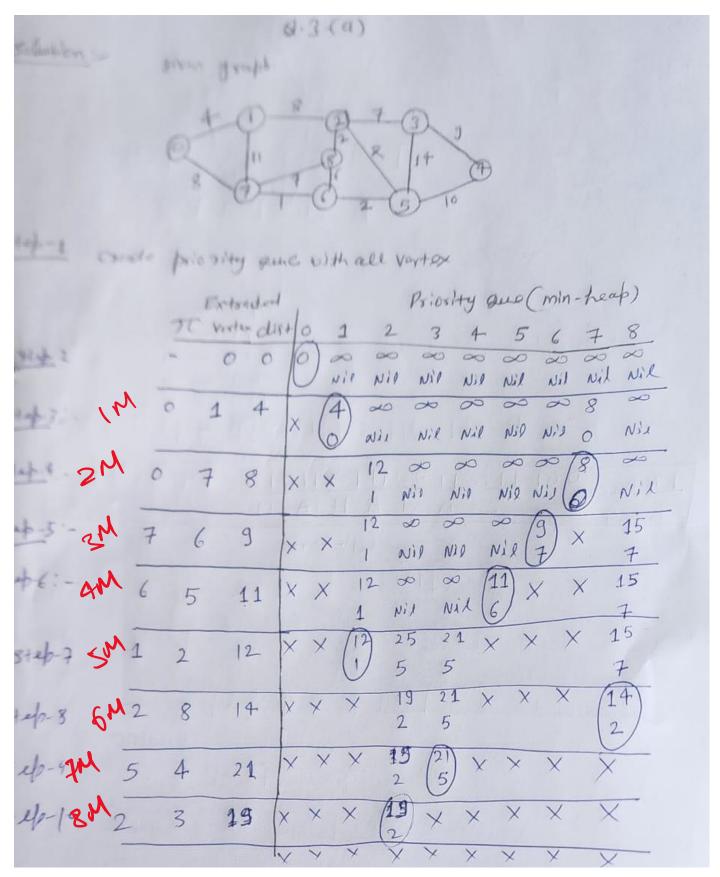
	1	2	3	4
1	0	1	0	0
2	0	0	0	0
3	1	1	0	0
4	1	1	1	0

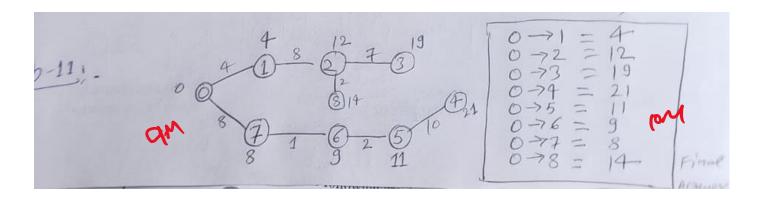


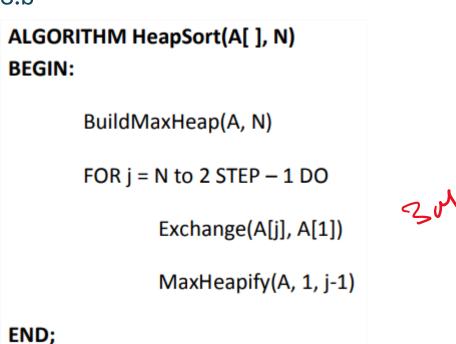




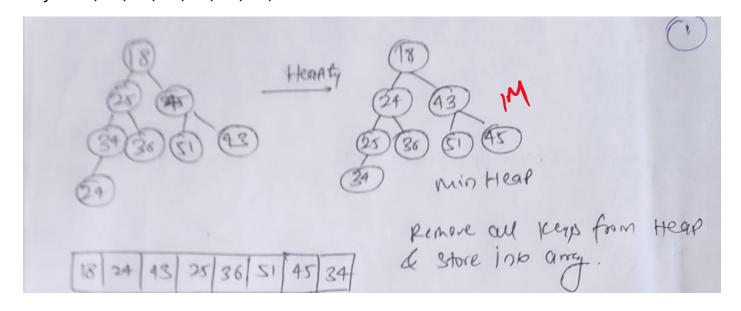


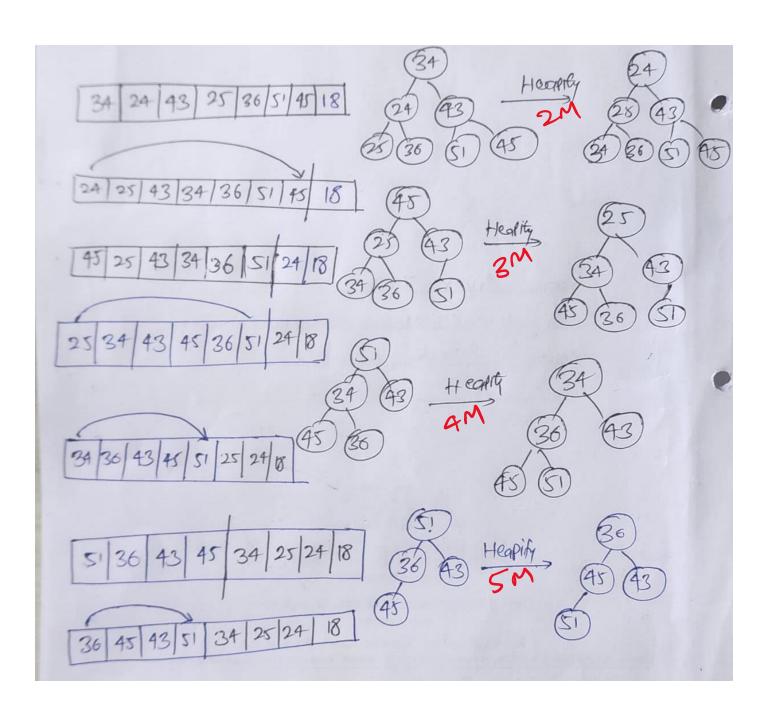


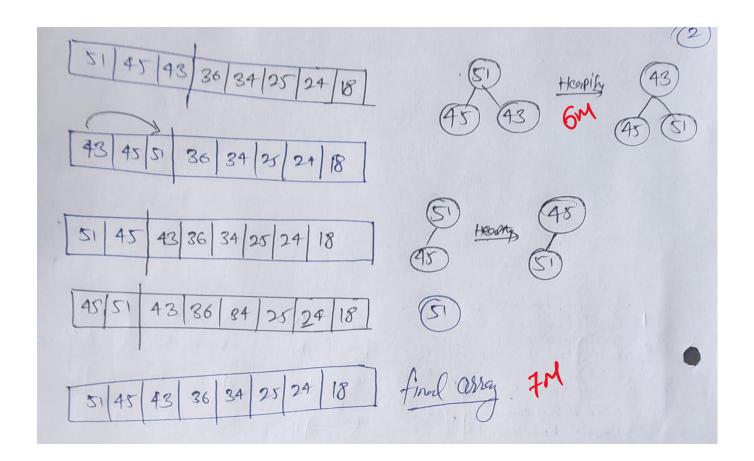


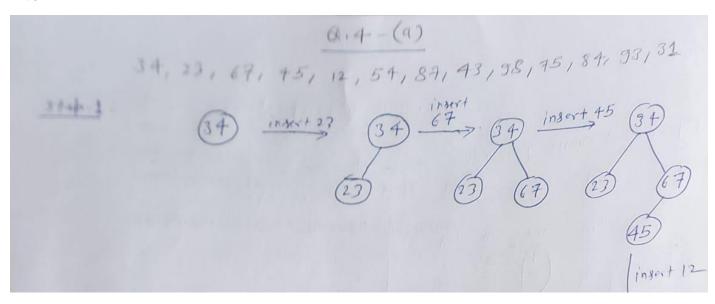


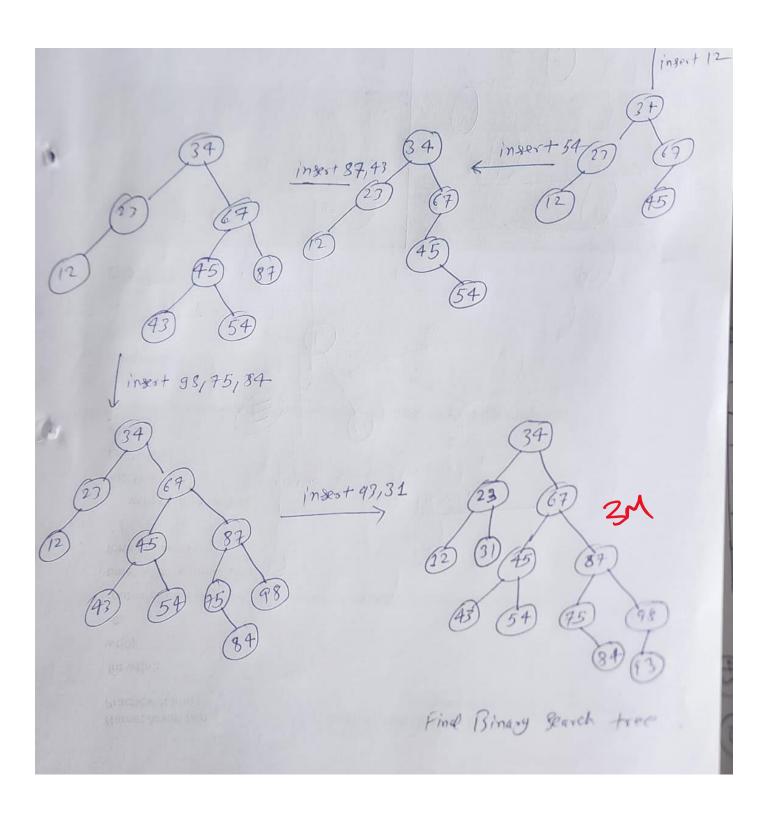
Build min Heap with given keys and remove all keys to sort in descending order Keys: 18, 25, 45, 34, 36, 51, 43, 24

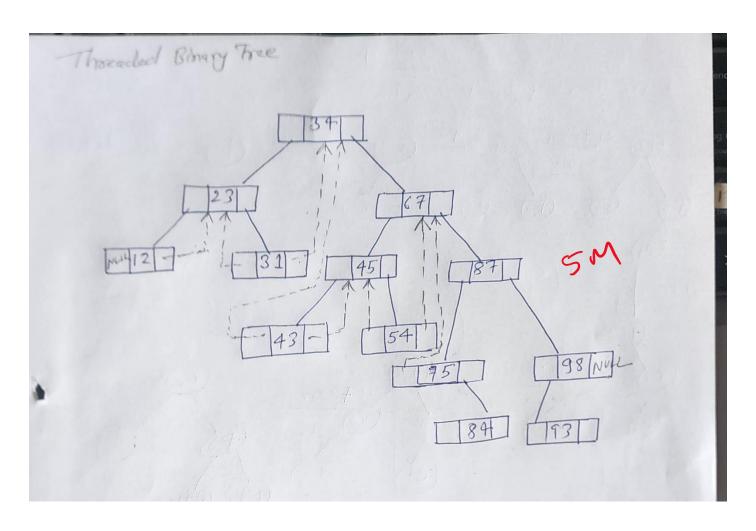




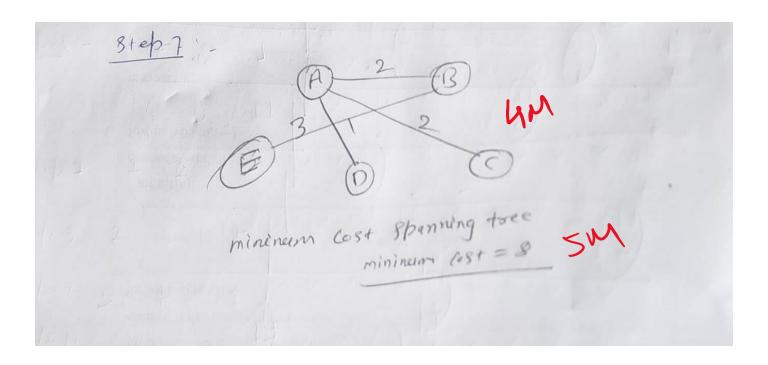


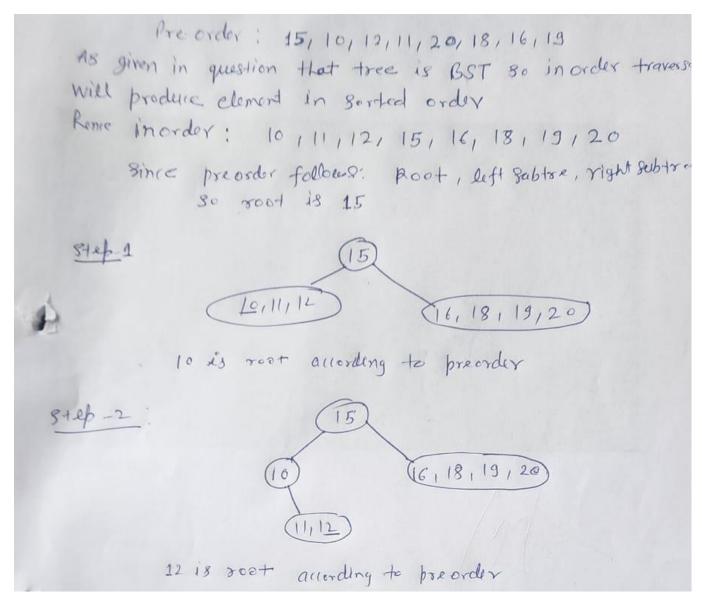


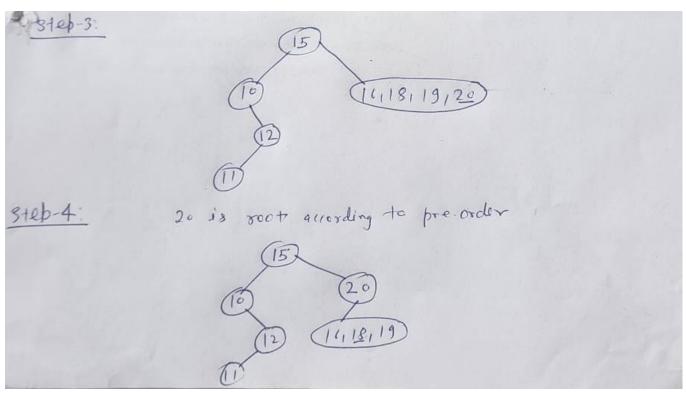


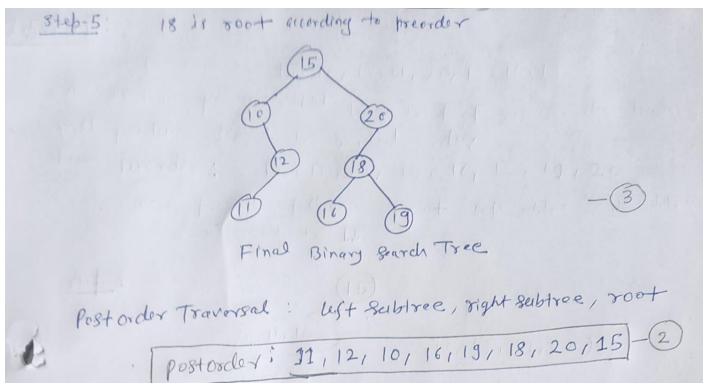


	Q.4-(b)
Central in	
	Step 1 de crede préority queue.
	A as Source Node Extracted Priority queue (min-heat
	TO VOSTEX COST A B C D E
1-1	step 2 - A 0 0 0 0 0 0 0
	8(e) A D 1 2 2 (1) 4 A A A A
	8tep 4 AMB 2 (2) 2 X 4
	8+ep-5 A C 2 Y Y (2) X 3
14	8+ep-6 B ZNE 3 XXXX (B)









1: abef->c or g should be covered

2: abefcgd correct

3: adgebcf correct 🔥

4: adbc->e or f should be covered 1

ALGORITHM HuffmanTree(A[], N)

// where A is the information about the character & their frequencies, and N is the total number of character appearing in the text file.

BEGIN:

Initialize(PQ) //Initialize a PriorityQueue PQ, which contains N elements in A

FOR I = 1 to N DO

Z=MakeNode(A[i])

PQInsert(PQ, Z)

FOR I = 1 to N-1 DO

X= PQDelete(PQ)

Y= PQDelete(PQ)

Z= MakeNode()

Z→Data = X→Data + Y→Data

 $Z \rightarrow Left = X$

 $Z \rightarrow Right = Y$

PQInsert(PQ, Z)

END;

301

cred frequency table for all alphabets in given mossage.

Chander count

A 4

H 2

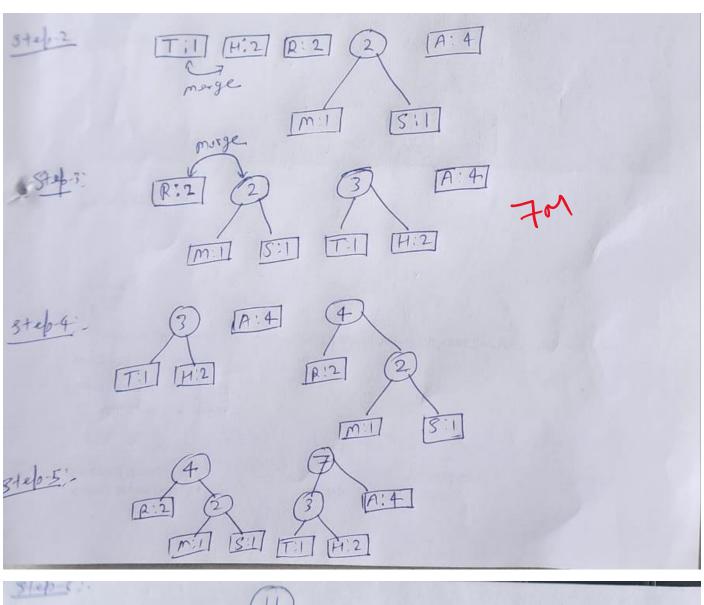
R 2

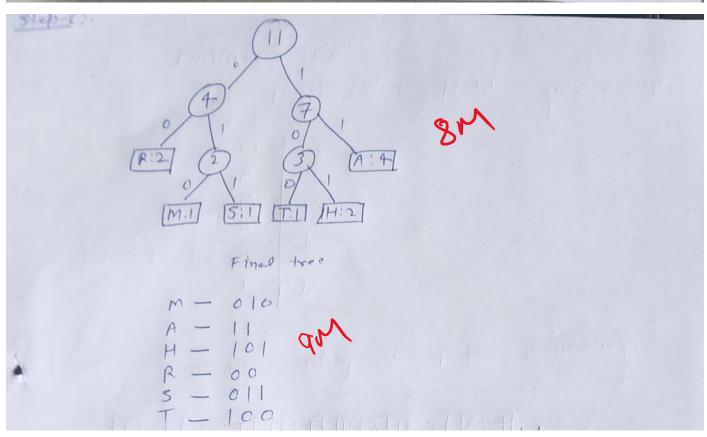
S 1

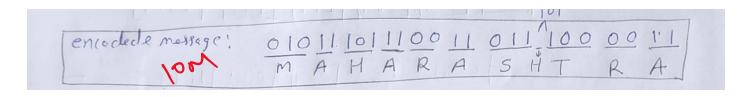
T 1

arrange in assembling order of their frequences.

M. L S: T T: 1 H: 2 [8:2] [A:4] 6M







Sparse Matrix - In computer science, a sparse matrix in the data structure is a matrix that has a large number of zero values compared to its total number of elements. Storing these matrices using a dense array representation would be inefficient in terms of both memory and computation time. To overcome this problem, sparse matrices can be represented using a more efficient data structure that only stores the non-zero elements. This can save memory and computation time for certain types of operations, such as matrix multiplication and inversion, and is an important concept in data structures and algorithms.

Representation of Sparse Matrix in Data Structure

Sparse matrix in data structure can be represented in two ways:

- 1. Array representation
- 2. Linked list representation

Array Representation of Sparse Matrix in Data Structure



Storing a sparse matrix in a 2D array can result in a lot of memory wastage because zero elements in the matrix do not carry any useful information, yet they occupy memory space. To overcome this limitation and optimize memory usage, we can represent a sparse matrix by only storing its non-zero elements. This approach reduces both traversal time and storage space requirements. By storing only the non-zero elements, we can achieve a more efficient representation of sparse matrices in data structures.

In the 2D array representation of a sparse matrix, there are typically three fields used to store the relevant information.

The given below are fields of the array representation of the sparse matrix:

- **Row index field:** This field stores the row indices of non-zero elements in the matrix.
- Column index field: This field stores the column indices of non-zero elements in the matrix.
- Value field: This field stores the actual values of the non-zero elements in the matrix.

The array representation of the sparse matrix in the data structure program converts a given matrix into its array representation where the non-zero elements of the matrix are stored in separate arrays for row, column, and value. It first counts the number of non-zero elements in the matrix, then initializes the arrays and stores the non-zero elements in them. Finally, it displays the array representation of the matrix. This program can reduce the storage space required for large matrices with many zero elements.

Linked List Representation of Sparse Matrix in Data Structure

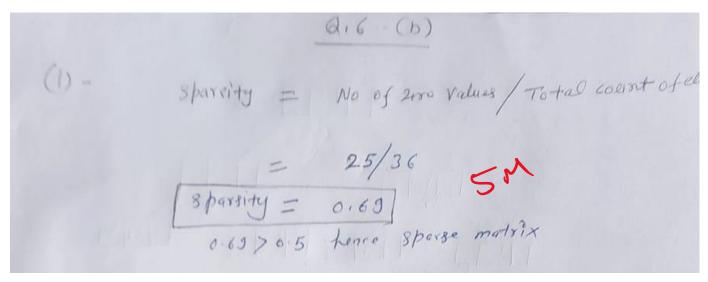


The sparse matrix in data structure can be represented using a linked list data structure, which offers the advantage of lower complexity when inserting or deleting a node compared to an array.

The linked list representation differs from the array representation in that each node has four fields, which are:

- **Row:** It indicates the index of the row where the non-zero element is located.
- Column: It indicates the index of the column where the non-zero element is located.
- Value: It represents the value of the non-zero element located at the index (row, column).
- Pointer to Next node: It stores the memory address of the next node in the linked list.

In the implementation of a linked list representation of a sparse matrix, the Node class represents a node in the linked list for a particular row. The SparseMatrix class contains a dynamic array of pointers to nodes, where each pointer points to the head of the linked list for a particular row. The insert function inserts a new element into the matrix by creating a new Node and inserting it into the appropriate linked list, sorted by column index. The display function prints out the entire matrix by iterating over each row and column and checking the linked list for each row to see if there is a corresponding element



(11) - Expression tree: 9+ is a special kind of tree which is used to represent expressions 9n expression tree operands are leaf nides and operators are Internal nodes. 21 expression: (a-b)/(c*d)+e)

step-1:
(a)

(b)

(c*d)

(c*d)

(c*d)

(c*d)

