

Near-Optimal Stochastic Approximation for Online Principal Component Estimation

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Outline

- 1 Online PCA
- 2 Discrete-Time Analysis
 - Sketch of Proofs
- 3 Diffusion Approximation Perspective

Principal Component Analysis (PCA)

PCA (Pearson, 1901; Hotelling, 1933) is one of the most popular **dimension reduction** methods for high-dimensional data analysis

- PCA aims at learning **principal leading eigenvector** (or eigenspace) of the covariance matrix of a distribution from its IID data samples
- Rank-one PCA learns the eigenvector that captures most variance in data
- Wide applications in bioinformatics, healthcare, imaging, computer vision, artificial intelligence, social science, finance, economics, etc.

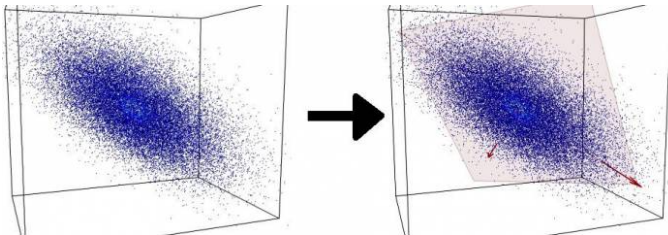


Figure 1: Illustration of PCA

PCA: Formulation

Let \mathbf{X} be a d -dimensional random vector with **mean zero** and unknown **covariance matrix**

$$\Sigma = \mathbb{E}[\mathbf{X}\mathbf{X}^\top] \in \mathbb{R}^{d \times d}$$

Projection of \mathbf{X} onto unit vector \mathbf{u} is $\mathbf{u}^\top \mathbf{X}$

- Rank-one PCA is formulated as a **nonconvex** stochastic optimization problem:

$$\begin{aligned} & \text{minimize} && -\mathbf{u}^\top \mathbb{E}[\mathbf{X}\mathbf{X}^\top] \mathbf{u} \\ & \text{subject to} && \mathbf{u} \in \mathbb{R}^d, \|\mathbf{u}\| = 1 \end{aligned} \tag{PCA}$$

- Nonconvexity due to the **unit spherical constraint**

Assume the eigengap of Σ is **nonzero**, so solution \mathbf{u}^* to (PCA) is unique

PCA Landscape: Simplest Nonconvex Problem?

Let the covariance matrix $\Sigma = \mathbf{O}\mathbf{\Lambda}\mathbf{O}^\top$ be spectral decomposition, $\mathbf{\Lambda}$ diagonal, \mathbf{O} orthogonal. Let $\mathbf{e}_i = (0, \dots, \underbrace{1}_{i^{\text{th}} \text{ coordinate}}, \dots, 0)$ be the i^{th} coordinate vector

The stationary points of PCA landscape ($\geq 2d$ many) are of two types:

- **Global minimizers:** $\pm\mathbf{O}\mathbf{e}_1$;
- **Global maximizers** or **saddle points:** $\pm\mathbf{O}\mathbf{e}_2, \pm\mathbf{O}\mathbf{e}_3, \dots, \pm\mathbf{O}\mathbf{e}_d$ and possibly more, all lying on the equator $\{\mathbf{u} : \mathbf{u}^\top \mathbf{u}^* = 0\}$,

“No spurious local minimizer” (Ge, Lee, Ma, 2016 NIPS)

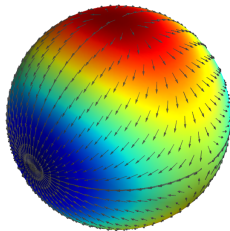


Figure 2: Quiver plot that denotes the negative-gradient directions of PCA

Classical PCA

Classical PCA estimates \mathbf{u}^* using a **sample average approximation** method: find the top eigenvector of $\hat{\Sigma}^{(N)}$

$$\hat{\Sigma}^{(N)} = \frac{1}{N} \sum_{i=1}^N \mathbf{x}^{(i)} \left(\mathbf{x}^{(i)} \right)^{\top}$$

as an estimator of \mathbf{u}^* , based on i.i.d. sample realizations $\mathbf{X}^{(1)}, \dots, \mathbf{X}^{(N)}$

- Classical PCA method produces **non-improvable** solution $\hat{\mathbf{u}}^{(N)}$: estimation error achieves the **minimax information lower bound** (to be discussed later)
- Nevertheless, classical PCA has **suboptimal (on d)** time complexity $\mathcal{O}(Nd^2)$ and space complexity $\mathcal{O}(d^2)$
- When d is large, computing and storing a large empirical covariance matrix is potentially inefficient

Turn to **stochastic approximation** method

Online PCA

We turn to [incremental or online methods](#) for PCA, which updates the iterates incrementally by processing data points one-by-one or [on-the-fly](#)

- The gradient of objective function

$$\frac{\partial}{\partial \mathbf{u}} \left\{ -\mathbf{u}^\top \mathbb{E}[\mathbf{X}\mathbf{X}^\top] \mathbf{u} \right\} = -2\mathbb{E}[\mathbf{X}\mathbf{X}^\top] \mathbf{u}$$

- At step t , stream in data point $\mathbf{X}^{(t)}$ and conduct [projected SGD step](#)

$$\mathbf{u}^{(t)} = \Pi \left\{ \mathbf{u}^{(t-1)} + \eta \mathbf{X}^{(t)} (\mathbf{X}^{(t)})^\top \mathbf{u}^{(t-1)} \right\} \quad (\text{Oja})$$

Here η is positive stepsize, $\Pi \mathbf{u} = \mathbf{u} / \|\mathbf{u}\|$ projects \mathbf{u} onto the unit sphere

- Iteration first proposed by [Oja \(1982\)](#), which only gives almost sure convergence
- Known as online PCA, streaming PCA, or noisy power method ([Hardt & Price, 2014 NIPS](#))

Online PCA

$$\mathbf{u}^{(t)} = \Pi \left\{ \mathbf{u}^{(t-1)} + \eta \mathbf{X}^{(t)} (\mathbf{X}^{(t)})^\top \mathbf{u}^{(t-1)} \right\} \quad (\text{Oja})$$

- 1 Essentially a **stochastic approximation** method for PCA but learns data **on-the-fly**, most applicable to both dimension d and number of samples N being large
- 2 Convergence rate analysis of **(Oja)** remains largely open until very recently. Theoretical challenge is due to the **nonconvex nature**

	Time complexity	Space complexity
Classical PCA	$\mathcal{O}(Nd^2)$	$\mathcal{O}(d^2)$
Oja's iteration	$\mathcal{O}(Nd)$	$\mathcal{O}(d)$

- **Pros:** iteration update requires only vector-vector product operation and stores only $\mathbf{u}^{(t)}$. **Time complexity $\mathcal{O}(Nd)$ and space complexity $\mathcal{O}(d)$**
- **Cons:** Choice of η , unknown convergence rate & initialization

Online PCA: New Convergence Rate Analysis

$$\mathbf{u}^{(t)} = \Pi \left\{ \mathbf{u}^{(t-1)} + \eta \mathbf{X}^{(t)} (\mathbf{X}^{(t)})^\top \mathbf{u}^{(t-1)} \right\} \quad (\text{Oja})$$

Our conclusion in one line ([L.-Wang-Liu-Zhang, 2017 Math. Prog.](#)):

Online PCA is *statistically optimal* and *globally convergent*

- The independent work by [Jain, Jin, Kakade, Netrapalli, & Sidford \(2016 COLT\)](#) also analyzes Oja's iteration and obtains an error bound that matches the [matrix Bernstein's inequality](#) under uniform initialization

Online PCA: Distributional Assumptions

Let the random samples $\mathbf{X} \equiv \mathbf{X}^{(1)}, \dots, \mathbf{X}^{(N)} \in \mathbb{R}^d$ be i.i.d. and satisfy ¹

① (Subgaussian) $\mathbf{X} = \Sigma^{1/2} \mathbf{Z}$ where

\mathbf{Z} is sub-Gaussian with mean zero, covariance matrix \mathbf{I}_d

Subgaussian norm $\|\mathbf{Z}\|_{\psi_2} = \sup_{\|\mathbf{u}\|=1} \|\mathbf{u}^\top \mathbf{Z}\|_{\psi_2} \leq 1$

This allows us to conclude $\mathbb{E}[\mathbf{X}] = \mathbf{0}$ and $\mathbb{E}[\mathbf{X}\mathbf{X}^\top] = \Sigma$

② (Eigengap) The eigenvalues of Σ satisfy $\lambda_1 > \lambda_2 \geq \dots \geq \lambda_d \geq 0$

¹In below the matrix square root $\Sigma^{1/2}$ satisfies $\Sigma^{1/2} \cdot \Sigma^{1/2} = \Sigma$

Theorem (Convergence result, L., Wang, Liu & Zhang, 2017 Math. Prog.)

Suppose the $\mathbf{u}^{(0)}$ is uniformly sampled from the unit sphere, and scaling condition

$$d\eta^{1-\varepsilon} \text{ is sufficiently small}$$

Then for any $\delta > 0$ there is an event \mathcal{A} with $\mathbb{P}(\mathcal{A}) \geq 1 - \delta$ such that the iterates generated by (Oja) satisfy for all $\eta > 0$ sufficiently small and t sufficiently large

$$\mathbb{E} \left[\sin^2 \angle(\mathbf{u}^{(t)}, \mathbf{u}^*) \mid \mathcal{A} \right] \leq \underbrace{C \cdot \delta^{-2} d \cdot (1 - \eta(\lambda_1 - \lambda_2))^{2t}}_{\text{optimization error}} + \underbrace{C \cdot \sum_{k=2}^d \frac{\lambda_1 \lambda_k}{\lambda_1 - \lambda_k} \cdot \eta}_{\text{statistical error}}$$

Corollary (Finite-sample result, L., Wang, Liu & Zhang, 2017 Math. Prog.)

Suppose the $\mathbf{u}^{(0)}$ is uniformly sampled from the unit sphere, and the scaling condition

$d/N^{1-\varepsilon}$ is sufficiently small

Let the stepsize $\eta = \bar{\eta}(N) \asymp \frac{\log N}{(\lambda_1 - \lambda_2)N}$. Then for any $\delta > 0$ there exists an event \mathcal{A} with $\mathbb{P}(\mathcal{A}) \geq 1 - \delta$ such that iterates generated by (Oja) satisfy

$$\mathbb{E} \left[\sin^2 \angle(\mathbf{u}^{(N)}, \mathbf{u}^*) \mid \mathcal{A} \right] \leq C \cdot \frac{\lambda_1}{\lambda_1 - \lambda_2} \sum_{k=2}^d \frac{\lambda_k}{\lambda_1 - \lambda_k} \cdot \frac{\log N}{N}$$

Significance of Our Result

Significance 1: statistical optimality

Oja's iteration produces estimator that **nearly** attains $\tilde{O}(\sqrt{d/N})$ -minimax rate

- Theorem 3.1 of **Vu and Lei (2013)** provides the **minimax information lower bound**:

$$\inf_{\tilde{\mathbf{u}}^{(N)}} \sup_{\mathbf{x} \in \mathcal{M}(\Sigma, d)} \mathbb{E} \left[\sin^2 \angle(\tilde{\mathbf{u}}^{(N)}, \mathbf{u}^*) \right] \geq c \cdot \frac{\lambda_1 \lambda_2}{(\lambda_1 - \lambda_2)^2} \cdot \frac{d - 1}{N}$$

- By choosing the stepsize carefully and under mild scaling assumptions, the output estimator nearly attains such lower bound:

$$\sup_{\mathbf{x} \in \mathcal{M}(\Sigma, d)} \mathbb{E} \left[\sin^2 \angle(\mathbf{u}^{(N)}, \mathbf{u}^*) \mid \mathcal{A} \right] \leq C \cdot \frac{\lambda_1 \lambda_2}{(\lambda_1 - \lambda_2)^2} \cdot \frac{d - 1}{N} \cdot \log N$$

inf of $\tilde{\mathbf{u}}^{(N)}$ is over all principal component estimators, and $\mathcal{M}(\Sigma, d)$ consists of all subgaussian distributions in \mathbb{R}^d with mean $\mathbf{0}$ and positive eigengap $\lambda_1 - \lambda_2$.

Significance of Our Result

Significance 2: global convergence

Finite-sample error bound of Oja's iteration holds under **uniform initialization**

- In contrast, most existing results requires a **good initialization**
 $\left| \sin \angle(\mathbf{u}^{(0)}, \mathbf{u}^*) \right| \leq 1 - \varepsilon$. As dimension d grows, **uniform initialization** does **not** attain such good initialization with high probability, since

$$\left| \sin \angle(\mathbf{u}^{(0)}, \mathbf{u}^*) \right| \approx 1 - C/d$$

- Favorite probability question: **what is the distribution of $\cos \angle(\mathbf{u}^{(0)}, \mathbf{u}^*)$?**

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Online PCA is rotationally invariant

- Let the diagonal decomposition of the covariance matrix be

$$\Sigma = \mathbb{E} [\mathbf{X}\mathbf{X}^\top] = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^\top$$

where $\mathbf{\Lambda} = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_d)$, \mathbf{U} is an orthogonal matrix consisting of column eigenvectors of Σ .

- Rescaled samples $\mathbf{Y}^{(t)} = \mathbf{U}^\top \mathbf{X}^{(t)}$, $\mathbf{v}^{(t)} = \mathbf{U}^\top \mathbf{u}^{(t)}$, $\mathbf{v}^* = \mathbf{U}^\top \mathbf{u}^*$ has

$$\mathbb{E}[\mathbf{Y}] = 0 \quad \mathbb{E} [\mathbf{Y}\mathbf{Y}^\top] = \mathbf{\Lambda} \quad \angle(\mathbf{u}^{(t)}, \mathbf{u}^*) = \angle(\mathbf{v}^{(t)}, \mathbf{v}^*)$$

Study the iteration $\mathbf{v}^{(t)}$: applying the linear transformation \mathbf{U}^\top to the stochastic process $\{\mathbf{u}^{(t)}\}$

$$\mathbf{v}^{(t)} \leftarrow \Pi \left\{ \mathbf{v}^{(t-1)} + \eta \mathbf{Y}^{(t)} (\mathbf{Y}^{(t)})^\top \mathbf{v}^{(t-1)} \right\} \quad (\text{Oja})$$

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Sketch of Proofs: Warm Initialization

Warm initialization: $\left| \sin \angle(\mathbf{v}^{(0)}, \mathbf{v}^*) \right| \leq 1/\sqrt{2}$, “Less than 45 degree”

Let the **rescaled stepsize** $\hat{\eta} = \lambda_1^2(\lambda_1 - \lambda_2)^{-1}\eta$, and rescaled time

$$N_{\eta,s}^* = \left\lceil \frac{s \log(\lambda_1^{-2}(\lambda_1 - \lambda_2)\eta^{-1})}{-\log(1 - \eta(\lambda_1 - \lambda_2))} \right\rceil \asymp s \cdot (\lambda_1 - \lambda_2)^{-1} \eta^{-1} \log(\hat{\eta}^{-1})$$

Assume WLOG Σ is diagonal and suppose $\mathbf{v}^{(0)}$ is a warm initialization. Then each ratio iteration $\mathbf{v}_k^{(t)}/\mathbf{v}_1^{(t)}$ decays geometrically at rate $1 - \eta(\lambda_1 - \lambda_k)$:

$$\mathbf{v}_k^{(t)}/\mathbf{v}_1^{(t)} \approx (1 - \eta(\lambda_1 - \lambda_k))^t \left(\mathbf{v}_k^{(0)}/\mathbf{v}_1^{(0)} \right)$$

We rigorously prove via martingale concentration inequalities that with high probability

$$\sup_{t \leq N_{\eta,s}^*} \left| \mathbf{v}_k^{(t)}/\mathbf{v}_1^{(t)} - (1 - \eta(\lambda_1 - \lambda_k))^t \left(\mathbf{v}_k^{(0)}/\mathbf{v}_1^{(0)} \right) \right| \leq C \hat{\eta}^{0.5-\varepsilon}.$$

This is a **manifestation of strong convergence**

Propositions

Using more careful second moment estimates in the $O(\eta^{0.5})$ neighborhood of the principal component \mathbf{v}^* :

Proposition 2

Assume $\mathbf{v}^{(0)}$ is a warm initialization. When $d\hat{\eta}^{1-2\epsilon}$ is sufficiently small, there exists a high-probability event \mathcal{H}_0 such that for $t \in [N_{\eta,1}^*, N_{\eta,s}^*]$

$$\mathbb{E} \left[\tan^2 \angle(\mathbf{v}^{(t)}, \mathbf{v}^*) ; \mathcal{H}_0 \right] \leq (1 - \eta(\lambda_1 - \lambda_2))^{2t} \tan^2 \angle(\mathbf{v}^{(0)}, \mathbf{v}^*) \\ + C \cdot \sum_{k=2}^d \frac{\lambda_1 \lambda_k + \lambda_1^2 \cdot \hat{\eta}^{0.5-4\epsilon}}{\lambda_1 - \lambda_k} \cdot \eta.$$

Also hold for uniform initialization? Yes! By analyzing the growth of $v_1^{(t)} / \sqrt{1 - (v_1^{(t)})^2}$ via [martingale concentration](#)

Proposition 3

Assume $\mathbf{v}^{(0)}$ is a uniform initialization. When $d\hat{\eta}^{1-2\epsilon}$ is sufficiently small, the time required to enter the warm region \mathcal{N}_c has with high probability

$$\mathcal{N}_c \leq N_{\eta,1}^*$$

Putting pieces together

Lemma

Given any $\delta > 0$, if $\mathbf{u}^{(0)}$ is sampled uniformly at random from S^{d-1} in \mathbb{R}^d then there exists a constant $C^ > 1$ independent of δ and d such that*

$$\mathbb{P} \left(\tan^2 \angle(\mathbf{u}^{(0)}, \mathbf{u}^*) \leq C^* \delta^{-2} d \right) \geq 1 - \delta.$$

- The uniform initialization $\mathbf{v}^{(0)}$ from unit sphere has $\tan^2 \angle(\mathbf{v}^{(0)}, \mathbf{v}^*) \leq c^* d$
- Running the algorithm for $N_\eta^o(c^*) \wedge \mathcal{N}_c < N_{\eta,1}^*$ steps, the iterate $\mathbf{v}^{(N_\eta^o(c^*) \wedge \mathcal{N}_c)}$ is with high probability in the warm region ([Proposition 2](#))
- By [strong Markov property](#) the iterates can be regarded as initialized from warm initialization $\mathbf{v}^{(N_\eta^o(c^*) \wedge \mathcal{N}_c)}$, then apply [Proposition 1](#) to run for another $N_{\eta,1}^*$ steps

Theorem (Convergence result with uniform initialization)

Suppose the $\mathbf{v}^{(0)}$ is uniformly sampled from the unit sphere, and scaling condition

$$d\eta^{1-\varepsilon} \text{ is sufficiently small}$$

Then for any $\delta > 0$ there is an event \mathcal{A} with $\mathbb{P}(\mathcal{A}) \geq 1 - \delta$ such that the iterates generated by (Oja) satisfy for all $\eta > 0$ sufficiently small and $t \in [N_{\eta,2}^*, N_{\eta,s}^*]$

$$\begin{aligned} \mathbb{E} \left[\tan^2 \angle(\mathbf{v}^{(t)}, \mathbf{v}^*) \mid \mathcal{A} \right] &\leq C \cdot \delta^{-2} d \cdot (1 - \eta(\lambda_1 - \lambda_2))^{2t} \\ &\quad + C \cdot \sum_{k=2}^d \frac{\lambda_1 \lambda_k + \lambda_1^2 \cdot \hat{\eta}^{0.5-4\varepsilon}}{\lambda_1 - \lambda_k} \cdot \eta \end{aligned}$$

- Plugging in

$$\eta \equiv \bar{\eta}(N) = \frac{2 \log N}{(\lambda_1 - \lambda_2)N}$$

so $N \approx N_{\bar{\eta}(N),2}^*$ and we obtain the finite-sample error bound:

Corollary (Finite-sample result with uniform initialization)

Suppose the $\mathbf{v}^{(0)}$ is uniformly sampled from the unit sphere, and the scaling condition

$$d/N^{1-\varepsilon} \text{ is sufficiently small}$$

Let the stepsize $\eta = \bar{\eta}(N)$. Then for any $\delta > 0$ there exists an event \mathcal{A} with $\mathbb{P}(\mathcal{A}) \geq 1 - \delta$ such that iterates generated by (Oja) satisfy

$$\mathbb{E} \left[\tan^2 \angle(\mathbf{v}^{(t)}, \mathbf{v}^*) \mid \mathcal{A} \right] \leq C \cdot \frac{\lambda_1}{\lambda_1 - \lambda_2} \sum_{k=2}^d \frac{\lambda_k}{\lambda_1 - \lambda_k} \cdot \frac{\log N}{N}$$

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Differential Equation Approximation

Theorem 1

When $\eta > 0$ is small, Oja's iteration can be approximated by the solution of an **ordinary differential equation (ODE)**, if we use an appropriate temporal scaling

The ODE is

$$\frac{dV_j}{ds} = V_j \sum_{k=1}^d (\lambda_j - \lambda_k) V_k^2, \quad j = 1, \dots, d \quad (\text{ODE})$$

Solution to (ODE) is available in closed-form (**$Z(s)$ be normalizing constant**):

$$V_j(s) = Z(s)^{-1/2} V_j(0) \exp(\lambda_j s)$$

“Generalized logistic curves” or **“Oja's flow”** (Helmke & Moore, 1994)

Differential Equation Approximation

We study how Oja's iteration **escapes from unstable stationary points** and **converges to stable stationary points**:

Theorem 2

When $\eta > 0$ is small and $\mathbf{v}^{(0)} \approx \pm \mathbf{e}_k$, Oja's iteration can be approximated by the solution of a **stochastic differential equation (SDE)**, if we use appropriate temporal and spatial scalings

The SDE is

$$d\mathcal{V}_j = (\lambda_j - \lambda_k)\mathcal{V}_j ds + (\lambda_j\lambda_k)^{1/2}dB_j(s) \quad (\text{SDE})$$

$B_j(s)$ is a standard Brownian motion **"white noise"**

"Ornstein-Uhlenbeck processes" (Uhlenbeck & Ornstein, 1930)

Three-Phase Analysis

Initialized near the equator $\{\mathbf{v} : \|\mathbf{v}\| = 1, v_1 = 0\}$, where all unstable stationary points lie on. Applying Theorems 1 and 2 gives the **three-phase analysis**:

Phase I: escaping from unstable stationary points characterized by **SDE**

Phase II: deterministic crossing characterized by **ODE**

Phase III: local converging characterized by **SDE**

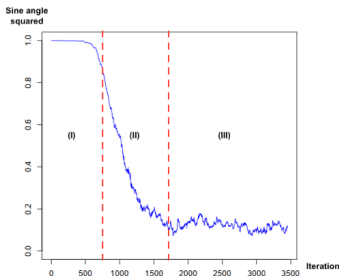
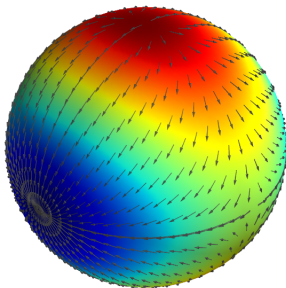


Figure 3: Animation of Oja's iteration; Illustration of three phases of diffusion processes.

Running Time Estimate and Finite-Sample Error Bound

Running time of Oja's iteration in each phase from differential equation approximation:

Phase I: iteration $T_1^\eta \asymp 0.5(\lambda_1 - \lambda_2)^{-1} \cdot \eta^{-1} \log(\eta^{-1})$

Phase II: iteration $T_2^\eta \asymp (\lambda_1 - \lambda_2)^{-1} \cdot \eta^{-1}$

Phase III: iteration $T_3^\eta \asymp 0.5(\lambda_1 - \lambda_2)^{-1} \cdot \eta^{-1} \log(\eta^{-1})$

Total running time $T^\eta = T_1^\eta + T_2^\eta + T_3^\eta \asymp (\lambda_1 - \lambda_2)^{-1} \eta^{-1} \log(\eta^{-1})$

$$\mathbb{E} \sin^2 \angle(\mathbf{v}^{(T^\eta)}, \mathbf{e}_1) \leq C \cdot \sum_{k=2}^d \frac{\lambda_1 \lambda_k}{\lambda_1 - \lambda_k} \cdot \eta$$

Given N samples, choosing $\eta = \bar{\eta}(N) \equiv \frac{\log N}{(\lambda_1 - \lambda_2)N}$ we have $N \asymp T^{\bar{\eta}(N)}$ and

$$\mathbb{E} \sin^2 \angle(\mathbf{v}^{(N)}, \mathbf{e}_1) \leq C \cdot \frac{\lambda_1 \lambda_2}{(\lambda_1 - \lambda_2)^2} \cdot \frac{d-1}{N} \cdot \log N$$

“Heuristically matches the statistical lower bound” (Vu & Lei, 2013 Ann. Stat.)

Summary

We provide a **diffusion approximation** perspective of convergence rate analysis and conclude:

Online **stochastic gradient descent** method for (rank-one) **principal component analysis** is both **statistically optimal** and **globally convergent**

Matching the statistical rate: by choosing the stepsize carefully, Oja's iteration attains $\mathcal{O}(\sqrt{d/N})$ -statistical rate for rank-one PCA

Global initialization: achieves optimal error bounds with **no** restriction on initialization, so can **fastly escape from saddle points**

Epilogue: Future Directions (and Non-Exhaustive Literatures)

- ① Develop and analyze online PCA method for **principal subspace learning** that matches the statistical rate?
- ② **Parallelizing** PCA for online data?
- ③ Extend the analysis beyond PCA to a broader class of **nonconvex statistical estimation problems**?
 - **Tensor decomposition for ICA**: (Ge, Huang, Jin, & Yuan, 2015 COLT) (L., Wang, & Liu, 2016 NIPS) (Wang & Lu, 2017 NIPS)
 - **Sparse PCA** (d'Aspremont, Bach, & El Ghaoui, 2008 JMLR)
 - **Partial least squares** (Chen, Yang, L., & Zhao, 2017 ICML)
 - **Phase retrieval, Dictionary learning** (Sun, Qu, & Wright, arXiv:1510.06096)
 - **Matrix completion & Sensing** (Sun, & Luo, 2014+ IEEE TIT) (Zheng & Lafferty, 2015 NIPS) (Zhao, Wang, & Liu, 2015 NIPS) (Ge, Jin, & Zheng, 2017 ICML)
 - **Deep Learning**: batch size VS generalization

Reference

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