# **II.3 QR factorisation**

Let  $A\in\mathbb{C}^{m\times n}$  be a rectangular or square matrix such that  $m\geq n$  (i.e. more rows then columns). In this chapter we consider two closely related factorisations:

### 1. The QR factorisation

$$A=QR=\underbrace{\left[oldsymbol{\mathbf{q}}_{1}|\cdots|oldsymbol{\mathbf{q}}_{m}
ight]}_{Q\in U(m)} egin{bmatrix} imes & \cdots & imes \ & \ddots & dots \ & & imes \ & & 0 \ & & dots \ & & 0 \ & & dots \ & & 0 \ \end{bmatrix}$$

where Q is unitary (i.e.,  $Q \in U(m)$ , satisfying  $Q^*Q = I$ , with columns  $\mathbf{q}_j \in \mathbb{C}^m$ ) and R is *right triangular*, which means it is only nonzero on or to the right of the diagonal ( $r_{kj} = 0$  if k > j).

#### 2. The reduced QR factorisation

$$A = \hat{Q}\hat{R} = \underbrace{\left[ \mathbf{q}_1 \middle| \cdots \middle| \mathbf{q}_n 
ight]}_{\hat{Q} \in \mathbb{C}^{m imes n}} \underbrace{\left[ egin{array}{ccc} imes & \cdots & imes \ & \ddots & dots \ & & imes \end{array} 
ight]}_{\hat{R} \in \mathbb{C}^{n imes n}}$$

where Q has orthonormal columns ( $Q^\star Q = I$ ,  $\mathbf{q}_j \in \mathbb{C}^m$ ) and  $\hat{R}$  is upper triangular.

Note for a square matrix the reduced QR factorisation is equivalent to the QR factorisation, in which case R is  $upper\ triangular$ . The importance of these decomposition for square matrices is that their component pieces are easy to invert:

$$A = QR$$
  $\Rightarrow$   $A^{-1}\mathbf{b} = R^{-1}Q^{\top}\mathbf{b}$ 

and we saw in the last two chapters that triangular and orthogonal matrices are easy to invert when applied to a vector  $\mathbf{b}$ , e.g., using forward/back-substitution.

For rectangular matrices we will see that they lead to efficient solutions to the *least*  $squares\ problem$ : find x that minimizes the 2-norm

$$||A\mathbf{x} - \mathbf{b}||$$
.

Note in the rectangular case the QR decomposition contains within it the reduced QR decomposition:

$$A = QR = \left[ \left. \hat{Q} | \mathbf{q}_{n+1} | \cdots | \mathbf{q}_m \, \right] \left[ egin{array}{c} \hat{R} \ \mathbf{0}_{m-n imes n} \end{array} 
ight] = \hat{Q} \hat{R}.$$

In this lecture we discuss the followng:

- 1. QR and least squares: We discuss the QR decomposition and its usage in solving least squares problems.
- 2. Reduced QR and Gram-Schmidt: We discuss computation of the Reduced QR decomposition using Gram-Schmidt.
- 3. Householder reflections and QR: We discuss computing the QR decomposition using Householder reflections.

In [1]: using LinearAlgebra, Plots, BenchmarkTools

# 1. QR and least squares

Here we consider rectangular matrices with more rows than columns. Given  $A \in \mathbb{C}^{m \times n}$  and  $\mathbf{b} \in \mathbb{C}^m$ , least squares consists of finding a vector  $\mathbf{x} \in \mathbb{C}^n$  that minimises the 2-norm:  $||A\mathbf{x} - \mathbf{b}||$ .

Theorem 1 (least squares via QR) Suppose  $A\in\mathbb{C}^{m imes n}$  has full rank. Given a QR decomposition A=QR then

$$\mathbf{x} = \hat{\boldsymbol{R}}^{-1} \hat{\boldsymbol{Q}}^{\star} \mathbf{b}$$

minimises  $\|A\mathbf{x} - \mathbf{b}\|$ .

### **Proof**

The norm-preserving property (see PS4 Q3.1) of unitary matrices tells us

$$\|A\mathbf{x}-\mathbf{b}\|=\|QR\mathbf{x}-\mathbf{b}\|=\|Q(R\mathbf{x}-Q^{\star}\mathbf{b})\|=\|R\mathbf{x}-Q^{\star}\mathbf{b}\|=egin{bmatrix} \hat{R} \ \mathbf{0}_{m-n imes n} \end{bmatrix}\mathbf{x}-egin{bmatrix} \mathbf{q} \ \mathbf{q} \end{bmatrix}$$

Now note that the rows k > n are independent of  $\mathbf{x}$  and are a fixed contribution. Thus to minimise this norm it suffices to drop them and minimise:

$$\|\hat{R}\mathbf{x} - \hat{Q}^{\star}\mathbf{b}\|$$

This norm is minimised if it is zero. Provided the column rank of A is full,  $\hat{R}$  will be invertible (Exercise: why is this?).

Example 1 (quadratic fit) Suppose we want to fit noisy data by a quadratic

$$p(x) = p_0 + p_1 x + p_2 x^2$$

That is, we want to choose  $p_0, p_1, p_2$  at data samples  $x_1, \ldots, x_m$  so that the following is true:

$$p_0 + p_1 x_k + p_2 x_k^2 pprox f_k$$

where  $f_k$  are given by data. We can reinterpret this as a least squares problem: minimise the norm

$$egin{bmatrix} 1 & x_1 & x_1^2 \ dots & dots & dots \ 1 & x_m & x_m^2 \end{bmatrix} egin{bmatrix} p_0 \ p_1 \ p_2 \end{bmatrix} - egin{bmatrix} f_1 \ dots \ f_m \end{bmatrix} egin{bmatrix} \end{bmatrix}$$

We can solve this using the QR decomposition:

```
In [2]: m,n = 100,3
x = range(0,1; length=m) # 100 points
f = 2 .+ x .+ 2x.^2 .+ 0.1 .* randn.() # Noisy quadratic
A = x .^ (0:2)' # 100 x 3 matrix, equivalent to [ones(m) x x.^2]
Q,\hat{R} = qr(A)
\hat{Q} = Q[:,1:n] # Q represents full orthogonal matrix so we take first 3 column po,p1,p2 = <math>\hat{R} \setminus \hat{Q}'f
```

Out[2]: 3-element Vector{Float64}:

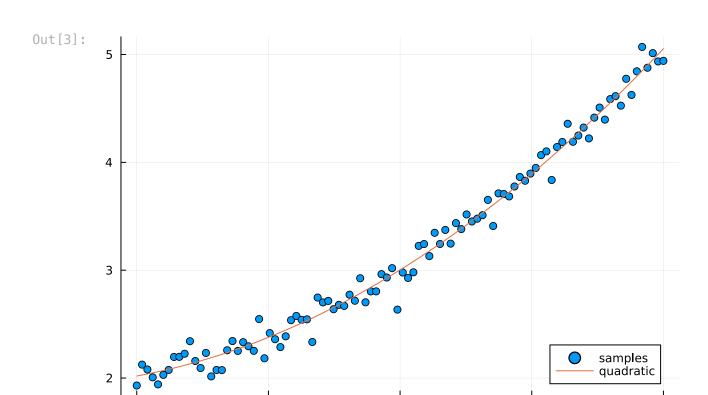
2.0187656687759863

0.9018225061725361

2,1328528824283475

We can visualise the fit:

```
In [3]: p = x -> p<sub>0</sub> + p<sub>1</sub>*x + p<sub>2</sub>*x^2
scatter(x, f; label="samples", legend=:bottomright)
plot!(x, p.(x); label="quadratic")
```



Note that \ with a rectangular system does least squares by default:

In [4]: A \ f

Out[4]: 3-element Vector{Float64}:

0.00

- 2.0187656687759885
- 0.901822506172533
- 2.1328528824283493

# 2. Reduced QR and Gram-Schmidt

0.25

How do we compute the QR decomposition? We begin with a method you may have seen before in another guise. Write

0.50

0.75

1.00

$$A = [\mathbf{a}_1|\cdots|\mathbf{a}_n]$$

where  $\mathbf{a}_k \in \mathbb{C}^m$  and assume they are linearly independent (A has full column rank).

**Proposition 1 (Column spaces match)** Suppose  $A=\hat{Q}\hat{R}$  where  $\hat{Q}=[\mathbf{q}_1|\dots|\mathbf{q}_n]$  has orthonormal columns and  $\hat{R}$  is upper-triangular, and A has full rank. Then the first j columns of  $\hat{Q}$  span the same space as the first j columns of A:

$$\operatorname{span}(\mathbf{a}_1,\ldots,\mathbf{a}_j)=\operatorname{span}(\mathbf{q}_1,\ldots,\mathbf{q}_j).$$

**Proof** 

Because A has full rank we know  $\hat{R}$  is invertible, i.e. its diagonal entries do not vanish:  $r_{jj} \neq 0$ . If  $\mathbf{v} \in \mathrm{span}(\mathbf{a}_1,\ldots,\mathbf{a}_j)$  we have for  $\mathbf{c} \in \mathbb{C}^j$ 

$$\mathbf{v} = \left[ \left. \mathbf{a}_1 \right| \cdots \left| \mathbf{a}_j \left. \right| \mathbf{c} = \left[ \left. \mathbf{q}_1 \right| \cdots \left| \mathbf{q}_j \left. \right| \hat{R}[1:j,1:j] \mathbf{c} \in \mathrm{span}(\mathbf{q}_1,\ldots,\mathbf{q}_j) 
ight.$$

while if  $\mathbf{w} \in \mathrm{span}(\mathbf{q}_1, \dots, \mathbf{q}_j)$  we have for  $\mathbf{d} \in \mathbb{R}^j$ 

$$\mathbf{w} = \left[ \left. \mathbf{q}_1 \right| \cdots \left| \mathbf{q}_j \right. \right] \mathbf{d} = \left[ \left. \mathbf{a}_1 \right| \cdots \left| \mathbf{a}_j \right. \right] \hat{R}[1:j,1:j]^{-1} \mathbf{d} \in \mathrm{span}(\mathbf{a}_1,\ldots,\mathbf{a}_j).$$

It is possible to find  $\hat{Q}$  and  $\hat{R}$  the using the *Gram–Schmidt algorithm*. We construct it column-by-column:

Algorithm 1 (Gram-Schmidt) For  $j=1,2,\ldots,n$  define

$$egin{aligned} \mathbf{v}_j &:= \mathbf{a}_j - \sum_{k=1}^{j-1} \underbrace{\mathbf{q}_k^\star \mathbf{a}_j}_{r_{kj}} \mathbf{q}_k \ & r_{jj} &:= \|\mathbf{v}_j\| \ & \mathbf{q}_j &:= rac{\mathbf{v}_j}{r_{jj}} \end{aligned}$$

**Theorem 2 (Gram-Schmidt and reduced QR)** Define  ${f q}_j$  and  $r_{kj}$  as in Algorithm 1 (with  $r_{kj}=0$  if k>j). Then a reduced QR decomposition is given by:

$$A = \underbrace{\left[ old{q}_1 ig| \cdots ig| old{q}_n 
ight]}_{Q \in \mathbb{C}^{m imes n}} \underbrace{\left[ egin{array}{ccc} r_{11} & \cdots & r_{1n} \ & \ddots & dots \ & & r_{nn} \end{array} 
ight]}_{\hat{R} \in \mathbb{C}^{n imes n}}$$

## **Proof**

We first show that  $\hat{Q}$  has orthonormal columns. Assume that  $\mathbf{q}_\ell^\star\mathbf{q}_k=\delta_{\ell k}$  for  $k,\ell< j$ . For  $\ell< j$  we then have

$$\mathbf{q}_{\ell}^{\star}\mathbf{v}_{j} = \mathbf{q}_{\ell}^{\star}\mathbf{a}_{j} - \sum_{k=1}^{j-1}\mathbf{q}_{\ell}^{\star}\mathbf{q}_{k}\mathbf{q}_{k}^{\star}\mathbf{a}_{j} = 0$$

hence  ${f q}_\ell^\star {f q}_j=0$  and indeed  $\hat Q$  has orthonormal columns. Further: from the definition of  ${f v}_j$  we find

$$\mathbf{a}_j = \mathbf{v}_j + \sum_{k=1}^{j-1} r_{kj} \mathbf{q}_k = \sum_{k=1}^j r_{kj} \mathbf{q}_k = \hat{Q} \hat{R} \mathbf{e}_j$$

Gram-Schmidt in action

We are going to compute the reduced QR of a random matrix

```
In [5]: m,n = 5,4
        A = randn(m,n)
        Q,\hat{R} = qr(A)
        \hat{Q} = Q[:,1:n]
Out[5]: 5×4 Matrix{Float64}:
                      -0.0219227 -0.0607257
         -0.957461
                                                0.0442422
          0.0544893
                      -0.379479 0.0347338
                                                0.922756
          0.00699221 0.650908 -0.688444
                                                0.295632
          0.279961
                      -0.117309
                                 -0.298817 -0.0716032
          0.0432704
                       0.646585 0.65716
                                                0.232463
        The first column of \hat Q is indeed a normalised first column of A:
In [6]: R = zeros(n,n)
        Q = zeros(m,n)
        R[1,1] = norm(A[:,1])
        Q[:,1] = A[:,1]/R[1,1]
Out[6]: 5-element Vector{Float64}:
          0.9574610639933926
         -0.05448932031064362
         -0.006992209601046934
         -0.2799607186634795
         -0.043270427765942907
        We now determine the next entries as
In [7]: R[1,2] = Q[:,1] 'A[:,2]
        V = A[:,2] - Q[:,1]*R[1,2]
        R[2,2] = norm(v)
        Q[:,2] = v/R[2,2]
Out[7]: 5-element Vector{Float64}:
          0.021922713685827575
          0.37947872668874755
         -0.650908195842938
          0.11730899753548062
         -0.6465851918324824
        And the third column is then:
In [8]: R[1,3] = Q[:,1] 'A[:,3]
        R[2,3] = Q[:,2]'A[:,3]
        v = A[:,3] - Q[:,1:2]*R[1:2,3]
        R[3,3] = norm(v)
        Q[:,3] = v/R[3,3]
```

```
Out[8]: 5-element Vector{Float64}:
-0.060725738323240394
0.034733790189702865
-0.6884444081388632
-0.298816849439798
0.6571595969909884
```

(Note the signs may not necessarily match.)

We can clean this up as a simple algorithm:

```
In [9]: function gramschmidt(A)
            m,n = size(A)
            m ≥ n || error("Not supported")
            R = zeros(n,n)
            Q = zeros(m,n)
            for j = 1:n
                 for k = 1:j-1
                     R[k,j] = Q[:,k]'*A[:,j]
                 V = A[:,j] - Q[:,1:j-1]*R[1:j-1,j]
                 R[j,j] = norm(v)
                 Q[:,j] = v/R[j,j]
            end
            Q,R
        end
        Q,R = gramschmidt(A)
        norm(A - Q*R)
```

Out[9]: 4.4367826167002116e-16

# Complexity and stability

We see within the for j = 1:n loop that we have O(mj) operations. Thus the total complexity is  $O(mn^2)$  operations.

Unfortunately, the Gram-Schmidt algorithm is *unstable*: the rounding errors when implemented in floating point accumulate in a way that we lose orthogonality:

```
In [10]: A = randn(300,300)
   Q,R = gramschmidt(A)
   norm(Q'Q-I)
```

Out[10]: 1.9520758901756154e-12

# 3. Householder reflections and QR

As an alternative, we will consider using Householder reflections to introduce zeros below the diagonal. Thus, if Gram–Schmidt is a process of *triangular orthogonalisation* 

(using triangular matrices to orthogonalise), Householder reflections is a process of *orthogonal triangularisation* (using orthogonal matrices to triangularise).

Consider multiplication by the Householder reflection corresponding to the first column, that is, for

$$Q_1 := Q_{\mathbf{a}_1}^{\mathrm{H}},$$

consider

$$Q_1 A = \left[egin{array}{cccc} imes & imes & imes & imes \ & imes & \cdots & imes \ & dots & \ddots & dots \ & imes & \cdots & imes \end{array}
ight] = \left[egin{array}{cccc} lpha & \mathbf{w}^ op \ & A_2 \end{array}
ight]$$

where

$$lpha := -\mathrm{csign}(a_{11}) \|\mathbf{a}_1\|, \mathbf{w} = (Q_1 A)[1,2:n] \qquad ext{and} \qquad A_2 = (Q_1 A)[2:m,2:n],$$

 $\mathrm{csign}(z):=\mathrm{e}^{\mathrm{i}\arg z}$ . That is, we have made the first column triangular. In terms of an algorithm, we then introduce zeros into the first column of  $A_2$ , leaving an  $A_3$ , and so-on. But we can wrap this iterative algorithm into a simple proof by induction:

**Theorem 3 (QR)** Every matrix  $A \in \mathbb{C}^{m \times n}$  has a QR factorisation:

$$A = QR$$

where  $Q \in U(m)$  and  $R \in \mathbb{C}^{m \times n}$  is right triangular.

### **Proof**

Assume  $m\geq n.$  If  $A=[{f a}_1]\in\mathbb{C}^{m imes 1}$  then we have for the Householder reflection  $Q_1=Q_{{f a}_1}^{
m H}$ 

$$Q_1A = [\alpha \mathbf{e}_1]$$

which is right triangular, where  $lpha=- ext{sign}(a_{11})\|\mathbf{a}_1\|.$  In other words

$$A = \underbrace{Q_1}_{Q} \underbrace{[lpha \mathbf{e_1}]}_{R}.$$

For n>1, assume every matrix with less columns than n has a QR factorisation. For  $A=[{f a}_1|\dots|{f a}_n]\in\mathbb{C}^{m\times n}$ , let  $Q_1=Q_{{f a}_1}^{\rm H}$  so that

$$Q_1 A = \left[egin{array}{cc} lpha & \mathbf{w}^ op \ & A_2 \end{array}
ight]$$

where  $A_2=(Q_1A)[2:m,2:n]$  and  ${\bf w}=(Q_1A)[1,2:n]$ . By assumption  $A_2=\tilde{Q}\tilde{R}$ . Thus we have

This proof by induction leads naturally to an iterative algorithm. Note that  $\tilde{Q}$  is a product of all Householder reflections that come afterwards, that is, we can think of Q as:

$$Q = Q_1 ilde{Q}_2 ilde{Q}_3 \cdots ilde{Q}_n \qquad ext{for} \qquad ilde{Q}_j = \left[egin{array}{cc} I_{j-1} & & \ & Q_j \end{array}
ight]$$

where  $Q_j$  is a single Householder reflection corresponding to the first column of  $A_j$ . This is stated cleanly in Julia code:

**Algorithm 2 (QR via Householder)** For  $A\in\mathbb{C}^{m\times n}$  with  $m\geq n$ , the QR factorisation can be implemented as follows:

```
In [11]: function householderreflection(x)
              y = copy(x)
              if x[1] == 0
                  y[1] += norm(x)
              else # note sign(z) = exp(im*angle(z)) where `angle` is the argument of
                  y[1] += sign(x[1])*norm(x)
              end
              w = y/norm(y)
              I - 2*w*w'
          end
          function householdergr(A)
              T = eltype(A)
              m,n = size(A)
              if n > m
                  error("More columns than rows is not supported")
              end
              R = zeros(T, m, n)
              Q = Matrix(one(T)*I, m, m)
              A_j = copy(A)
              for j = 1:n
                  a_1 = A_j[:,1] # first columns of A_j
                  Q_1 = householderreflection(a_1)
                  Q_1A_1 = Q_1*A_1
                  \alpha, w = Q_1A_1[1,1], Q_1A_1[1,2:end]
                  A_{j+1} = Q_1A_j [2:end, 2:end]
                  # populate returned data
                  R[j,j] = \alpha
                  R[j,j+1:end] = w
```

```
# following is equivalent to Q = Q*[I 0; 0 Q;]
Q[:,j:end] = Q[:,j:end]*Q1

A; = A; +1 # this is the "induction"
end
Q,R
end

m,n = 100,50
A = randn(m,n)
Q,R = householderqr(A)
@test Q'Q ≈ I
@test Q*R ≈ A
```

### Out[11]: Test Passed

Note because we are forming a full matrix representation of each Householder reflection this is a slow algorithm, taking  $O(n^4)$  operations. The problem sheet will consider a better implementation that takes  $O(n^3)$  operations.

**Example 2** We will now do an example by hand. Consider the 4 imes 3 matrix

$$A = \left[ egin{array}{cccc} 2 & 3 & 0 \ 0 & 0 & 1 \ -2 & -3 & 0 \ -1 & -3 & -3 \end{array} 
ight]$$

For the first column we have

$$\mathbf{y}_1 := [-1, 0, -2, -1]$$

where  $\|\mathbf{y}_1\|^2 = 6$ . Hence

$$Q_1 := I - \frac{1}{6} \begin{bmatrix} -1 \\ 0 \\ -2 \\ -1 \end{bmatrix} \begin{bmatrix} -1 & 0 & -2 & -1 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & 0 & -2 & -1 \\ 0 & 3 & 0 & 0 \\ -2 & 0 & -1 & -2 \\ -1 & 0 & -2 & 2 \end{bmatrix}$$

so that

$$Q_1 A = egin{bmatrix} 3 & 5 & 1 \ & 0 & 1 \ & 1 & 2 \ & -1 & -2 \end{bmatrix}$$

For the second column we have

$$\mathbf{y}_2:=[-\sqrt{2},1,1]$$

where  $\|\mathbf{y}_2\|^2=4.$  Thus we have

$$Q_2 := I - rac{1}{2} \left[ egin{array}{ccc} -\sqrt{2} \ 1 \ 1 \end{array} 
ight] \left[ egin{array}{ccc} -\sqrt{2} & 1 & 1 \end{array} 
ight] = \left[ egin{array}{ccc} 0 & 1/\sqrt{2} & -1/\sqrt{2} \ 1/\sqrt{2} & 1/2 & 1/2 \ -1/\sqrt{2} & 1/2 & 1/2 \end{array} 
ight]$$

so that

$$ilde{Q}_2 Q_1 A = egin{bmatrix} 3 & 5 & 1 \ & \sqrt{2} & 2\sqrt{2} \ & 0 & 1/\sqrt{2} \ & 0 & -1/\sqrt{2} \end{bmatrix}$$

The final vector is

$$\mathbf{y}_3 := [1/\sqrt{2} - 1, -1/\sqrt{2}]$$

where  $\|\mathbf{y}_3\|^2 = 2 - 2/\sqrt{2}$ . Hence

$$Q_3:=I-rac{\sqrt{2}}{\sqrt{2}-1}\left[egin{array}{cc}1/\sqrt{2}-1\-1/\sqrt{2}\end{array}
ight]\left[egin{array}{cc}1/\sqrt{2}-1\-1/\sqrt{2}\end{array}
ight]=\left[egin{array}{cc}\sqrt{2}\-\sqrt{2}\-\sqrt{2}\end{array}
ight]$$

so that

$$ilde{Q}_3 ilde{Q}_2 Q_1 A = egin{bmatrix} 3 & 5 & 1 \ & \sqrt{2} & 2 \sqrt{2} \ & 0 & 1 \ & 0 & 0 \end{bmatrix} =: R$$

and

$$Q:=Q_1 ilde{Q}_2 ilde{Q}_3 = \left[ egin{array}{cccc} 2/3 & -1/(3\sqrt{2}) & 0 & 1/\sqrt{2} \ 0 & 0 & 1 & 0 \ -2/3 & 1/(3\sqrt{2}) & 0 & 1/\sqrt{2} \ -1/3 & -4/(3\sqrt{2}) & 0 & 0 \end{array} 
ight].$$